

# 12-Bit, 1 GSPS/500 MSPS JESD204B, Dual Analog-to-Digital Converter

Data Sheet AD9234

#### **FEATURES**

JESD204B (Subclass 1) coded serial digital outputs
1.5 W total power per channel at 1 GSPS (default settings)
SEDR

79 dBFS at 340 MHz (1 GSPS) 86 dBFS at 340 MHz (500 MSPS)

**SNR** 

63.4 dBFS at 340 MHz ( $A_{IN} = -1.0$  dBFS, 1 GSPS)

65.6 dBFS at 340 MHz ( $A_{IN} = -1.0 dBFS$ , 500 MSPS)

ENOB = 10.4 bits at 10 MHz

DNL =  $\pm 0.16$  LSB; INL =  $\pm 0.35$  LSB

**Noise density** 

-151 dBFS/Hz (1 GSPS)

-150 dBFS/Hz (500 MSPS)

1.25 V, 2.5 V, and 3.3 V dc supply operation

Low swing full scale input

1.34 V p-p nominal (1 GSPS)

1.63 V p-p nominal (500 MSPS)

No missing codes

Internal ADC voltage reference

Flexible termination impedance

400  $\Omega$ , 200  $\Omega$ , 100  $\Omega$ , and 50  $\Omega$  differential

2 GHz usable analog input full power bandwidth

95 dB channel isolation/crosstalk

**Amplitude detect bits for efficient AGC implementation** 

Differential clock input

Optional decimate-by-2 DDC per channel

Differential clock input

Integer clock divide by 1, 2, 4, or 8

Flexible JESD204B lane configurations

Small signal dither

## **APPLICATIONS**

**Communications** 

Diversity multiband, multimode digital receivers

3G/4G, TD-SCDMA, W-CDMA, GSM, LTE

Point-to-point radio systems

Digital predistortion observation path

**General-purpose software radios** 

Ultrawideband satellite receiver

Instrumentation (spectrum analyzers, network analyzers,

integrated RF test solutions)

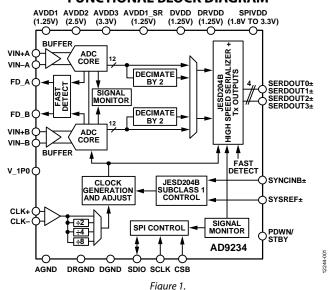
**Digital oscilloscopes** 

High speed data acquisition systems

**DOCSIS 3.0 CMTS upstream receive paths** 

HFC digital reverse path receivers

### **FUNCTIONAL BLOCK DIAGRAM**



## **PRODUCT HIGHLIGHTS**

- 1. Low power consumption analog core, 12-bit, 1.0 GSPS dual analog-to-digital converter (ADC) with 1.5 W per channel.
- 2. Wide full power bandwidth supports IF sampling of signals up to 2 GHz.
- 3. Buffered inputs with programmable input termination eases filter design and implementation.
- 4. Flexible serial port interface (SPI) controls various product features and functions to meet specific system requirements.
- 5. Programmable fast overrange detection.
- 6. 9 mm  $\times$  9 mm 64-lead LFCSP.
- Pin compatible with the AD9680 14-bit, 1 GSPS/500 MSPS dual ADC.

Rev. A

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• AD9680/AD9234/AD9690 Evaluation Board

## Documentation <a>□</a>

## **Data Sheet**

• AD9234: 12-Bit, 1 GSPS JESD204B, Dual Analog-to-Digital Converter Data Sheet

## Tools and Simulations

• AD9234 IBIS Model

## Reference Materials

## **Technical Articles**

• Clocking Wideband GSPS JESD204B ADCs

# Design Resources <a> □</a>

- AD9234 Material Declaration
- · PCN-PDN Information
- · Quality And Reliability
- · Symbols and Footprints

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**Data Sheet** 

# AD9234

# **TABLE OF CONTENTS**

Features	1
Applications	1
Functional Block Diagram	1
Product Highlights	1
Revision History	3
General Description	4
Specifications	5
DC Specifications	5
AC Specifications	6
Digital Specifications	8
Switching Specifications	9
Timing Specifications	9
Absolute Maximum Ratings1	1
Thermal Characteristics	1
ESD Caution1	1
Pin Configuration and Function Descriptions1	2
Typical Performance Characteristics	4
AD9234-10001	4
AD9234-5001	8
Equivalent Circuits	2
Theory of Operation	4
ADC Architecture	4
Analog Input Considerations2	4
Voltage Reference	7
Clock Input Considerations	8
Power-Down/Standby Mode2	9
Temperature Diode2	9
ADC Overrange and Fast Detect	0
ADC Overrange3	0
Fast Threshold Detection (FD_A and FD_B)3	0
Signal Monitor	1

Digital Downconverter (DDC)
DDC General Description34
Half-Band Filter35
DDC Gain Stage
DDC Complex to Real Conversion
Digital Outputs
Introduction to the JESD204B Interface
JESD204B Overview
Functional Overview
JESD204B Link Establishment
Physical Layer (Driver) Outputs41
Configuring the JESD204B Link
Multichip Synchronization
SYSREF± Setup/Hold Window Monitor
Test Modes
ADC Test Modes50
JESD204B Block Test Modes51
Serial Port Interface
Configuration Using the SPI53
Hardware Interface
SPI Accessible Features
Memory Map
Reading the Memory Map Register Table54
Memory Map Register Table55
Without With Register Table
Applications Information
, , ,
Applications Information
Applications Information
Applications Information

## **REVISION HISTORY**

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Added AD9234-500	Universal
Changes to Features Section	1
Changes to Table 1	5
Changes to Table 2	6
Changes to Table 4	9
Changes to Table 6, Thermal Characteristics Section, as	nd
Table 7	11
Added AD9234-500 Section and Figure 29 to Figure 51	18
Changes to Figure 63 and Figure 64 Captions, Analog I	
Controls and SFDR Optimization Section, and Figure 6	-
Changes to Figure 70 and Figure 71	
Changes to Voltage Referece Section	

Changes to Figure 79	28
Changes to Figure 80	29
Changes to Figure 91	38
Changes to DDC General Description Section	34
Added Example 2: Full Bandwidth Mode at 500 MSPS Section.	44
Added Test Modes Section and Table 15 to Table 19	
Changes to Table 22	
Changes to Power Supply Recommendations Section and	
Figure 106	65
Changes to Ordering Guide	
0 0	

## 8/14—Revision 0: Initial Version

## **GENERAL DESCRIPTION**

The AD9234 is a dual, 12-bit, 1 GSPS/500 MSPS ADC. The device has an on-chip buffer and sample-and-hold circuit designed for low power, small size, and ease of use. This product is designed for sampling wide bandwidth analog signals. The AD9234 is optimized for wide input bandwidth, high sampling rate, excellent linearity, and low power in a small package.

The dual ADC cores feature a multistage, differential pipelined architecture with integrated output error correction logic. Each ADC features wide bandwidth buffered inputs supporting a variety of user-selectable input ranges. An integrated voltage reference eases design considerations. Each ADC data output is internally connected to an optional decimate-by-2 block.

The AD9234 has several functions that simplify the automatic gain control (AGC) function in a communications receiver. The programmable threshold detector allows monitoring of the incoming signal power using the fast detect output bits of the ADC. If the input signal level exceeds the programmable threshold, the fast detect indicator goes high. Because this threshold indicator has low latency, the user can quickly turn

down the system gain to avoid an overrange condition at the ADC input. In addition to the fast detect outputs, the AD9234 also offers signal monitoring capability. The signal monitoring block provides additional information about the signal being digitized by the ADC.

Users can configure the Subclass 1 JESD204B-based high speed serialized output in a variety of one-, two-, or four-lane configurations, depending on the acceptable lane rate of the receiving logic device and the sampling rate of the ADC. Multiple device synchronization is supported through the SYSREF± and SYNCINB± input pins.

The AD9234 has flexible power-down options that allow significant power savings when desired. All of these features can be programmed using a 1.8 V to 3.3 V capable 3-wire SPI.

The AD9234 is available in a Pb-free, 64-lead LFCSP and is specified over the  $-40^{\circ}$ C to  $+85^{\circ}$ C industrial temperature range. This product is protected by a U.S. patent.

# **SPECIFICATIONS**

## **DC SPECIFICATIONS**

 $AVDD1 = 1.25 \text{ V}, AVDD2 = 2.5 \text{ V}, AVDD3 = 3.3 \text{ V}, AVDD1\_SR = 1.25 \text{ V}, DVDD = 1.25 \text{ V}, DRVDD = 1.25 \text{ V}, SPIVDD = 1.8 \text{ V}, specified maximum sampling rate, } A_{IN} = -1.0 \text{ dBFS}, clock divider = 2, default SPI settings, } T_A = 25^{\circ}\text{C}, unless otherwise noted.}$ 

Table 1.

	AD9234-500		500	1				
Parameter	Temp	Min	Тур	Max	Min	Тур	Max	Unit
RESOLUTION	Full	12			12			Bits
ACCURACY								
No Missing Codes	Full		uarante	eed		Guarante	ed	
Offset Error	Full	-0.22	0	+0.20	-0.22	0	+0.20	% FSR
Offset Matching	Full		0	+0.19		0	+0.19	% FSR
Gain Error	Full	-13.8	-5.1	+3.6		0		% FSR
Gain Matching	Full	-3.9	+1	+5.9		1	+4.8	% FSR
Differential Nonlinearity (DNL)	Full	-0.3		+0.3	-0.3	±0.16	+0.3	LSB
Integral Nonlinearity (INL)	Full	-0.8		+1.1	-1.2	±35	+1.4	LSB
TEMPERATURE DRIFT								
Offset Error	25°C		±2.6			±6		ppm/°C
Gain Error	25°C		±36			±36		ppm/°C
INTERNAL VOLTAGE REFERENCE								1
Voltage	Full		1.0			1.0		V
INPUT-REFERRED NOISE								
$V_{REF} = 1.0 V$	25°C		0.74			1.02		LSB rms
ANALOG INPUTS								
Differential Input Voltage Range	Full		1.63			1.34		V p-p
Common-Mode Voltage (V <sub>CM</sub> )	25°C		2.05			2.05		V .
Differential Input Capacitance <sup>1</sup>	25°C		1.5			1.5		pF
Analog Input Full Power Bandwidth	25°C		2			2		GHz
POWER SUPPLY								
AVDD1	Full	1.22	1.25	1.28	1.22	1.25	1.28	V
AVDD2	Full	2.44	2.50	2.56	2.44	2.50	2.56	V
AVDD3	Full	3.2	3.3	3.4	3.2	3.3	3.4	V
AVDD1_SR	Full	1.22	1.25	1.28	1.22	1.25	1.28	V
DVDD	Full	1.22	1.25	1.28	1.22	1.25	1.28	٧
DRVDD	Full	1.22	1.25	1.28	1.22	1.25	1.28	V
SPIVDD	Full	1.7	1.8	3.4	1.7	1.8	3.4	V
lavdd1	Full		430	480		675	740	mA
I <sub>AVDD2</sub>	Full		380	430		525	590	mA
I <sub>AVDD3</sub>	Full		65	75		75	91	mA
lavdd1_sr	Full		15	18		16	18	mA
l <sub>DVDD</sub> <sup>2</sup>	Full		140	152		230	236	mA
I <sub>DRVDD</sub> <sup>1</sup>	Full		190	246		205	225	mA
$I_{DRVDD}$ (L = 2 mode)	25°C		140			$N/A^3$		mA
Ispivdd	Full		5	6		5	6	mA

		AD9234-500			1			
Parameter	Temp	Min	Тур	Max	Min	Тур	Max	Unit
POWER CONSUMPTION								
Total Power Dissipation (Including Output Drivers) <sup>2</sup>	Full		2.15	2.5		3.0	3.3	W
Total Power Dissipation (L = 2 Mode)	25°C		2.08			$N/A^3$		W
Power-Down Dissipation	Full		670			750		mW
Standby⁴	Full		1.1			1.25		W

<sup>&</sup>lt;sup>1</sup> All lanes running. Power dissipation on DRVDD changes with lane rate and number of lanes used.

## **AC SPECIFICATIONS**

AVDD1 = 1.25 V, AVDD2 = 2.5 V, AVDD3 = 3.3 V,  $AVDD1\_SR = 1.25 \text{ V}$ , DVDD = 1.25 V, DRVDD = 1.25 V, SPIVDD = 1.8 V, specified maximum sampling rate,  $A_{IN} = -1.0 \text{ dBFS}$ , clock divider = 2, default SPI settings,  $T_A = 25^{\circ}\text{C}$ , unless otherwise noted.

Table 2.

		A	D9234-500	A	AD9234-1000		
Parameter <sup>1</sup>	Temp	Min	Тур Ма	x Min	Typ Max	Unit	
ANALOG INPUT FULL SCALE	Full		1.63		1.34	V p-p	
NOISE DENSITY <sup>2</sup>	Full		-150		-151	dBFS/Hz	
SIGNAL-TO-NOISE RATIO (SNR) <sup>3</sup>							
$f_{IN} = 10 \text{ MHz}$	25°C		65.9		64.2	dBFS	
$f_{IN} = 170 \text{ MHz}$	Full	65.1	65.8	61.6	63.9	dBFS	
$f_{IN} = 340 \text{ MHz}$	25°C		65.6		63.4	dBFS	
$f_{IN} = 450 \text{ MHz}$	25°C		65.3		63.1	dBFS	
$f_{IN} = 737 \text{ MHz}$	25°C		64.2		61.6	dBFS	
$f_{IN} = 985 \text{ MHz}$	25°C		63.6		60.7	dBFS	
$f_{IN} = 1410 \text{ MHz}$	25°C		62.2		58.8	dBFS	
SNR AND DISTORTION RATIO (SINAD) <sup>3</sup>							
$f_{IN} = 10 \text{ MHz}$	25°C		65.8		64.1	dBFS	
$f_{IN} = 170 \text{ MHz}$	Full	65.0	65.7	61.2	63.8	dBFS	
$f_{IN} = 340 \text{ MHz}$	25°C		65.5		63.3	dBFS	
$f_{IN} = 450 \text{ MHz}$	25°C		65.2		63.0	dBFS	
$f_{IN} = 737 \text{ MHz}$	25°C		63.7		61.5	dBFS	
$f_{IN} = 985 \text{ MHz}$	25°C		63.1		60.6	dBFS	
$f_{IN} = 1410 \text{ MHz}$	25°C		61.2		58.7	dBFS	
EFFECTIVE NUMBER OF BITS (ENOB)							
$f_{IN} = 10 \text{ MHz}$	25°C		10.7		10.4	Bits	
$f_{IN} = 170 \text{ MHz}$	Full	10.5	10.6	9.9	10.3	Bits	
$f_{IN} = 340 \text{ MHz}$	25°C		10.6		10.2	Bits	
$f_{IN} = 450 \text{ MHz}$	25°C		10.5		10.2	Bits	
$f_{IN} = 737 \text{ MHz}$	25°C		10.3		9.9	Bits	
$f_{IN} = 985 \text{ MHz}$	25°C		10.2		9.8	Bits	
$f_{IN} = 1410 \text{ MHz}$	25°C		9.9		9.5	Bits	
SPURIOUS-FREE DYNAMIC RANGE (SFDR) <sup>3</sup>							
$f_{IN} = 10 \text{ MHz}$	25°C		84		89	dBFS	
$f_{IN} = 170 \text{ MHz}$	Full	77	85	70	80	dBFS	
$f_{IN} = 340 \text{ MHz}$	25°C		85		79	dBFS	
$f_{IN} = 450 \text{ MHz}$	25°C		87		80	dBFS	
$f_{IN} = 737 \text{ MHz}$	25°C		75		81	dBFS	
$f_{IN} = 985 \text{ MHz}$	25°C		75		79	dBFS	
$f_{IN} = 1410 \text{ MHz}$	25°C		71		78	dBFS	

Rev. A | Page 6 of 66

<sup>&</sup>lt;sup>2</sup> Default mode. No DDCs used. L = 4, M = 2, F = 1.

 $<sup>^3</sup>$  N/A = not applicable. At the maximum sample rate, it is not applicable to use L = 2 mode on the JESD204B output interface because this exceeds the maximum lane rate of 12.5 Gbps. L = 2 mode is supported when the equation ((M × N′ × (10/8) × f<sub>OUT</sub>)/L) results in a line rate that is ≤12.5 Gbps. f<sub>OUT</sub> is the output sample rate and is denoted by f<sub>S</sub>/DCM, where DCM = decimation ratio.

<sup>&</sup>lt;sup>4</sup> Can be controlled by the SPI.

		AD9234-500		AD9234-1000				
Parameter <sup>1</sup>	Temp	Min	Тур	Max	Min	Тур	Max	Unit
WORST HARMONIC, SECOND OR THIRD <sup>3</sup>								
$f_{IN} = 10 \text{ MHz}$	25°C		-84			-89		dBFS
$f_{IN} = 170 \text{ MHz}$	Full		-85	-77		-80	-70	dBFS
$f_{IN} = 340 \text{ MHz}$	25°C		-85			-79		dBFS
$f_{IN} = 450 \text{ MHz}$	25°C		-87			-80		dBFS
$f_{IN} = 737 \text{ MHz}$	25°C		-75			-82		dBFS
$f_{IN} = 985 \text{ MHz}$	25°C		-75			-79		dBFS
$f_{IN} = 1410 \text{ MHz}$	25°C		-71			-78		dBFS
WORST OTHER, EXCLUDING SECOND OR THIRD HARMONIC <sup>3</sup>								
$f_{IN} = 10 \text{ MHz}$	25°C		-96			-89		dBFS
$f_{IN} = 170 \text{ MHz}$	Full	-82	-95			-85	-76	dBFS
$f_{IN} = 340 \text{ MHz}$	25°C		-94			-83		dBFS
$f_{IN} = 450 \text{ MHz}$	25°C		-93			-82		dBFS
$f_{IN} = 737 \text{ MHz}$	25°C		-88			-81		dBFS
$f_{IN} = 985 \text{ MHz}$	25°C		-89			-85		dBFS
$f_{IN} = 1410 \text{ MHz}$	25°C		-86			-80		dBFS
TWO-TONE INTERMODULATION DISTORTION (IMD), $A_{IN1}$ AND $A_{IN2} = -7$ dBFS								
$f_{IN1} = 187 \text{ MHz}, f_{IN2} = 190 \text{ MHz}$	25°C		-90			-81		dBFS
$f_{IN1} = 338 \text{ MHz}, f_{IN2} = 341 \text{ MHz}$	25°C		-86			-78		dBFS
CROSSTALK <sup>4</sup>	25°C		95			95		dB
FULL POWER BANDWIDTH <sup>5</sup>	25°C		2			2		GHz

<sup>&</sup>lt;sup>1</sup> See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for definitions and for details on how these tests were completed.
<sup>2</sup> Noise density is measured at a low analog input frequency (30 MHz).
<sup>3</sup> See Table 9 for recommended settings for the buffer current setting optimized for SFDR.
<sup>4</sup> Crosstalk is measured at 170 MHz with a –1.0 dBFS analog input on one channel and no input on the adjacent channel.

<sup>&</sup>lt;sup>5</sup> Measured with circuit shown in Figure 64.

## **DIGITAL SPECIFICATIONS**

AVDD1 = 1.25 V, AVDD2 = 2.5 V, AVDD3 = 3.3 V,  $AVDD1\_SR = 1.25 \text{ V}$ , DVDD = 1.25 V, DRVDD = 1.25 V, SPIVDD = 1.8 V, specified maximum sampling rate,  $A_{IN} = -1.0 \text{ dBFS}$ , default SPI settings,  $T_A = 25^{\circ}\text{C}$ , unless otherwise noted.

Table 3.

Parameter	Temperature	Min	Тур	Max	Unit
CLOCK INPUTS (CLK+, CLK-)					
Logic Compliance	Full	LV	DS/LVPECL		
Differential Input Voltage	Full	600	1200	1800	mV p-p
Input Common-Mode Voltage	Full		0.85		V
Input Resistance (Differential)	Full		35		kΩ
Input Capacitance	Full			2.5	pF
SYSTEM REFERENCE INPUTS (SYSREF+, SYSREF-)					
Logic Compliance	Full	LV	DS/LVPECL		
Differential Input Voltage	Full	400	1200	1800	mV p-p
Input Common-Mode Voltage	Full	0.6	0.85	2.0	V
Input Resistance (Differential)	Full		35		kΩ
Input Capacitance (Differential)	Full			2.5	pF
LOGIC INPUTS (SDIO, SCLK, CSB, PDWN/STBY)					
Logic Compliance	Full		CMOS		
Logic 1 Voltage	Full	0.8 × SPIVDD			V
Logic 0 Voltage	Full	0		0.5	V
Input Resistance	Full		30		kΩ
LOGIC OUTPUT (SDIO)					
Logic Compliance	Full		CMOS		
Logic 1 Voltage (I <sub>OH</sub> = 800 μA)	Full	0.8 × SPIVDD			٧
Logic 0 Voltage ( $I_{OL} = 50 \mu A$ )	Full	0		0.5	٧
SYNC INPUTS (SYNCINB+, SYNCINB-)					
Logic Compliance	Full	LVDS	/LVPECL/CMO	S	
Differential Input Voltage	Full	400	1200	1800	mV p-p
Input Common-Mode Voltage	Full	0.6	0.85	2.0	٧
Input Resistance (Differential)	Full		35		kΩ
Input Capacitance	Full			2.5	рF
LOGIC OUTPUTS (FD_A, FD_B)					
Logic Compliance	Full		CMOS		
Logic 1 Voltage	Full	0.8 × SPIVDD			٧
Logic 0 Voltage	Full	0		0.5	٧
Input Resistance	Full		30		kΩ
DIGITAL OUTPUTS (SERDOUTx±, x = 0 TO 3)					
Logic Compliance	Full		CML		
Differential Output Voltage	Full	360		770	mV p-p
Output Common-Mode Voltage (V <sub>CM</sub> )					
AC-Coupled	25°C	0		1.8	V
Short-Circuit Current (I <sub>Dshort</sub> )	25°C	-100		+100	mA
Differential Return Loss (RL <sub>DIFF</sub> ) <sup>1</sup>	25°C	8			dB
Common-Mode Return Loss (RL <sub>CM</sub> ) <sup>1</sup>	25°C	6			dB
Differential Termination Impedance	Full	80	100	120	Ω

 $<sup>^{\</sup>rm 1}$  Differential and common-mode return loss is measured from 100 MHz to 0.75 MHz  $\times$  baud rate.

## **SWITCHING SPECIFICATIONS**

AVDD1 = 1.25 V, AVDD2 = 2.5 V, AVDD3 = 3.3 V,  $AVDD1\_SR = 1.25 \text{ V}$ , DVDD = 1.25 V, DRVDD = 1.25 V, SPIVDD = 1.8 V, specified maximum sampling rate,  $A_{IN} = -1.0 \text{ dBFS}$ , default SPI settings,  $T_A = 25^{\circ}C$ , unless otherwise noted.

Table 4.

		AD9234-500			AD	9234-1		
Parameter	Temperature	Min	Тур	Max	Min	Тур	Max	Unit
CLOCK								
Clock Rate (at CLK+/CLK- Pins)	Full	0.3		4	0.3		4	GHz
Maximum Sample Rate <sup>1</sup>	Full	500			1000			MSPS
Minimum Sample Rate <sup>2</sup>	Full	300			300			MSPS
Clock Pulse Width High	Full	1000			500			ps
Clock Pulse Width Low	Full	1000			500			ps
OUTPUT PARAMETERS								
Unit Interval (UI) <sup>3</sup>	Full	80	200		80	100		ps
Rise Time ( $t_R$ ) (20% to 80% into 100 $\Omega$ Load)	25°C	24	32		24	32		ps
Fall Time ( $t_F$ ) (20% to 80% into 100 $\Omega$ Load)	25°C	24	32		24	32		ps
PLL Lock Time	25°C		2			2		ms
Data Rate per Channel (NRZ) <sup>4</sup>	25°C	3.125	5	12.5	3.125	10	12.5	Gbps
LATENCY <sup>5</sup>								
Pipeline Latency	Full		55			55		Clock cycles
Fast Detect Latency	Full			28			28	Clock cycles
Wake-Up Time <sup>6</sup>								
Standby	25°C		1			1		ms
Power-Down	25°C			4			4	ms
APERTURE								
Aperture Delay (t <sub>A</sub> )	Full		530			530		ps
Aperture Uncertainty (Jitter, t <sub>j</sub> )	Full		55			55		fs rms
Out-of-Range Recovery Time	Full		1			1		Clock Cycles

 $<sup>^{\</sup>mbox{\tiny 1}}$  The maximum sample rate is the clock rate after the divider.

## **TIMING SPECIFICATIONS**

Table 5.

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
CLK+ to SYSREF+ TIMING REQUIREMENTS	See Figure 2				
$t_{SU\_SR}$	Device clock to SYSREF+ setup time		117		ps
t <sub>H_SR</sub>	Device clock to SYSREF+ hold time		-96		ps
SPITIMING REQUIREMENTS	See Figure 3				
t <sub>DS</sub>	Setup time between the data and the rising edge of SCLK	2			ns
t <sub>DH</sub>	Hold time between the data and the rising edge of SCLK	2			ns
t <sub>CLK</sub>	Period of the SCLK	40			ns
ts	Setup time between CSB and SCLK	2			ns
t <sub>H</sub>	Hold time between CSB and SCLK	2			ns
thigh	Minimum period that SCLK must be in a logic high state	10			ns
t <sub>LOW</sub>	Minimum period that SCLK must be in a logic low state	10			ns
t <sub>en_sdio</sub>	Time required for the SDIO pin to switch from an input to an output relative to the SCLK falling edge (not shown in Figure 3)	10			ns
t <sub>DIS_SDIO</sub>	Time required for the SDIO pin to switch from an output to an input relative to the SCLK rising edge (not shown in Figure 3)	10			ns

 $<sup>^{2}</sup>$  The minimum sample rate operates at 300 MSPS with L = 2 or L = 1.

 $<sup>^{3}</sup>$  Baud rate = 1/UI. A subset of this range can be supported.

 $<sup>^4</sup>$  Default L = 4. This number can be changed based on the sample rate and decimation ratio.

<sup>&</sup>lt;sup>5</sup> No DDCs used. L = 4, M = 2, F = 1.

<sup>&</sup>lt;sup>6</sup> Wake-up time is defined as the time required to return to normal operation from power-down mode.

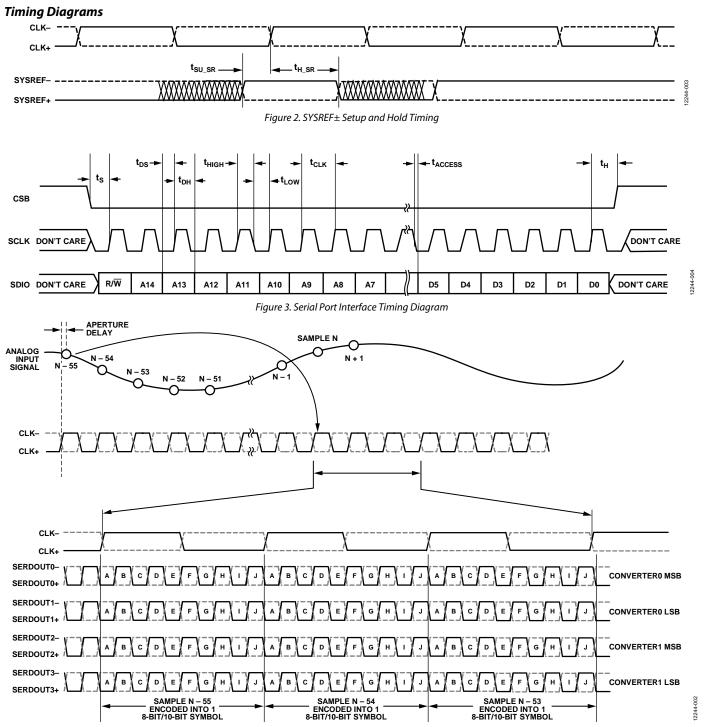


Figure 4. Data Output Timing (Full Bandwidth Mode; L = 4; M = 2; F = 1)

## **ABSOLUTE MAXIMUM RATINGS**

Table 6.

Parameter	Rating
Electrical	
AVDD1 to AGND	1.32 V
AVDD1_SR to AGND	1.32 V
AVDD2 to AGND	2.75 V
AVDD3 to AGND	3.63 V
DVDD to DGND	1.32 V
DRVDD to DRGND	1.32 V
SPIVDD to AGND	3.63 V
AGND to DRGND	-0.3 V to +0.3 V
VIN±x to AGND	3.2 V
SCLK, SDIO, CSB to AGND	-0.3 V to SPIVDD + 0.3 V
PDWN/STBY to AGND	-0.3 V to SPIVDD + 0.3 V
Operating Temperature Range	−40°C to +85°C
Junction Temperature Range	−40°C to +115°C
Storage Temperature Range (Ambient)	−65°C to +150°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

### THERMAL CHARACTERISTICS

Typical  $\theta_{JA}$ ,  $\theta_{JB}$ , and  $\theta_{JC}$  are specified vs. the number of printed circuit board (PCB) layers in different airflow velocities (in m/sec). Airflow increases heat dissipation effectively reducing  $\theta_{JA}$  and  $\theta_{JB}$ . In addition, metal in direct contact with the package leads and exposed pad from metal traces, through holes, ground, and power planes, reduces the  $\theta_{JA}$ . Thermal performance for actual applications requires careful inspection of the conditions in an application. The use of appropriate thermal management techniques is recommended to ensure that the maximum junction temperature does not exceed the limits shown in Table 6.

**Table 7. Thermal Resistance Values** 

PCB Type	Airflow Velocity (m/sec)	θја	Ψյв	<b>Ө</b> ЈС_ТОР	<b>Ө</b> JС_ВОТ	Unit
JEDEC	0.0	17.8 <sup>1, 2</sup>	6.3 <sup>1, 3</sup>	4.7 <sup>1, 5</sup>	1.2 <sup>1, 5</sup>	°C/W
2s2p	1.0	15.6 <sup>1, 2</sup>	5.9 <sup>1,3</sup>	N/A <sup>4</sup>		°C/W
Board	2.5	15.0 <sup>1, 2</sup>	5.7 <sup>1, 3</sup>	N/A <sup>4</sup>		°C/W

<sup>&</sup>lt;sup>1</sup> Per JEDEC 51-7, plus JEDEC 51-5 2s2p test board.

### **ESD CAUTION**



**ESD (electrostatic discharge) sensitive device.**Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

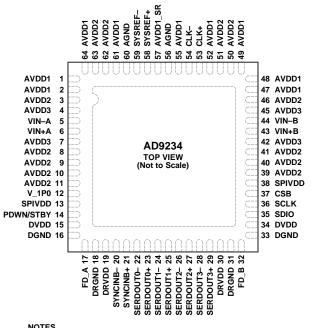
<sup>&</sup>lt;sup>2</sup> Per JEDEC JESD51-2 (still air) or JEDEC JESD51-6 (moving air).

<sup>&</sup>lt;sup>3</sup> Per JEDEC JESD51-8 (still air).

 $<sup>^4</sup>$  N/A = not applicable.

<sup>&</sup>lt;sup>5</sup> Per MIL-STD 883, Method 1012.1.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



NOTES
1. THE EXPOSED THERMAL PAD ON THE BOTTOM OF THE PACKAGE PROVIDES THE GROUND REFENCE FOR AVDDX. THIS EXPOSED PAD MUST BE CONNECTED TO GROUND FOR PROPER OPERATION.

Figure 5. Pin Configuration

**Table 8. Pin Function Descriptions** 

Pin No.	Mnemonic	Туре	Description
Power Supplies			
0	EPAD	Ground	Exposed Pad. The exposed thermal pad on the bottom of the package provides the ground reference for AVDDx. This exposed pad must be connected to ground for proper operation.
1, 2, 47, 48, 49, 52, 55, 61, 64	AVDD1	Supply	Analog Power Supply (1.25 V Nominal).
3, 8, 9, 10, 11, 39, 40, 41, 46, 50, 51, 62, 63	AVDD2	Supply	Analog Power Supply (2.5 V Nominal).
4, 7, 42, 45	AVDD3	Supply	Analog Power Supply (3.3 V Nominal).
13, 38	SPIVDD	Supply	Digital Power Supply for SPI (1.8 V to 3.3 V).
15, 34	DVDD	Supply	Digital Power Supply (1.25 V Nominal).
16, 33	DGND	Ground	Ground Reference for DVDD.
18, 31	DRGND	Ground	Ground Reference for DRVDD.
19, 30	DRVDD	Supply	Digital Driver Power Supply (1.25 V Nominal).
56, 60	AGND <sup>1</sup>	Ground	Ground Reference for SYSREF±.
57	AVDD1_SR1	Supply	Analog Power Supply for SYSREF± (1.25 V Nominal).
Analog			
5, 6	VIN-A, VIN+A	Input	ADC A Analog Input Complement/True.
12	V_1P0	Input/DNC	1.0 V Reference Voltage Input/Do Not Connect. This pin is configurable through the SPI as a no connect or an input. Do not connect this pin if using the internal reference. This pin requires a 1.0 V reference voltage input if using an external voltage reference source.
43, 44	VIN+B, VIN-B	Input	ADC B Analog Input True/Complement.
53, 54	CLK+, CLK-	Input	Clock Input True/Complement.
CMOS Outputs			
17, 32	FD_A, FD_B	Output	Fast Detect Outputs for Channel A and Channel B.

Pin No.	Mnemonic	Туре	Description
Digital Inputs			
20, 21	SYNCINB-, SYNCINB+	Input	Active Low JESD204B LVDS Sync Input Complement/True.
58, 59	SYSREF+, SYSREF-	Input	Active High JESD204B LVDS System Reference Input True/Complement.
Data Outputs			
22, 23	SERDOUTO-, SERDOUTO+	Output	Lane 0 Output Data Complement/True.
24, 25	SERDOUT1-, SERDOUT1+	Output	Lane 1 Output Data Complement/True.
26, 27	SERDOUT2-, SERDOUT2+	Output	Lane 2 Output Data Complement/True.
28, 29	SERDOUT3-, SERDOUT3+	Output	Lane 3 Output Data Complement/True.
Device Under Test (DUT) Controls			
14	PDWN/STBY	Input	Power-Down Input (Active High). The operation of this pin depends on the SPI mode and can be configured as power-down or standby.
35	SDIO	Input/output	SPI Serial Data Input/Output.
36	SCLK	Input	SPI Serial Clock.
37	CSB	Input	SPI Chip Select (Active Low).

<sup>&</sup>lt;sup>1</sup> To ensure proper ADC operation, connect AVDD1\_SR and AGND separately from the AVDD1 and EPAD connection. For more information, refer to the Applications Information section.

## TYPICAL PERFORMANCE CHARACTERISTICS

### AD9234-1000

AVDD1 = 1.25 V,  $AVDD1\_SR = 1.25 \text{ V}$ , AVDD2 = 2.5 V, AVDD3 = 3.3 V, DVDD = 1.25 V, DRVDD = 1.25 V, SPIVDD = 1.8 V, 1.34 V p-p full-scale differential input,  $A_{IN} = -1.0 \text{ dBFS}$ , default SPI settings, clock divider = 2,  $T_A = 25^{\circ}\text{C}$ , 128k FFT sample, unless otherwise noted.

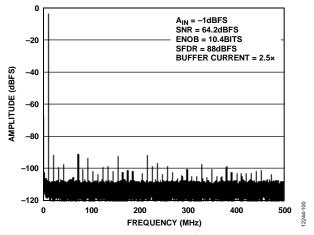


Figure 6. Single-Tone FFT with  $f_{IN} = 10.3 \text{ MHz}$ 

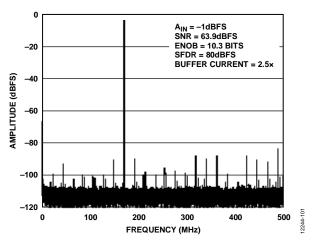


Figure 7. Single-Tone FFT with  $f_{IN} = 170.3 \text{ MHz}$ 

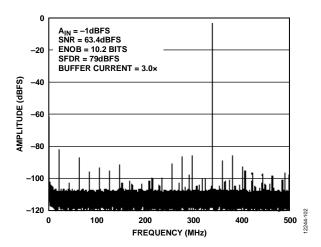


Figure 8. Single-Tone FFT with  $f_{\text{IN}}$  = 340.3 MHz

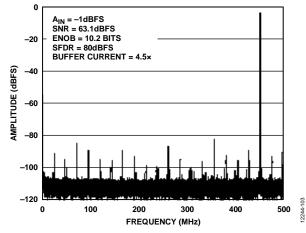


Figure 9. Single-Tone FFT with  $f_{IN} = 450.3 \text{ MHz}$ 

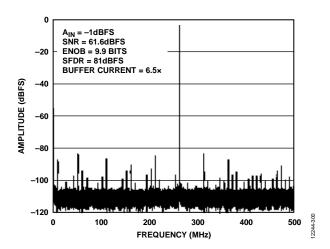


Figure 10. Single-Tone FFT with  $f_{IN} = 737.3$  MHz

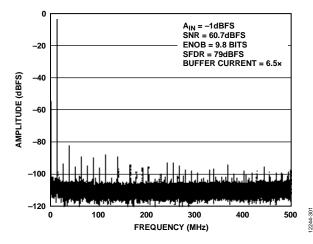


Figure 11. Single-Tone FFT with  $f_{IN} = 985.3$  MHz

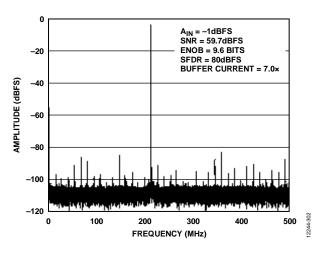


Figure 12. Single-Tone FFT with  $f_{IN} = 1213.3$  MHz

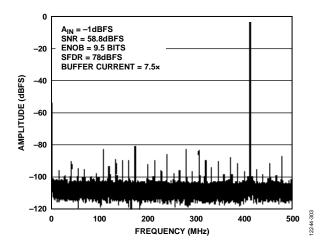


Figure 13. Single-Tone FFT with  $f_{IN} = 1413.3 \text{ MHz}$ 

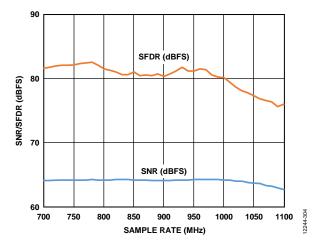


Figure 14. SNR/SFDR vs. Sample Rate ( $f_s$ ),  $f_{IN} = 170.3$  MHz; Buffer Current = 3.0×

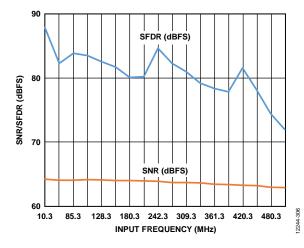


Figure 15. SNR/SFDR vs. Input Frequency  $(f_{IN})$ ;  $f_{IN} < 500$  MHz; Buffer Current = 3.5× (Uses Circuit Shown in Figure 63)

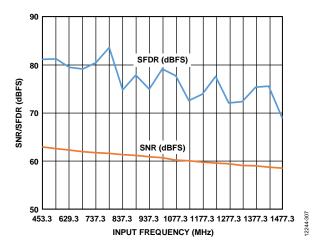


Figure 16. SNR/SFDR vs. Input Frequency ( $f_{\rm IN}$ ); 450 MHz <  $f_{\rm IN}$  < 1500 MHz; Buffer Current = 7.5× (Uses Circuit Shown in Figure 64)

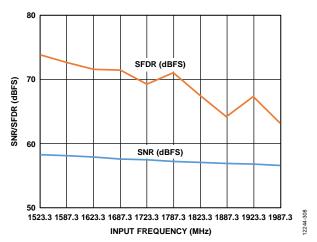


Figure 17. SNR/SFDR vs. Input Frequency ( $f_{\rm IN}$ ); 1500 MHz <  $f_{\rm IN}$  < 2000 MHz; Buffer Current = 8.5× (Uses Circuit Shown in Figure 64)

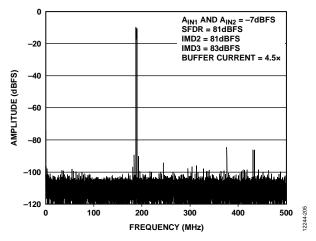


Figure 18. Two-Tone FFT;  $f_{IN1} = 184 \text{ MHz}$ ,  $f_{IN2} = 187 \text{ MHz}$ 

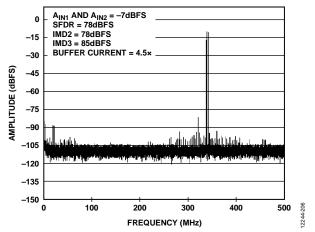


Figure 19. Two-Tone FFT;  $f_{IN1} = 338$  MHz,  $f_{IN2} = 341$  MHz

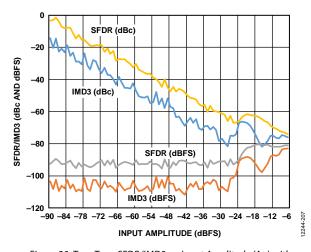


Figure 20. Two-Tone SFDR/IMD3 vs. Input Amplitude (A<sub>IN</sub>) with  $f_{\rm IN1}=184$  MHz and  $f_{\rm IN2}=187$  MHz

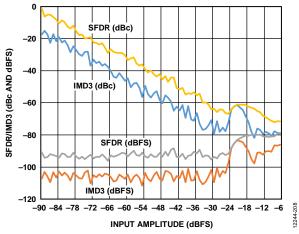


Figure 21. Two-Tone SFDR/IMD3 vs. Input Amplitude ( $A_{IN}$ ) with  $f_{IN1} = 338$  MHz and  $f_{IN2} = 341$  MHz

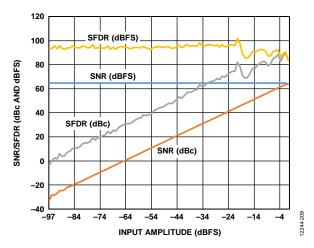


Figure 22. SNR/SFDR vs. Analog Input Level,  $f_{\rm IN}$  = 10.3 MHz; Buffer Current = 2.0×

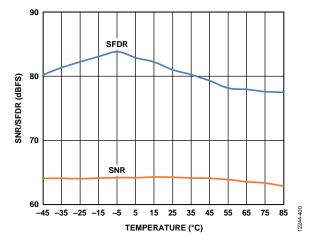


Figure 23. SNR/SFDR vs. Temperature,  $f_{IN} = 170.3 \text{ MHz}$ 

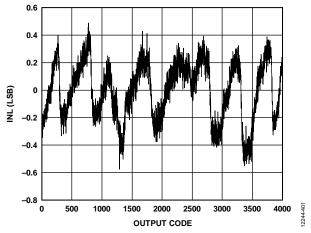


Figure 24. INL,  $f_{IN} = 10.3 MHz$ 

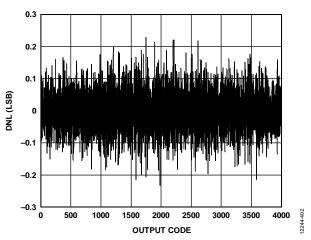


Figure 25. DNL,  $f_{IN} = 10 \text{ MHz}$ 

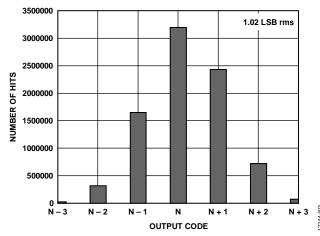


Figure 26. Input-Referred Noise Histogram

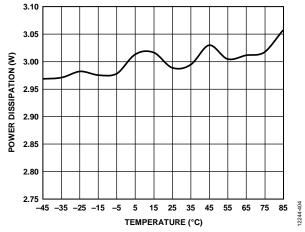


Figure 27. Power Dissipation vs. Temperature

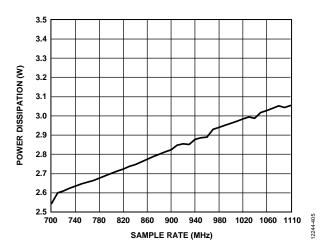


Figure 28. Power Dissipation vs. Sample Rate (f<sub>s</sub>)

### AD9234-500

AVDD1 = 1.25 V,  $AVDD1\_SR = 1.25 \text{ V}$ , AVDD2 = 2.5 V, AVDD3 = 3.3 V, DVDD = 1.25 V, DRVDD = 1.25 V, SPIVDD = 1.8 V, 1.63 V p-p full-scale differential input,  $A_{IN} = -1.0 \text{ dBFS}$ , default SPI settings, clock divider = 2,  $T_A = 25^{\circ}C$ , 128k FFT sample, unless otherwise noted.

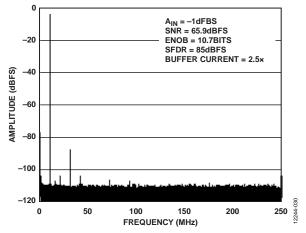


Figure 29. Single-Tone FFT with  $f_{IN} = 10.3 \text{ MHz}$ 

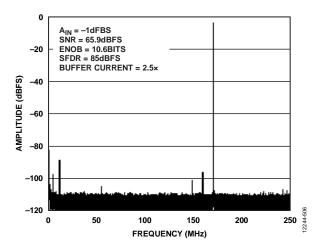


Figure 30. Single-Tone FFT with  $f_{IN} = 170.3 \text{ MHz}$ 

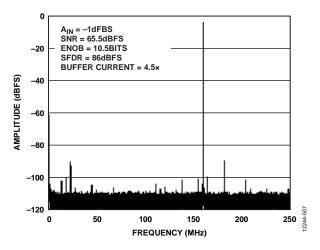


Figure 31. Single-Tone FFT with  $f_{IN} = 340.3 \text{ MHz}$ 

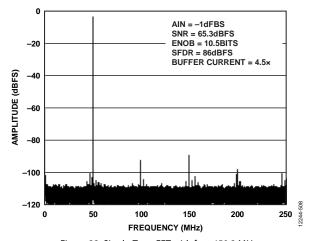


Figure 32. Single-Tone FFT with  $f_{IN} = 450.3 \text{ MHz}$ 

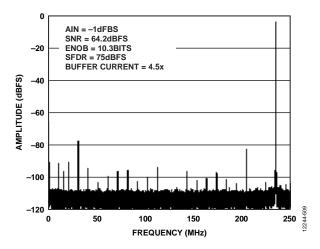


Figure 33. Single-Tone FFT with  $f_{IN} = 737.3 \text{ MHz}$ 

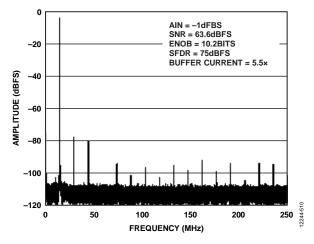


Figure 34. Single-Tone FFT with  $f_{IN} = 985.3 \text{ MHz}$ 

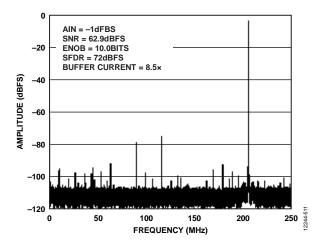


Figure 35. Single-Tone FFT with  $f_{IN} = 1213.3$  MHz

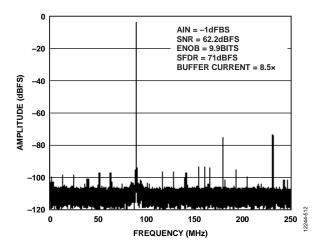


Figure 36. Single-Tone FFT with  $f_{IN} = 1413.3 \text{ MHz}$ 

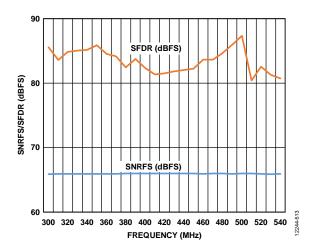


Figure 37. SNR/SFDR vs. Sample Rate ( $f_s$ ),  $f_{IN} = 170.3$  MHz; Buffer Current = 3.0×

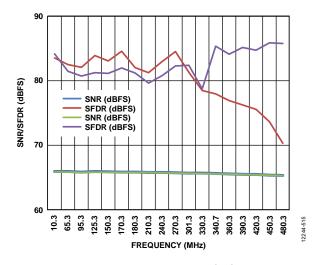


Figure 38. SNR/SFDR vs. Input Frequency ( $f_{IN}$ );  $f_{IN}$  < 500 MHz; Buffer Current = 2.5× and 4.5× (Uses Circuit Shown in Figure 63)

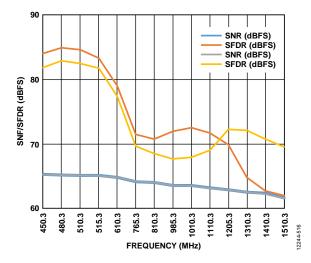


Figure 39. SNR/SFDR vs. Input Frequency ( $f_{\rm IN}$ ); 450 MHz <  $f_{\rm IN}$  < 1500 MHz; Buffer Current = 6.5× and 8.5× (Uses Circuit Shown in Figure 64)

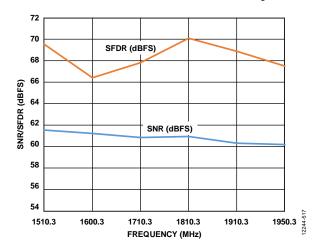


Figure 40. SNR/SFDR vs. Input Frequency ( $f_{IN}$ ); 1500 MHz <  $f_{IN}$  < 2000 MHz; Buffer Current =  $8.5 \times$  (Uses Circuit Shown in Figure 64)

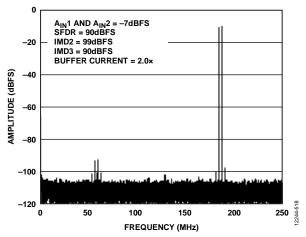


Figure 41. Two-Tone FFT;  $f_{IN1} = 184$  MHz,  $f_{IN2} = 187$  MHz

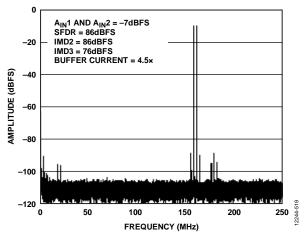


Figure 42. Two-Tone FFT;  $f_{IN1} = 338$  MHz,  $f_{IN2} = 341$  MHz

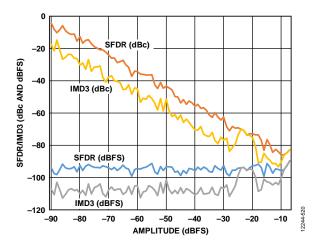


Figure 43. Two-Tone SFDR/IMD3 vs. Input Amplitude (A<sub>IN</sub>) with  $f_{\rm IN1}=184$  MHz and  $f_{\rm IN2}=187$  MHz

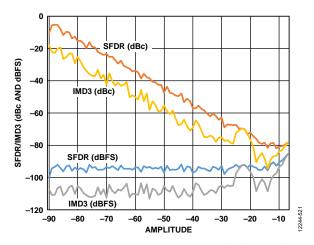


Figure 44. Two-Tone SFDR/IMD3 vs. Input Amplitude (A<sub>IN</sub>) with  $f_{\rm IN1}=338$  MHz and  $f_{\rm IN2}=341$  MHz

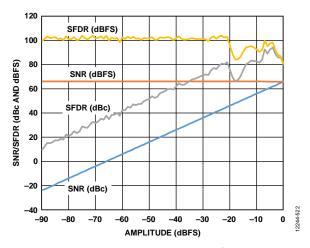


Figure 45. SNR/SFDR vs. Analog Input Level,  $f_{\rm IN}$  = 10.3 MHz; Buffer Current = 2.0×

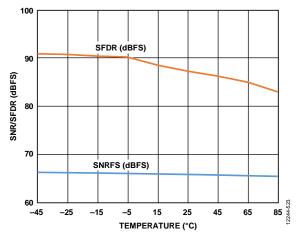


Figure 46. SNR/SFDR vs. Temperature,  $f_{IN} = 170.3 \text{ MHz}$ 

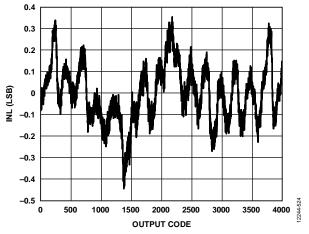


Figure 47. INL,  $f_{IN} = 10.3 \, MHz$ 

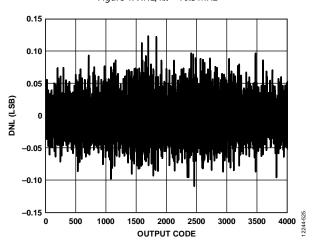


Figure 48. DNL,  $f_{IN} = 10 MHz$ 

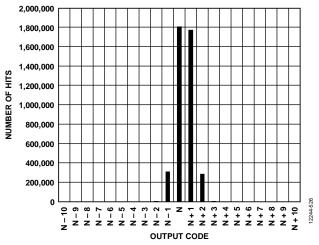


Figure 49. Input-Referred Noise Histogram

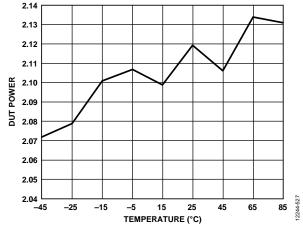


Figure 50. Power Dissipation vs. Temperature

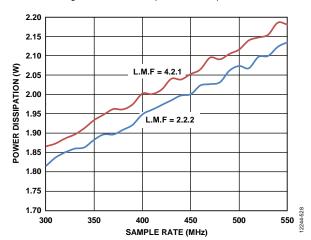


Figure 51. Power Dissipation vs. Sample Rate (f<sub>S</sub>)

# **EQUIVALENT CIRCUITS**

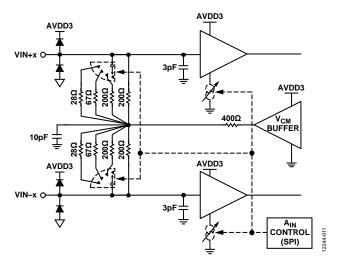


Figure 52. Analog Inputs

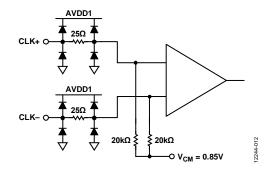


Figure 53. Clock Inputs

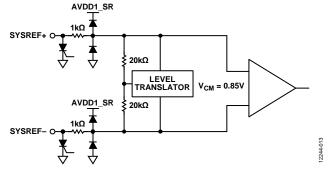


Figure 54. SYSREF± Inputs

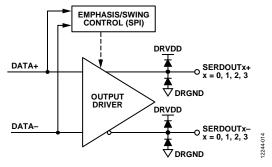


Figure 55. Digital Outputs

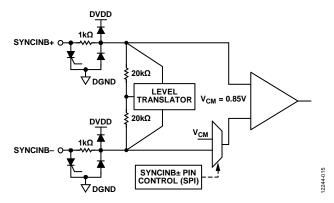


Figure 56. SYNCINB± Inputs

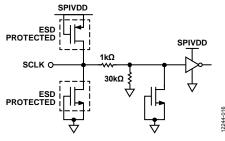


Figure 57. SCLK Input

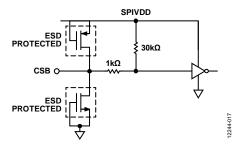


Figure 58. CSB Input

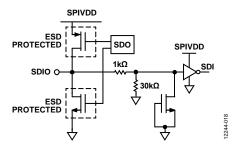


Figure 59. SDIO Input

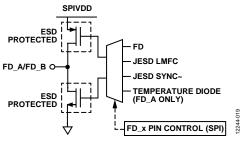


Figure 60. FD\_A/FD\_B Outputs

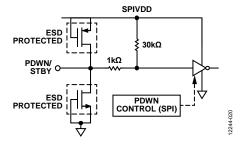


Figure 61. PDWN/STBY Input

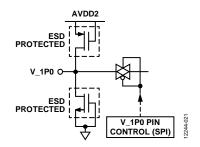


Figure 62. V\_1P0 Input

## THEORY OF OPERATION

The AD9234 has two analog input channels and four JESD204B output lane pairs. The ADC is designed to sample wide bandwidth analog signals of up to 2 GHz. The AD9234 is optimized for wide input bandwidth, high sampling rate, excellent linearity, and low power in a small package.

The dual ADC cores feature a multistage, differential pipelined architecture with integrated output error correction logic. Each ADC features wide bandwidth inputs supporting a variety of user-selectable input ranges. An integrated voltage reference eases design considerations.

The AD9234 has several functions that simplify the AGC function in a communications receiver. The programmable threshold detector allows monitoring of the incoming signal power using the fast detect output bits of the ADC. If the input signal level exceeds the programmable threshold, the fast detect indicator goes high. Because this threshold indicator has low latency, the user can quickly turn down the system gain to avoid an overrange condition at the ADC input.

The Subclass 1 JESD204B-based high speed serialized output data rate can be configured in one-lane (L = 1), two-lane (L = 2), and four-lane (L = 4) configurations, depending on the sample rate and the decimation ratio. Multiple device synchronization is supported through the SYSREF $\pm$  and SYNCINB $\pm$  input pins.

### **ADC ARCHITECTURE**

The architecture of the AD9234 consists of an input buffered pipelined ADC. The input buffer is designed to provide a termination impedance to the analog input signal. This termination impedance can be changed using the SPI to meet the termination needs of the driver/amplifier. The default termination value is set to 400  $\Omega$ . The equivalent circuit diagram of the analog input termination is shown in Figure 52. The input buffer is optimized for high linearity, low noise, and low power.

The input buffer provides a linear high input impedance (for ease of drive) and reduces kickback from the ADC. The buffer is optimized for high linearity, low noise, and low power. The quantized outputs from each stage are combined into a final 12-bit result in the digital correction logic. The pipelined architecture permits the first stage to operate with a new input sample; at the same time, the remaining stages operate with the preceding samples. Sampling occurs on the rising edge of the clock.

### **ANALOG INPUT CONSIDERATIONS**

The analog input to the AD9234 is a differential buffer. The internal common-mode voltage of the buffer is 2.05 V. The clock signal alternately switches the input circuit between sample mode and hold mode. When the input circuit is switched into sample mode, the signal source must be capable of charging the sample capacitors and settling within one-half of a clock cycle. A small resistor, in series with each input, helps reduce the peak transient current injected from the output stage of the driving source. In addition, low Q inductors or ferrite beads can be placed on each leg of the input to reduce high differential capacitance at the analog inputs and, thus, achieve the maximum bandwidth of the ADC. Such use of low Q inductors or ferrite beads is required when driving the converter front end at high IF frequencies. Either a differential capacitor or two single-ended capacitors can be placed on the inputs to provide a matching passive network. This ultimately creates a low-pass filter at the input, which limits unwanted broadband noise. For more information, refer to the AN-742 Application Note, the AN-827 Application Note, and the Analog Dialogue article "Transformer-Coupled Front-End for Wideband A/D Converters" (Volume 39, April 2005). In general, the precise values depend on the application.

For best dynamic performance, the source impedances driving VIN+x and VIN-x must be matched such that common-mode settling errors are symmetrical. These errors are reduced by the common-mode rejection of the ADC. An internal reference buffer creates a differential reference that defines the span of the ADC core.

Maximum SNR performance is achieved by setting the ADC to the largest span in a differential configuration. In the case of the AD9234, the available span is 1.34 V p-p differential for AD9234-1000 and 1.63 V p-p differential for AD9234-500.

## **Differential Input Configurations**

There are several ways to drive the AD9234, either actively or passively. However, optimum performance is achieved by driving the analog input differentially.

For applications where SNR and SFDR are key parameters, differential transformer coupling is the recommended input configuration (see Figure 63 and Figure 64) because the noise performance of most amplifiers is not adequate to achieve the true performance of the AD9234.

For low to midrange frequencies, a double balun or double transformer network (see Figure 63) is recommended for optimum performance of the AD9234. For higher frequencies in the second and third Nyquist zones, it is better to remove some of the front-end passive components to ensure wideband operation (see Figure 64).

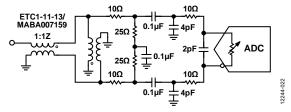


Figure 63. Differential Transformer-Coupled Configuration for Frequencies Up to 500 MHz

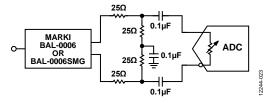


Figure 64. Differential Transformer-Coupled Configuration for Frequencies > 500 MHz

## **Input Common Mode**

The analog inputs of the AD9234 are internally biased to the common mode as shown in Figure 65. The common-mode buffer has a limited range in that the performance suffers greatly if the common-mode voltage drops by more than 100 mV. Therefore, in dc-coupled applications, set the common-mode voltage to 2.05 V,  $\pm 100$  mV to ensure proper ADC operation.

## **Analog Input Controls and SFDR Optimization**

The AD9234 offers flexible controls for the analog inputs, such as input termination and buffer current. All of the available controls are shown in Figure 65.

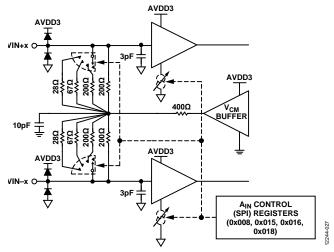


Figure 65. Analog Input Controls

Using Register 0x018, the buffer currents on each channel can be scaled to optimize the SFDR over various input frequencies and bandwidths of interest. As the input buffer currents are set, the amount of current required by the AVDD3 supply changes. This relationship is shown in Figure 66. For a complete list of buffer current settings, see Table 22.

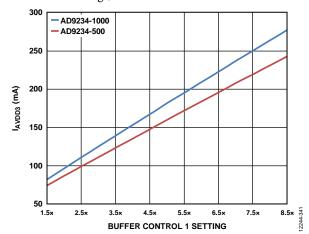


Figure 66. AVDD3 Power (I<sub>AVDD3</sub>) vs. Buffer Current Setting

Figure 67, Figure 68, and Figure 69 show how the SFDR for AD9234-1000 can be optimized using the buffer current setting in Register 0x018 for different Nyquist zones. Figure 70, Figure 71, and Figure 72 show how the SFDR for AD9234-500 can be optimized using the buffer current setting in Register 0x018 for different Nyquist zones. At frequencies greater than 1 GHz, it is better to run the ADC at input amplitudes less than –1 dBFS (–3 dBFS, for example). This greatly improves the linearity of the converted signal without sacrificing SNR performance.

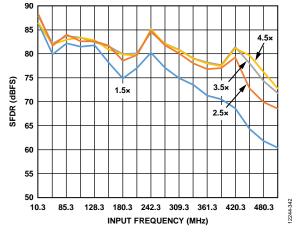


Figure 67. Buffer Current Sweeps, AD9234-1000; SFDR vs. Input Frequency ( $I_{BUFF}$ );  $f_{IN} < 500 \text{ MHz}$ 

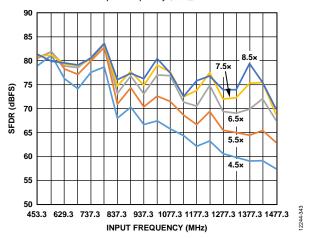


Figure 68. Buffer Current Sweeps, AD9234-1000; SFDR vs. Input Frequency ( $I_{BUFF}$ ); 500 MHz <  $f_{IN}$  < 1500 MHz



Figure 69. Buffer Current Sweeps, AD9234-1000; SFDR vs. Input Frequency ( $I_{BUFF}$ );1500 MHz <  $f_{IN}$  < 2000 MHz

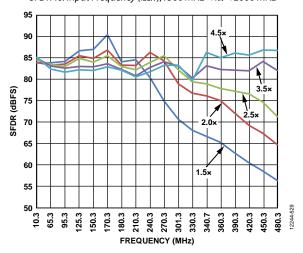


Figure 70. Buffer Current Sweeps, AD9234-500; SFDR vs. Input Frequency ( $I_{BUFF}$ );  $f_{IN} < 500$  MHz

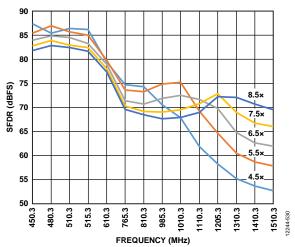


Figure 71. Buffer Current Sweeps, AD9234-500; SFDR vs. Input Frequency ( $I_{BUFF}$ ); 500 MHz  $< f_{IN} < 1500$  MHz

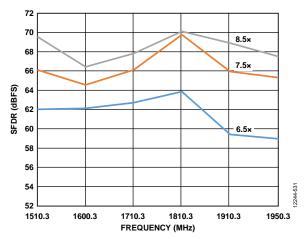


Figure 72. Buffer Current Sweeps, AD9234-500; SFDR vs. Input Frequency ( $I_{BUFF}$ ); 1500 MHz <  $f_{IN}$  < 2000 MHz

Table 9 shows the recommended buffer current and full-scale voltage settings for the different analog input frequency ranges.

Table 9. SFDR Optimization for Input Frequencies

Input Frequency	Input Buffer Current Control Setting, Register 0x018
<400 MHz	2.5× or 3.0×
400 MHz to 1 GHz	4.5× or 6.5×
>1 GHz	6.5× or higher

## **Absolute Maximum Input Swing**

The absolute maximum input swing allowed at the inputs of the AD9234 is 4.3 V p-p differential. Signals operating near or at this level can cause permanent damage to the ADC.

## **VOLTAGE REFERENCE**

A stable and accurate 1.0 V voltage reference is built into the AD9234. This internal 1.0 V reference is used to set the full-scale input range of the ADC. For more information on adjusting the input swing, see Table 22. Figure 73 shows the block diagram of the internal 1.0 V reference controls.

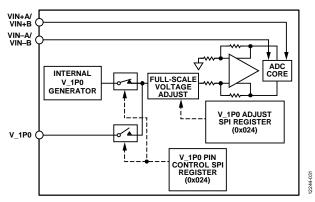


Figure 73. Internal Reference Configuration and Controls

The SPI Register 0x024 enables the user to either use this internal  $1.0~\rm V$  reference, or to provide an external  $1.0~\rm V$  reference. When using an external voltage reference, provide a  $1.0~\rm V$  reference.

The use of an external reference may be necessary, in some applications, to enhance the gain accuracy of the ADC or improve thermal drift characteristics. Figure 74 shows the typical drift characteristics of the internal 1.0 V reference.

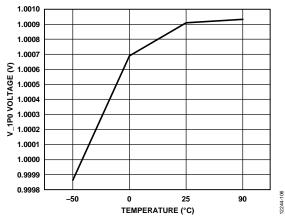


Figure 74. Typical V\_1P0 Drift

The external reference must be a stable 1.0 V reference. The ADR130 is a good option for providing the 1.0 V reference. Figure 75 shows how the ADR130 can be used to provide the external 1.0 V reference to the AD9234. The grayed out areas show unused blocks within the AD9234 while using the ADR130 to provide the external reference.

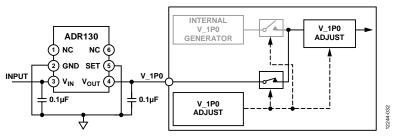


Figure 75. External Reference Using ADR130

#### **CLOCK INPUT CONSIDERATIONS**

For optimum performance, drive the AD9234 sample clock inputs (CLK+ and CLK-) with a differential signal. This signal is typically ac-coupled to the CLK+ and CLK- pins via a transformer or clock drivers. These pins are biased internally and require no additional biasing.

Figure 76 shows a preferred method for clocking the AD9234. The low jitter clock source is converted from a single-ended signal to a differential signal using an RF transformer.

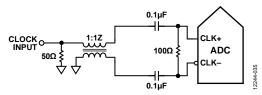


Figure 76. Transformer-Coupled Differential Clock

Another option is to ac couple a differential CML or LVDS signal to the sample clock input pins, as shown in Figure 77 and Figure 78.

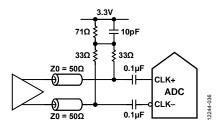


Figure 77. Differential CML Sample Clock

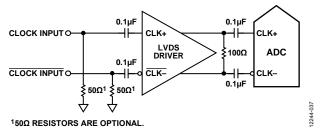


Figure 78. Differential LVDS Sample Clock

## **Clock Duty Cycle Considerations**

Typical high speed ADCs use both clock edges to generate a variety of internal timing signals. As a result, these ADCs may be sensitive to clock duty cycle. Commonly, a 5% tolerance is required on the clock duty cycle to maintain dynamic performance characteristics. In applications where the clock duty cycle cannot be guaranteed to be 50%, a higher multiple frequency clock can be supplied to the device. The AD9234 can be clocked at 2 GHz with the internal clock divider set to 2. The output of the divider offers a 50% duty cycle, high slew rate (fast edge) clock signal to the internal ADC. See the Memory Map section for more details on using this feature.

#### **Input Clock Divider**

The AD9234 contains an input clock divider with the ability to divide the Nyquist input clock by 1, 2, 4, and 8. The divider ratios can be selected using Register 0x10B. This is shown in Figure 79.

The maximum frequency at the CLK± inputs is 4 GHz. This is the limit of the divider. In applications where the clock input is a multiple of the sample clock, care must be taken to program the appropriate divider ratio into the clock divider before applying the clock signal. This ensures that the current transients during device startup are controlled.

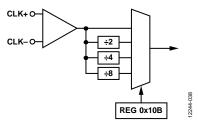


Figure 79. Clock Divider Circuit

The AD9234 clock divider can be synchronized using the external SYSREF± input. A valid SYSREF± causes the clock divider to reset to a programmable state. This feature is enabled by setting Bit 7 of Register 0x10D. This synchronization feature allows multiple devices to have their clock dividers aligned to guarantee simultaneous input sampling. See the Multichip Synchronization section for more information

## Input Clock Divider 1/2 Period Delay Adjust

The input clock divider inside the AD9234 provides phase delay in increments of ½ the input clock cycle. Register 0x10C can be programmed to enable this delay independently for each channel. Changing this register does not affect the stability of the JESD204B link.

## **Clock Fine Delay Adjust**

The AD9234 sampling edge instant can be adjusted by writing to Register 0x117 and Register 0x118. Setting Bit 0 of Register 0x117 enables the feature, and Register 0x118, Bits[7:0] set the value of the delay. This value can be programmed individually for each channel. The clock delay can be adjusted from -151.7 ps to +150 ps in  $\sim 1.7$  ps increments. The clock delay adjust takes effect immediately when it is enabled via SPI writes. Enabling the clock fine delay adjust in Register 0x117 causes a datapath reset. However, the contents of Register 0x118 can be changed without affecting the stability of the JESD204B link.

#### **Clock Jitter Considerations**

High speed, high resolution ADCs are sensitive to the quality of the clock input. The degradation in SNR at a given input frequency  $(f_A)$  due only to aperture jitter  $(t_I)$  can be calculated by

$$SNR = 20 \times \log 10 \ (2 \times \pi \times f_A \times t_J)$$

In this equation, the rms aperture jitter represents the root mean square of all jitter sources, including the clock input, analog input signal, and ADC aperture jitter specifications. IF undersampling applications are particularly sensitive to jitter (see Figure 80).

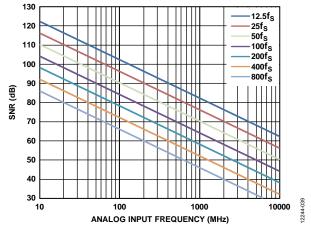


Figure 80. Ideal SNR vs. Analog Input Frequency and Jitter

Treat the clock input as an analog signal in cases where aperture jitter may affect the dynamic range of the AD9234. Separate power supplies for clock drivers from the ADC output driver supplies to avoid modulating the clock signal with digital noise. If the clock is generated from another type of source (by gating, dividing, or other methods), retime the clock by the original clock at the last step. Refer to the AN-501 Application Note and the AN-756 Application Note for more in-depth information about jitter performance as it relates to ADCs.

#### POWER-DOWN/STANDBY MODE

The AD9234 has a PDWN/STBY pin that can be used to configure the device in power-down or standby mode. The default operation is the PDWN function. The PDWN/STBY pin is a logic high pin. When in power-down mode, the JESD204B link is disrupted. The power-down option can also be set via Register 0x03F and Register 0x040.

In standby mode, the JESD204B link is not disrupted and transmits zeroes for all converter samples. This can be changed using Register 0x571, Bit 7 to select /K/ characters.

#### **TEMPERATURE DIODE**

The AD9234 contains a diode-based temperature sensor for measuring the temperature of the die. This diode can output a voltage and serve as a coarse temperature sensor to monitor the internal die temperature.

The temperature diode voltage can be output to the FD\_A pin using the SPI. Use Register 0x028, Bit 0 to enable or disable the diode. Register 0x028 is a local register. Channel A must be selected in the device index register (Register 0x008) to enable the temperature diode readout. Configure the FD\_A pin to output the diode voltage by programming Register 0x040[2:0]. See Table 22 for more information.

The voltage response of the temperature diode (SPIVDD = 1.8 V) is shown in Figure 81.

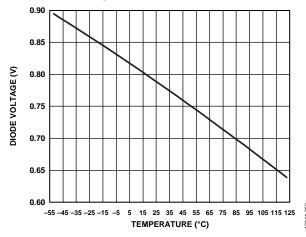


Figure 81. Diode Voltage vs. Temperature

## ADC OVERRANGE AND FAST DETECT

In receiver applications, it is desirable to have a mechanism to reliably determine when the converter is about to be clipped. The standard overrange bit in the JESD204B outputs provides information on the state of the analog input that is of limited usefulness. Therefore, it is helpful to have a programmable threshold below full scale that allows time to reduce the gain before the clip actually occurs. In addition, because input signals can have significant slew rates, the latency of this function is of major concern. Highly pipelined converters can have significant latency. The AD9234 contains fast detect circuitry for individual channels to monitor the threshold and assert the FD\_A and FD\_B pins.

#### **ADC OVERRANGE**

The ADC overrange indicator is asserted when an overrange is detected on the input of the ADC. The overrange indicator can be embedded within the JESD204B link as a control bit (when CSB > 0). The latency of this overrange indicator matches the sample latency.

The AD9234 also records any overrange condition in any of the four virtual converters. For more information on the virtual converters, refer to Figure 87. The overrange status of each virtual converter is registered as a sticky bit in Register 0x563. The contents of Register 0x563 can be cleared using Register 0x562, by toggling the bits corresponding to the virtual converter to set and reset position.

## FAST THRESHOLD DETECTION (FD A AND FD B)

The FD bit (enabled via the control bits in Register 0x559 and Register 0x55A) is immediately set whenever the absolute value of the input signal exceeds the programmable upper threshold level. The FD bit is only cleared when the absolute value of the input signal drops below the lower threshold level for greater than the programmable dwell time. This feature provides hysteresis and prevents the FD bit from excessively toggling.

The operation of the upper threshold and lower threshold registers, along with the dwell time registers, is shown in Figure 82.

The FD indicator is asserted if the input magnitude exceeds the value programmed in the fast detect upper threshold registers, located at Register 0x247 and Register 0x248. The selected threshold register is compared with the signal magnitude at the output of the ADC. The fast upper threshold detection has a latency of 28 clock cycles (maximum). The approximate upper threshold magnitude is defined by

*Upper Threshold Magnitude* (dBFS) =  $20 \log (Threshold Magnitude/2^{13})$ 

The FD indicators are not cleared until the signal drops below the lower threshold for the programmed dwell time. The lower threshold is programmed in the fast detect lower threshold registers, located at Register 0x249 and Register 0x24A. The fast detect lower threshold register is a 13-bit register that is compared with the signal magnitude at the output of the ADC. This comparison is subject to the ADC pipeline latency, but is accurate in terms of converter resolution. The lower threshold magnitude is defined by

Lower Threshold Magnitude (dBFS) = 20 log (Threshold Magnitude/2<sup>13</sup>)

For example, to set an upper threshold of −6 dBFS, write 0xFFF to Register 0x247 and Register 0x248. To set a lower threshold of −10 dBFS, write 0xA1D to Register 0x249 and Register 0x24A.

The dwell time can be programmed from 1 to 65,535 sample clock cycles by placing the desired value in the fast detect dwell time registers, located at Register 0x24B and Register 0x24C. See the Memory Map section (Register 0x040, and Register 0x245 to Register 0x24C in Table 22) for more details.

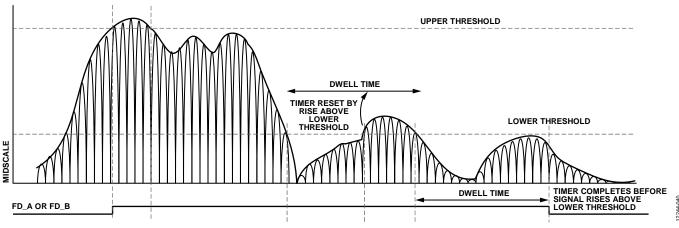


Figure 82. Threshold Settings for FD\_A and FD\_B Signals

## SIGNAL MONITOR

The signal monitor block provides additional information about the signal being digitized by the ADC. The signal monitor computes the peak magnitude of the digitized signal. This information can be used to drive an AGC loop to optimize the range of the ADC in the presence of real-world signals.

The results of the signal monitor block can be obtained either by reading back the internal values from the SPI port or by embedding the signal monitoring information into the JESD204B interface as special control bits. A global, 24-bit programmable period controls the duration of the measurement. Figure 83 shows the simplified block diagram of the signal monitor block.

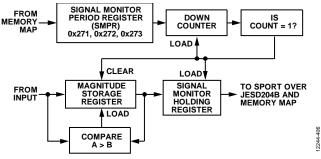


Figure 83. Signal Monitor Block

The peak detector captures the largest signal within the observation period. The detector only observes the magnitude of the signal. The resolution of the peak detector is a 13-bit value and the observation period is 24 bits and represents converter output samples. The peak magnitude can be derived by using the following equation:

 $Peak\ Magnitude\ (dBFS) = 20\ log\ (Peak\ Detector\ Value/2^{13})$ 

The magnitude of the input port signal is monitored over a programmable time period, which is determined by the signal monitor period register (SMPR). The peak detector function is enabled by setting Bit 1 of Register 0x270 in the signal monitor control register. The 24-bit SMPR must be programmed before activating this mode.

After enabling this mode, the value in the SMPR is loaded into a monitor period timer, which decrements at the decimated clock rate. The magnitude of the input signal is compared with the value in the internal magnitude storage register (not accessible to the user), and the greater of the two is updated as the current peak level. The initial value of the magnitude storage register is set to the current ADC input signal magnitude. This comparison continues until the monitor period timer reaches a count of 1.

When the monitor period timer reaches a count of 1, the 13-bit peak level value is transferred to the signal monitor holding register, which can be read through the memory map or output through the SPORT over the JESD204B interface. The monitor period timer is reloaded with the value in the SMPR, and the countdown is restarted. In addition, the magnitude of the first input sample is updated in the magnitude storage register, and the comparison and update procedure, as explained previously, continues.

#### **SPORT Over JESD204B**

The signal monitor data can also be serialized and sent over the JESD204B interface as control bits. These control bits must be deserialized from the samples to reconstruct the statistical data. This function is enabled by setting Bit 1 and Bit 0 of Register 0x279 and Bit 1 of Register 0x27A. Figure 84 shows two different example configurations for the signal monitor control bit locations inside the JESD204B samples. There are a maximum of three control bits that can be inserted into the JESD204B samples; however, only one control bit is required for the signal monitor. Control bits are inserted from MSB to LSB. If only one control bit is to be inserted (CS = 1), then only the most significant control bit is used (see Example Configuration 1 and Example Configuration 2 in Figure 84). To select the SPORT over JESD204B option, program Register 0x559, Register 0x55A, and Register 0x58F. See Table 22 for more information on setting these bits.

Figure 85 shows the 25-bit frame data that encapsulates the peak detector value. The frame data is transmitted MSB first with five 5-bit subframes. Each subframe contains a start bit that can be used by a receiver to validate the deserialized data. Figure 86 shows the SPORT over JESD204B signal monitor data with a monitor period timer set to 80 samples.

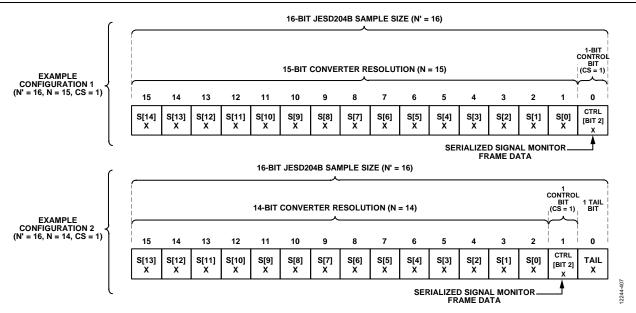


Figure 84. Signal Monitor Control Bit Locations

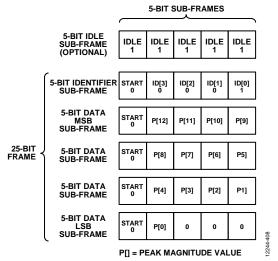


Figure 85. SPORT over JESD204B Signal Monitor Frame Data

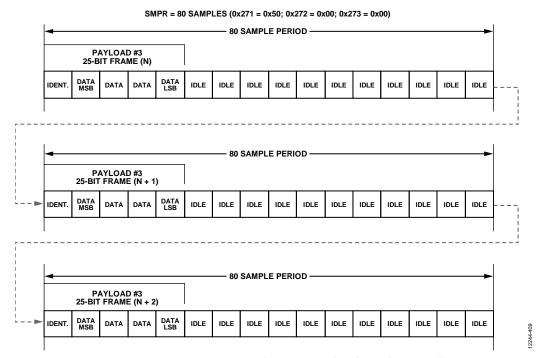


Figure 86. SPORT over JESD204B Signal Monitor Example with Period = 80 Samples

## DIGITAL DOWNCONVERTER (DDC)

The AD9234 includes two digital downconverters (DDC 0 and DDC 1) that provide filtering and reduce the output data rate. This digital processing section includes a half-band decimating filter, a gain stage, and a complex to real conversion stage. Each of these processing blocks has control lines that allow it to be independently enabled and disabled to provide the desired processing function. The digital downconverter can be configured to output either real data or complex output data.

### **DDC GENERAL DESCRIPTION**

The two DDC blocks are used to extract a portion of the full digital spectrum captured by the ADC(s). They are intended for IF sampling or oversampled baseband radios requiring wide bandwidth input signals.

Each DDC block contains a decimate-by-2 digital processing block, as shown in Figure 87.

When DDCs have different decimation ratios, the chip decimation ratio (Register 0x201) must be set to the lowest decimation ratio of all the DDC blocks. In this scenario, samples of higher decimation ratio DDCs are repeated to match the chip decimation ratio sample rate. Whenever the NCO frequency is set or changed, the DDC soft reset must be issued. If the DDC soft reset is not issued, the output may potentially show amplitude variations. The DDCs output a 16-bit stream. To enable this operation, the converter number of bits N is set to a default value of 16, even though the analog core only outputs 12 bits.

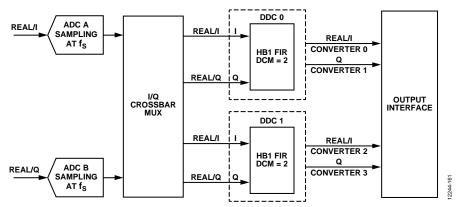


Figure 87. DDC Detailed Block Diagram

## **HALF-BAND FILTER**

The AD9234 offers one half-band filter per DDC to enable digital signal processing of the ADC converted data.

The decimate-by-2, half-band (HB), low-pass FIR filter uses a 55-tap, symmetrical, fixed coefficient filter implementation, optimized for low power consumption. The HB filter is enabled when the DDC is selected. Table 10 and Figure 88 show the coefficients and response of the HB1 filter.

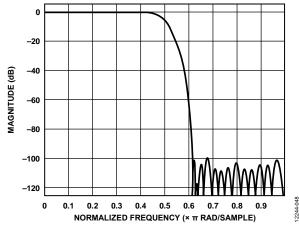


Figure 88. HB1 Filter Response

Table 10. Half-Band Filter Coefficients

HB1 Coefficient Normalized		Decimal	
Number	Coefficient	Coefficient (21-Bit)	
C1, C55	-0.000023	-24	
C2, C54	0	0	
C3, C53	0.000097	102	
C4, C52	0	0	
C5, C51	-0.000288	-302	
C6, C50	0	0	
C7, C49	0.000696	730	
C8, C48	0	0	
C9, C47	-0.0014725	-1544	
C10, C46	0	0	
C11, C45	0.002827	2964	
C12, C44	0	0	
C13, C43	-0.005039	-5284	
C14, C42	0	0	
C15, C41	0.008491	8903	
C16, C40	0	0	
C17, C39	-0.013717	-14,383	
C18, C38	0	0	
C19, C37	0.021591	22640	
C20, C36	0	0	
C21, C35	-0.033833	-35476	
C22, C34	0	0	
C23, C33	0.054806	57468	
C24, C32	0	0	
C25, C31	-0.100557	-105442	
C26, C30	0	0	
C27, C29	0.316421	331,792	
C28	0.500000	524,288	

#### **DDC GAIN STAGE**

Each DDC contains an independently controlled gain stage. The gain is selectable as either 0 dB or 6 dB. When mixing a real input signal down to baseband, it is recommended that the user enable the 6 dB of gain to recenter the dynamic range of the signal within the full scale of the output bits.

When mixing a complex input signal down to baseband, the mixer has already recentered the dynamic range of the signal within the full scale of the output bits and no additional gain is necessary. However, the optional 6 dB gain can be used to compensate for low signal strengths. The downsample by 2 portion of the HB1 FIR filter is bypassed when using the complex to real conversion stage (see Figure 89).

#### **DDC COMPLEX TO REAL CONVERSION**

Each DDC contains an independently controlled complex to real conversion block. The complex to real conversion block reuses the last filter (HB1 FIR) in the filtering stage, along with an  $f_{\rm S}/4$  complex mixer, to upconvert the signal.

After upconverting the signal, the Q portion of the complex mixer is no longer needed and is dropped.

Figure 89 shows a simplified block diagram of the complex to real conversion.

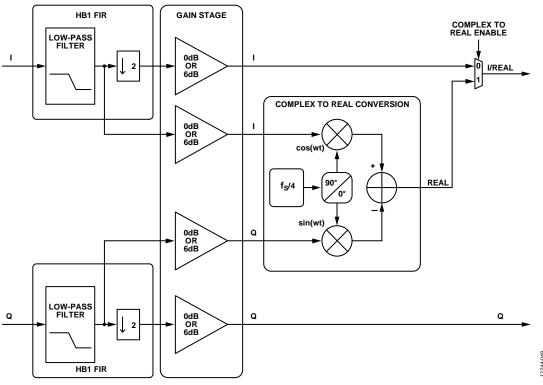


Figure 89. Complex to Real Conversion Block

## DIGITAL OUTPUTS

## **INTRODUCTION TO THE JESD204B INTERFACE**

The AD9234 digital outputs are designed to the JEDEC standard JESD204B, serial interface for data converters. JESD204B is a protocol to link the AD9234 to a digital processing device over a serial interface with lane rates of up to 10 Gbps. The benefits of the JESD204B interface over LVDS include a reduction in required board area for data interface routing, and an ability to enable smaller packages for converter and logic devices.

#### **JESD204B OVERVIEW**

The JESD204B data transmit block assembles the parallel data from the ADC into frames and uses 8B/10B encoding as well as optional scrambling to form serial output data. Lane synchronization is supported through the use of special control characters during the initial establishment of the link. Additional control characters are embedded in the data stream to maintain synchronization thereafter. A JESD204B receiver is required to complete the serial link. For additional details on the JESD204B interface, users are encouraged to refer to the JESD204B standard.

The AD9234 JESD204B data transmit block maps up to two physical ADCs or up to eight virtual converters (when DDCs are enabled) over a link. A link can be configured to use one, two, or four JESD204B lanes. The JESD204B specification refers to a number of parameters to define the link, and these parameters must match between the JESD204B transmitter (the AD9234 output) and the JESD204B receiver (the logic device input).

The JESD204B link is described according to the following parameters:

- L = number of lanes/converter device (lanes/link) (AD9234 value = 1, 2, or 4)
- M = number of converters/converter device (virtual converters/link) (AD9234 value = 1, 2, 4, or 8)
- F = octets/frame (AD9234 value = 1, 2, 4, 8, or 16)
- N' = number of bits per sample (JESD204B word size) (AD9234 value = 8 or 16)
- N = converter resolution (AD9234 value = 7 to 16)
- CS = number of control bits/sample (AD9234 value = 0, 1, 2, or 3)

- K = number of frames per multiframe (AD9234 value = 4, 8, 12, 16, 20, 24, 28, or 32)
- S = samples transmitted/single converter/frame cycle (AD9234 value = set automatically based on L, M, F, and N')
- HD = high density mode (AD9234 = set automatically based on L, M, F, and N')
- CF = number of control words/frame clock cycle/converter device (AD9234 value = 0)

Figure 90 shows a simplified block diagram of the AD9234 JESD204B link. By default, the AD9234 is configured to use two converters and four lanes. Converter A data is output to SERDOUT0 $\pm$  and/or SERDOUT1 $\pm$ , and Converter B is output to SERDOUT2 $\pm$  and/or SERDOUT3 $\pm$ . The AD9234 allows other configurations such as combining the outputs of both converters onto a single lane, or changing the mapping of the A and B digital output paths. These modes are set up via a quick configuration register in the SPI register map, along with additional customizable options.

By default in the AD9234, the 12-bit converter word from each converter is broken into two octets (eight bits of data). Bit 13 (MSB) through Bit 6 are in the first octet. The second octet contains Bit 5 through Bit 0 (LSB) and two tail bits. The tail bits can be configured as zeros or a pseudorandom number sequence. The tail bits can also be replaced with control bits indicating overrange, SYSREF±, signal monitor, or fast detect output.

The two resulting octets can be scrambled. Scrambling is optional; however, it is recommended to avoid spectral peaks when transmitting similar digital data patterns. The scrambler uses a self-synchronizing, polynomial-based algorithm defined by the equation  $1 + x^{14} + x^{15}$ . The descrambler in the receiver is a self-synchronizing version of the scrambler polynomial.

The two octets are then encoded with an 8B/10B encoder. The 8B/10B encoder works by taking eight bits of data (an octet) and encoding them into a 10-bit symbol. Figure 91 shows how the 12-bit data is taken from the ADC, the tail bits are added, the two octets are scrambled, and how the octets are encoded into two 10-bit symbols. Figure 91 illustrates the default data format.

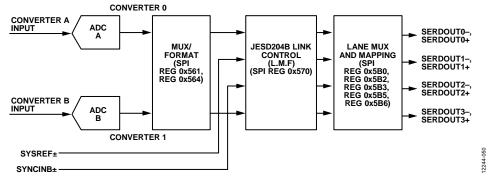


Figure 90. Transmit Link Simplified Block Diagram Showing Full Bandwidth Mode (Register 0x200 = 0x00)

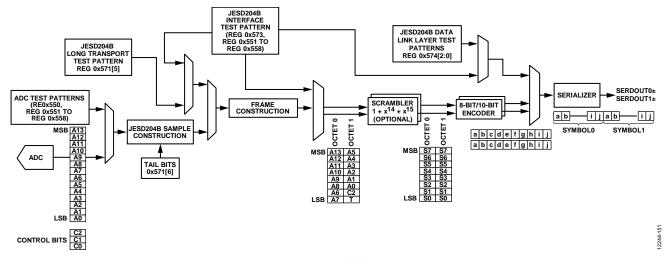


Figure 91. ADC Output Datapath Showing Data Framing

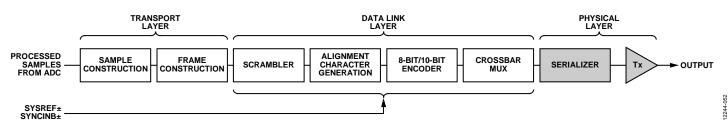


Figure 92. Data Flow

#### **FUNCTIONAL OVERVIEW**

The block diagram in Figure 92 shows the flow of data through the JESD204B hardware from the sample input to the physical output. The processing can be divided into layers that are derived from the open-source initiative (OSI) model widely used to describe the abstraction layers of communications systems. These layers are the transport layer, data link layer, and physical layer (serializer and output driver).

#### **Transport Layer**

The transport layer handles packing the data (consisting of samples and optional control bits) into JESD204B frames that are mapped to 8-bit octets. These octets are sent to the data link layer. The transport layer mapping is controlled by rules derived from the link parameters. Tail bits are added to fill gaps where required. The following equation can be used to determine the

number of tail bits within a sample (JESD204B word):

$$T = N' - N - CS$$

## **Data Link Layer**

The data link layer is responsible for the low level functions of passing data across the link. These include optionally scrambling the data, inserting control characters for multichip synchronization/lane alignment/monitoring, and encoding 8-bit octets into 10-bit symbols. The data link layer is also responsible for sending the initial lane alignment sequence (ILAS), which contains the link configuration data used by the receiver to verify the settings in the transport layer.

#### **Physical Layer**

The physical layer consists of the high speed circuitry clocked at the serial clock rate. In this layer, parallel data is converted into one, two, or four lanes of high speed differential serial data.

#### **JESD204B LINK ESTABLISHMENT**

The AD9234 JESD204B transmitter (Tx) interface operates in Subclass 1 as defined in the JEDEC Standard JESD204B (July 2011 specification). The link establishment process is divided into the following steps: code group synchronization and SYNCINB±, initial lane alignment sequence, and user data and error correction.

#### Code Group Synchronization (CGS) and SYNCINB±

The CGS is the process by which the JESD204B receiver finds the boundaries between the 10-bit symbols in the stream of data. During the CGS phase, the JESD204B transmit block transmits /K28.5/ characters. The receiver must locate /K28.5/ characters in its input data stream using clock and data recovery (CDR) techniques.

The receiver issues a synchronization request by asserting the SYNCINB± pin of the AD9234 low. The JESD204B Tx then begins sending /K/ characters. After the receiver has synchronized, it waits for the correct reception of at least four consecutive /K/ symbols. It then deasserts SYNCINB±. The AD9234 then transmits an ILAS on the following local multiframe clock (LMFC) boundary.

For more information on the code group synchronization phase, refer to the JEDEC Standard JESD204B, July 2011, Section 5.3.3.1.

The SYNCINB± pin operation can also be controlled by the SPI. The SYNCINB± signal is a differential dc-coupled LVDS mode signal by default, but it can also be driven single-ended. For more information on configuring the SYNCINB± pin operation, refer to Register 0x572.

#### **Initial Lane Alignment Sequence (ILAS)**

The ILAS phase follows the CGS phase and begins on the next LMFC boundary. The ILAS consists of four multiframes, with an /R/ character marking the beginning and an /A/ character marking the end. The ILAS begins by sending an /R/ character followed by 0 to 255 ramp data for one multiframe. On the second multiframe, the link configuration data is sent, starting with the third character. The second character is a /Q/ character to confirm that the link configuration data follows. All undefined data slots are filled with ramp data. The ILAS sequence is never scrambled.

The ILAS sequence construction is shown in Figure 93. The four multiframes include the following:

- Multiframe 1. Begins with an /R/ character (/K28.0/) and ends with an /A/ character (/K28.3/).
- Multiframe 2. Begins with an /R/ character followed by a /Q/ (/K28.4/) character, followed by link configuration parameters over 14 configuration octets (see Table 11) and ends with an /A/ character. Many of the parameter values are of the value 1 notation.
- Multiframe 3. Begins with an /R/ character (/K28.0/) and ends with an /A/ character (/K28.3/).
- Multiframe 4. Begins with an /R/ character (/K28.0/) and ends with an /A/ character (/K28.3/).

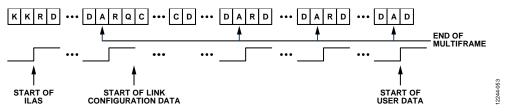


Figure 93. Initial Lane Alignment Sequence

#### **User Data and Error Detection**

After the initial lane alignment sequence is complete, the user data is sent. Normally, within a frame, all characters are considered user data. However, to monitor the frame clock and multiframe clock synchronization, there is a mechanism for replacing characters with /F/ or /A/ alignment characters when the data meets certain conditions. These conditions are different for unscrambled and scrambled data. The scrambling operation is enabled by default, but it can be disabled using the SPI.

For scrambled data, any 0xFC character at the end of a frame is replaced by an /F/, and any 0x7C character at the end of a multiframe is replaced with an /A/. The JESD204B receiver (Rx) checks for /F/ and /A/ characters in the received data stream and verifies that they only occur in the expected locations. If an unexpected /F/ or /A/ character is found, the receiver handles the situation by using dynamic realignment or asserting the SYNCINB± signal for more than four frames to initiate a resynchronization. For unscrambled data, if the final character of two subsequent frames is equal, the second character is replaced with an /F/ if it is at the end of a frame, and an /A/ if it is at the end of a multiframe.

Insertion of alignment characters can be modified using SPI. The frame alignment character insertion (FACI) is enabled by default. More information on the link controls is available in the Memory Map section, Register 0x571.

#### 8B/10B Encoder

The 8B/10B encoder converts 8-bit octets into 10-bit symbols and inserts control characters into the stream when needed. The control characters used in JESD204B are shown in Table 11. The 8B/10B encoding ensures that the signal is dc balanced by using the same number of ones and zeros across multiple symbols.

The 8B/10B interface has options that can be controlled via the SPI. These operations include bypass and invert. These options are intended to be troubleshooting tools for the verification of the digital front end (DFE). Refer to the Memory Map section, Register 0x572[2:1] for information on configuring the 8B/10B encoder.

Table 11. AD9234 Control Characters Used in JESD204B

Abbreviation	Control Symbol	8-Bit Value	10-Bit Value, RD¹ = −1	10-Bit Value, RD <sup>1</sup> = +1	Description
/R/	/K28.0/	000 11100	001111 0100	110000 1011	Start of multiframe
/A/	/K28.3/	011 11100	001111 0011	110000 1100	Lane alignment
/Q/	/K28.4/	100 11100	001111 0010	110000 1101	Start of link configuration data
/K/	/K28.5/	101 11100	001111 1010	110000 0101	Group synchronization
/F/	/K28.7/	111 11100	001111 1000	110000 0111	Frame alignment

<sup>&</sup>lt;sup>1</sup> RD means running disparity.

#### PHYSICAL LAYER (DRIVER) OUTPUTS

#### **Digital Outputs, Timing, and Controls**

The AD9234 physical layer consists of drivers that are defined in the JEDEC Standard JESD204B, July 2011. The differential digital outputs are powered up by default. The drivers use a dynamic  $100~\Omega$  internal termination to reduce unwanted reflections.

Place a  $100 \Omega$  differential termination resistor at each receiver, which results in a nominal 300 mV p-p swing at the receiver (see Figure 94). It is recommended to use ac coupling to connect the AD9234 SERDES outputs to the receiver.

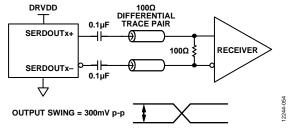


Figure 94. AC-Coupled Digital Output Termination Example

If there is no far-end receiver termination, or if there is poor differential trace routing, timing errors may result. To avoid such timing errors, it is recommended that the trace length be less than six inches, and that the differential output traces be close together and at equal lengths.

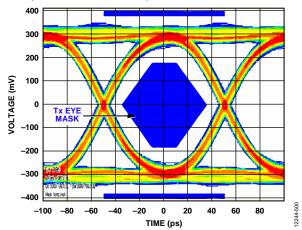


Figure 95. Digital Outputs Data Eye, External 100  $\Omega$  Terminations at 10 Gbps

Figure 95 to Figure 100 show examples of the digital output data eye, time interval error (TIE) jitter histogram, and bathtub curve for one AD9234 lane running at 10 Gbps and 6 Gbps, respectively. The format of the output data is twos complement by default. To change the output data format, see the Memory Map section (Register 0x561 in Table 22).

#### **De-Emphasis**

De-emphasis enables the receiver eye diagram mask to be met in conditions where the interconnect insertion loss does not meet the JESD204B specification. Use the de-emphasis feature only when the receiver is unable to recover the clock due to excessive insertion loss. Under normal conditions, it is disabled to conserve power. Additionally, enabling and setting too high a de-emphasis value on a short link may cause the receiver eye diagram to fail. Use the de-emphasis setting with caution because it may increase electromagnetic interference (EMI). See the Memory Map section (Register 0x5C1 to Register 0x5C5 in Table 22) for more details.

## **Phase-Locked Loop**

The PLL is used to generate the serializer clock, which will operate at the JESD204B lane rate. The JESD204B lane rate Register 0x056E[4:3] must be set to correspond with the lane rate.

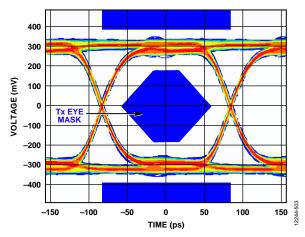


Figure 96. Digital Outputs Data Eye, External 100  $\Omega$  Terminations at 6 Gbps

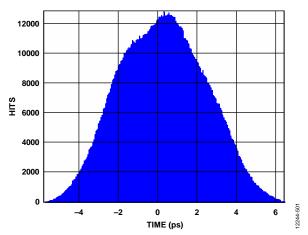


Figure 97. Digital Outputs Histogram, External 100  $\Omega$  Terminations at 10 Gbps

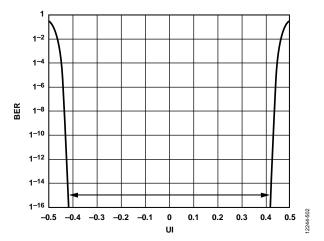


Figure 98. Digital Outputs Bathtub Curve, External 100  $\Omega$  Terminations at 10 Gbps

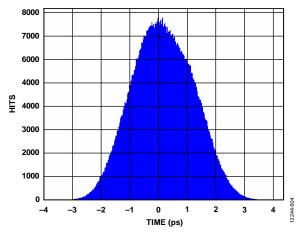


Figure 99. Digital Outputs Histogram, External 100  $\Omega$  Terminations at 6 Gbps

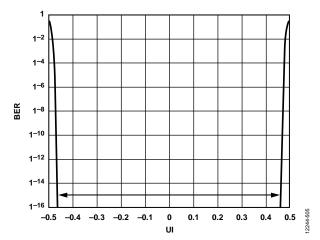


Figure 100. Digital Outputs Bathtub Curve, External 100  $\Omega$  Terminations at 6 Gbps

#### **CONFIGURING THE JESD204B LINK**

The AD9234 has one JESD204B link. The device offers an easy way to set up the JESD204B link through the quick configuration register (Register 0x570). The serial outputs (SERDOUT0± to SERDOUT3±) are considered to be part of one JESD204B link. The basic parameters that determine the link setup are

- Number of lanes per link (L)
- Number of converters per link (M)
- Number of octets per frame (F)

The maximum lane rate allowed by the JESD204B specification is 12.5 Gbps. The lane line rate is related to the JESD204B parameters using the following equation:

$$Lane\ Line\ Rate = \frac{M \times N' \times \left(\frac{10}{8}\right) \times f_{OUT}}{L}$$

where  $f_{OUT} = f_{ADC\_CLOCK}/decimation ratio$ .

The following steps can be used to configure the output:

- Power down the link.
- 2. Select quick configuration options.
- 3. Configure detailed options.
- 4. Set output lane mapping (optional).
- 5. Set additional driver configuration options (optional).
- 6. Power up the link.

If the lane line rate calculated is less than 6.25 Gbps, select the low line rate option. This is done by programming a value of 0x10 to Register 0x56E.

Table 12 and Table 13 show the JESD204B output configurations supported for both N'=16 and N'=8 for a given number of virtual converters. Care must be taken to ensure that the serial line rate for a given configuration is within the supported range of 3.125 Gbps to 12.5 Gbps.

Table 12. JESD204B Output Configurations for N' = 16

Number of Virtual					J	ESD2	04B Tra	nsport La	yer Se	ettings <sup>2</sup>	
Converters Supported (Same Value as M)	JESD204B Quick Configuration (0x570)	JESD204B Serial Line Rate <sup>1</sup>	L	М	F	s	HD	N	N'	cs	<b>K</b> <sup>3</sup>
1	0x01	20 × f <sub>оит</sub>	1	1	2	1	0	8 to 16	16	0 to 3	Only valid K
	0x40	10 × f <sub>оит</sub>	2	1	1	1	1	8 to 16	16	0 to 3	values that
	0x41	10 × f <sub>оит</sub>	2	1	2	2	0	8 to 16	16	0 to 3	are divisible by 4 are supported
	0x80	$5 \times f_{\text{OUT}}$	4	1	1	2	1	8 to 16	16	0 to 3	
	0x81	$5 \times f_{\text{OUT}}$	4	1	2	4	0	8 to 16	16	0 to 3	Supported
2	0x0A	40 × f <sub>OUT</sub>	1	2	4	1	0	8 to 16	16	0 to 3	
	0x49	20 × f <sub>оит</sub>	2	2	2	1	0	8 to 16	16	0 to 3	
	0x88	10 × f <sub>оит</sub>	4	2	1	1	1	8 to 16	16	0 to 3	
	0x89	10 × f <sub>оит</sub>	4	2	2	2	0	8 to 16	16	0 to 3	
4	0x13	80 × f <sub>OUT</sub>	1	4	8	1	0	8 to 16	16	0 to 3	
	0x52	40 × f <sub>оит</sub>	2	4	4	1	0	8 to 16	16	0 to 3	
	0x91	$20 \times f_{OUT}$	4	4	2	1	0	8 to 16	16	0 to 3	

 $<sup>^1</sup>$  f<sub>OUT</sub> = output sample rate = ADC sample rate/chip decimation ratio. The JESD204B serial line rate must be ≥3.125 Gbps and ≤12.5 Gbps; when the serial line rate is ≤12.5 Gbps and ≥6.25 Gbps, the low line rate mode must be disabled (set Bit 4 to 0x0 in 0x56E). When the serial line rate is <6.25 Gbps and ≥3.125 Gbps, the low line rate mode must be enabled (set Bit 4 to 0x1 in 0x56E).

Table 13. JESD204B Output Configurations for N' = 8

Number of Virtual	JESD204B Quick			JESD204B Transport Layer Settings <sup>2</sup>								
Converters Supported (Same Value as M)	Configuration (0x570)	Serial Line Rate <sup>1</sup>		м	F	s	HD	N	N'	cs	K³	
1	0x00	10 × f <sub>оит</sub>	1	1	1	1	0	7 to 8	8	0 to 1	Only valid K	
	0x01	10 × f <sub>o∪T</sub>	1	1	2	2	0	7 to 8	8	0 to 1	values which	
	0x40	$5 \times f_{OUT}$	2	1	1	2	0	7 to 8	8	0 to 1	are divisible by 4 are	
	0x41	$5 \times f_{OUT}$	2	1	2	4	0	7 to 8	8	0 to 1	supported	
	0x42	5 × f <sub>OUT</sub>	2	1	4	8	0	7 to 8	8	0 to 1		
	0x80	2.5 × f <sub>оит</sub>	4	1	1	4	0	7 to 8	8	0 to 1		
	0x81	2.5 × f <sub>OUT</sub>	4	1	2	8	0	7 to 8	8	0 to 1		

<sup>&</sup>lt;sup>2</sup> JESD204B transport layer descriptions are as described in the JESD204B Overview section.

<sup>&</sup>lt;sup>3</sup> For F = 1, K = 20, 24, 28, and 32. For F = 2, K = 12, 16, 20, 24, 28, and 32. For F = 4, K = 8, 12, 16, 20, 24, 28, and 32. For F = 8 and F = 16, K = 4, 8, 12, 16, 20, 24, 28, and 32.

Number of Virtual	JESD204B Quick		JESD204B Transport Layer Settings <sup>2</sup>								2
Converters Supported Configuration (Same Value as M) (0x570)		Serial Line Rate <sup>1</sup>	L	М	F	s	HD	N	N'	cs	<b>K</b> <sup>3</sup>
2	0x09	$20 \times f_{OUT}$	1	2	2	1	0	7 to 8	8	0 to 1	
	0x48	$10 \times f_{OUT}$	2	2	1	1	0	7 to 8	8	0 to 1	
	0x49	$10 \times f_{OUT}$	2	2	2	2	0	7 to 8	8	0 to 1	
	0x88	$5 \times f_{OUT}$	4	2	1	2	0	7 to 8	8	0 to 1	
	0x89	5 × f <sub>out</sub>	4	2	2	4	0	7 to 8	8	0 to 1	
	0x8A	5 × f <sub>OUT</sub>	4	2	4	8	0	7 to 8	8	0 to 1	

¹  $f_{OUT}$  = output sample rate = ADC sample rate/chip decimation ratio. The JESD204B serial line rate must be ≥3125 Mbps and ≤12,500 Mbps; when the serial line rate is ≤12.5 Gbps and ≥6.25 Gbps, the low line rate mode must be disabled (set Bit 4 to 0x0 in Register 0x56E). When the serial line rate is <6.25 Gbps and ≥3.125 Gbps, the low line rate mode must be enabled (set Bit 4 to 0x1 in Register 0x56E).

See the Example 1: Full Bandwidth Mode section, the Example 2: Full Bandwidth Mode at 500 MSPS section, and the Example 3: ADC with DDC Option (Two ADCs Plus Two DDCs) section for examples describing which JESD204B transport layer settings are valid for a given chip mode.

#### **Example 1: Full Bandwidth Mode at 1 GSPS**

Chip application mode is full bandwidth mode (see Figure 101).

- Two 12-bit converters at 1000 MSPS
- Full bandwidth application layer mode
- No decimation

JESD204B output configuration includes the following:

- Two virtual converters required (see Table 12)
- Output sample rate  $(f_{OUT}) = 1000/1 = 1000 \text{ MSPS}$

JESD204B supported output configurations (see Table 12) include

- N' = 16 bits
- N = 12 bits
- L = 4, M = 2, and F = 1, or L = 4, M = 2, and F = 2 (quick configuration = 0x88 or 0x89)
- CS = 0 to 2
- K = 32
- Output serial line rate = 10 Gbps per lane, low line rate mode disabled

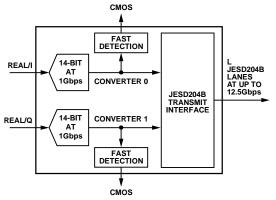


Figure 101. Full Bandwidth Mode

#### **Example 2: Full Bandwidth Mode at 500 MSPS**

Chip application mode is full bandwidth mode (see Figure 101).

- Two 12-bit converters at 500 MSPS
- Full bandwidth application layer mode
- No decimation

JESD204B output configuration includes the following:

- Two virtual converters required (see Table 12)
- Output sample rate  $(f_{OUT}) = 500/1 = 500 \text{ MSPS}$

JESD204B supported output configurations (see Table 12) include

- N' = 16 bits
- N = 12 bits
- L = 4, M = 2, and F = 1, or L = 2, M = 2, and F = 2 (quick configuration = 0x88 or 0x49)
- CS = 0 to 2
- K = 32
- Output serial line rate
  - 5 Gbps per lane for L.M.F = 4.2.1, low line rate mode enabled (0x56E = 0x00)
  - 10 Gbps per lane for L.M.F = 2.2.2, low line rate mode disabled (0x56E = 0x00)

<sup>&</sup>lt;sup>2</sup> JESD204B transport layer descriptions are as described in the JESD204B Overview section.

<sup>&</sup>lt;sup>3</sup> For F = 1, K = 20, 24, 28, and 32. For F = 2, K = 12, 16, 20, 24, 28, and 32. For F = 4, K = 8, 12, 16, 20, 24, 28, and 32. For F = 8 and F = 16, K = 4, 8, 12, 16, 20, 24, 28, and 32.

## Example 3: ADC with DDC Option (Two ADCs Plus Two DDCs)

Chip application mode is two-DDC mode. (see Figure 102).

- Two 12-bit converters at 1 MSPS
- Two DDC application layer mode with complex outputs (I/Q)
- Chip decimation ratio = 2
- DDC decimation ratio = 2 (see Table 22)

JESD204B output configuration includes the following:

- Virtual converters required = 4 (see Table 12)
- Output sample rate  $(f_{OUT}) = 1000/2 = 500 \text{ MSPS}$

JESD204B supported output configurations include (see Table 12)

- N' = 16 bits
- N = 12 bits
- L = 4, M = 4, and F = 2 (quick configuration = 0x91)
- CS = 0 to 1
- K = 32
- Output serial line rate = 10 Gbps per lane (L = 4)
- Low line rate mode is disabled (0x56E = 0x00).

Example 2 shows the flexibility in the digital and lane configurations for the AD9234. The sample rate is 1 GSPS, but the outputs are all combined in either one or two lanes, depending on the I/O speed capability of the receiving device.

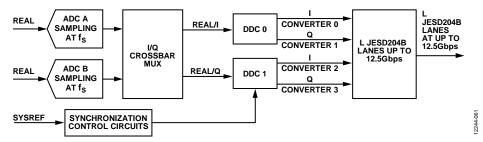


Figure 102. Two-ADC Plus Two-DDC Mode

## MULTICHIP SYNCHRONIZATION

The AD9234 has a SYSREF± input that allows the user flexible options for synchronizing the internal blocks. The SYSREF± input is a source synchronous system reference signal that enables multichip synchronization. The input clock divider, DDCs, signal monitor block, and JESD204B link can be synchronized using the SYSREF± input. For the highest level of timing accuracy, SYSREF± must meet setup and hold requirements relative to the CLK± input.

The flowchart in Figure 103 describes the internal mechanism by which multichip synchronization can be achieved in the AD9234. The AD9234 supports several features which aid users in meeting the requirements set out for capturing a SYSREF± signal. The SYSREF sample event can be defined as either a synchronous low to high transition, or synchronous high to low transition. Additionally, the AD9234 allows the SYSREF signal to be sampled using either the rising edge or falling edge of the CLK± input. The AD9234 also has the ability to ignore a programmable number (up to 16) of SYSREF± events. The SYSREF± control options can be selected using Register 0x120 and Register 0x121.

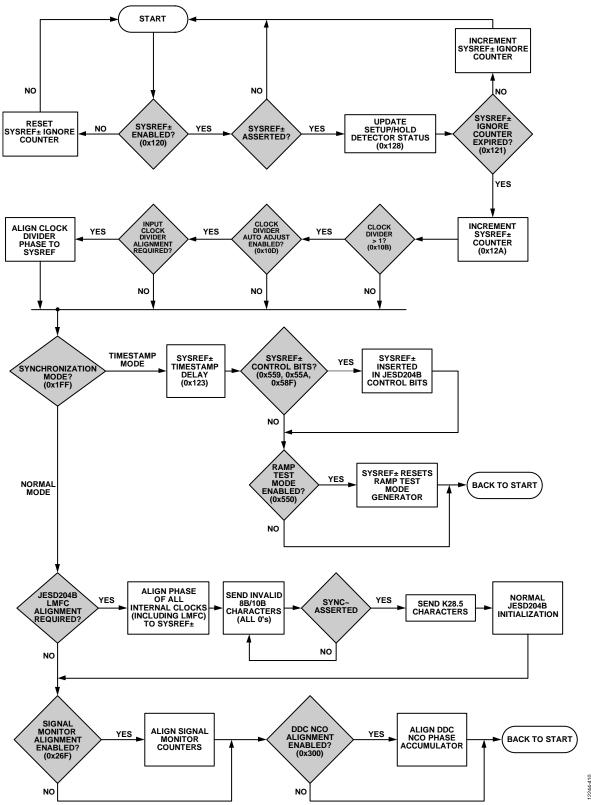


Figure 103. Multichip Synchronization

#### SYSREF± SETUP/HOLD WINDOW MONITOR

To assist in ensuring a valid SYSREF signal capture, the AD9234 has a SYSREF $\pm$  setup/hold window monitor. This feature allows the system designer to determine the location of the SYSREF $\pm$  signals relative to the CLK $\pm$  signals by reading back the amount of setup/hold margin on the interface through the memory map. Figure 104 and Figure 105 show the setup and hold status

values for different phases of SYSREF±. The setup detector returns the status of the SYSREF±signal before the CLK± edge and the hold detector returns the status of the SYSREF signal after the CLK± edge. Register 0x128 stores the status of SYSREF± and lets the user know if the SYSREF± signal is successfully captured by the ADC.

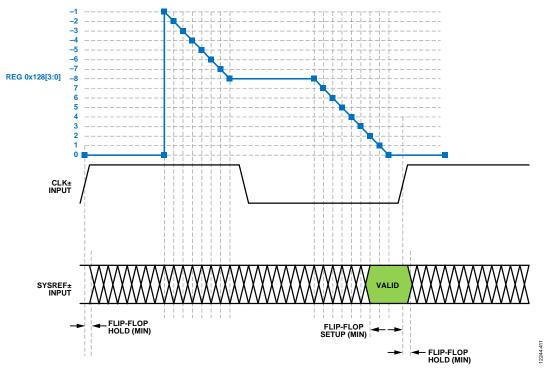


Figure 104. SYSREF± Setup Detector

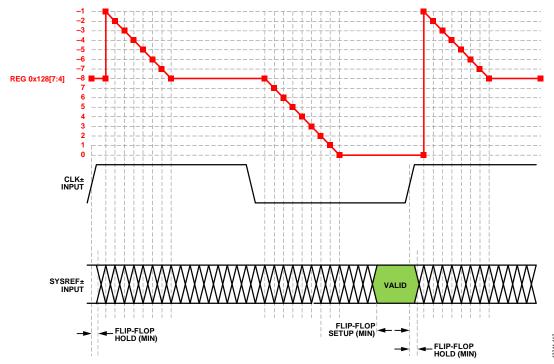


Figure 105. SYSREF± Hold Detector Rev. A | Page 48 of 66

Table 14 shows the description of the contents of Register 0x128 and how to interpret them.

Table 14. SYSREF± Setup/Hold Monitor, Register 0x128

Register 0x128[7:4] Hold Status	Register 0x128[3:0] Setup Status	Description
0x0	0x0 to 0x7	Possible setup error. The smaller this number, the smaller the setup margin.
0x0 to 0x8	0x8	No setup or hold error (best hold margin).
0x8	0x9 to 0xF	No setup or hold error (best setup and hold margin).
0x8	0x0	No setup or hold error (best setup margin).
0x9 to 0xF	0x0	Possible hold error. The larger this number, the smaller the hold margin.
0x0	0x0	Possible setup or hold error.

# TEST MODES ADC TEST MODES

The AD9234 has various test options that aid in the system level implementation. The AD9234 has ADC test modes that are available in Register 0x550. These test modes are described in Table 15. When an output test mode is enabled, the analog section of the ADC is disconnected from the digital back-end blocks, and the test pattern is run through the output formatting block. Some of the test patterns are subject to output formatting, and

some are not. The PN generators from the PN sequence tests can be reset by setting Bit 4 or Bit 5 of Register 0x550. These tests can be performed with or without an analog signal (if present, the analog signal is ignored); however, they do require an encode clock. For more information, see the AN-877 Application Note, *Interfacing to High Speed ADCs via SPI*.

Table 15. ADC Test Modes<sup>1</sup>

Output Test Mode			Default/	
Bit Sequence	Pattern Name	Expression	Seed Value	Sample (N, N + 1, N + 2,)
0000	Off (default)	N/A	N/A	N/A
0001	Midscale short	0000 0000 0000	N/A	N/A
0010	+Full-scale short	0111 1111 1111	N/A	N/A
0011	–Full-scale short	1000 0000 0000	N/A	N/A
0100	Checkerboard	1010 1010 1010	N/A	0x0AAA, 0x0555, 0x0AAA, 0x0555, 0x0AAA
0101	PN sequence long	$X^{23} + X^{18} + 1$	0x3AFF	0x3FD7, 0x0002, 0x26E0, 0x0A3D, 0x1CA6
0110	PN sequence short	$X^9 + X^5 + 1$	0x0092	0x125B, 0x3C9A, 0x2660, 0x0c65, 0x0697
0111	One-/zero-word toggle	1111 1111 1111	N/A	0x0FFF, 0x0000, 0x0FFF, 0x0000, 0x0FFF
1000	User input	Register 0x551 to	N/A	User Pat 1[15:2], User Pat 2[15:2], User Pat 3[15:2], User Pat 4[15:2], User Pat 4[15:2] for repeat mode
		Register 0x558		User Pat 1[15:2], User Pat 1[15:2] for repeat mode
				User Pat 4[15:2], 0x0000 for single mode
1111	Ramp output	(X) % 2 <sup>12</sup>	N/A	$(X) \% 2^{12}, (X+1) \% 2^{12}, (X+2) \% 2^{12}, (X+3) \% 2^{12}$

<sup>&</sup>lt;sup>1</sup> N/A means not applicable.

#### **JESD204B BLOCK TEST MODES**

In addition to the ADC pipeline test modes, the AD9234 also has flexible test modes in the JESD204B block. These test modes are listed in Register 0x573 and Register 0x574. These test patterns can be injected at various points along the output data path. These test injection points are shown in Figure 91. Table 16 describes the various test modes available in the JESD204B block. For the AD9234, a transition from test modes (Register 0x573  $\neq$  0x00) to normal mode (Register 0x573 = 0x00) requires an SPI soft reset. This is done by writing 0x81 to Register 0x00 (self cleared).

#### **Transport Layer Sample Test Mode**

The transport layer samples are implemented in the AD9234 as defined by section 5.1.6.3 in the JEDEC JESD204B Specification. These tests are shown in Register 0x571[5]. The test pattern is equivalent to the raw samples from the ADC.

#### **Interface Test Modes**

The interface test modes are described in Register 0x573 Bits[3:0]. These test modes are also explained in Table 16. The interface tests can be injected at various points along the data. See Figure 91 for more information on the test injection points. Register 0x573 Bits[5:4] show where these tests are injected.

Table 17, Table 18, and Table 19 show examples of some of the test modes when injected at the JESD Sample Input, PHY 10-bit Input, and Scrambler 8-bit Input. UP in the tables represent the user pattern control bits from the customer register map.

Table 16. JESD204B Interface Test Modes

Output Test Mode Bit Sequence	Pattern Name	Expression	Default
0000	Off (default)	Not applicable	Not applicable
0001	Alternating checker board	0x5555, 0xAAAA, 0x5555	Not applicable
0010	1/0 word toggle	0x0000, 0xFFFF, 0x0000	Not applicable
0011	31-bit PN sequence	$X^{31} + X^{28} + 1$	0x0003AFFF
0100	23-bit PN sequence	$X^{23} + X^{18} + 1$	0x003AFF
0101	15-bit PN sequence	$X^{15} + X^{14} + 1$	0x03AF
0110	9-bit PN sequence	$X^9 + X^5 + 1$	0x092
0111	7-bit PN sequence	$X^7 + X^6 + 1$	0x07
1000	Ramp output	(X) % 2 <sup>16</sup>	Ramp size depends on test injection point
1110	Continuous/repeat user test	Register 0x551 to Register 0x558	User Pat 1 to User Pat 4, then repeat
1111	Single user test	Register 0x551 to Register 0x558	User Pat 1 to User Pat 4, then zeroes

Table 17. JESD204B Sample Input for M = 2, S = 2, N' = 16 (Register 0x573[5:4] = 'b00)

Frame	Converter	Sample	Alternating	1/0 Word					
Number	Number	Number	Checkerboard	Toggle	Ramp	PN9	PN23	User Repeat	User Single
0	0	0	0x5555	0x0000	(X) % 2 <sup>16</sup>	0x496F	0xFF5C	UP1[15:0]	UP1[15:0]
0	0	1	0x5555	0x0000	(X) % 2 <sup>16</sup>	0x496F	0xFF5C	UP1[15:0]	UP1[15:0]
0	1	0	0x5555	0x0000	(X) % 2 <sup>16</sup>	0x496F	0xFF5C	UP1[15:0]	UP1[15:0]
0	1	1	0x5555	0x0000	(X) % 2 <sup>16</sup>	0x496F	0xFF5C	UP1[15:0]	UP1[15:0]
1	0	0	0xAAAA	0xFFFF	$(X + 1) \% 2^{16}$	0xC9A9	0x0029	UP2[15:0]	UP2[15:0]
1	0	1	0xAAAA	0xFFFF	$(X + 1) \% 2^{16}$	0xC9A9	0x0029	UP2[15:0]	UP2[15:0]
1	1	0	0xAAAA	0xFFFF	$(X + 1) \% 2^{16}$	0xC9A9	0x0029	UP2[15:0]	UP2[15:0]
1	1	1	0xAAAA	0xFFFF	$(X + 1) \% 2^{16}$	0xC9A9	0x0029	UP2[15:0]	UP2[15:0]
2	0	0	0x5555	0x0000	$(X +2) \% 2^{16}$	0x980C	0xB80A	UP3[15:0]	UP3[15:0]
2	0	1	0x5555	0x0000	(X +2) % 2 <sup>16</sup>	0x980C	0xB80A	UP3[15:0]	UP3[15:0]
2	1	0	0x5555	0x0000	$(X +2) \% 2^{16}$	0x980C	0xB80A	UP3[15:0]	UP3[15:0]
2	1	1	0x5555	0x0000	(X +2) % 2 <sup>16</sup>	0x980C	0xB80A	UP3[15:0]	UP3[15:0]
3	0	0	0xAAAA	0xFFFF	$(X +3) \% 2^{16}$	0x651A	0x3D72	UP4[15:0]	UP4[15:0]
3	0	1	0xAAAA	0xFFFF	$(X +3) \% 2^{16}$	0x651A	0x3D72	UP4[15:0]	UP4[15:0]
3	1	0	0xAAAA	0xFFFF	$(X +3) \% 2^{16}$	0x651A	0x3D72	UP4[15:0]	UP4[15:0]
3	1	1	0xAAAA	0xFFFF	(X +3) % 2 <sup>16</sup>	0x651A	0x3D72	UP4[15:0]	UP4[15:0]
4	0	0	0x5555	0x0000	(X +4) % 2 <sup>16</sup>	0x5FD1	0x9B26	UP1[15:0]	0x0000
4	0	1	0x5555	0x0000	$(X +4) \% 2^{16}$	0x5FD1	0x9B26	UP1[15:0]	0x0000
4	1	0	0x5555	0x0000	$(X +4) \% 2^{16}$	0x5FD1	0x9B26	UP1[15:0]	0x0000
4	1	1	0x5555	0x0000	(X +4) % 2 <sup>16</sup>	0x5FD1	0x9B26	UP1[15:0]	0x0000

Table 18. Physical Layer 10-Bit Input (Register 0x573[5:4] = 'b01)

10-Bit Symbol	Alternating	1/0 Word					
Number	Checkerboard	Toggle	Ramp	PN9	PN23	User Repeat	User Single
0	0x155	0x000	(X) % 2 <sup>10</sup>	0x125	0x3FD	UP1[15:6]	UP1[15:6]
1	0x2AA	0x3FF	$(X + 1)\% 2^{10}$	0x2FC	0x1C0	UP2[15:6]	UP2[15:6]
2	0x155	0x000	$(X + 2)\% 2^{10}$	0x26A	0x00A	UP3[15:6]	UP3[15:6]
3	0x2AA	0x3FF	$(X + 3)\% 2^{10}$	0x198	0x1B8	UP4[15:6]	UP4[15:6]
4	0x155	0x000	$(X + 4)\% 2^{10}$	0x031	0x028	UP1[15:6]	0x000
5	0x2AA	0x3FF	$(X + 5)\% 2^{10}$	0x251	0x3D7	UP2[15:6]	0x000
6	0x155	0x000	$(X + 6)\% 2^{10}$	0x297	0x0A6	UP3[15:6]	0x000
7	0x2AA	0x3FF	$(X + 7)\% 2^{10}$	0x3D1	0x326	UP4[15:6]	0x000
8	0x155	0x000	$(X + 8)\% 2^{10}$	0x18E	0x10F	UP1[15:6]	0x000
9	0x2AA	0x3FF	$(X + 9)\% 2^{10}$	0x2CB	0x3FD	UP2[15:6]	0x000
10	0x155	0x000	$(X + 10)\% 2^{10}$	0x0F1	0x31E	UP3[15:6]	0x000
11	0x2AA	0x3FF	$(X + 11)\% 2^{10}$	0x3DD	0x008	UP4[15:6]	0x000

Table 19. Scrambler 8-Bit Input (Register 0x573[5:4] = 'b10)

8-Bit Octet Number	Alternating Checkerboard	1/0 Word	Rome	PN9	PN23	User Repeat	User Single
Number		Toggle	Ramp			•	
0	0x55	0x00	(X) % 2 <sup>8</sup>	0x49	0xFF	UP1[15:9]	UP1[15:9]
1	0xAA	0xFF	$(X + 1)\% 2^8$	0x6F	0x5C	UP2[15:9]	UP2[15:9]
2	0x55	0x00	$(X + 2)\% 2^8$	0xC9	0x00	UP3[15:9]	UP3[15:9]
3	0xAA	0xFF	$(X + 3)\% 2^8$	0xA9	0x29	UP4[15:9]	UP4[15:9]
4	0x55	0x00	$(X + 4)\% 2^8$	0x98	0xB8	UP1[15:9]	0x00
5	0xAA	0xFF	$(X + 5)\% 2^8$	0x0C	0x0A	UP2[15:9]	0x00
6	0x55	0x00	$(X + 6)\% 2^8$	0x65	0x3D	UP3[15:9]	0x00
7	0xAA	0xFF	$(X + 7)\% 2^8$	0x1A	0x72	UP4[15:9]	0x00
8	0x55	0x00	$(X + 8)\% 2^8$	0x5F	0x9B	UP1[15:9]	0x00
9	0xAA	0xFF	$(X + 9)\% 2^8$	0xD1	0x26	UP2[15:9]	0x00
10	0x55	0x00	(X + 10)% 2 <sup>8</sup>	0x63	0x43	UP3[15:9]	0x00
11	0xAA	0xFF	(X + 11)% 2 <sup>8</sup>	0xAC	0xFF	UP4[15:9]	0x00

#### **Data Link Layer Test Modes**

The data link layer test modes are implemented in the AD9234 as defined by Section 5.3.3.8.2 in the JEDEC JESD204B Specification. These tests are shown in Register 0x574 Bits[2:0].

Test patterns inserted at this point are useful for verifying the functionality of the data link layer. When the data link layer test modes are enabled, disable SYNCINB $\pm$  by writing 0xC0 to Register 0x572.

## SERIAL PORT INTERFACE

The AD9234 SPI allows the user to configure the converter for specific functions or operations through a structured register space provided inside the ADC. The SPI gives the user added flexibility and customization, depending on the application. Addresses are accessed via the serial port and can be written to or read from via the port. Memory is organized into bytes that can be further divided into fields. These fields are documented in the Memory Map section. For detailed operational information, see the Serial Control Interface Standard (Rev. 1.0).

#### **CONFIGURATION USING THE SPI**

Three pins define the SPI of this ADC: the SCLK pin, the SDIO pin, and the CSB pin (see Table 20). The SCLK (serial clock) pin synchronizes the read and write data presented from/to the ADC. The SDIO (serial data input/output) pin is a dual-purpose pin that allows data to be sent and read from the internal ADC memory map registers. The CSB (chip select bar) pin is an active low control that enables or disables the read and write cycles.

**Table 20. Serial Port Interface Pins** 

	· · · · · · · · · · · · · · · · · · ·						
Pin	Function						
SCLK	Serial clock. The serial shift clock input, which is used to synchronize serial interface reads and writes.						
SDIO	Serial data input/output. A dual-purpose pin that typically serves as an input or an output, depending on the instruction being sent and the relative position in the timing frame.						
CSB	Chip select bar. An active low control that gates the read and write cycles.						

The falling edge of CSB, in conjunction with the rising edge of SCLK, determines the start of the framing. An example of the serial timing and its definitions can be found in Figure 3 and Table 5.

Other modes involving the CSB pin are available. The CSB pin can be held low indefinitely, which permanently enables the device; this is called streaming. The CSB pin can stall high between bytes to allow additional external timing. When CSB is tied high, SPI functions are placed in a high impedance mode. This mode turns on any SPI pin secondary functions.

All data is composed of 8-bit words. The first bit of each individual byte of serial data indicates whether a read or write command is issued. This allows the SDIO pin to change direction from an input to an output.

In addition to word length, the instruction phase determines whether the serial frame is a read or write operation, allowing the serial port to be used both to program the chip and to read the contents of the on-chip memory. If the instruction is a readback operation, performing a readback causes the SDIO pin to change direction from an input to an output at the appropriate point in the serial frame.

Data can be sent in MSB first mode or in LSB first mode. MSB first is the default on power-up and can be changed via the SPI port configuration register. For more information about this and other features, see the Serial Control Interface Standard (Rev. 1.0).

#### HARDWARE INTERFACE

The pins described in Table 20 comprise the physical interface between the user programming device and the serial port of the AD9234. The SCLK pin and the CSB pin function as inputs when using the SPI. The SDIO pin is bidirectional, functioning as an input during write phases and as an output during readback.

The SPI is flexible enough to be controlled by either FPGAs or microcontrollers. One method for SPI configuration is described in detail in the AN-812 Application Note, *Microcontroller-Based Serial Port Interface (SPI) Boot Circuit*.

Do not activate the SPI port during periods when the full dynamic performance of the converter is required. Because the SCLK signal, the CSB signal, and the SDIO signal are typically asynchronous to the ADC clock, noise from these signals can degrade converter performance. If the on-board SPI bus is used for other devices, it may be necessary to provide buffers between this bus and the AD9234 to prevent these signals from transitioning at the converter inputs during critical sampling periods.

#### **SPI ACCESSIBLE FEATURES**

Table 21 provides a brief description of the general features that are accessible via the SPI. These features are described in detail in the Serial Control Interface Standard (Rev. 1.0). The AD9234 device specific features are described in the Memory Map section.

Table 21. Features Accessible Using the SPI

Feature Name	Description
Mode	Allows the user to set either power-down mode or standby mode.
Clock	Allows the user to access the clock divider via the SPI.
DDC	Allows the user to set up decimation filters for different applications.
Test Input/Output	Allows the user to set test modes to have known data on output bits.
Output Mode	Allows the user to set up outputs.
SERDES Output Setup	Allows the user to vary SERDES settings such as swing and emphasis.

## MEMORY MAP

#### **READING THE MEMORY MAP REGISTER TABLE**

Each row in the memory map register table has eight bit locations. The memory map is divided into four sections: the Analog Devices SPI registers (Register 0x000 to Register 0x00D), the ADC function registers (Register 0x015 to Register 0x27A), The DDC function registers (Register 0x300 to Register 0x347), and the digital outputs and test modes registers (Register 0x550 to Register 0x5C5).

Table 22 (see the Memory Map section) documents the default hexadecimal value for each hexadecimal address shown. The column with the heading Bit 7 (MSB) is the start of the default hexadecimal value given. For example, Address 0x561, the output mode register, has a hexadecimal default value of 0x01. This means that Bit 0=1, and the remaining bits are 0x. This setting is the default output format value, which is twos complement. For more information on this function and others, see the Table 22.

#### **Open and Reserved Locations**

All address and bit locations that are not included in Table 22 are not currently supported for this device. Write unused bits of a valid address location with 0s unless the default value is set otherwise. Writing to these locations is required only when part of an address location is unassigned (for example, Address 0x561). If the entire address location is open (for example, Address 0x013), do not write to this address location.

#### **Default Values**

After the AD9234 is reset, critical registers are loaded with default values. The default values for the registers are given in Table 22.

#### **Logic Levels**

An explanation of logic level terminology follows:

- "Bit is set" is synonymous with "bit is set to Logic 1" or "writing Logic 1 for the bit."
- "Clear a bit" is synonymous with "bit is set to Logic 0" or "writing Logic 0 for the bit."
- X denotes a don't care bit.

#### **Channel-Specific Registers**

Some channel setup functions, such as the input termination (Register 0x016), can be programmed to a different value for each channel. In these cases, channel address locations are internally duplicated for each channel. These registers and bits are designated in Table 22 as local. These local registers and bits can be accessed by setting the appropriate Channel A or Channel B bits in Register 0x008. If both bits are set, the subsequent write affects the registers of both channels. In a read cycle, set only Channel A or Channel B to read one of the two registers. If both bits are set during an SPI read cycle, the device returns the value for Channel A. Registers and bits designated as global in Table 22 affect the entire device and the channel features for which independent settings are not allowed between channels. The settings in Register 0x005 do not affect the global registers and bits.

#### **SPI Soft Reset**

After issuing a soft reset by programming 0x81 to Register 0x000, the AD9234 requires 5 ms to recover. When programming the AD9234 for application setup, ensure that an adequate delay is programmed into the firmware after asserting the soft reset and before starting the device setup.

### **MEMORY MAP REGISTER TABLE**

All address locations that are not included in Table 22 are not currently supported for this device and must not be written.

Table 22. Memory Map Registers

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
· · · · · ·	Devices SPI Regist		12.00	15.115	12	15.1.5		12.0.	2.00 (200)		1.10100
0x000	INTERFACE_ CONFIG_A	Soft reset (self clearing)	LSB first 0 = MSB 1 = LSB	Address ascension	0	0	Address ascension	LSB first 0 = MSB 1 = LSB	Soft reset (self clearing)	0x00	
0x001	INTERFACE_ CONFIG_B	Single instruction	0	0	0	0	0	Datapath soft reset (self clearing)	0	0x00	
0x002	DEVICE_ CONFIG (local)	0	0	0	0	0	0	10 =	nal operation standby wer-down	0x00	
0x003	CHIP_TYPE	0	0	0	0		011 = hig	h speed ADC		0x03	Read only
0x004	CHIP_ID (low byte)	1	1	0	0	1	1	1	0	0xCE	Read only
0x005	CHIP_ID (high byte)	0	0	0	0	0	0	0	0	0x00	Read only
0x006	CHIP_GRADE			000 MSPS 500 MSPS		X	X	X	X	0xAX for AD9234- 1000 0x5X for AD9234- 500	Read only
0x008	Device index	0	0	0	0	0	0	Channel B	Channel A	0x03	
0x00A	Scratch pad	0	0	0	0	0	0	0	0	0x00	
0x00B	SPI revision	0	0	0	0	0	0	0	1	0x01	
0x00C	Vendor ID (low byte)	0	1	0	1	0	1	1	0	0x56	Read only
0x00D	Vendor ID (high byte)	0	0	0	0	0	1	0	0	0x04	Read only
ADC Fur	nction Registers										
0x015	Analog Input (local)	0	0	0	0	0	0	0	Input disable 0 = normal operation 1 = input disabled	0x00	
0x016	Input termination (local)	Analo	0000 0001 0010	erential term = $400 \Omega$ = $200 \Omega$ = $100 \Omega$ = $50 \Omega$	ination			D9234-1000 \D9234-500		0x03 for AD9234- 1000; 0x01 for AD9234- 500	
0x018	Input buffer current control (local)		0001 = 1 $0010 = 2$ $0011 = 2$ $0100 = 3$ $0101 = 3$	.0× buffer cu .5× buffer cu .0× buffer cu .5× buffer cu .0× buffer cu .5× buffer cu	rrent rrent rrent rrent rrent	0	0	0	0	0x30 for AD9234- 1000; 0x20 for AD9234- 500	
0x024	V_1P0 control	0	1111 = 8	.5× buffer cu	o 0	0	0	0	1.0 V reference select 0 = internal 1 = external	0x00	

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x028	Temperature diode (local)	0	0	0	0	0	0	0	Diode selection 0 = no diode selected 1 = temperature diode selected	0x00	Used in conjunc- tion with Reg. 0x040
0x03F	PDWN/ STBY pin control (local)	0 = PDWN/ STBY enabled 1 = disabled	0	0	0	0	0	0	0	0x00	Used in conjunc- tion with Reg. 0x040
0x040	Chip pin control	PDWN/STB 00 = pow 01 = st 10 = di	er down andby	000 = 001 = J	st Detect B (FI Fast Detect B ESD204B LMF SD204B inter output 111 = disable	output C output nal SYNC~	000 = 001 = J 010 = JE	st Detect A (F Fast Detect A ESD204B LMF ESD204B inter output = temperature 111 = disable	output C output nal SYNC~	0x3F	
0x10B	Clock divider	0	0	0	0	0	(	000 = divide b 001 = divide b 011 = divide b 111 = divide b	y 2 y 4	0x00	
0x10C	Clock divider phase (local)	0	0	0	0	00 000 00 001 010	lently controls Channel A and Channel B clock divider phase offset  100 = 0 input clock cycles delayed  101 = ½ input clock cycles delayed  10 = 1½ input clock cycles delayed  10 = 1½ input clock cycles delayed  10 = 2½ input clock cycles delayed  11 = 1½ input clock cycles delayed  12 = 1½ input clock cycles delayed  13 = 1½ input clock cycles delayed			0x00	
0x10D	Clock divider and SYSREF control	Clock divider auto phase adjust 0 = disabled 1 = enabled	0	0	0	Clock divic skew v 00 = no ne 01 = 1 dev negati 10 = 2 devi negati 11 = 3 devi	der negative window gative skew rice clock of ve skew rice clocks of ve skew	Clock divi skew 00 = no p 01 = 1 de positi 10 = 2 dev positi 11 = 3 dev	der positive window ositive skew vice clock of ve skew vice clocks of ve skew vice clocks of ve skew vice clocks of	0x00	Clock divider must be >1
0x117	Clock delay control	0	0	0	0	0	0	0	Clock fine delay adjust enable 0 = disabled 1 = enabled	0x00	Enabling the clock fine delay adjust causes a datapath reset
0x118	Clock fine delay (local)	tv	vos complen	nent coded c	ontrol to adju ≤ -88 = - -87 = - 0 = 0	delay adjust[7 delay adjust[7 delay adjust[7 -151.7 ps skev -150 ps skew 	mple clock ske v	ew in ~1.7 ps s	teps	0x00	Used in conjunction with Reg. 0x0117
0x11C	Clock status	0	0	0	0	0	0	0	0 = no input clock detected 1 = input clock det- ected	Read only	

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x120	SYSREF± Control 1	0	SYSREF± flag reset 0 = normal operation 1 = flags held in reset	0	SYSREF± transition select 0 = low to high 1 = high to low	CLK± edge select 0 = rising 1 = falling	SYSREF± r 00 = c 01 = co	mode select disabled ontinuous : N shot		0x00	Notes
0x121	SYSREF± Control 2	0	0	0	0	0001 = 0010 = iç	0000 = next ignore the fignore the first	gnore counte : SYSREF± On rst SYSREF± t : two SYSREF±  tt 16 SYSREF±	ly ransitions Etransitions	0x00	Mode select, Reg. 0x120 Bits[2:1], must be N shot
0x123	SYSREF± timestamp delay control	0			(	± timestamp c 0x00 = no d 0x01 = 1 clock  c7F = 127 clock	elay delay			0x00	Ignored when Reg. 0x01FF = 0x00
0x128	SYSREF± Status 1	SYSRI	EF± hold statu	s, Register 0 Table 14	)x128[7:4],	SYSRE		us, Register 0: 5 Table 14	x128[3:0],	Read	
0x129	SYSREF± and clock divider status	0	0	0	0	0001 = 9 0010 = 9 001 010	der phase wh 0000 = 5YSREF± is ½ SYSREF± is 1 0 1 = 1½ input 00 = 2 input c 1 = 2½ input	en SYSREF± v in-phase cycle delayed cycle delayed clock cycles de lock cycles de clock cycles de 	from clock from clock lelayed elayed lelayed	only Read only	
0x12A	SYSREF± counter		SYSREF	± counter, B	Bits[7:0] increm				clock cycles delayed I is captured		
0x1FF	Chip sync mode	0	0	0	0	0	0	00 =	ization mode normal imestamp	0x00	
0x200	Chip application mode	0	0	Chip Q ignore 0 = normal (I/Q) 1 = ignore (I- only)	0	0	0	Chip ope 00 = full n 01 = I	prating mode bandwidth node DDC 0 on 0 and DDC 1	0x00	
0x201	Chip decimation ratio	0	0	0	0	0	000 = full	decimation ra sample rate ( 01 = decimat	decimate = 1	0x00	
0x228	Customer offset		Offse	et adjust in l	LSBs from +127	7 to -128 (two	s complemer	nt format)	•	0x00	
0x245	Fast detect (FD) control (local)	0	0	0	0	Force FD_A/FD_B pins; 0 = normal function; 1 = force to value	Force value of FD_A/FD_B pins if force pins is true, this value is output on FD pins	0	Enable fast detect output	0x00	
0x247	FD upper threshold LSB (local)		l	F	ast detect upp	er threshold, I	'			0x00	
0x248	FD upper threshold MSB (local)	0	0	0		Fast detect	upper thresh	pper threshold, Bits[12:8]			

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x249	FD lower threshold LSB (local)	(11133)	Dit 0	Jul 3	Fast detect low			ואשן	Jit v (L3b)	0x00	itotes
0x24A	FD lower threshold MSB (local)	0	0	0		Fast det	ect lower thr	eshold, Bits[12:8	]	0x00	
0x24B	FD dwell time LSB (local)				Fast detect o	dwell time, I	Bits[7:0]			0x00	
0x24C	FD dwell time MSB (local)				Fast detect d	well time, B	its[15:8]			0x00	
0x26F	Signal ,onitor synchronizatio n control	0	0	0	0	0	0	00 = 01 = c	ization mode disabled ontinuous one shot	0x00	Refer to the Signal Monitor section
0x270	Signal monitor control (local)	0	0	0	0	0	0	Peak detector 0 = disabled 1 = enabled	0	0x00	
0x271	Signal Monitor Period Register 0 (local)				Signal moni	tor period, I	Bits[7:0]			0x80	In decimated output clock cycles
0x272	Signal Monitor Period Register 1 (local)				Signal monit	or period, B	0x00	In decimated output clock cycles			
0x273	Signal Monitor Period Register 2 (local)				Signal monito	or period, Bi	ts[23:16]			0x00	In decimated output clock cycles
0x274	Signal monitor result control (local)	0	0	0	Result update 1 = update results (self clear)	0	0	0	Result selection 0 = reserved 1 = peak detector	0x01	
0x275	Signal Monitor Result Register 0 (local)	When Re	egister 0x02	74[0] = 1, re	Signal moni sult bits [19:7] =			value [12:0]; resu	It bits [6:0] = 0	Read only	Updated based on Reg. 0x274[4]
0x276	Signal Monitor Result Register 1 (local)				Signal monit	tor result, B	ts[15:8]			Read only	Updated based on Reg. 0x274[4]
0x277	Signal Monitor Result Register 1 (local)	0	0	0	0		Signal mon	itor result, Bits[1	9:16]	Read only	Updated based on Reg. 0x274[4]
0x278	Signal monitor period counter result (local)		·	·	Period cou	nt result, Bi	ts[7:0]		Read only	Updated based on Reg. 0x274[4]	
0x279	Signal monitor SPORT over JESD204B control (local)	0	0	0	0	0	0		reserved = enable	0x00	
0x27A	SPORT over JESD204B input selection (local)	0	0	0	0	0	0	Peak detector 0 = disabled 1 = enabled	0	0x00	

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
<u> </u>	nction Registers (					1511.5	10112	10101	DIC 0 (135)	Delaut	itotes
0x300	DDC synch control	0	0	0	DDC NCO soft reset 0 = normal operation 1 = reset	0	0	Synchronization mode (triggered by SYSREF± 00 = disabled 01 = continuous 11 = 1-shot			
0x310	DDC 0 control	Mixer select 0 = real mixer 1 = complex mixer	Gain select 0 = 0 dB gain 1 = 6 dB gain	freque 00 = vari (mixer en 01 = 0 (mixer by dis 10 = f <sub>ADC</sub> /4 (f <sub>ADC</sub> /4 c n 11 = test inputs fo	ermediate ency) mode able IF mode able IF mode s and NCO abled) Hz IF mode /passed, NCO sabled) '4 Hz IF mode downmixing mode) mode (mixer orced to +FS, enabled)	Complex to real enable 0 = disabled 1 = enabled	0	(comp dis 11 = ded (comp end	on rate select lex to real abled) cimate by 2 lex to real abled) cimate by 1	0x00	
0x311	DDC 0 input selection	0	0	0	0	0	Q input select 0 = Ch A 1 = Ch B	0	I input select 0 = Ch A 1 = Ch B	0x00	
0x314	DDC 0 frequency LSB			D		uency value, omplement	Bits[7:0],			0x00	
0x315	DDC0 frequency MSB	Х	Х	X	Х	DD	C 0 NCO freque twos co	ency value, Bit mplement	ts[11:8],	0x00	
0x320	DDC 0 phase LSB				DDC 0 NCO pł twos c	nase value, Bi complement	its[7:0],	0x00			
0x321	DDC 0 phase MSB	Х	Х	Х	X	D	DDC 0 NCO phase value, Bits[11:8], twos complement				
0x327	DDC 0 output test mode selection	0	0	0	0	0	Q output test mode enable 0 = disabled 1 = enabled from Ch B	0	I output test mode enable 0 = disabled 1 = enabled from Ch A	0x00	
0x330	DDC 1 control	Mixer select 0 = real mixer 1 = complex mixer	Gain select 0 = 0 dB gain 1 = 6 dB gain	freque 00 = vari (mixer en 01 = 0 (mixer by dis 10 = f <sub>ADC</sub> /4 c n 11 = test inputs fc NCO	ermediate ency) mode able IF mode s and NCO nabled) Hz IF mode (passed, NCO sabled) 4 Hz IF mode downmixing node) mode (mixer preed to +FS, enabled)	Complex to real enable 0 = disabled 1 = enabled	0	Decimation rate select (complex to real disabled)  11 = decimate by 2 (complex to real enabled)  11 = decimate by 1		0x00	
0x331	DDC 1 input selection	0	0	0	0	0	Q input select 0 = Ch A 1 = Ch B	0	I input select 0 = Ch A 1 = Ch B	0x00	
0x334	DDC 1 frequency LSB			D	twos c	uency value, Bits[7:0], complement			0x00		
0x335	DDC 1 frequency MSB	Х	Х	Х	Х	DDC 1 NCO frequency value, Bits[11:8], twos complement			ts[11:8],	0x00	
0x340	DDC 1 phase LSB					CO phase value, Bits[7:0], wos complement				0x00	
0x341	DDC 1 phase MSB	Х	Х	Х	Х	DDC 1 NCO phase value, Bits[11:8], twos complement				0x00	

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x347	DDC 1 output test mode selection	0	0	0	0	0	Q output test mode enable 0 = disabled 1 = enabled from Ch B	0	I output test mode enable 0 = disabled 1 = enabled from Ch A	0x00	Notes
Digital 0 0x550	Outputs and Test I	Modes User	То	Reset PN	Reset PN		Test mo	de selection		0x00	
0,550	modes (local)	pattern selection 0 = contin- uous repeat 1 = single pattern		long gen 0 = long PN enable 1 = long PN reset	short gen 0 = short PN enable 1 = short PN reset	1000	0000 = off, n 0001 = m 0010 = pos 0011 = neg 0100 = alternat 0101 = PN s 0110 = PN s 0111 = 1/(0) = the user patte ter 0x550, Bit 7 a	ormal operation ormal operation of the state	0.00		
0x551	User Pattern 1 LSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x552	User Pattern 1 MSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x553	User Pattern 2 LSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x554	User Pattern 2 MSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x555	User Pattern 3 LSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x556	User Pattern 3 MSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x557	User Pattern 4 LSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x558	User Pattern 4 MSB	0	0	0	0	0	0	0	0	0x00	Used with Reg. 0x550 and Reg. 0x573
0x559	Output Mode Control 1	0	00 00 010 = 011 =	er control Bit 00 = tie low ( 1 = overrang = signal mon = fast detect 101 = SYSRE nly used who ister 0x58F)	ge bit nitor bit (FD) bit :F± en CS	0	0 0 010 011	ter control Bit 100 = tie low (101 = overrang 1 = signal mon 1 = fast detect 101 = SYSRE 101 only used whe 101 ester 0x58F	I'b0) ie bit itor bit (FD) bit F± n CS	0x00	-

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x55A	Output Mode Control 2	0	0	0	0	0	Convert 0 00 010 011	rter control Bit 2 selection 000 = tie low (1'b0) 001 = overrange bit 0 = signal monitor bit 1 = fast detect (FD) bit 101 = SYSREF en CS (Register 0x58F) = 1, 2 or 3		0x01	Notes
0x561	Output mode	0	0	0	0	0	Sample invert 0 = normal 1 = sample invert	00 = of	rmat select fset binary complement	0x01	
0x562	Output overrange (OR) clear	Virtual Converter 7 OR 0 = OR bit enabled 1 = OR bit cleared	Virtual Converter 6 OR 0 = OR bit enabled 1 = OR bit cleared	Virtual Con- verter 5 OR 0 = OR bit enabled 1 = OR bit cleared	Virtual Converter 4 OR 0 = OR bit enabled 1 = OR bit cleared	Virtual Con-verter 3 OR 0 = OR bit enabled 1 = OR bit cleared	Virtual Converter 2 OR 0 = OR bit enabled 1 = OR bit cleared	Virtual Con- verter 1 OR 0 = OR bit enabled 1 = OR bit cleared	Virtual Converter 0 OR 0 = OR bit enabled 1 = OR bit cleared	0x00	
0x563	Output OR status	Virtual Converter 7 OR 0 = no OR 1 = OR occured	Virtual Con- verter 6 OR 0 = no OR 1 = OR occured	Virtual Con- verter 5 OR 0 = no OR 1 = OR occured	Virtual Converter 4 OR 0 = no OR 1 = OR occured	Virtual Converter 3 OR 0 = no OR 1 = OR occured	Virtual Converter 2 OR 0 = no OR 1 = OR occured	Virtual Con- verter 1 OR 0 = no OR 1 = OR occured	Virtual Converter 0 OR 0 = no OR 1 = OR occured	0x00	Read only
0x564	Output channel select	0	0	0	0	0	0	0	Converter channel swap 0 = normal channel ordering 1 = channel swap enabled	0x00	
0x56E	JESD204B lane rate control	0	0	0	0 = serial lane rate ≥ 6.25 Gbps and ≤12.5 Gbps 1 = serial lane rate must be ≥ 3.125 Gbps and ≤ 6.25 Gbps	0	0	0	0	0x00 for AD9234- 1000; 0x10 for AD9234- 500	
0x570	JESD204B quick config- uration		•	M = n	JESD204B questions of land umber of contractions of contractions of cottess o	verters = 2 <sup>Regis</sup>	x570, Bits[7:6] ster 0x570, Bits[5:3]			0x88	Refer to Table 12 and Table 13
0x571	JESD204B Link Mode Control 1	Standby mode 0 = all converter outputs 0 1 = CGS (/K28.5/)	Tail bit (t) PN 0 = disable 1 = enable T = N' - N - CS	Long transport layer test 0 = disable 1 = enable	Lane synchron- ization 0 = disable FACI uses /K28.7/ 1 = enable FACI uses /K28.3/ and /K28.7/	ILAS sequen 00 = ILAS dis 01 = ILAS en	ce mode sabled	FACI 0 = enabled 1 = disabled	Link control 0 = active 1 = power down	0x14	

Reg Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x572	JESD204B Link Mode Control 2	SYNCINB± p 00 = normal 10 = ignore (force CGS) 11 = ignore (force ILAS/u	in control SYNCINB± SYNCINB±	SYNC- INB± pin invert 0 = active low 1 = active high	SYNCINB± pin type 0 = differential 1 = cmos	0	8B/10B bypass 0 = normal 1 = bypass	8B/10B bit invert 0 = normal 1 = invert the aj symbols	0	0x00	
0x573	JESD204B Link Mode Control 3	CHKSUM 00 = sum of link configure 01 = sum of link configure 10 = check ze	of all 8-bit gregisters findividual ig fields sum set to	00 = N' sa 01 = 10- 8B/10B o PHY 10 = 8-l	ction point ample input bit data at output (for testing) bit data at oler input	0000 = r 00 0011 : 0100 0101 : 0110 0111	JESD204B tes normal operat 001 = alternat 0010 = 1/0 = 31-bit PN se = 23-bit PN se = 15-bit PN se 0 = 9-bit PN se 1 = 7-bit PN se 1000 = ra 100 = continuo	0x00			
0x574	JESD204B Link Mode Control 4	0001 = tr	transmit ILA SYNCINB± ansmit ILAS SYNCINB± transmit ILA	delay S on first LM deasserted on second L deasserted  S on 16 <sup>th</sup> LM deasserted	.MFC after	0	Link layer test mode  000 = normal operation (link layer test mode disabled)  001 = continuous sequence of /D21.5/ characters  100 = modified RPAT test sequence  101 = JSPAT test sequence  110 = JTSPAT test sequence				
0x578	JESD204B LMFC offset	0	0	0		LMFC ph	nase offset val	0x00			
0x580	JESD204B DID config				JESD204B Tx	DID value, Bit	s[7:0]			0x00	
0x581	JESD204B BID config	0	0	0	0	J	ESD204B Tx B	BID value, Bits	[7:0]	0x00	
0x583	JESD204B LID Config 1	0	0	0		Lan	e 0 LID value, E	Bits[4:0]		0x00	
0x584	JESD204B LID Config 2	0	0	0		Lan	e 1 LID value, E	Bits[4:0]		0x01	
0x585	JESD204B LID Config 3	0	0	0		Lan	e 2 LID value, E	Bits[4:0]		0x01	
0x586	JESD204B LID Config 4	0	0	0		Lan	e 3 LID value, E	Bits[4:0]		0x03	
0x58B	JESD204B parameters SCR/L	JESD204B scrambling (SCR) 0 = disabled 1 = enabled	0	0	0	0	0	00 = 01 = 11 = Read	4B lanes (L) = 1 lane - 2 lanes - 4 lanes only, see ter 0x570	0x8X	
0x58C	JESD204B F config		N	lumber of oc	tets per frame	me, F = Register 0x58C, Bits[7:0] + 1				0x88	Read only, see Reg. 0x570
0x58D	JESD204B K config	0	0	0		nber of frames per multiframe, $K = Register 0x58D$ , $Bits[4:0] + 1$ Only values where $(F \times K) \mod 4 = 0$ are supported				0x1F	See Reg. 0x570
0x58E	JESD204B M config			0x00 = link 0x01 = link 0x03 = link	connected to connected to connected to	onverters per link, Bits[7:0] ed to one virtual converter (M = 1) ed to two virtual converters (M = 2) ed to four virtual converters (M = 4) d to eight virtual converters (M = 8)					Read only

Reg Addr	Register	Bit 7									
(Hex)	Name	(MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x58F	JESD204B CS/N config	Number of bits (CS) p 00 = no cc (CS 01 = 1 con = 1); Control = 2); Control E 11 = 3 cont = 3); all cor 1,	er sample ontrol bits = 0) trol bit (CS ol Bit 2 only rol bits (CS ol Bit 2 and Bit 1 only rol bits (CS trol bits (CS)) bits (CS) bits (CS)	0		ADC 0 0 0 0 0 0 0 0 0		0x0F			
0x0590	JESD204B N' config	000 = Subc	s support (S version) lass 0 (no de latency) 11 = Subclass	terministic		ADC nu	omber of bits pe 0x7 = 8 bits 0xF = 16 bit	5		0x2F	
0x591	JESD204B S config	0	0	1			per converter f le = Register 0x5				Read only
0x592	JESD204B HD and CF configuration	HD value 0 = disabled 1 = enabled	0	0			s per frame cloci ne = Register 0x5		k (CF)	0x80	Read only
0x5A0	JESD204B CHKSUM 0		•	Cŀ	KSUM value	e for SERDOUTO	)±, Bits[7:0]			0x81	Read only
0x5A1	JESD204B CHKSUM 1			Cŀ	HKSUM value	e for SERDOUT1	1±, Bits[7:0]			0x82	Read only
0x5A2	JESD204B CHKSUM 2			Cŀ	HKSUM value	e for SERDOUT2	2±, Bits[7:0]			0x82	Read only
0x5A3	JESD204B CHKSUM 3			Cŀ	HKSUM value	e for SERDOUT3	8±, Bits[7:0]			0x84	Read only
0x5B0	JESD204B lane power-down	1	SERD- OUT3± 0 = on 1 = off	1	SERD- OUT2± 0 = on 1 = off	1	SERD- OUT1± 0 = on 1 = off	1	SERDOUT0± 0 = on 1 = off	0xAA	
0x5B2	JESD204B lane SERDOUT0± assign	X	Х	Х	X	0	00 00 01	0UT0± lane as 00 = Logical L 01 = Logical L 10 = Logical L 11 = Logical L	ane 0 ane 1 ane 2	0x00	
0x5B3	JESD204B lane SERDOUT1± assign	X	X	X	X	0	00 00 01	OUT1± lane as OO = Logical La O1 = Logical La O = Logical La O1 = Logical La	ane 0 ane 1 ane 2	0x11	
0x5B5	JESD204B lane SERDOUT2± assign	X	X	X	X	0	00 00 01	OUT2± lane as 00 = Logical L 01 = Logical L 10 = Logical L 11 = Logical L	ane 0 ane 1 ane 2	0x22	
0x5B6	JESD204B lane SERDOUT3± assign	X	X	X	X	0	00 00 01	OUT3± lane as 00 = Logical La 01 = Logical La 10 = Logical La 11 = Logical La	ane 0 ane 1 ane 2	0x33	

Reg Addr	Register	Bit 7									
(Hex)	Name	(MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default	Notes
0x5BF	JESD serializer drive adjust	0	0	0	0		0000 = 0001 = 0001 = 0010 = 0101 = 300 = 0111 = 1000 = 1001 = 1001 = 1100 = 1101 = 1100 = 1101 = 1100 = 1101 = 1110 = 111	g voltage 237.5 mV = 250 mV 262.5 mV = 275 mV = 287.5 mV 0 mV (default) 312.5 mV = 325 mV = 350 mV = 350 mV = 375 mV = 375 mV = 375 mV = 400 mV 412.5 mV = 425 mV		0x05	
0x5C1	De-emphasis select	0	SERD- OUT3± 0 = disable 1 = enable	0	SERD- OUT2± 0 = disable 1 = enable	0	SERD- OUT1± 0 = disable 1 = enable	0	SERDOUT0± 0 = disable 1 = enable	0x00	
0x5C2	De-emphasis setting for SERDOUT0±	0	0	0	0		0001 0010 0011 0100 0101 0110	emphasis set 0 = 0 dB = 0.3 dB = 0.8 dB = 1.4 dB = 2.2 dB = 3.0 dB = 4.0 dB = 5.0 dB	tings:	0x00	
0x5C3	De-emphasis setting for SERDOUT1±	0	0	0	0		0001 0010 0011 0100 0101 0110	emphasis set 0 = 0 dB = 0.3 dB = 0.8 dB = 1.4 dB = 2.2 dB = 3.0 dB = 4.0 dB = 5.0 dB	tings:	0x00	
0x5C4	De-emphasis setting for SERDOUT2±	0	0	0	0		SERDOUT2± de- 0000 0001 0010 0011 0100 0101 0110		tings:	0x00	
0x5C5	De-emphasis setting for SERDOUT3±	0	0	0	0		0001 0010 0011 0100 0101 0110	emphasis set 0 = 0 dB = 0.3 dB = 0.8 dB = 1.4 dB = 2.2 dB = 3.0 dB = 4.0 dB = 5.0 dB	tings:	0x00	

# APPLICATIONS INFORMATION POWER SUPPLY RECOMMENDATIONS

The AD9234 must be powered by the following seven supplies: AVDD1 = 1.25 V, AVDD2 = 2.5 V, AVDD3 = 3.3 V, AVDD1\_SR = 1.25 V, DVDD = 1.25 V, DRVDD = 1.25 V, and SPIVDD = 1.8 V. For applications requiring an optimal high power efficiency and low noise performance, it is recommended that the ADP2164 and ADP2370 switching regulators be used to convert the 3.3 V, 5.0 V, or 12 V input rails to an intermediate rail (1.8 V and 3.8 V). These intermediate rails are then postregulated by very low noise, low dropout (LDO) regulators (ADP1741, ADM7172, and ADP125). Figure 106 shows the recommended power supply scheme for AD9234.

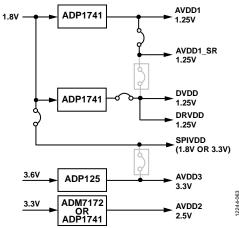


Figure 106. High Efficiency, Low Noise Power Solution for the AD9234

It is not necessary to split all of these power domains in all cases. The recommended solution shown in Figure 106 provides the lowest noise, highest efficiency power delivery system for the AD9234. If only one 1.25 V supply is available, route to AVDD1 first and then tap it off and isolate it with a ferrite bead or a filter choke, preceded by decoupling capacitors for AVDD1\_SR, SPIVDD, DVDD, and DRVDD, in that order. The user can employ several different decoupling capacitors to cover both high and low frequencies. These must be located close to the point of entry at the PCB level and close to the devices, with minimal trace lengths.

# EXPOSED PAD THERMAL HEAT SLUG RECOMMENDATIONS

It is required that the exposed pad on the underside of the ADC be connected to ground to achieve the best electrical and thermal performance of the AD9234. Connect an exposed continuous copper plane on the PCB to the AD9234 exposed pad, Pin 0. The copper plane must have several vias to achieve the lowest possible resistive thermal path for heat dissipation to flow through the bottom of the PCB. These vias must be solder filled or plugged. The number of vias and the fill determine the resultant  $\theta_{\rm IA}$  measured on the board. This is shown in Table 7.

To maximize the coverage and adhesion between the ADC and PCB, partition the continuous copper plane by overlaying a silkscreen on the PCB into several uniform sections. This provides several tie points between the ADC and PCB during the reflow process, whereas using one continuous plane with no partitions only guarantees one tie point. See Figure 107 for a PCB layout example. For detailed information on packaging and the PCB layout of chip scale packages, see the AN-772 Application Note, A Design and Manufacturing Guide for the Lead Frame Chip Scale Package (LFCSP).

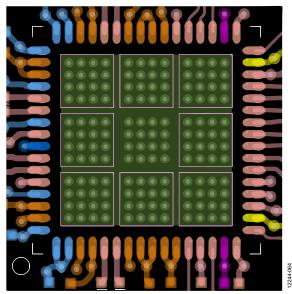


Figure 107. Recommended PCB Layout of Exposed Pad for the AD9234

#### AVDD1\_SR (PIN 57) AND AGND (PIN 56 AND PIN 60)

AVDD1\_SR (Pin 57) and AGND (Pin 56 and Pin 60) can be used to provide a separate power supply node to the SYSREF± circuits of AD9234. If running in Subclass 1, the AD9234 can support periodic one-shot or gapped signals. To minimize the coupling of this supply into the AVDD1 supply node, adequate supply bypassing is needed.

## **OUTLINE DIMENSIONS**

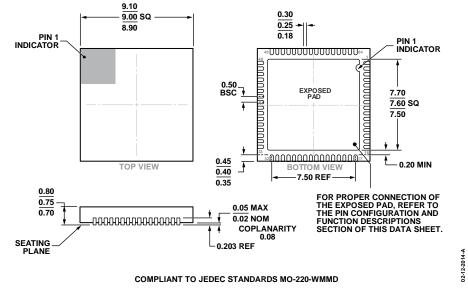


Figure 108. 64-Lead Lead Frame Chip Scale Package [LFCSP\_WQ] 9 mm × 9 mm Body, Very Thin Quad (CP-64-15) Dimensions shown in millimeters

#### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Package Option
AD9234BCPZ-500	-40°C to +85°C	64-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-64-15
AD9234BCPZRL7-500	−40°C to +85°C	64-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-64-15
AD9234BCPZ-1000	-40°C to +85°C	64-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-64-15
AD9234BCPZRL7-1000	-40°C to +85°C	64-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-64-15
AD9234-500EBZ		Evaluation Board for AD9234-500 (Optimized for Full Analog Input Frequency Range)	
AD9234-1000EBZ		Evaluation Board for AD9234-1000 (Optimized for Full Analog Input Frequency Range)	

 $<sup>^{1}</sup>$  Z = RoHS Compliant Part.

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## **Analog Devices Inc.:**

<u>AD9234BCPZ-1000</u> <u>AD9234-1000EBZ</u> <u>AD9234BCPZRL7-1000</u> <u>AD9234BCPZ-500</u> <u>AD9234BCPZRL7-500</u> <u>AD9234-500EBZ</u> AD9234-LF500EBZ