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Team Nexperia

HEF4557B

1-to-64 bit variable length shift register Rev. 7 — 1 April 2016

Product data sheet

1. **General description**

The HEF4557B is a static clocked serial shift register whose length may be programmed to be any number of bits between 1 and 64. The number of bits selected is equal to the sum of the subscripts of the enabled length control inputs (L1, L2, L4, L8, L16, and L32) plus one. Serial data may be selected from the DA or DB data inputs with the A/B select input. This feature is useful for recirculation purposes. Information on DA or DB is shifted into the first register position and all the data in the register is shifted one position to the right on the LOW to HIGH transition of CP0 while CP1 is LOW or on the HIGH to LOW transition of CP1 while CP0 is HIGH. A HIGH on master reset (MR) resets the register and forces Q to LOW and Q to HIGH, independent of the other inputs.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

Features and benefits 2.

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from -40 °C to +85 °C
- Complies with JEDEC standard JESD 13-B

3. Ordering information

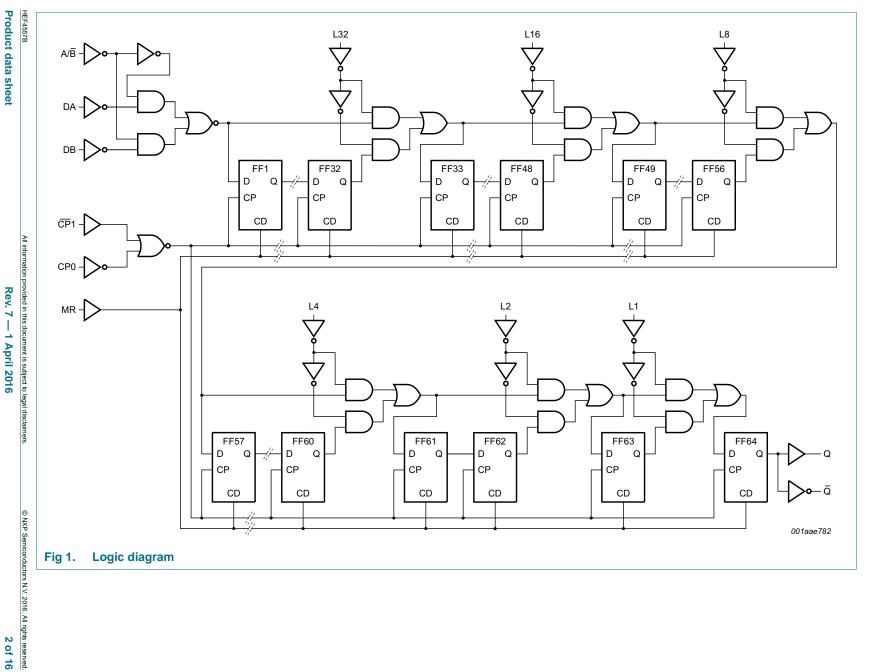
Table 1. Ordering information

All types operate from −40 °C to +85 °C

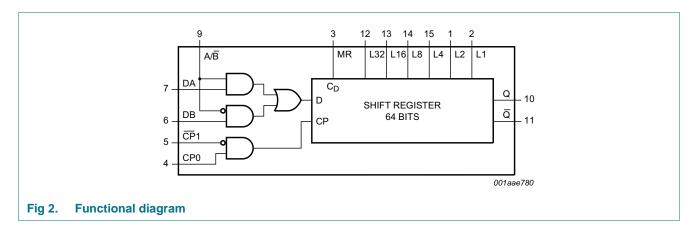
Type number	Package								
	Name	Description	Version						
HEF4557BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1						



Functional diagram

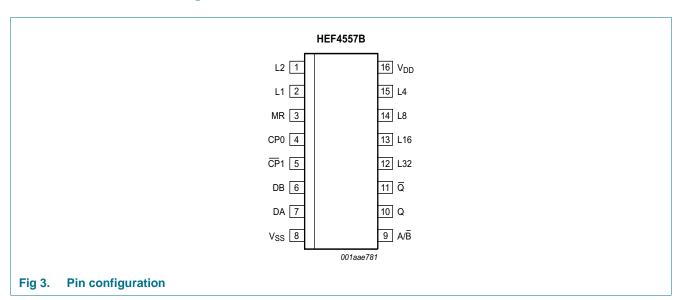


1-to-64 bit variable length shift register



5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description table

Symbol	Pin	Description
L1, L2, L4, L8, L16, L32	2, 1, 15, 14, 13, 12	bit-length control input
MR	3	asynchronous master reset
CP0	4	clock input
CP1	5	clock input
DA, DB	7, 6	data input
V _{SS}	8	ground (0 V)
A/B	9	select data input

1-to-64 bit variable length shift register

Table 2. Pin description table ...continued

Symbol	Pin	Description		
Q	10	buffered output		
Q	11	complementary buffered output		
V_{DD}	16	supply voltage		

6. Functional description

Table 3. Function table[1]

Inputs	puts							
MR	A/B	DA	DB	CP0	CP1	Q		
L	L	D ₁	D ₂	↑	L	D ₂		
L	Н	D ₁	D ₂	↑	L	D ₁		
L	L	D ₁	D ₂	Н	\	D_2		
L	Н	D ₁	D ₂	Н	\	D ₁		
Н	X	X	X	X	X	L		

^[1] The moment D_n appears at Q depends on the bit-length shown in Table 4; H = HIGH voltage level; L = LOW voltage level; X = don't care; $\uparrow = positive-going transition$; $\downarrow = negative-going transition$; D_1 , $D_2 = either HIGH$ or LOW.

Table 4. Bit-length select function table

L32	L16	L8	L4	L2	L1	Register length
L	L	L	L	L	L	1-bit
L	L	L	L	L	Н	2-bits
L	L	L	L	Н	L	3-bits
L	L	L	L	Н	Н	4-bits
L	L	L	Н	L	L	5-bits
L	L	L	Н	L	Н	6-bits
L	L	L	Н	Н	L	7-bits
L	L	L	Н	Н	Н	8-bits
	,	L1 to L16 cor	tinue to increme	ent in a binary co	unt with L32 LOV	V
L	Н	Н	Н	Н	Н	32-bits
Н	L	L	L	L	L	33-bits
Н	L	L	L	L	Н	34-bits
		L1 to L16 con	tinue to increme	nt in a binary co	unt with L32 HIG	Н
Н	Н	Н	Н	L	L	61-bits
Н	Н	Н	Н	L	Н	62-bits
Н	Н	Н	Н	Н	L	63-bits
Н	Н	Н	Н	Н	Н	64-bits

1-to-64 bit variable length shift register

7. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
V_{DD}	supply voltage			-0.5	+18	V
I _{IK}	input clamping current	$V_{I} < -0.5 \text{ V or } V_{I} > V_{DD} + 0.5 \text{ V}$		-	±10	mA
VI	input voltage			-0.5	$V_{DD} + 0.5$	V
I _{OK}	output clamping current	$V_{O} < -0.5 \text{ V or } V_{O} > V_{DD} + 0.5 \text{ V}$		-	±10	mA
I _{I/O}	input/output current			-	±10	mA
I_{DD}	supply current			-	50	mA
T _{stg}	storage temperature			-65	+150	°C
T _{amb}	ambient temperature			-40	+85	°C
P _{tot}	total power dissipation	SO16 package	[1]	-	500	mW
Р	power dissipation	per output		-	100	mW

^[1] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

8. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V_{DD}	supply voltage		3	-	15	V
V _I	input voltage		0	-	V_{DD}	V
T _{amb}	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	$V_{DD} = 5 V$	-	-	3.75	μs/V
		V _{DD} = 10 V	-	-	0.5	μs/V
		V _{DD} = 15 V	-	-	0.08	μs/V

1-to-64 bit variable length shift register

9. Static characteristics

Table 7. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	T _{amb} =	-40 °C	T _{amb} =	= 25 °C	T _{amb} = 85 °C		Unit
				Min	Max	Min	Max	Min	Max	
V_{IH}	HIGH-level input voltage	$ I_{O} < 1 \mu A$	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V_{IL}	LOW-level input voltage	$ I_{O} < 1 \mu A$	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level output voltage	$ I_{O} < 1 \mu A$	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V _{OL}	LOW-level output voltage	$ I_{O} < 1 \mu A$	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level output current	V _O = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V _O = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V _O = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I _{OL}	LOW-level output current	V _O = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		$V_0 = 0.5 \ V$	10 V	1.3	-	1.1	-	0.9	-	mA
		V _O = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
I _I	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μΑ
I _{DD}	supply current	I _O = 0 A	5 V	-	50	-	50	-	375	μΑ
			10 V	-	100	-	100	-	750	μΑ
			15 V	-	200	-	200	-	1500	μΑ
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

1-to-64 bit variable length shift register

10. Dynamic characteristics

Table 8. Dynamic characteristics

 $V_{SS} = 0 \text{ V; } T_{amb} = 25 \text{ °C; for test circuit see }$ <u>Figure 6; unless otherwise specified.</u>

Symbol	Parameter	Conditions	V_{DD}		Extrapolation formula	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW	CP0, CP1 to Q, Q;	5 V	[1]	213 ns + (0.55 ns/pF)C _L	-	240	480	ns
	propagation delay	see Figure 4	10 V		79 ns + (0.23 ns/pF)C _L	-	90	180	ns
			15 V		57 ns + (0.16 ns/pF)C _L	-	65	130	ns
		MR to Q; see Figure 4	5 V		143 ns + (0.55 ns/pF)C _L	-	170	340	ns
			10 V		69 ns + (0.23 ns/pF)C _L	-	80	160	ns
			15 V		52 ns + (0.16 ns/pF)C _L	-	60	120	ns
t _{PLH}	LOW to HIGH	CP0, $\overline{CP1}$ to Q, \overline{Q} ;	5 V	[1]	213 ns + (0.55 ns/pF)C _L	-	240	480	ns
	propagation delay	see Figure 4	10 V		79 ns + (0.23 ns/pF)C _L	-	90	180	ns
			15 V		57 ns + (0.16 ns/pF)C _L	-	65	130	ns
		MR to \overline{Q} ; see Figure 4	5 V		113 ns + (0.55 ns/pF)C _L	-	140	280	ns
			10 V		59 ns + (0.23 ns/pF)C _L	-	70	140	ns
			15 V		47 ns + (0.16 ns/pF)C _L	-	55	110	ns
t _t	transition time	see Figure 4	5 V	[1]	10 ns + (1.00 ns/pF)C _L	-	60	120	ns
			10 V		9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V		6 ns + (0.28 ns/pF)C _L	-	20	40	ns
t _{su}	set-up time	\overline{DA} , DB, $\overline{A/B}$ to CP0,	5 V	[2]		360	180	-	ns
		CP1; L1 to L32 = LOW; see Figure 5	10 V			140	70	-	ns
			15 V			90	45	-	ns
		\overline{DA} , DB, $\overline{A/B}$ to CP0,	5 V			+40	-20	-	ns
		CP1; L32 = HIGH; see Figure 5	10 V			+35	-10	-	ns
		see <u>rigure s</u>	15 V			+30	-5	-	ns
t _h	hold time	\overline{DA} , DB, $\overline{A/B}$ to CP0,	5 V	[2]		-40	-110	-	ns
		CP1; L1 to L32 = LOW; see Figure 5	10 V			-10	-45	-	ns
		see <u>rigure s</u>	15 V			0	-30	-	ns
		\overline{DA} , DB, $\overline{A/B}$ to CP0,	5 V			90	30	-	ns
		CP1; L1 to L32 = HIGH;	10 V			60	20	-	ns
		see Figure 5	15 V			50	15	-	ns
t _W	pulse width	CP0 input LOW;	5 V			180	90	-	ns
		minimum width;	10 V			60	30	-	ns
		see <u>Figure 5</u>	15 V			40	20	-	ns
		CP1 input HIGH;	5 V			180	90	-	ns
		minimum width;	10 V			60	30	-	ns
		see <u>Figure 5</u>	15 V			40	20	-	ns
		MR input HIGH;	5 V			150	75	-	ns
		minimum width;	10 V			70	35	-	ns
		see Figure 5	15 V			50	25	-	ns

1-to-64 bit variable length shift register

 Table 8.
 Dynamic characteristics ...continued

 $V_{SS} = 0 \text{ V}$; $T_{amb} = 25 \,^{\circ}\text{C}$; for test circuit see <u>Figure 6</u>; unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
t _{rec}	recovery time	MR input;	5 V [2]		500	250	-	ns
		L1 to L32 = LOW; see Figure 5	10 V		250	125	-	ns
	see <u>Figure 5</u>	15 V		150	75	-	ns	
		MR input; L32 = HIGH	5 V		110	50	-	ns
			10 V		70	30	-	ns
			15 V		60	25	-	ns
f _{max}	maximum	see Figure 5	5 V		2.5	5	-	MHz
	frequency		10 V		7	14	-	MHz
			15 V		10	20	-	MHz

^[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 9. Interpolation table [1]

Lengt	h contro	l inputs				Minimum number of	Set-up, hold, and	Example: t _{rec}
L1	L2	L4	L8	L16	L32	bits selected	recovery times	minimum, $V_{DD} = 5 \text{ V}$
L	L	L	L	L	L	1	see <u>Table 8</u>	500 ns
Н	L	L	L	L	L	2	(interpolate in 6	435 ns
Χ	Н	L	L	L	L	3	equal steps)	370 ns
Χ	Х	Н	L	L	L	5		305 ns
Χ	Х	Х	Н	L	L	9		240 ns
Χ	Х	Х	Х	Н	L	17		175 ns
Χ	Х	Х	Х	Х	Н	33	see <u>Table 8</u>	110 ns

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care

Table 10. Dynamic power dissipation P_D

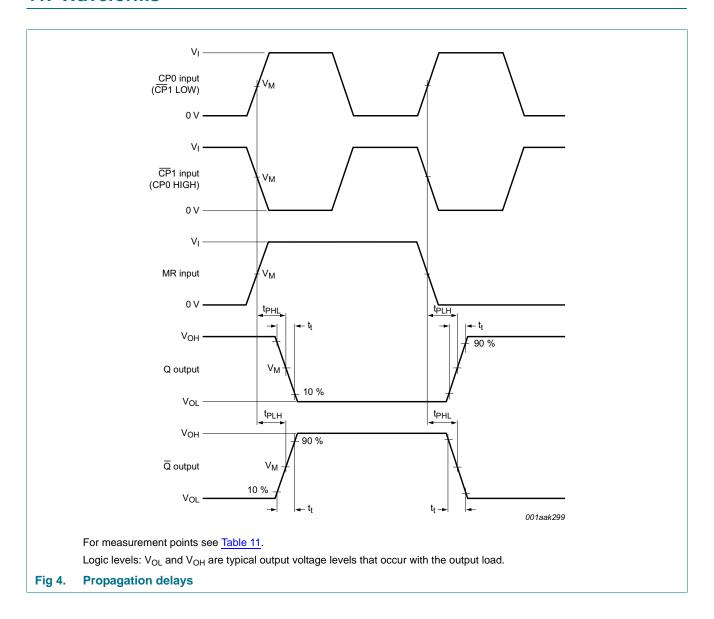
 P_D can be calculated from the formulas shown. $V_{SS} = 0$ V; $t_r = t_f \le 20$ ns; $T_{amb} = 25$ °C.

Symbol	Parameter	V _{DD}	Typical formula for P _D (μW)	where:
P_D	dynamic power	5 V	$P_D = 3500 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f _i = input frequency in MHz,
	dissipation	10 V	$P_D = 15000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f _o = output frequency in MHz,
		15 V	$P_D = 37000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	C_L = output load capacitance in pF,
				V _{DD} = supply voltage in V,
				$\Sigma(f_0 \times C_L)$ = sum of the outputs.

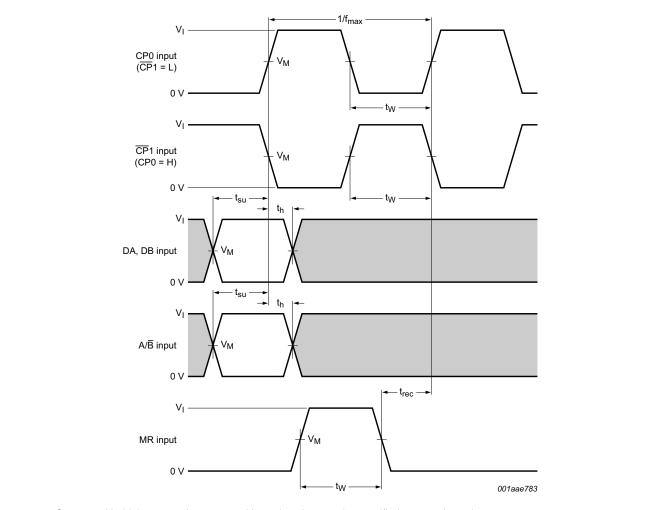
^[2] The set-up, hold, and recovery times vary with the minimum number of bits selected. For intermediate numbers not specified, interpolate as shown in Table 9.

1-to-64 bit variable length shift register

11. Waveforms



1-to-64 bit variable length shift register



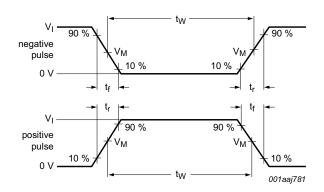
Set-up and hold times are shown as positive values but may be specified as negative values.

The shaded area indicates where data can change for predictable performance.

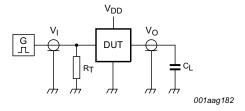
For measurement points see <u>Table 11</u>.

Fig 5. Waveforms showing recovery time for MR and minimum CP0, CP1, and MR pulse widths, set-up and hold times for DA, DB, and A/B to CP0 and CP1

1-to-64 bit variable length shift register



a. Input waveforms



b. Test circuit

Test data is given in Table 11.

Definitions for test circuit:

Device Under Test (DUT)

C_L = Load capacitance including jig and probe capacitance;

 R_T = Termination resistance should be equal to output impedance Z_0 of the pulse generator.

Fig 6. Test circuit for measuring switching times

Table 11. Measurement points and test data

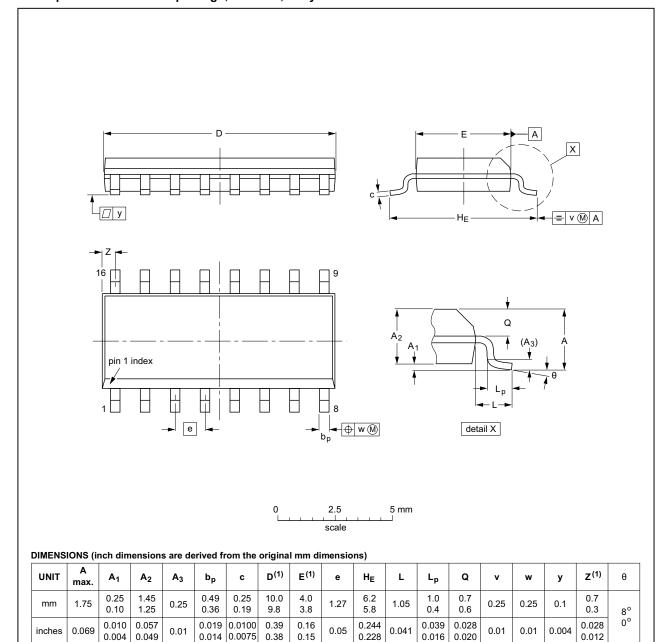
Supply voltage	Input			Load
V_{DD}	VI	V _M	t _r , t _f	C _L
5 V to 15 V	V_{DD}	0.5V _I	≤ 20 ns	50 pF

1-to-64 bit variable length shift register

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES			EUROPEAN	ISSUE DATE	
	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT109-1	076E07	MS-012				99-12-27 03-02-19

Fig 7. Package outline SOT109-1 (SO16)

HEF4557B

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1-to-64 bit variable length shift register

13. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
HEF4557B v.7	20160401	Product data sheet	-	HEF4557B v.6	
Modifications:	Type number HEF4557BP (SOT38-4) removed.				
HEF4557B v.6	20111118	Product data sheet	-	HEF4557B v.5	
Modifications:	 Section Applications removed Table 7: I_{OH} minimum values changed to maximum 				
	 Figure 5: "Ā/B input" changed to "A/B input" 				
HEF4557B v.5	20091216	Product data sheet	-	HEF4557B v.4	
HEF4557B v.4	20090916	Product data sheet	-	HEF4557B_CNV v.3	
HEF4557B_CNV v.3	19950101	Product specification	-	HEF4557B_CNV v.2	
HEF4557B_CNV v.2	19950101	Product specification	-	-	

1-to-64 bit variable length shift register

14. Legal information

14.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

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16. Contents

1	General description	. 1
2	Features and benefits	. 1
3	Ordering information	. 1
4	Functional diagram	. 2
5	Pinning information	. 3
5.1	Pinning	. 3
5.2	Pin description	. 3
6	Functional description	. 4
7	Limiting values	. 5
8	Recommended operating conditions	. 5
9	Static characteristics	. 6
10	Dynamic characteristics	. 7
11	Waveforms	. 9
12	Package outline	12
13	Revision history	13
14	Legal information	14
14.1	Data sheet status	14
14.2	Definitions	14
14.3	Disclaimers	14
14.4	Trademarks	15
15	Contact information	15
16	Contents	16

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