Features

- Fast read access time – 90ns
- Low-power CMOS operation
  - 100µA max standby
  - 40mA max active at 5MHz
- JEDEC standard packages
  - 32-lead PLCC
  - 32-lead PDIP
- 5V ± 10% supply
- High-reliability CMOS technology
  - 2,000V ESD protection
  - 200mA latchup immunity
- Rapid programming algorithm – 50µs/byte (typical)
- CMOS- and TTL-compatible inputs and outputs
- Integrated product identification code
- Industrial temperature range
- Green (Pb/halide-free) packaging option

8Mb (1M x 8) One-time Programmable, Read-only Memory
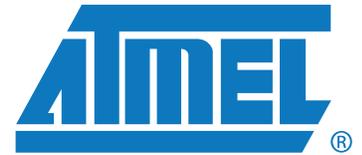
Atmel AT27C080

1. Description

The Atmel® AT27C080 is a low-power, high-performance 8,388,608-bit, one-time programmable, read-only memory (OTP EPROM) organized as 1M by 8 bits. The AT27C080 requires only one 5V power supply in normal read mode operation. Any byte can be accessed in less than 90ns, eliminating the need for speed reducing WAIT states on high-performance microprocessor systems.

The Atmel scaled CMOS technology provides low active power consumption and fast programming. Power consumption is typically 10mA in active mode and less than 10µA in standby mode.

The AT27C080 is available in a choice of industry standard, JEDEC-approved, one-time programmable (OTP) PLCC and PDIP packages. All devices feature two-line control ($\overline{CE}$, $\overline{OE}$) to give designers the flexibility to prevent bus contention.

With high-density, 8Mb storage capability, the AT27C080 allows firmware to be stored reliably and to be accessed by the system without the delays of mass storage media.

The AT27C080 has additional features to ensure high quality and efficient production use. The rapid programming algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 50µs/byte. The integrated product identification code electronically identifies the device and manufacturer. This feature is used by industry standard programming equipment to select the proper programming algorithms and voltages.
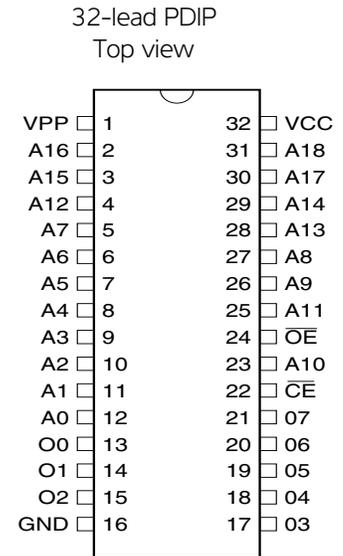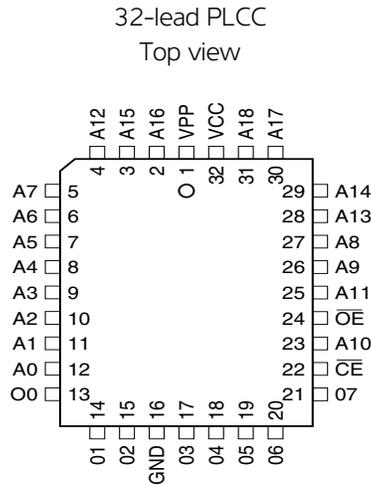
2. Pin configurations

Pin name	Function
A0 – A19	Addresses
O0 – O7	Outputs
$\overline{CE}$	Chip enable
$\overline{OE}$/VPP	Output enable/Program supply

32-lead PLCC
Top view

```
        A12 A15 A16 VPP VCC A18 A17
         4   3   2   1  32  31  30
    A7 □ 5                          29 □ A14
    A6 □ 6              O 1         28 □ A13
    A5 □ 7                          27 □ A8
    A4 □ 8                          26 □ A9
    A3 □ 9                          25 □ A11
    A2 □ 10                         24 □ OE
    A1 □ 11                         23 □ A10
    A0 □ 12                         22 □ CE
    O0 □ 13                         21 □ 07
         14  15  16  17  18  19  20
        01  02  GND  03  04  05  06
```

32-lead PDIP
Top view

```
   VPP □ 1         32 □ VCC
   A16 □ 2         31 □ A18
   A15 □ 3         30 □ A17
   A12 □ 4         29 □ A14
    A7 □ 5         28 □ A13
    A6 □ 6         27 □ A8
    A5 □ 7         26 □ A9
    A4 □ 8         25 □ A11
    A3 □ 9         24 □ OE
    A2 □ 10        23 □ A10
    A1 □ 11        22 □ CE
    A0 □ 12        21 □ 07
    O0 □ 13        20 □ 06
    O1 □ 14        19 □ 05
    O2 □ 15        18 □ 04
   GND □ 16        17 □ 03
```

3. System considerations

Switching between active and standby conditions via the chip enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device nonconformance. At a minimum, a 0.1µF, high-frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the V_{CC} and ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7µF bulk electrolytic capacitor should be utilized, again connected between the V_{CC} and ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

Figure 3-1. Block diagram
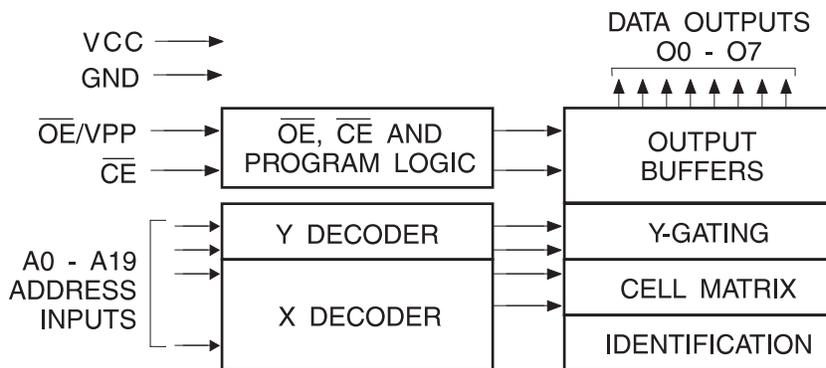
4. Absolute maximum ratings*

Temperature under bias . . . .-55°C to +125°C

Storage temperature . . . .-65°C to +150°C

Voltage on any pin with
respect to ground . . . . -2.0V to +7.0V[1]

Voltage on A9 with
respect to ground . . . . -2.0V to +14.0V[1]

V_{PP} supply voltage with
respect to ground . . . . -2.0V to +14.0V[1]

Integrated UV erase dose . . . . 7258W•s/cm^2

*NOTICE: Stresses beyond those listed under ˝Absolute maximum ratings˝ may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: 1.   Minimum voltage is –0.6V DC, which may undershoot to –2.0V for pulses of less than 20ns. Maximum output pin voltage is V_{CC} + 0.75V DC, which may overshoot to +7.0V for pulses of less than 20ns.

5. DC and AC characteristics

Table 5-1.   Operating modes

Mode/Pin	$\overline{CE}$	$\overline{OE}/V_{PP}$	Ai	Outputs
Read	V_{IL}	V_{IL}	Ai	D_{OUT}
Output disable	X	V_{IH}	X[1]	High Z
Standby	V_{IH}	X	X	High Z
Rapid program[2]	V_{IL}	V_{PP}	Ai	D_{IN}
PGM verify	V_{IL}	V_{IL}	Ai	D_{OUT}
PGM inhibit	V_{IH}	V_{PP}	X	High Z
Product identification[4]	V_{IL}	V_{IL}	A9 = V_H[3] A0 = V_{IH} or V_{IL} A1 - A19 = V_{IL}	Identification code

Notes: 1.   X can be V_{IL} or V_{IH}.

2.   Refer to programming characteristics.

3. V_H = 12.0 ± 0.5V.

4.   Two identifier bytes may be selected. All Ai inputs are held low (V_{IL}), except A9, which is set to V_H, and A0, which is toggled low (V_{IL}) to select the manufacturer's identification byte and high (V_{IH}) to select the device code byte.

Table 5-2.   DC and AC operating conditions for read operation

	Atmel AT27C080–90
Industrial operating temperature（case）	–40·C – 85·C
V_{CC} **power** supply	5V ± 10%

Table 5-3. DC and operating characteristics for read operation

Symbol	Parameter	Condition	Min	Max	Units
I_{LI}	Input load current	V_{IN} = 0V to V_{CC} (Com., Ind.)		±1.0	µA
I_{LO}	Output leakage current	V_{OUT} = 0V to V_{CC} (Com., Ind.)		±5.0	µA
I_{SB}	V_{CC}[1] standby current	I_{SB1} (CMOS), $\overline{CE}$ = V_{CC} ± 0.3V		100	µA
		I_{SB2} (TTL), $\overline{CE}$ = 2.0 to V_{CC} + 0.5V		1.0	mA
I_{CC}	V_{CC} active current	f = 5MHz, I_{OUT} = 0mA, $\overline{CE}$ = V_{IL}		40	mA
V_{IL}	Input low voltage		-0.6	0.8	V
V_{IH}	Input high voltage		2.0	V_{CC} + 0.5	V
V_{OL}	Output low voltage	I_{OL} = 2.1mA		0.4	V
V_{OH}	Output high voltage	I_{OH} = -400µA	2.4		V

Note: 1. V_{CC} must be applied simultaneously or before $\overline{OE}$/V_{PP}, and removed simultaneously or after $\overline{OE}$/V_{PP}

Table 5-4. AC characteristics for read operation

Symbol	Parameter	Condition	Atmel AT27C080-90		Units
			Min	Max	
t_{ACC}[4]	Address to output delay	$\overline{CE}$ = $\overline{OE}$/V_{PP} = V_{IL}		90	ns
t_{CE}[3]	$\overline{CE}$ to output delay	$\overline{OE}$ = V_{IL}		90	ns
t_{OE}[3][4]	$\overline{OE}$ to output delay	$\overline{CE}$ = V_{IL}		20	ns
t_{DF}[2][5]	$\overline{OE}$ or $\overline{CE}$ high to output float, whichever occurred first			30	ns
t_{OH}	Output hold from address, $\overline{CE}$ or $\overline{OE}$/V_{PP}, whichever occurred first		0		ns

Figure 5-1.   AC waveforms for read operation[1]
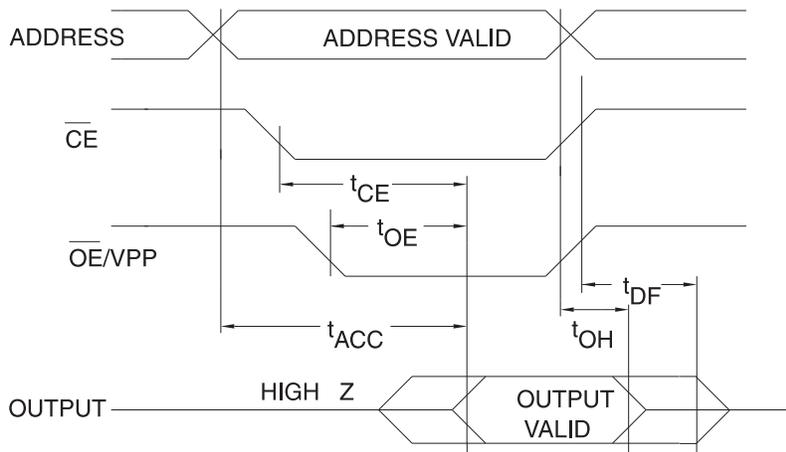
Notes: 1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.

2. t_{DF} is specified form $\overline{OE}/V_{PP}$ or $\overline{CE}$, whichever occurs first. Output float is defined as the point when data is no longer driven.

3. $\overline{OE}/V_{PP}$ may be delayed up to $t_{CE} - t_{OE}$ after the falling edge of $\overline{CE}$ without impact on t_{CE}.

4. $\overline{OE}/V_{PP}$ may be delayed up to $t_{ACC} - t_{OE}$ after the address is valid without impact on t_{ACC}.

5. This parameter is only sampled and is not 100% tested.

Figure 5-2.   Input test waveform and measurement levels
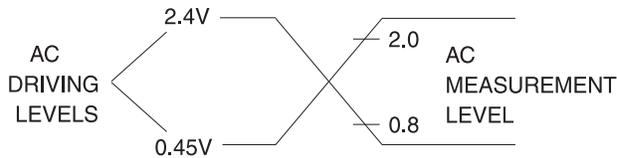
t_R, t_F < 20ns (10% to 90%)

Figure 5-3.   Output test load
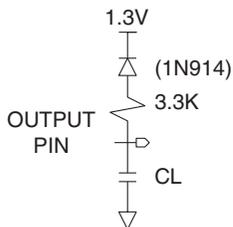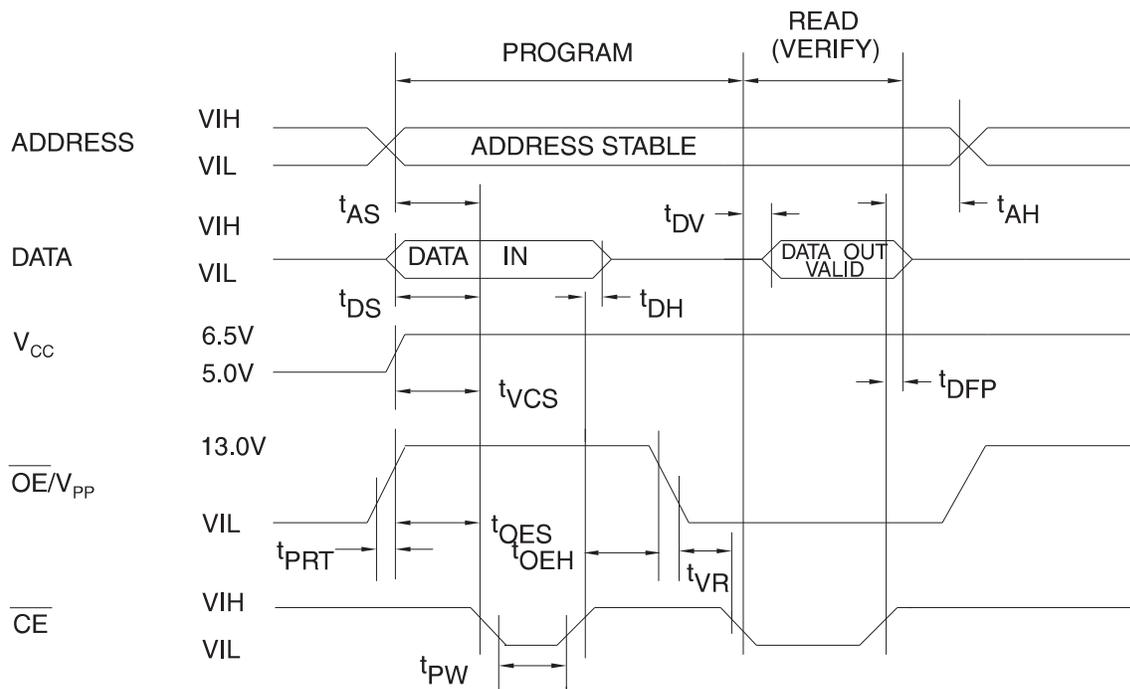

Note: CL = 100pF including jig capacitance.

Table 5-5. Pin capacitance

f = 1MHz, T = 25°C [1]

Symbol	Typ	Max	Units	Conditions
C_{IN}	4	8	pF	$V_{IN} = 0V$
C_{OUT}	8	12	pF	$V_{OUT} = 0V$

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.

Figure 5-4. Programming waveforms

Notes: 1. The input timing reference is 0.8V for V_{IL} and 2.0V for V_{IH}.

2. t_{OE} and t_{DFP} are characteristics of the device, but must be accommodated by the programmer.

Table 5-6.   DC programming characteristics

$T_A = 25 \pm 5°C$, $V_{CC} = 6.5 \pm 0.25V$, $\overline{OE}/V_{PP} = 13.0 \pm 0.25V$

Symbol	Parameter	Test Conditions	Limits Min	Limits Max	Units
I_{LI}	Input load current	$V_{IN} = V_{IL}, V_{IH}$		±10	µA
V_{IL}	Input low level		-0.6	0.8	V
V_{IH}	Input high level		2.0	$V_{CC} + 1.0$	V
V_{OL}	Output low voltage	$I_{OL} = 2.1mA$		0.4	V
V_{OH}	Output high voltage	$I_{OH} = -400µA$	2.4		V
I_{CC2}	V_{CC} supply current (program and verify)			40	mA
I_{PP2}	$\overline{OE}/V_{PP}$ supply current	$\overline{CE} = V_{IL}$		25	mA
V_{ID}	A9 product identification voltage		11.5	12.5	V

Table 5-7.   AC programming characteristics

$T_A = 25 \pm 5°C$, $V_{CC} = 6.5 \pm 0.25V$, $\overline{OE}/V_{PP} = 13.0 \pm 0.25V$

Symbol	Parameter	Test conditions[1]	Limits Min	Limits Max	Units
t_{AS}	Address setup time		2.0		µs
t_{OES}	$\overline{OE}/V_{PP}$ setup time	Input rise and fall times: (10% to 90%) 20ns	2.0		µs
t_{OEH}	$\overline{OE}/V_{PP}$ hold time		2.0		µs
t_{DS}	Data setup time		2.0		µs
t_{AH}	Address hold time	Input pulse levels: 0.45V to 2.4V	0.0		µs
t_{DH}	Data hold time		2.0		µs
t_{DFP}	$\overline{CE}$ high to output float delay[2]		0.0	130	ns
t_{VCS}	V_{CC} setup time	Input timing reference level: 0.8V to 2.0V	2.0		µs
t_{PW}	$\overline{CE}$ program pulse width[3]		47.5	52.5	µs
t_{DV}	Data valid from $\overline{CE}$	Output timing reference level: 0.8V to 2.0V		1.0	µs
t_{VR}	$\overline{OE}/V_{PP}$ recovery time		2.0		ns
t_{PRT}	$\overline{OE}/V_{PP}$ pulse rise time during programming		50		ns

Notes: 1. V_{CC} must be applied simultaneously with or before $\overline{OE}/V_{PP}$ and removed simultaneously with or after $\overline{OE}/V_{PP}$.

2. This parameter is only sampled, and is not 100% tested. Output float is defined as the point where data is no longer driven. See timing diagram.

3. Program pulse width tolerance is 50µs ± 5%.

Table 5-8.   The Atmel AT27C080 integrated product identification code

Codes	Pins A0	O7	O6	O5	O4	O3	O2	O1	O0	Hex data
Manufacturer	0	0	0	0	1	1	1	1	0	1E
Device type	1	1	0	0	0	1	0	1	0	8A

6. Rapid programming algorithm

A 50µs $\overline{CE}$ pulse width is used to program. The address is set to the first location. V_{CC} is raised to 6.5V and $\overline{OE}/V_{PP}$ is raised to 13.0V. Each address is first programmed with one 50µs $\overline{CE}$ pulse without verification. Then a verification reprogramming loop is executed for each address. In the event a byte fails to pass verification, up to 10 successive 50µs pulses are applied with a verification after each pulse. If the byte fails to verify after 10 pulses have been applied, the part is considered failed. After the byte verifies properly, the next address is selected until all have been checked. $\overline{OE}/V_{PP}$ is then lowered to V_{IL} and V_{CC} to 5.0V. All bytes are read again and compared with the original data to determine if the device passes or fails.

Figure 6-1.   Rapid programming algorithm
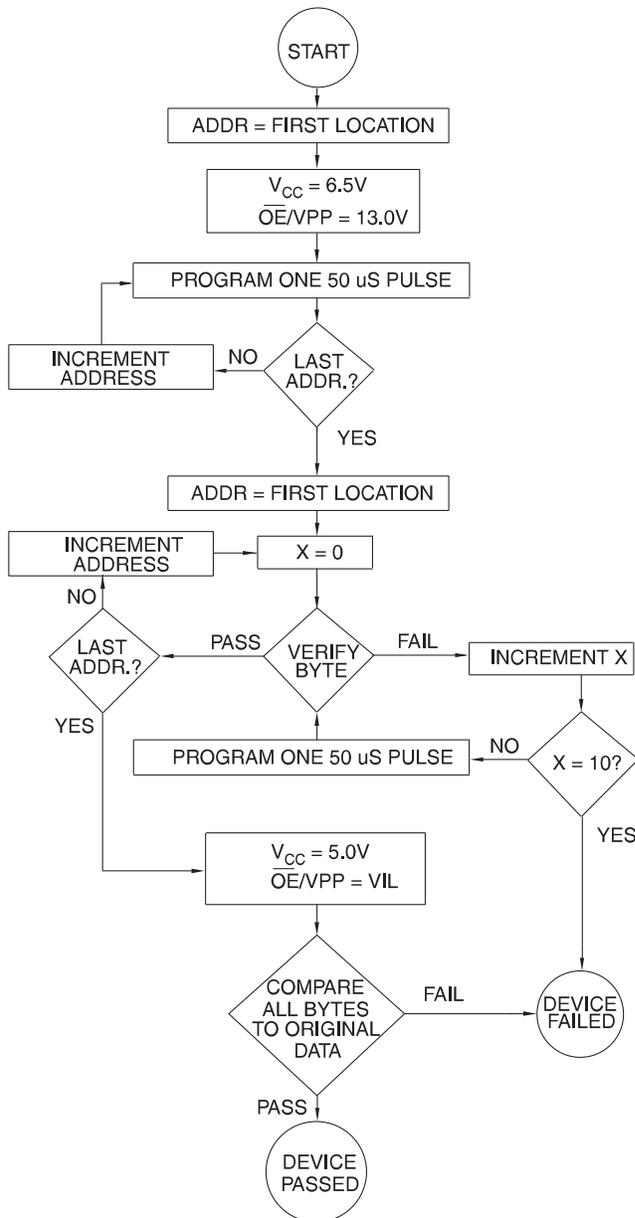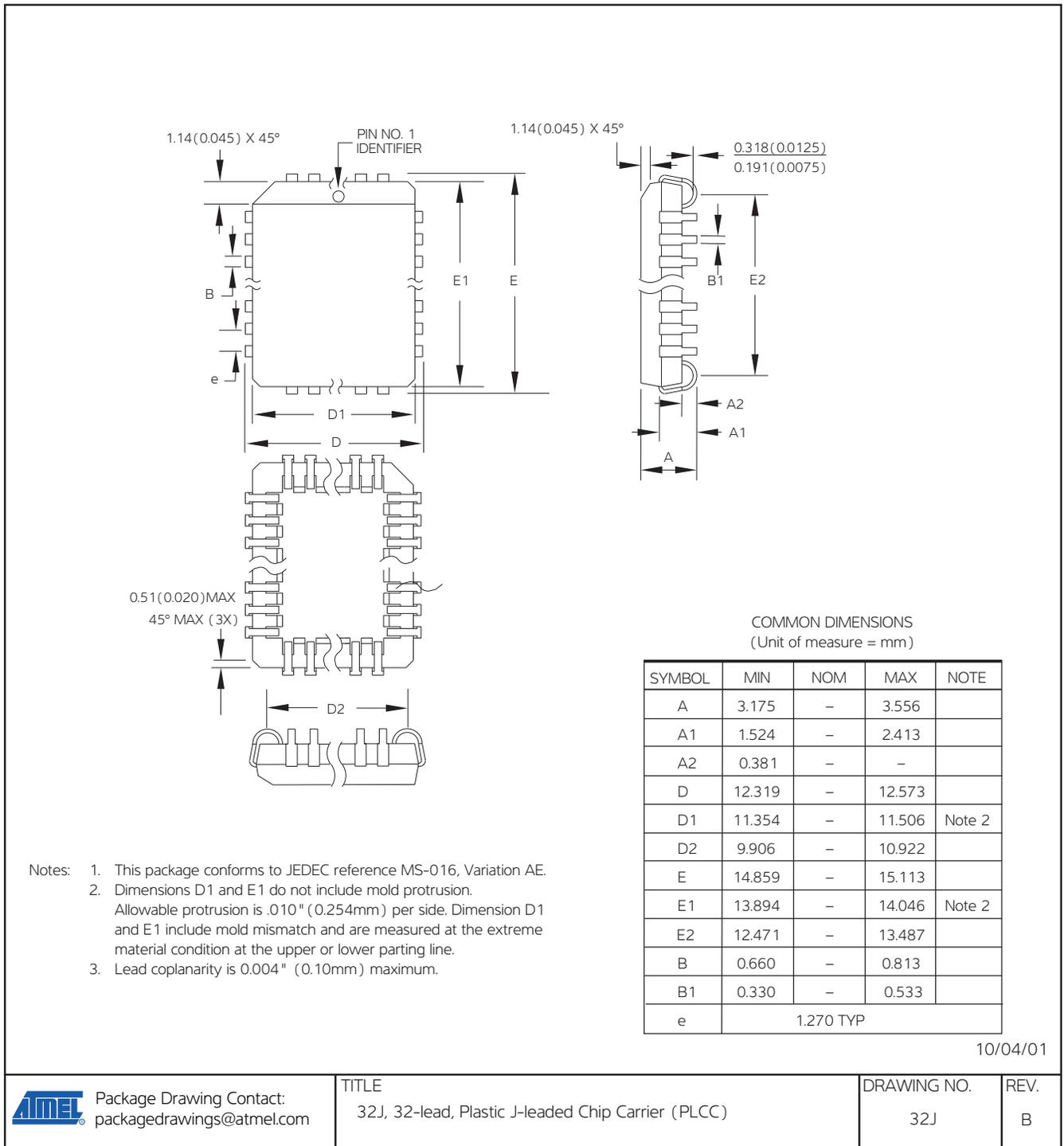
7. Ordering information

Green package (Pb/halide-free)

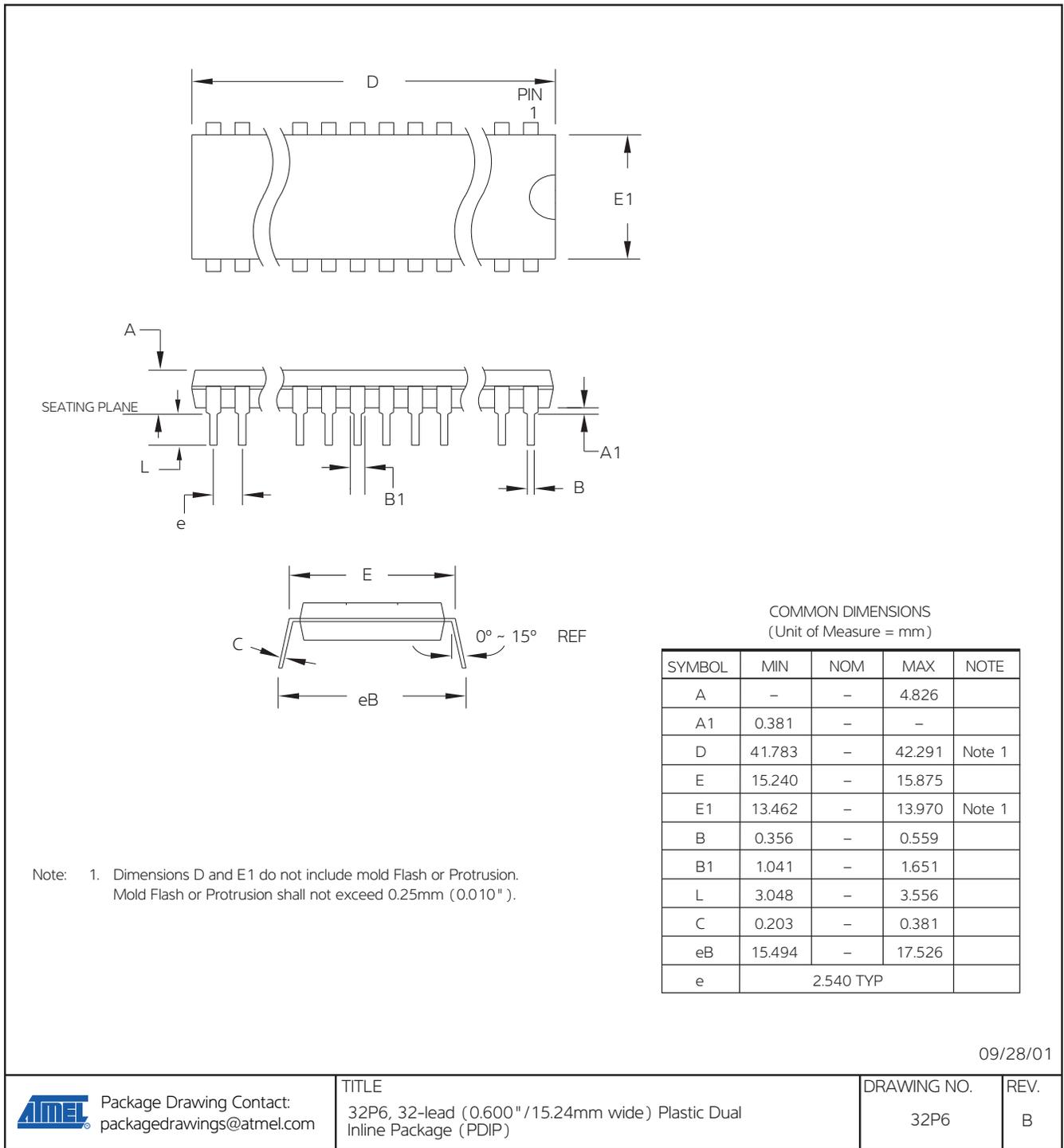| t_{ACC} (ns)	I_{CC} (mA)		Atmel ordering code	Package	Lead finish	Operation range
	Active	Standby				
90	40	0.1	AT27C080-90JU	32J	Matte tin	Industrial
			AT27C080-90PU	32P6	Matte tin	(-40°C to 85°C)

Package type	
32J	32-lead, plastic, J-leaded chip carrier (PLCC)
32P6	32-lead, 0.600" wide, plastic, dual inline package (PDIP)

8. Package information

32J – PLCC

1.14(0.045) X 45°

PIN NO. 1 IDENTIFIER

1.14(0.045) X 45°

0.318(0.0125)
0.191(0.0075)

0.51(0.020)MAX
45° MAX (3X)

Notes:
1. This package conforms to JEDEC reference MS-016, Variation AE.
2. Dimensions D1 and E1 do not include mold protrusion.
   Allowable protrusion is .010" (0.254mm) per side. Dimension D1
   and E1 include mold mismatch and are measured at the extreme
   material condition at the upper or lower parting line.
3. Lead coplanarity is 0.004" (0.10mm) maximum.

COMMON DIMENSIONS
(Unit of measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
A	3.175	–	3.556	
A1	1.524	–	2.413	
A2	0.381	–	–	
D	12.319	–	12.573	
D1	11.354	–	11.506	Note 2
D2	9.906	–	10.922	
E	14.859	–	15.113	
E1	13.894	–	14.046	Note 2
E2	12.471	–	13.487	
B	0.660	–	0.813	
B1	0.330	–	0.533	
e	1.270 TYP			

10/04/01

	Package Drawing Contact: packagedrawings@atmel.com	TITLE 32J, 32-lead, Plastic J-leaded Chip Carrier (PLCC)	DRAWING NO. 32J	REV. B

32P6 – PDIP

COMMON DIMENSIONS
(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	4.826	
A1	0.381	–	–	
D	41.783	–	42.291	Note 1
E	15.240	–	15.875	
E1	13.462	–	13.970	Note 1
B	0.356	–	0.559	
B1	1.041	–	1.651	
L	3.048	–	3.556	
C	0.203	–	0.381	
eB	15.494	–	17.526	
e	2.540 TYP			

Note: 1. Dimensions D and E1 do not include mold Flash or Protrusion.
Mold Flash or Protrusion shall not exceed 0.25mm (0.010").

09/28/01

	Package Drawing Contact: packagedrawings@atmel.com	TITLE 32P6, 32-lead (0.600"/15.24mm wide) Plastic Dual Inline Package (PDIP)	DRAWING NO. 32P6	REV. B

9. Revision history

Doc. Rev.	Date	Comments
0360M	04/2011	Remove TSOP package Add lead finish to ordering information
0360L	12/2007	

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