74ABT827

10-bit buffer/line driver; non-inverting; 3-state Rev. 5 — 7 November 2011

Product data sheet

General description 1.

The 74ABT827 high-performance BiCMOS device combines low static and dynamic power dissipation with high speed and high output drive.

The 74ABT827 10-bit buffers provide high performance bus interface buffering for wide data/address paths or buses carrying parity. They have NOR Output Enables (OE0, OE1) for maximum control flexibility.

Features and benefits 2.

- Ideal where high speed, light loading, or increased fan-in are required
- Flow-through pinout architecture for microprocessor oriented applications
- Output capability: +64 mA and –32 mA
- Power-up 3-state
- Inputs are disabled during 3-state mode
- Latch-up protection exceeds 500 mA per JESD78B class II level A
- ESD protection:
 - ◆ HBM JESD22-A114F exceeds 2000 V
 - MM JESD22-A115-A exceeds 200 V

Ordering information 3.

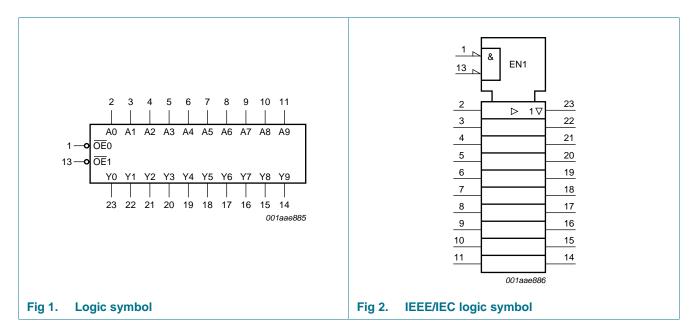
Table 1. **Ordering information**

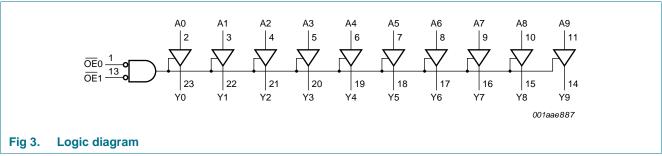
Type number	Package			
	Temperature range	Name	Description	Version
74ABT827D	–40 °C to +85 °C	SO24	plastic small outline package; 24 leads; body width 7.5 mm	SOT137-1
74ABT827DB	–40 °C to +85 °C	SSOP24	plastic shrink small outline package; 24 leads; body width 5.3 mm	SOT340-1
74ABT827PW	–40 °C to +85 °C	TSSOP24	plastic thin shrink small outline package; 24 leads; body width 4.4 mm	SOT355-1



10-bit buffer/line driver; non-inverting; 3-state

4. Functional diagram

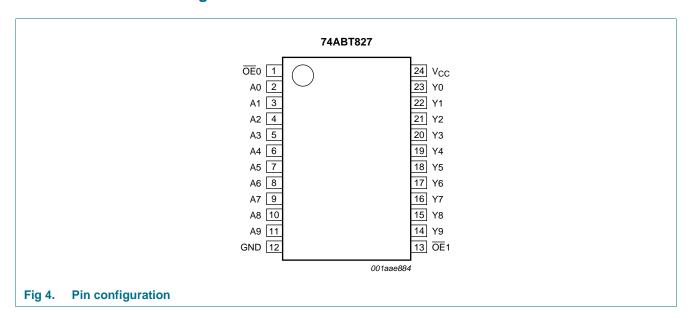




10-bit buffer/line driver; non-inverting; 3-state

5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
OE0	1	output enable input (active LOW)
A0 to A9	2, 3, 4, 5, 6, 7, 8, 9, 10, 11	data input
GND	12	ground (0 V)
OE1	13	output enable input (active LOW)
Y0 to Y9	23, 22, 21, 20, 19, 18, 17, 16, 15, 14	data output
V_{CC}	24	supply voltage

6. Functional description

6.1 Function table

Table 3. Function table[1]

Inputs		Output	Operating mode
OEn	An	Yn	
L	L	L	transparent
L	Н	Н	transparent
Н	X	Z	high-impedance

^[1] H = HIGH voltage level;

L = LOW voltage level;

X = don t care;

Z = high-impedance OFF-state.

74ABT827

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10-bit buffer/line driver; non-inverting; 3-state

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{CC}	supply voltage		-0.5	+7.0	V
VI	input voltage		<u>[1]</u> –1.2	+7.0	V
Vo	output voltage	output in OFF-state or HIGH-state	[<u>1</u>] -0.5	+5.5	V
I _{IK}	input clamping current	V _I < 0 V	-18	-	mA
I _{OK}	output clamping current	V _O < 0 V	-50	-	mA
Io	output current	output in LOW-state	-	128	mA
Tj	junction temperature		[2] _	150	°C
T _{stg}	storage temperature		-65	+150	°C

^[1] The input and output voltage ratings may be exceeded if the input and output current ratings are observed.

8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V_{CC}	supply voltage		4.5	-	5.5	V
VI	input voltage		0	-	V_{CC}	V
V _{IH}	HIGH-level input voltage		2.0	-	-	V
V _{IL}	LOW-level input voltage		-	-	0.8	V
I _{OH}	HIGH-level output current		-32	-	-	mA
I _{OL}	LOW-level output current		-	-	64	mA
Δt/ΔV	input transition rise and fall rate		0	-	5	ns/V
T_{amb}	ambient temperature	in free air	-40	-	+85	°C

^[2] The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures which are detrimental to reliability. The maximum junction temperature of this integrated circuit should not exceed 150 °C.

10-bit buffer/line driver; non-inverting; 3-state

9. Static characteristics

Table 6. Static characteristics

Parameter	Conditions			25 °€		-40 °C to +85 °C		
raiailletei	Conditions		Min		May			Unit
input elemning veltage	V - 4.5.V: L - 19.mA						IVIAA	V
	**		-1.2	-0.9	-	-1.2	-	V
•	=		0.5	0.0		0.5		\ /
· onago								V
							-	V
							-	V
LOW-level output voltage	$V_{CC} = 4.5 \text{ V}; I_{OL} = 64 \text{ mA};$ $V_{I} = V_{IL} \text{ or } V_{IH}$		-	0.42	0.55	-	0.55	V
input leakage current	V_{CC} = 5.5 V; V_I = GND or 5.5 V		-	±0.01	±1.0	-	±1.0	μΑ
power-off leakage current	V_{CC} = 0 V; V_{I} or $V_{O} \le 4.5$ V		-	±5.0	±100	-	±100	μΑ
power-up/power-down output current	$V_{CC} = 2.0 \text{ V}; V_O = \underline{0.5} \text{ V};$ $V_I = \text{GND or } V_{CC}; \overline{\text{OEn HIGH}}$	[1]	-	±5.0	±50	-	±50	μΑ
OFF-state output current	$V_{CC} = 5.5 \text{ V}; V_I = V_{IL} \text{ or } V_{IH}$							
	V _O = 2.7 V		-	5.0	50	-	50	μΑ
	V _O = 0.5 V		-	-5.0	-50	-	-50	μΑ
output leakage current	HIGH-state; $V_O = 5.5 \text{ V}$; $V_{CC} = 5.5 \text{ V}$; $V_I = \text{GND or } V_{CC}$		-	5.0	50	-	50	μΑ
output current	$V_{CC} = 5.5 \text{ V}; V_{O} = 2.5 \text{ V}$	[2]	-180	-80	-50	-180	-50	mΑ
supply current	V_{CC} = 5.5 V; V_I = GND or V_{CC}							
	outputs HIGH-state		-	0.5	250	-	250	μΑ
	outputs LOW-state		-	25	38	-	38	mΑ
	outputs disabled		-	0.5	250	-	250	μΑ
additional supply current	per input pin; V_{CC} = 5.5 V; one input at 3.4 V; other inputs at V_{CC} or GND	[3]						
	outputs enabled		-	0.5	1.5	-	1.5	mΑ
	outputs 3-state, one data input		-	0.01	50	-	50	mΑ
	outputs 3-state; one enable input		-	0.5	1.5	-	1.5	mA
input capacitance	$V_I = 0 \text{ V or } V_{CC}$		-	4	-	-	-	pF
output capacitance	outputs disabled; $V_O = 0 \text{ V}$ or V_{CC}		-	7	-	-	-	pF
	input clamping voltage HIGH-level output voltage LOW-level output voltage input leakage current power-off leakage current power-up/power-down output current OFF-state output current output leakage current aupply current additional supply current	input clamping voltage $V_{CC} = 4.5 \text{ V}; I_{IK} = -18 \text{ mA}$ $V_{IGH} = V_{IL} \text{ or } V_{IH}$ $V_{CC} = 4.5 \text{ V}; I_{OH} = -3 \text{ mA}$ $V_{CC} = 5.0 \text{ V}; I_{OH} = -3 \text{ mA}$ $V_{CC} = 4.5 \text{ V}; I_{OH} = -3 \text{ mA}$ $V_{CC} = 4.5 \text{ V}; I_{OH} = -32 \text{ mA}$ $V_{CC} = 4.5 \text{ V}; I_{OH} = -32 \text{ mA}$ $V_{CC} = 4.5 \text{ V}; I_{OH} = -32 \text{ mA}$ $V_{CC} = 4.5 \text{ V}; I_{OH} = 64 \text{ mA}; V_{I} = V_{IL} \text{ or } V_{IH}$ input leakage current $V_{CC} = 5.5 \text{ V}; V_{I} = \text{GND or } 5.5 \text{ V}$ power-off leakage current $V_{CC} = 0 \text{ V}; V_{I} \text{ or } V_{O} = 4.5 \text{ V}$ $V_{I} = \text{GND or } V_{CC}; \text{OEn HIGH}$ $V_{CC} = 2.0 \text{ V}; V_{I} \text{ or } V_{IL} \text{ or } V_{IH}$ $V_{CC} = 5.5 \text{ V}; V_{I} = V_{IL} \text{ or } V_{IH}$ $V_{CC} = 5.5 \text{ V}; V_{I} = V_{IL} \text{ or } V_{IH}$ $V_{CC} = 5.5 \text{ V}; V_{I} = V_{IL} \text{ or } V_{IH}$ $V_{CC} = 5.5 \text{ V}; V_{I} = \text{GND or } V_{CC}$ output current $V_{CC} = 5.5 \text{ V}; V_{I} = \text{GND or } V_{CC}$ output current $V_{CC} = 5.5 \text{ V}; V_{I} = \text{GND or } V_{CC}$ outputs HIGH-state outputs LOW-state outputs LOW-state outputs LOW-state outputs disabled $V_{CC} = 0 \text{ Or } V_{CC} = 0 \text{ Or } V_{C$	$ Input clamping voltage V_{CC} = 4.5 \text{ V; } I_{IK} = -18 \text{ mA} V_{IC} = 4.5 \text{ V; } I_{IK} = -18 \text{ mA} V_{IC} = 4.5 \text{ V; } I_{IK} = -18 \text{ mA} V_{IC} = 4.5 \text{ V; } I_{OH} = -3 \text{ mA} V_{CC} = 4.5 \text{ V; } I_{OH} = -3 \text{ mA} V_{CC} = 4.5 \text{ V; } I_{OH} = -3 \text{ mA} V_{CC} = 4.5 \text{ V; } I_{OH} = -32 \text{ mA} V_{CC} = 4.5 \text{ V; } I_{OH} = -32 \text{ mA} V_{IC} = 4.5 \text{ V; } I_{OH} = 64 \text{ mA; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10 \text{ V; } V_{IC} = 10$	$ Input clamping voltage V_{CC} = 4.5 \ V; \ I_{IK} = -18 \ mA $		N N N N N N N N N	Normal Normal	Note Note

^[1] This parameter is valid for any V_{CC} between 0 V and 2.1 V with a transition time of up to 10 ms. For V_{CC} = 2.1 V to V_{CC} = 5 V \pm 10 %, a transition time of up to 100 μ s is permitted.

^[2] Not more than one output should be tested at a time, and the duration of the test should not exceed one second.

^[3] This is the increase in supply current for each input at 3.4 V.

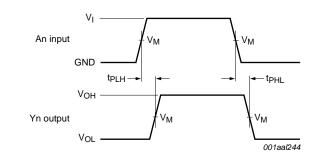
10-bit buffer/line driver; non-inverting; 3-state

10. Dynamic characteristics

Table 7. Dynamic characteristics GND = 0 *V; for test circuit, see <u>Figure 7.</u>*

Symbol	Parameter	Conditions		25 °C; _C = 5.0		-40 °C to V _{CC} = 5.0	+85 °C; V ± 0.5 V	Unit
			Min	Тур	Max	Min	Max	
t_{PLH}	LOW to HIGH propagation delay	An to Yn; see Figure 5	1.1	3.0	4.4	1.1	4.8	ns
t _{PHL}	HIGH to LOW propagation delay	An to Yn; see Figure 5	1.1	2.9	4.1	1.1	4.7	ns
t _{PZH}	OFF-state to HIGH propagation delay	OEn to Yn; see Figure 6	1.6	3.7	5.1	1.6	5.9	ns
t _{PZL}	OFF-state to LOW propagation delay	OEn to Yn; see Figure 6	2.6	4.6	5.9	2.6	6.9	ns
t _{PHZ}	HIGH to OFF-state propagation delay	OEn to Yn; see Figure 6	2.0	4.8	6.3	2.0	6.8	ns
t _{PLZ}	LOW to OFF-state propagation delay	OEn to Yn; see Figure 6	2.5	5.1	6.6	2.5	6.9	ns

11. Waveforms

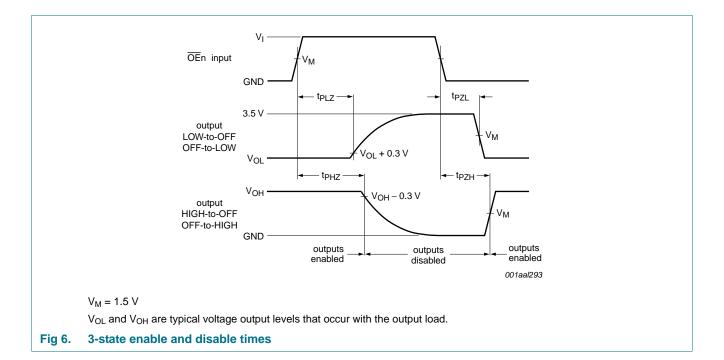


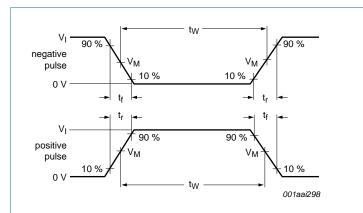
V_M = 1.5 V

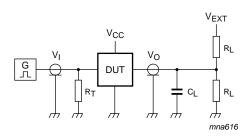
 V_{OL} and V_{OH} are typical voltage output levels that occur with the output load.

Fig 5. Propagation delay input (An) to output (Yn)

10-bit buffer/line driver; non-inverting; 3-state







a. Input pulse definition

b. Test circuit

Test data and V_{EXT} levels are given in <u>Table 8</u>.

 R_L = Load resistance.

 C_L = Load capacitance including jig and probe capacitance.

 R_T = Termination resistance should be equal to output impedance Z_o of the pulse generator.

 V_{EXT} = Test voltage for switching times.

Fig 7. Test circuit for measuring switching times

Table 8. Test data

Input				Load		V _{EXT}		
V_{l}	f _l	f _I t _W		CL	R_L	t _{PHL} , t _{PLH}	t _{PZH} , t _{PHZ}	t _{PZL} , t _{PLZ}
3.0 V	1 MHz	500 ns	\leq 2.5 ns	50 pF	500Ω	open	open	7.0 V

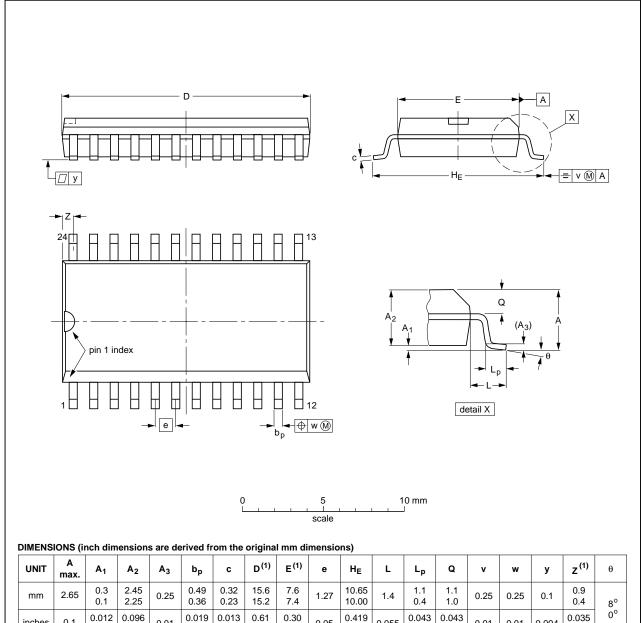
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12. Package outline

SO24: plastic small outline package; 24 leads; body width 7.5 mm

SOT137-1



inches

Note 1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

0.014

0.009

0.01

0.089

OUTLINE		REFER	ENCES	EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE
SOT137-1	075E05	MS-013			-99-12-27 03-02-19

0.05

0.055

0.016

0.394

0.01

0.01

0.004

Package outline SOT137-1 (SO24) Fig 8.

74ABT827

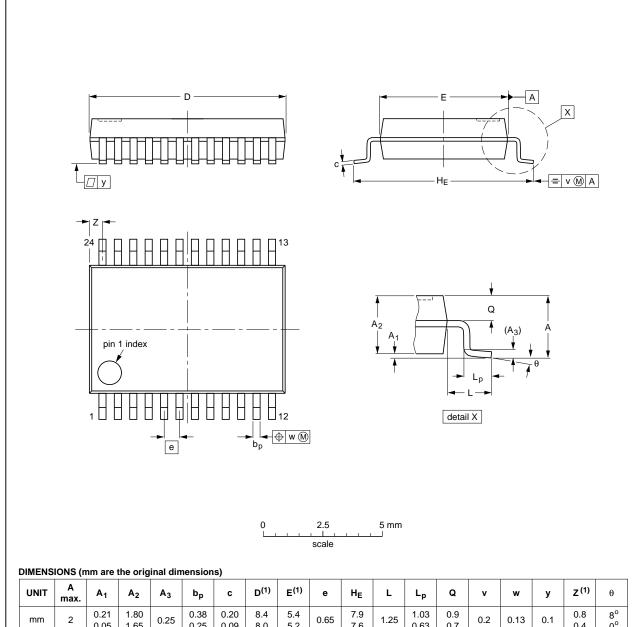
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10-bit buffer/line driver; non-inverting; 3-state

SSOP24: plastic shrink small outline package; 24 leads; body width 5.3 mm

SOT340-1



UNIT	A max.	A ₁	A ₂	A ₃	bp	C	D ⁽¹⁾	E ⁽¹⁾	Ф	HE	L	Lp	ø	v	w	у	Z ⁽¹⁾	θ
mm	2	0.21 0.05	1.80 1.65	0.25	0.38 0.25	0.20 0.09	8.4 8.0	5.4 5.2	0.65	7.9 7.6	1.25	1.03 0.63	0.9 0.7	0.2	0.13	0.1	0.8 0.4	8° 0°

Note

1. Plastic or metal protrusions of 0.2 mm maximum per side are not included.

OUTLINE		REFER	ENCES	EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE
SOT340-1		MO-150			99-12-27 03-02-19

Fig 9. Package outline SOT340-1 (SSOP24)

74ABT827

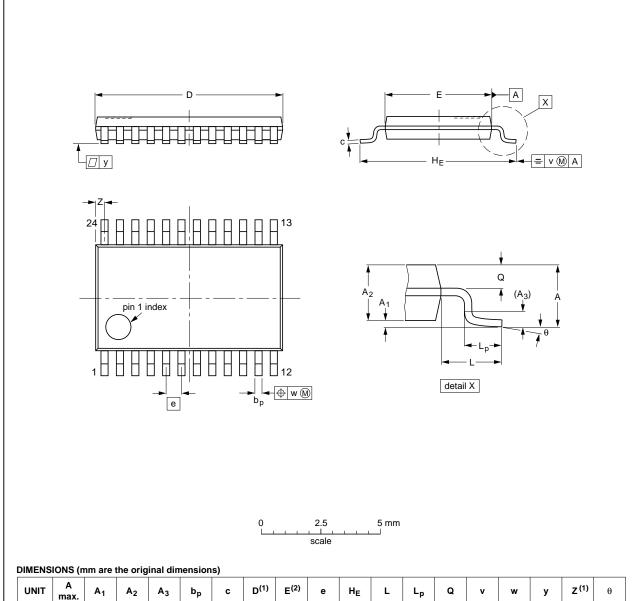
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10-bit buffer/line driver; non-inverting; 3-state

TSSOP24: plastic thin shrink small outline package; 24 leads; body width 4.4 mm

SOT355-1



						٠,												
UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	Q	v	w	у	Z ⁽¹⁾	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	7.9 7.7	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.5 0.2	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

IEC JEI)FC				ISSUE DATE
)EC .	JEITA		PROJECTION	,
МО	-153				-99-12-27 03-02-19
	МО	MO-153	MO-153	MO-153	MO-153

Fig 10. Package outline SOT355-1 (TSSOP24)

74ABT82

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10-bit buffer/line driver; non-inverting; 3-state

13. Abbreviations

Table 9. Abbreviations

Acronym	Description
BiCMOS	Bipolar Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model

14. Revision history

Table 10. Revision history

Release date	Data sheet status	Change notice	Supersedes
20111107	Product data sheet	-	74ABT827 v.4
• Legal pages u	updated.		
20100401	Product data sheet	-	74ABT827 v.3
20100224	Product data sheet	-	74ABT827 v.2
19980116	Product specification	-	74ABT827 v.1
19950906	Product specification	-	-
	• Legal pages (20100401 20100224 19980116	 Legal pages updated. 20100401 Product data sheet 20100224 Product data sheet 19980116 Product specification 	 Legal pages updated. 20100401 Product data sheet - 20100224 Product data sheet - 19980116 Product specification -

10-bit buffer/line driver; non-inverting; 3-state

15. Legal information

15.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

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10-bit buffer/line driver; non-inverting; 3-state

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17. Contents

1	General description 1
2	Features and benefits
3	Ordering information 1
4	Functional diagram 2
5	Pinning information 3
5.1	Pinning
5.2	Pin description
6	Functional description 3
6.1	Function table
7	Limiting values 4
8	Recommended operating conditions 4
9	Static characteristics 5
10	Dynamic characteristics 6
11	Waveforms 6
12	Package outline 8
13	Abbreviations
14	Revision history 11
15	Legal information
15.1	Data sheet status
15.2	Definitions 12
15.3	Disclaimers
15.4	Trademarks13
16	Contact information
17	Contents

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