GP1A038RBK/GP1A038RBKL/ GP1A038RCK/GP1A038RCKL

■ Features

- 1. Linear encoder for reading linear scale
- 2. Since the multi-divided photodiode system is adopted, highprecision reading is possible even if the angle is deviated between the scale and encoder.
- 3. High resolution:

Resolution 150LPI (GP1A038RBK/GP1A038RBKL) Resolution 180LPI (GP1A038RCK/GP1A038RCKL)

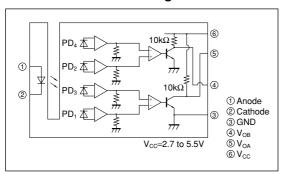
■ Applications

1. Printers

Absolute Maximum Ratings $(T_a=25^{\circ}C)$								
Parameter		Symbol	Rating	Unit				
Input	*1 Forward current	I_F	50	mA				
	Reverse voltage	V _R	4	V				
Output	Supply voltage	V_{CC}	7	V				
	Low level output current	I_{OL}	8	mA				
	*1 Power dissipation	Po	150	mW				
Operating temperature		Topr	-10 to +70	°C				
Storage temperature		T _{stg}	-40 to +80	°C				
*2 Soldering temperature		T _{sol}	260	°C				

^{*1} The derating factors of absolute maximum ratings due to ambient temperature are shown in Fig.2 to 3

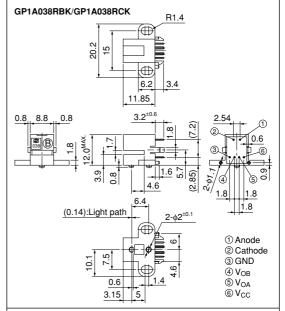
■ Internal connection diagram

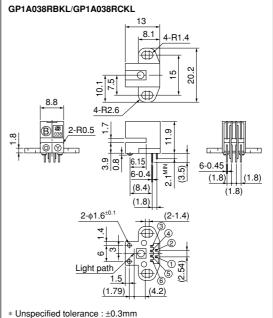


OPIC Photointerrupter with Encoder Function

■ Outline Dimensions

(Unit: mm)





^{*2} For 5s

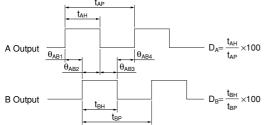
■ Electro-optical Characteristics (T _a =25°C)									
Parameter		Symbol	Conditions	MIN.	TYP.	MAX.	Unit		
Input	Forward voltage	$V_{\rm F}$	I _F =11mA	-	1.3	1.5	V		
	Reverse current	I_R	$V_R=1V$	_	_	100	μΑ		
Output	Operating supply voltage	V_{CC}	_	2.7	5.0	5.5	V		
	Low level output voltage	V _{OL}	V_{CC} =2.7 to 5.5V, I_F =11mA, I_{OL} =8mA	_	_	0.4	V		
	High level output voltage	V _{OH}	V _{CC} =2.7 to 5.5V, I _F =11mA	V _{CC} -0.3	_	_	V		
	Supply current	ent I_{CC} V_{CC} =2.7 to 5.5V, I_F =11mA, A and B low level		_	_	5	mA		
*1 Transfer charac-	Duty ratio	D _A D _B	V 07. 55V V 11. A	35	50	65	%		
	Phase difference	θ _{AB1 to 4}	$V_{CC}=2.7$ to 5.5V, $I_F=11$ mA, $f=10$ kHz, $Z=0.3^{+0.7}_{-0.2}$ mm	45	90	135	۰		
	Response time	t _r	1-10K112, 2-0.3-0.2HIIII	_	1.0	2.0	μs		
		$t_{\rm f}$		-	1.0	2.0	μs		

^{*1} Refer to the measuring condition. The values of transfer characteristics do not include an error of linear scale. Z is the distance between scale face and holder on the detector side.

 $V_{CC}=2.7$ to 5.5V, $I_F=11$ mA, $Z=0.3^{+0.7}_{-0.2}$ mm

Fig.1 Output Waveforms

Response frequency



Scale moving direction is shown in the measuring condition (Refer to Fig.4).



Fig.2 Forward Current vs. Ambient Temperature

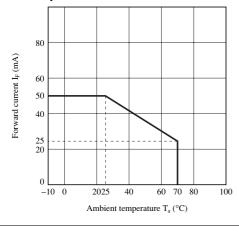


Fig.3 Output Power Dissipation vs.
Ambient Temperature

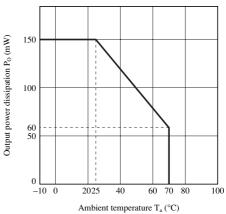
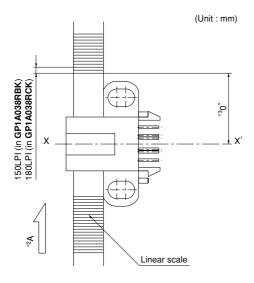
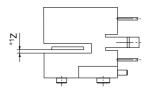
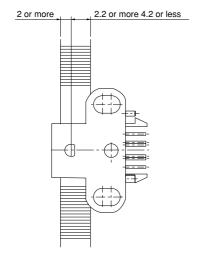


Fig.4 Measuring Condition







- *1 Distance between scale face and holder on the detector side
- *2 Scale moving direction
- *3 X-X' is the line which is through the center of holder positioning pin, and it is parallel to the scale slit.

NOTICE

- The circuit application examples in this publication are provided to explain representative applications of SHARP
 devices and are not intended to guarantee any circuit design or license any intellectual property rights. SHARP takes
 no responsibility for any problems related to any intellectual property right of a third party resulting from the use of
 SHARP's devices.
- Contact SHARP in order to obtain the latest device specification sheets before using any SHARP device. SHARP
 reserves the right to make changes in the specifications, characteristics, data, materials, structure, and other contents
 described herein at any time without notice in order to improve design or reliability. Manufacturing locations are
 also subject to change without notice.
- Observe the following points when using any devices in this publication. SHARP takes no responsibility for damage
 caused by improper use of the devices which does not meet the conditions and absolute maximum ratings to be used
 specified in the relevant specification sheet nor meet the following conditions:
 - (i) The devices in this publication are designed for use in general electronic equipment designs such as:
 - --- Personal computers
 - --- Office automation equipment
 - --- Telecommunication equipment [terminal]
 - --- Test and measurement equipment
 - --- Industrial control
 - --- Audio visual equipment
 - --- Consumer electronics
 - (ii) Measures such as fail-safe function and redundant design should be taken to ensure reliability and safety when SHARP devices are used for or in connection with equipment that requires higher reliability such as:
 - --- Transportation control and safety equipment (i.e., aircraft, trains, automobiles, etc.)
 - --- Traffic signals
 - --- Gas leakage sensor breakers
 - --- Alarm equipment
 - --- Various safety devices, etc.
 - (iii)SHARP devices shall not be used for or in connection with equipment that requires an extremely high level of reliability and safety such as:
 - --- Space applications
 - --- Telecommunication equipment [trunk lines]
 - --- Nuclear power control equipment
 - --- Medical and other life support equipment (e.g., scuba).
- Contact a SHARP representative in advance when intending to use SHARP devices for any "specific" applications
 other than those recommended by SHARP or when it is unclear which category mentioned above controls the
 intended use.
- If the SHARP devices listed in this publication fall within the scope of strategic products described in the Foreign Exchange and Foreign Trade Control Law of Japan, it is necessary to obtain approval to export such SHARP devices.
- This publication is the proprietary product of SHARP and is copyrighted, with all rights reserved. Under the copyright laws, no part of this publication may be reproduced or transmitted in any form or by any means, electronic or mechanical, for any purpose, in whole or in part, without the express written permission of SHARP. Express written permission is also required before any use of this publication may be made by a third party.
- Contact and consult with a SHARP representative if there are any questions about the contents of this publication.

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Sharp Microelectronics:

GP1A038RBK0F GP1A038RBKLF GP1A038RCK0F