

General Description

The 9DMV0441 is a member of IDT's SOC-Friendly 1.8V Very-Low-Power (VLP) PCIe Gen1-2-3 family. It has integrated output terminations providing $Z_o=100\Omega$ for direct connection to 100Ω transmission lines. Each of the 4 outputs has its own dedicated OE# pin for optimal system control and power management. The part provides asynchronous and glitch-free switching modes.

Recommended Application

2:4 PCIe Gen1-2-3 Clock Multiplexer

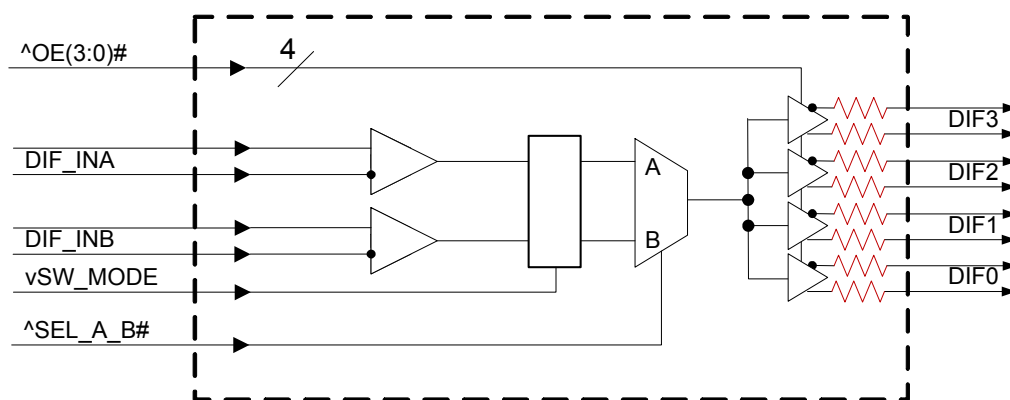
Output Features

- 4 -Low-Power (LP) HCSL DIF pairs w/ $Z_o=100\Omega$

Key Specifications

- DIF *additive* cycle-to-cycle jitter <5ps
- DIF phase jitter is PCIe Gen1-2-3 compliant
- Additive phase jitter @ 125MHz: 420fs rms typical (12kHz to 20MHz)
- DIF output-to-output skew <50ps

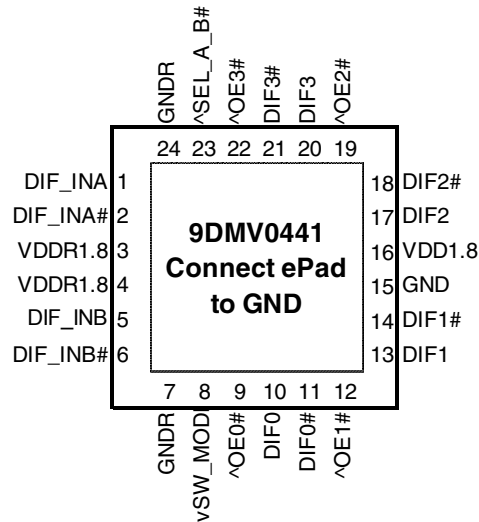
Block Diagram



Features/Benefits

- LP-HCSL outputs w/integrated terminations; saves 16 resistors compared to standard HCSL outputs
- 1.8V operation; 36mW typical power consumption
- Selectable asynchronous or glitch-free switching; allows the mux to be selected at power up even if both inputs are not running, then transition to glitch-free switching mode
- Spread Spectrum Compatible; supports EMI reduction
- OE# pins; support DIF power management
- HCSL differential inputs; can be driven by common clock sources
- 1MHz to 200MHz operating frequency
- Space saving 24-pin 4x4mm VFQFPN; minimal board space

Pin Configuration



24 VFQFPN, 4x4 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor
v prefix indicates internal 120KOhm pull down resistor

Power Management Table

OEx# Pin	DIF_IN	DIFx	
		True O/P	Comp. O/P
0	Running	Running	Running
1	Running	Low	Low

Power Connections

Pin Number		Description
VDD	GND	
3	24	Input A receiver analog
4	7	Input B receiver analog
16	15	DIF outputs

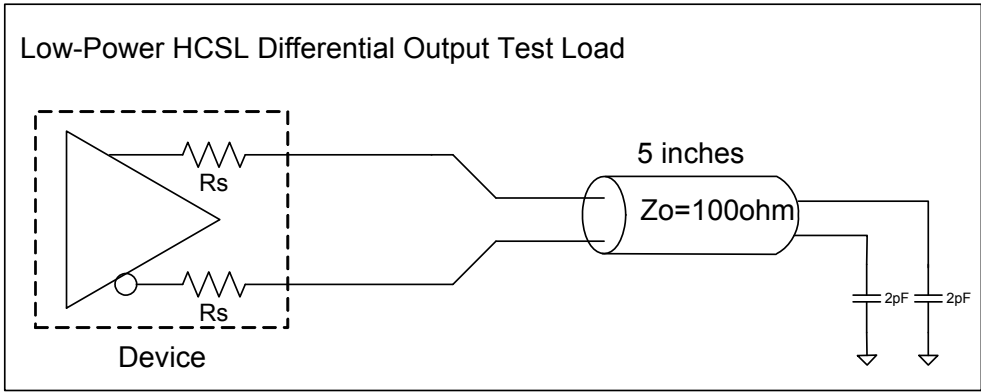
Pin Descriptions

Pin#	Pin Name	Type	Pin Description
1	DIF_INA	IN	HCSL Differential True input
2	DIF_INA#	IN	HCSL Differential Complement Input
3	VDDR1.8	PWR	1.8V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.
4	VDDR1.8	PWR	1.8V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.
5	DIF_INB	IN	HCSL Differential True input
6	DIF_INB#	IN	HCSL Differential Complement Input
7	GNDR	GND	Analog Ground pin for the differential input (receiver)
8	vSW_MODE	IN	Switch Mode. This pin selects either asynchronous or glitch-free switching of the mux. Use asynchronous mode if 0 or 1 of the input clocks is running. Use glitch-free mode if both input clocks are running. This pin has an internal pull down resistor of ~120kohms. 0 = asynchronous mode 1 = glitch-free mode
9	^OE0#	IN	Active low input for enabling DIF pair 0. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs
10	DIF0	OUT	Differential true clock output
11	DIF0#	OUT	Differential Complementary clock output
12	^OE1#	IN	Active low input for enabling DIF pair 1. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs
13	DIF1	OUT	Differential true clock output
14	DIF1#	OUT	Differential Complementary clock output
15	GND	GND	Ground pin.

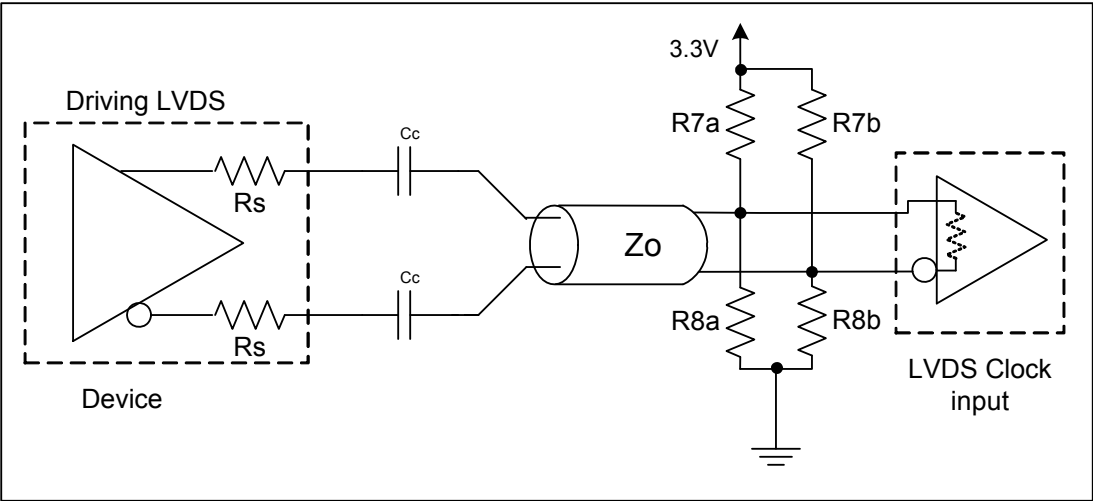
Pin Descriptions (cont.)

Pin#	Pin Name	Type	Pin Description
16	VDD1.8	PWR	Power supply, nominal 1.8V
17	DIF2	OUT	Differential true clock output
18	DIF2#	OUT	Differential Complementary clock output
19	^OE2#	IN	Active low input for enabling DIF pair 2. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs
20	DIF3	OUT	Differential true clock output
21	DIF3#	OUT	Differential Complementary clock output
22	^OE3#	IN	Active low input for enabling DIF pair 3. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs
23	^SEL_A_B#	IN	Input to select differential input clock A or differential input clock B. This input has an internal pull-up resistor. 0 = Input B selected, 1 = Input A selected.
24	GNDR	GND	Analog Ground pin for the differential input (receiver)
25	EPAD	GND	Connect to Ground.

Test Loads



Driving LVDS



Driving LVDS inputs

Component	Value		Note
	Receiver has termination	Receiver does not have termination	
R7a, R7b	10K ohm	140 ohm	
R8a, R8b	5.6K ohm	75 ohm	
Cc	0.1 uF	0.1 uF	
Vcm	1.2 volts	1.2 volts	

Electrical Characteristics–Absolute Maximum Ratings

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDxx	Applies to all VDD	-0.5		2.5	V	1,2
Input Voltage	V _{IN}		-0.5		V _{DD} +0.5V	V	1, 3
Input High Voltage, SMBus	V _{IHSMB}	SMBus clock and data pins			3.6V	V	1
Storage Temperature	T _s		-65		150	°C	1
Junction Temperature	T _j				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

²Operation under these conditions is neither implied nor guaranteed.

³Not to exceed 2.5V.

Electrical Characteristics–Input/Supply/Common Parameters–Normal Operating Conditions

T_A = T_{AMB}, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDxx	Applies to all VDD	1.7	1.8	1.9	V	1
Ambient Operating Temperature	T _{AMB}	Industrial range	-40	25	85	°C	1
Input High Voltage	V _{IH}	Single-ended inputs, except SMBus	0.75 V _{DD}		V _{DD} + 0.3	V	1
Input Low Voltage	V _{IL}	Single-ended inputs, except SMBus	-0.3		0.25 V _{DD}	V	1
Input Current	I _{IN}	Single-ended inputs, V _{IN} = GND, V _{IN} = VDD	-5		5	uA	1
	I _{INP}	Single-ended inputs V _{IN} = 0 V; Inputs with internal pull-up resistors V _{IN} = VDD; Inputs with internal pull-down resistors	-200		200	uA	1
Input Frequency	F _{ibyp}		1		200	MHz	1
Pin Inductance	L _{pin}				7	nH	1
Capacitance	C _{IN}	Logic Inputs, except DIF_IN	1.5		5	pF	1
	C _{INDIF_IN}	DIF_IN differential clock inputs	1.5		2.7	pF	1,4
	C _{OUT}	Output pin capacitance			6	pF	1
Input SS Modulation Frequency	f _{MODIN}	Allowable Frequency (Triangular Modulation)	0	31.5	66	kHz	1
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	1		3	clocks	1,3
T _{fall}	t _F	Fall time of single-ended control inputs			5	ns	1,2
T _{rise}	t _R	Rise time of single-ended control inputs			5	ns	1,2

¹Guaranteed by design and characterization, not 100% tested in production.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

⁴DIF_IN input

Electrical Characteristics–Clock Input Parameters

TA = T_{AMB}, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage - DIF_IN	V _{IHDIF}	Differential inputs (single-ended measurement)	300	750	1150	mV	1
Input Low Voltage - DIF_IN	V _{ILDIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	0	300	mV	1
Input Common Mode Voltage - DIF_IN	V _{COM}	Common Mode Input Voltage	200		725	mV	1
Input Amplitude - DIF_IN	V _{SWING}	Peak to Peak value (V _{IHDIF} - V _{ILDIF})	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.35		8	V/ns	1,2
Input Leakage Current	I _{IN}	V _{IN} = V _{DD} , V _{IN} = GND	-5		5	uA	
Input Duty Cycle	d _{in}	Measurement from differential waveform	45	50	55	%	1
Input Jitter - Cycle to Cycle	J _{DIFn}	Differential Measurement	0		150	ps	1

¹ Guaranteed by design and characterization, not 100% tested in production.

² Slew rate measured through +/-75mV window centered around differential zero

Electrical Characteristics–DIF Low-Power HCSL Outputs

TA = T_{AMB}, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	Trf	Scope averaging on	2.0	3.0	4.4	V/ns	1,2,3
Slew rate matching	ΔTrf	Slew rate matching, Scope averaging on		3	20	%	1,2,4
Voltage High	V _{HIGH}	Statistical measurement on single-ended signal using oscilloscope math function. (Scope averaging on)	660	783	850	mV	
Voltage Low	V _{LOW}		-150	26	150		
Max Voltage	V _{max}	Measurement on single ended signal using absolute value. (Scope averaging off)		790	1150	mV	
Min Voltage	V _{min}		-300	9			
Vswing	Vswing	Scope averaging off	300	1514		mV	1,2
Crossing Voltage (abs)	V _{cross_abs}	Scope averaging off	250	393	550	mV	1,5
Crossing Voltage (var)	ΔV _{cross}	Scope averaging off		12	140	mV	1,6

¹ Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ V_{cross} is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all V_{cross} measurements in any particular system. Note that this is a subset of V_{cross_min/max} (V_{cross} absolute) allowed. The intent is to limit V_{cross} induced modulation by setting ΔV_{cross} to be smaller than V_{cross} absolute.

Electrical Characteristics–Current Consumption

TA = T_{AMB}, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Operating Supply Current	I _{DDOP}	VDD rails, All outputs active @100MHz		20	28	mA	
Disable Current	I _{DDIS}	VDD rails, All outputs disabled Low/Low		1.5	2.5	mA	2

¹ Guaranteed by design and characterization, not 100% tested in production.

² Input clock stopped after outputs have parked Low/Low.

Electrical Characteristics–Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T_{AMB}, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Duty Cycle Distortion	t _{DCD}	Measured differentially, Bypass Mode @100MHz	-1	-0.12	1	%	1,3
Skew, Input to Output	t _{pdBYP}	V _T = 50%	1850	2409	3150	ps	1
Skew, Output to Output	t _{sk3}	V _T = 50%		12	50	ps	1
Jitter, Cycle to cycle	t _{jcy-cyc}	Additive Jitter		0.1	5	ps	1,2

¹ Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Duty cycle distortion is the difference in duty cycle between the output and the input clock .

Electrical Characteristics–Phase Jitter Parameters

TA = T_{AMB}, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	INDUSTRY LIMIT	UNITS	Notes
Additive Phase Jitter, Bypass Mode	t _{jphPCleG1}	PCle Gen 1		1.3	5	N/A	ps (p-p)	1,2,3,5
	t _{jphPCleG2}	PCle Gen 2 Lo Band 10kHz < f < 1.5MHz		0.1	0.3	N/A	ps (rms)	1,2,3,4,5
		PCle Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.1	0.2	N/A	ps (rms)	1,2,3,4
	t _{jphPCleG3}	PCle Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.065	0.1	N/A	ps (rms)	1,2,3,4
	t _{jph125M0}	125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		285	300	N/A	fs (rms)	1,6
	t _{jph125M1}	125MHz, 12KHz to 20MHz, -20dB/decade rollover < 12kHz, -40db/decade rolloff > 20MHz		420	450	N/A	fs (rms)	1,6

¹ Guaranteed by design and characterization, not 100% tested in production.

² See <http://www.pcisig.com> for complete specs

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

⁴ For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)² - (input jitter)²]

⁵ Driven by 9FGV0831 or equivalent

⁶ Driven by Rohde& Schartz SMA100

Marking Diagram



Notes:

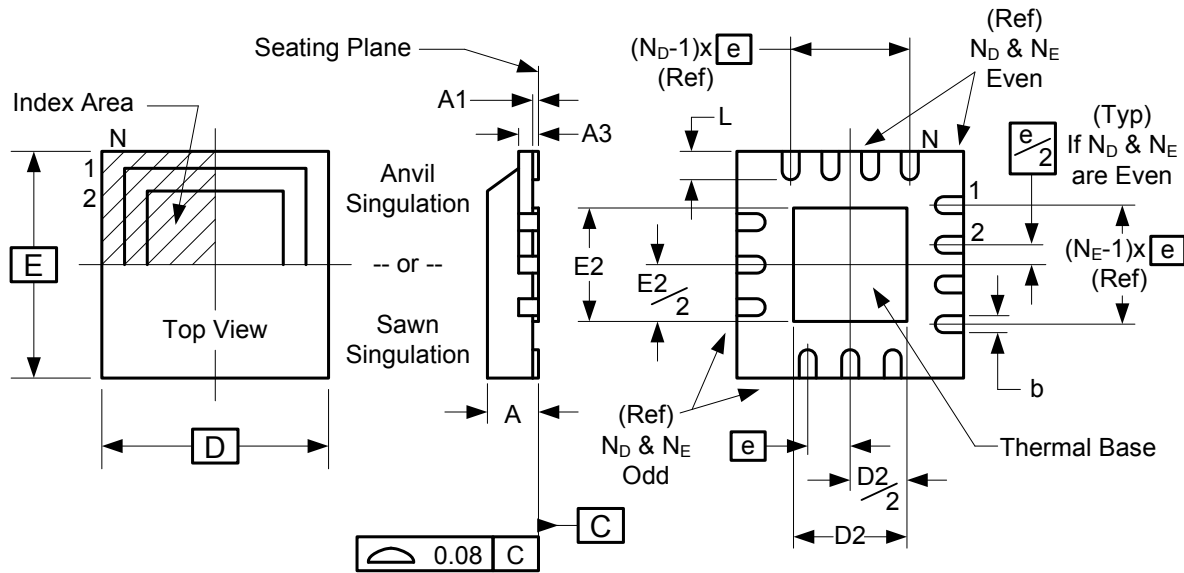
- 1. “LOT” denotes the lot number.
- 2. “YYWW” is the last two digits of the year and week that the part was assembled.
- 3. Line 2: truncated part number
- 4. “L” denotes RoHS compliant package.
- 5. “I” denotes industrial temperature grade.

Thermal Characteristics

PARAMETER	SYMBOL	CONDITIONS	PKG	TYP VALUE	UNITS	NOTES
Thermal Resistance	θ_{JC}	Junction to Case	NLG24	42	°C/W	1
	θ_{Jb}	Junction to Base		2.4	°C/W	1
	θ_{JA0}	Junction to Air, still air		39	°C/W	1
	θ_{JA1}	Junction to Air, 1 m/s air flow		33	°C/W	1
	θ_{JA3}	Junction to Air, 3 m/s air flow		28	°C/W	1
	θ_{JA5}	Junction to Air, 5 m/s air flow		27	°C/W	1

¹ePad soldered to board

Package Outline and Package Dimensions (NLG24)



Symbol	Millimeters	
	Min	Max
A	0.80	1.00
A1	0	0.05
A3	0.25 Reference	
b	0.18	0.30
e	0.50 BASIC	
D x E BASIC	4.00 x 4.00	
D2 MIN./MAX.	2.3	2.55
E2 MIN./MAX.	2.3	2.55
L MIN./MAX.	0.30	0.50
N	24	
ND	6	
NE	6	

Ordering Information

Part / Order Number	Shipping Packaging	Package	Temperature
9DMV0441AKILF	Tubes	24-pin VFQFPN	-40 to +85° C
9DMV0441AKILFT	Tape and Reel	24-pin VFQFPN	-40 to +85° C

"LF" to the suffix denotes Pb-Free configuration, RoHS compliant.

"A" is the device revision designator (will not correlate with the datasheet revision).

Revision History

Rev.	Initiator	Issue Date	Description	Page #
A	RDW	9/24/2014	1. Updated Electrical Tables with Char data 2. Updated General Description 3. Move to final	Various



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