# HEF4040B-Q100

# 12-stage binary ripple counter Rev. 1 — 4 April 2013

**Product data sheet** 

#### **General description** 1.

The HEF4040B-Q100 is a 12-stage binary ripple counter with a clock input ( $\overline{CP}$ ), an overriding asynchronous master reset input (MR) and twelve fully buffered outputs (Q0 to Q11). The counter advances on the HIGH-to-LOW transition of  $\overline{\text{CP}}$ . A HIGH on MR clears all counter stages and forces all outputs LOW, independent of CP. Each counter stage is a static toggle flip-flop. The clock input is highly tolerant of slow rise and fall times due to its Schmitt trigger action.

It operates over a recommended V<sub>DD</sub> power supply range of 3 V to 15 V referenced to V<sub>SS</sub> (usually ground). Unused inputs must be connected to V<sub>DD</sub>, V<sub>SS</sub>, or another input.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

#### Features and benefits 2.

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)
  - ◆ Specified from -40 °C to +85 °C
- Tolerant of slow clock rise and fall time
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
  - MIL-STD-883, method 3015 exceeds 2000 V
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-A exceeds 200 V (C = 200 pF, R = 0 Ω)
- Complies with JEDEC standard JESD 13-B

## **Applications**

- Frequency dividing circuits
- Time delay circuits
- Control counters



# 4. Ordering information

#### Table 1. Ordering information

All types operate from -40 °C to +85 °C.

Type number	Package		
	Name	Description	Version
HEF4040BT-Q100	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1

# 5. Functional diagram

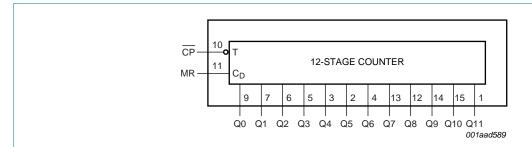


Fig 1. Functional diagram

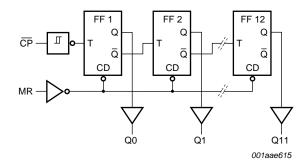
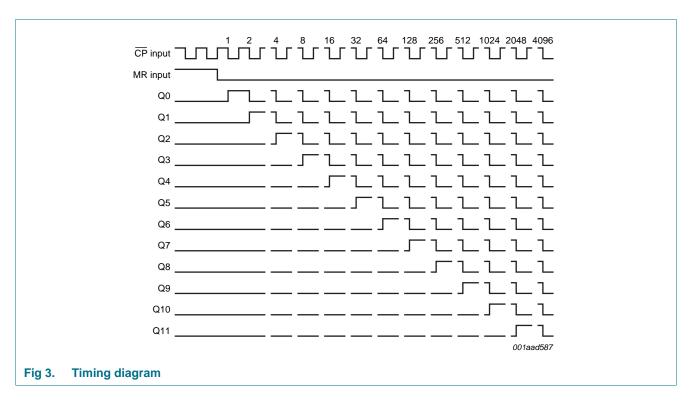
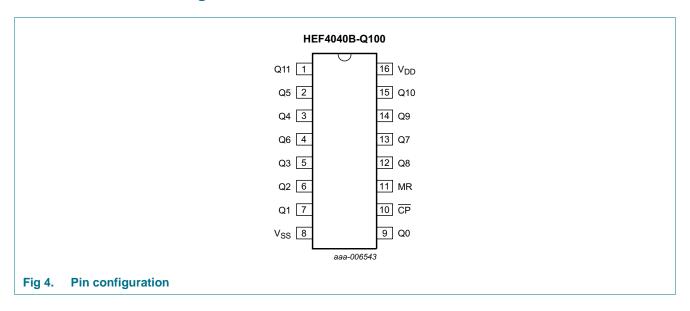


Fig 2. Logic diagram



## 6. Pinning information

#### 6.1 Pinning



### 6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
V <sub>SS</sub>	8	ground supply voltage
Q0 to Q11	9, 7, 6, 5, 3, 2, 4, 13, 12, 14, 15, 1	parallel output
CP	10	clock input (HIGH-to-LOW edge-triggered)
MR	11	master reset input (active HIGH)
$V_{DD}$	16	supply voltage

# 7. Limiting values

Table 3. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
$I_{IK}$	input clamping current	$V_I < -0.5 \text{ V or } V_I > V_{DD} + 0.5 \text{ V}$	-	±10	mA
$V_{I}$	input voltage		-0.5	$V_{DD} + 0.5$	V
I <sub>OK</sub>	output clamping current	$V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
$I_{DD}$	supply current		-	50	mA
$T_{stg}$	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
P <sub>tot</sub>	total power dissipation		<u>[1]</u> _	500	mW
Р	power dissipation	per output	-	100	mW

<sup>[1]</sup> For SO16 package:  $P_{tot}$  derates linearly with 8 mW/K above 70 °C.

# 8. Recommended operating conditions

Table 4. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{DD}$	supply voltage		3	-	15	V
VI	input voltage		0	-	$V_{DD}$	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	$V_{DD} = 5 V$	-	-	3.75	ms/V
		V <sub>DD</sub> = 10 V	-	-	0.5	ms/V
		V <sub>DD</sub> = 15 V	-	-	0.08	ms/V

### 9. Static characteristics

Table 5. Static characteristics

 $V_{SS} = 0$  V;  $V_I = V_{SS}$  or  $V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	T <sub>amb</sub> =	–40 °C	T <sub>amb</sub> = 25 °C		T <sub>amb</sub> = 85 °C		Unit
				Min	Max	Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	$ I_{O}  < 1 \mu A$	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
$V_{IL}$	LOW-level input voltage	$ I_{O}  < 1 \mu A$	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
$V_{OH}$	HIGH-level output voltage	$ I_{O}  < 1 \mu A$	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
		15 V	14.95	-	14.95	-	14.95	-	V	
V <sub>OL</sub> LOW-level output voltage	$ I_{O}  < 1 \mu A$	5 V	-	0.05	-	0.05	-	0.05	V	
		10 V	-	0.05	-	0.05	-	0.05	V	
			15 V	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	$V_0 = 2.5 \text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	mΑ
		$V_0 = 4.6 \text{ V}$	5 V	-	-0.52	-	-0.44	-	-0.36	mΑ
		$V_0 = 9.5 \text{ V}$	10 V	-	-1.3	-	-1.1	-	-0.9	mΑ
		$V_0 = 13.5 \text{ V}$	15 V	-	-3.6	-	-3.0	-	-2.4	mΑ
$I_{OL}$	LOW-level output current	$V_0 = 0.4 \text{ V}$	5 V	0.52	-	0.44	-	0.36	-	mΑ
		$V_0 = 0.5 \ V$	10 V	1.3	-	1.1	-	0.9	-	mΑ
		$V_0 = 1.5 \text{ V}$	15 V	3.6	-	3.0	-	2.4	-	mΑ
ILI	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μΑ
$I_{DD}$	supply current	I <sub>O</sub> = 0 A	5 V	-	20	-	20	-	150	μΑ
			10 V	-	40	-	40	-	300	μΑ
			15 V	-	80	-	80	-	600	μΑ
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

# 10. Dynamic characteristics

Table 6. Dynamic characteristics

 $V_{SS} = 0 \text{ V}$ ;  $T_{amb} = 25 \,^{\circ}\text{C}$ ; unless otherwise specified; for test circuit see <u>Figure 6</u>.

Symbol	Parameter	Conditions	$V_{DD}$		Extrapolation formula[1]	Min	Тур	Max	Unit
t <sub>PHL</sub>	HIGH to LOW	$\overline{CP} \to Q0$	5 V		78 ns + $(0.55 \text{ ns/pF})C_L$	-	105	210	ns
	propagation delay	see Figure 5	10 V		34 ns + (0.23 ns/pF)C <sub>L</sub>	-	45	90	ns
			15 V		27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns
		$Qn \rightarrow Qn + 1$	5 V	[	(0.55 ns/pF)C <sub>L</sub>	-	35	70	ns
			10 V	[	(0.23 ns/pF)C <sub>L</sub>	-	15	30	ns
			15 V	[	(0.16 ns/pF)C <sub>L</sub>	-	10	20	ns
		$MR \to Qn$	5 V		63 ns + (0.55 ns/pF)C <sub>L</sub>	-	90	180	ns
		see Figure 5	10 V		29 ns + (0.23 ns/pF)C <sub>L</sub>	-	40	80	ns
			15 V		22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	$\overline{CP} \to Q0$	5 V		58 ns + (0.55 ns/pF)C <sub>L</sub>	-	85	170	ns
		see Figure 5	10 V		29 ns + (0.23 ns/pF)C <sub>L</sub>	-	40	80	ns
			15 V		22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
		$Qn \rightarrow Qn + 1$	5 V	[	2 (0.55 ns/pF)C <sub>L</sub>	-	35	70	ns
		10 V	[	(0.23 ns/pF)C <sub>L</sub>	-	15	30	ns	
		15 V	[	2 (0.16 ns/pF)C <sub>L</sub>	-	10	20	ns	
t <sub>t</sub>	transition time	nsition time see Figure 5	5 V	[	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V		9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V		6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>W</sub>	pulse width	CP input HIGH;	5 V			50	25	-	ns
		minimum width; see Figure 5	10 V			30	15	-	ns
		see <u>Figure 5</u>	15 V			20	10	-	ns
		MR input HIGH;	5 V			40	20	-	ns
		minimum width; see Figure 5	10 V			30	15	-	ns
		see <u>Figure 5</u>	15 V			20	10	-	ns
t <sub>rec</sub>	recovery time	MR input;	5 V			40	20	-	ns
		see Figure 5	10 V			30	15	-	ns
		15 V			20	10	-	ns	
f <sub>max</sub>	maximum	CP input;	5 V			10	20	-	MHz
	frequency	see Figure 5	10 V			15	30	-	MHz
			15 V			25	50	-	MHz

<sup>[1]</sup> The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown ( $C_L$  in pF).

<sup>[2]</sup> For loads other than 50 pF at the nth output, use the slope given.

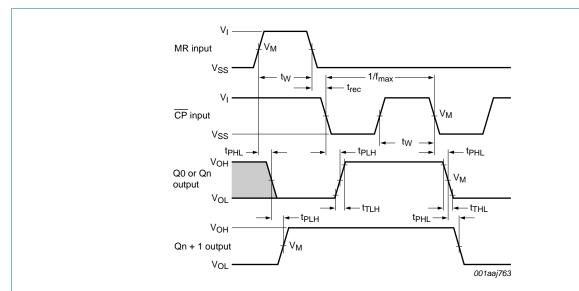
<sup>[3]</sup>  $t_t$  is the same as  $t_{THL}$  and  $t_{TLH}$ .

Table 7. Dynamic power dissipation P<sub>D</sub>

 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0 \text{ V}$ ;  $t_r = t_f \le 20 \text{ ns}$ ;  $T_{amb} = 25 \text{ }^{\circ}\text{C}$ .

Symbol	Parameter	$V_{DD}$	Typical formula for P <sub>D</sub> (μW)	where:
$P_D$	dynamic power 5		$P_D = 400 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f <sub>i</sub> = input frequency in MHz,
dissipation		10 V	$P_D = 2000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f <sub>o</sub> = output frequency in MHz,
			$P_D = 5200 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	$C_L$ = output load capacitance in pF,
				$V_{DD}$ = supply voltage in V,
				$\Sigma(f_0 \times C_L)$ = sum of the outputs.

#### 11. Waveforms



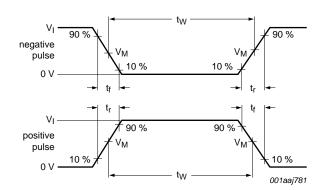
Logic levels:  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Transition times: transition time ( $t_t$ ) = HIGH LOW ( $t_{THL}$ ) or LOW HIGH ( $t_{TLH}$ ) transition times. Measurement points are given in Table 8, test circuit in Figure 6 and test data in Table 9

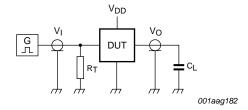
Fig 5. Waveforms showing propagation delays for MR to Qn and  $\overline{\text{CP}}$  to Q0, minimum MR and  $\overline{\text{CP}}$  pulse widths

Table 8. Measurement points

Supply voltage	Input	Output	
$V_{DD}$	VI	$V_{M}$	V <sub>M</sub>
5 V to 15 V	V <sub>DD</sub> or V <sub>SS</sub>	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>



#### a. Input waveforms



#### b. Test circuit

Test data is given in Table 9.

Definitions test circuit:

DUT = Device Under Test;

C<sub>L</sub> = load capacitance, including the jig and probe capacitance;

 $R_L$  = load resistance, which should be equal to the output impedance of the pulse generator.

Fig 6. Test circuit for measuring switching times

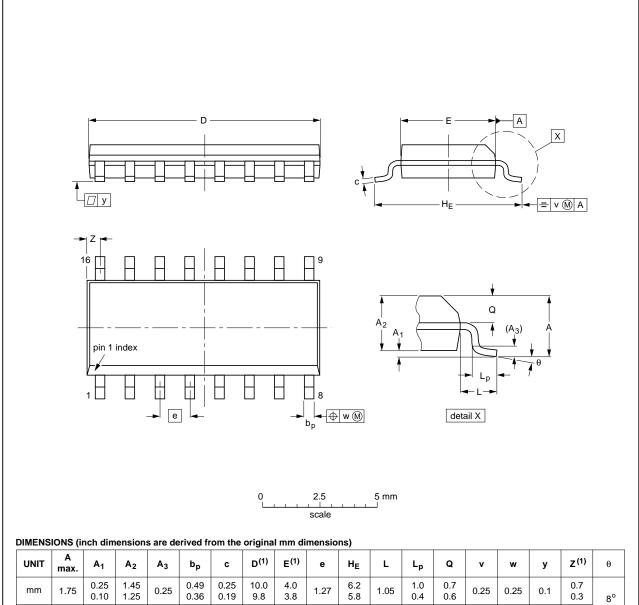
Table 9. Test data

Supply voltage	Input	Load	
$V_{DD}$	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	≤ 20 ns	50 pF

# 12. Package outline

#### SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(1)</sup>	е	HE	L	Lp	ø	v	w	у	Z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	10.0 9.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01	l	0.0100 0.0075	0.39 0.38	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.020	0.01	0.01	0.004	0.028 0.012	0°

#### Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE		REFER		EUROPEAN	ICCUE DATE		
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT109-1	076E07	MS-012				<del>-99-12-27-</del> 03-02-19	

Fig 7. Package outline SOT109-1 (SO16)

HEF4040B\_Q100

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### 13. Abbreviations

#### Table 10. Abbreviations

Acronym	Description
НВМ	Human Body Model
ESD	ElectroStatic Discharge
MM	Machine Model
MIL	Military

# 14. Revision history

#### Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4040B_Q100 v.1	20130404	Product data sheet	-	-

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Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

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# HEF4040B-Q100

12-stage binary ripple counter

### 17. Contents

1	General description 1
2	Features and benefits
3	Applications
4	Ordering information 2
5	Functional diagram 2
6	Pinning information 3
6.1	Pinning
6.2	Pin description 4
7	Limiting values 4
8	Recommended operating conditions 4
9	Static characteristics 5
10	Dynamic characteristics 6
11	Waveforms
12	Package outline
13	Abbreviations
14	Revision history
15	Legal information
15.1	Data sheet status
15.2	Definitions
15.3	Disclaimers
15.4	Trademarks
16	Contact information 12
17	Contents

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