



# 2 Mbit / 4 Mbit Single Operating Voltage Serial Flash Memory With 80 MHz Dual-Output SPI Bus Interface

## **FEATURES**

#### Single Power Supply Operation

- Low voltage range: 1.65 V - 1.95 V

#### Memory Organization

- IS25WD020: 256K x 8 (2 Mbit)

- IS25WD040: 512K x 8 (4 Mbit)

#### Cost Effective Sector/Block Architecture

 2Mb : Uniform 4KByte sectors / Four uniform 64KByte blocks

- 4Mb : Uniform 4KByte sectors / Eight uniform 64KByte blocks

#### Serial Peripheral Interface (SPI) Compatible

- Supports single- or dual-output
- Supports SPI Modes 0 and 3
- Maximum 30 MHz clock rate for normal read
- Maximum 80 MHz clock rate for fast read

#### Page Program (up to 256 Bytes) Operation

- Typical 2 ms per page program

#### Sector, Block or Chip Erase Operation

- Typical 1.7 ms sector, block or chip erase

## Low Power Consumption

- Typical 2 mA active read current
- Typical 6 mA program/erase current

#### • Hardware Write Protection

- Protect and unprotect the device from write operation by Write Protect (WP#) Pin

#### Software Write Protection

 The Block Protect (BP2, BP1, BP0) bits allow partial or entire memory to be configured as readonly

#### High Product Endurance

- Guaranteed 200,000 program/erase cycles per single sector
- Minimum 20 years data retention

#### Industrial Standard Pin-out and Package

- 8-pin SOIC 208mil
- 8-pin SOIC 150mil
- 8-pin VVSOP 150mil
- 8-pin WSON
- KGD (Call Factory)
- Lead-free (Pb-free) package
- Automotive Temperature Ranges Available

### **GENERAL DESCRIPTION**

The IS25WD020/040 are 2 Mbit / 4Mbit Serial Peripheral Interface (SPI) Flash memories, providing single- or dual-output. The devices are designed to support a 30 MHz fclock rate in normal read mode, and 80 MHz in fast read, the fastest in the industry. The devices use a single low voltage power supply, wide operating voltage ranging from 1.65 Volt to 1.95 Volt, to perform read, erase and program operations. The devices can be programmed in standard EPROM programmers.

The IS25WD020/040 are accessed through a 4-wire SPI Interface consisting of Serial Data Input/Output (SIO), Serial Data Output (SO), Serial Clock (SCK), and Chip Enable (CE#) pins. They comply with all recognized command codes and operations. The dual-output fast read operation provides and effective serial data rate of 160MHz.

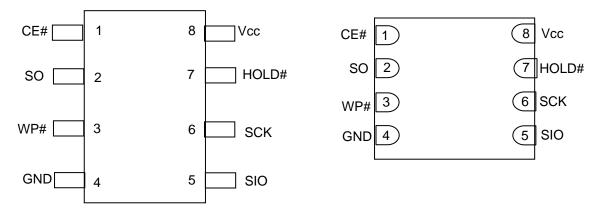
The devices support page program mode, where 1 to 256 bytes data can be programmed into the memory in one program operation. These devices are divided into uniform 4 KByte sectors or uniform 64 KByte blocks.

The IS25WD020/040 are manufactured on pFLASH™'s advanced non-volatile technology. The devices are offered in 8-pin SOIC 208mil, 8-pin SOIC 150mil, 8-pin VVSOP 150mil and 8-pin WSON. The devices operate at wide temperatures between -40°C to +105°C.





# **CONNECTION DIAGRAMS**



8-Pin SOIC/VVSOP

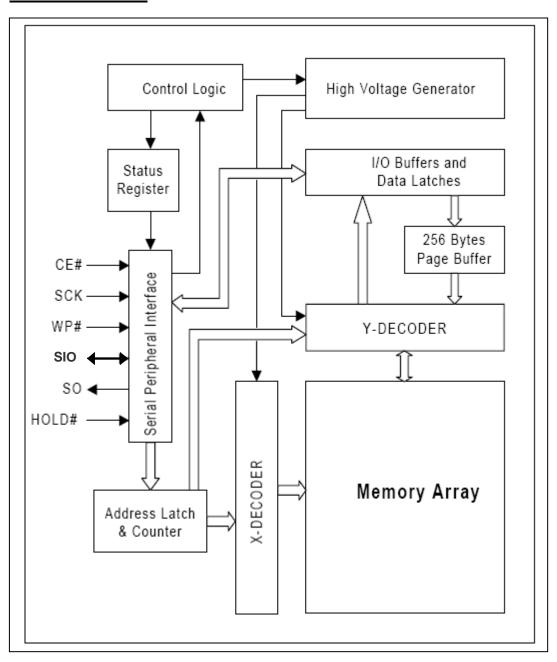
**8-Contact WSON** 

# **PIN DESCRIPTIONS**

SYMBOL	TYPE	DESCRIPTION
CE#	INPUT	Chip Enable: CE# low activates the devices internal circuitries for device operation. CE# high deselects the devices and switches into standby mode to reduce the power consumption. When a device is not selected, data will not be accepted via the serial input pin (SI), and the serial output pin (SO) will remain in a high impedance state.
SCK	INPUT	Serial Data Clock
SIO	INPUT/OUTPUT	Serial Data Input/Output
SO	OUTPUT	Serial Data Output
GND		Ground
Vcc		Device Power Supply
WP#	INPUT	Write Protect: A hardware program/erase protection for all or part of a memory array. When the WP# pin is low, memory array write-protection depends on the setting of BP2, BP1 and BP0 bits in the Status Register. When the WP# is high, the devices are not write-protected.
HOLD#	INPUT	Hold: Pause serial communication by the master device without resetting the serial sequence.



# **BLOCK DIAGRAM**







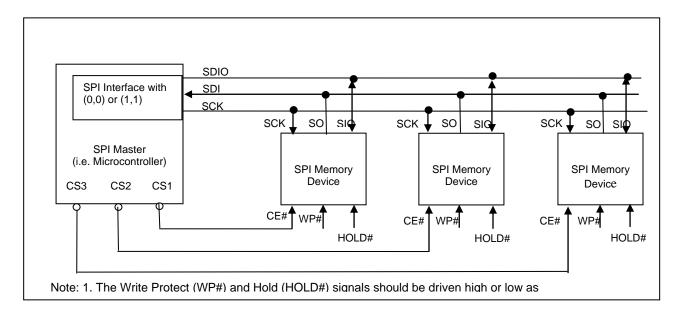
### SPI MODES DESCRIPTION

Multiple IS25WD020/040 devices can be connected on the SPI serial bus and controlled by a SPI Master, i.e. microcontroller, as shown in Figure 1. The devices support either of two SPI modes:

> Mode 0 (0, 0) Mode 3 (1, 1)

The difference between these two modes is the clock polarity when the SPI master is in Stand-by mode: the serial clock remains at "0" (SCK = 0) for Mode 0 and the clock remains at "1" (SCK = 1) for Mode 3. Please refer to Figure 2. For both modes, the input data is latched on the rising edge of Serial Clock (SCK), and the output data is available from the falling edge of SCK.

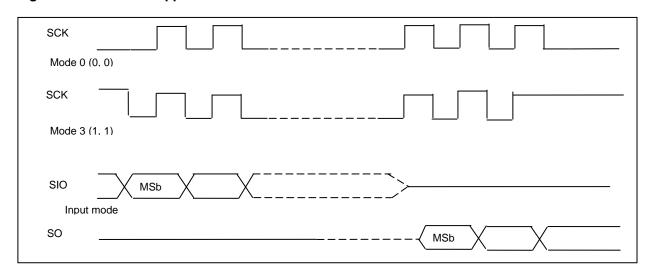
Figure 1. Connection Diagram among SPI Master and SPI Slaves (Memory Devices)







## Figure 2. SPI Modes Supported







## SYSTEM CONFIGURATION

The IS25WD020/040 devices are designed to interface directly with the synchronous Serial Peripheral Interface (SPI) of the Motorola MC68HCxx series of microcontrollers or any SPI interface-equipped system controllers. The devices have two superset features that can be enabled through specific software instructions and the Configuration Register:

Table 1 illustrates the memory map of the devices. The Configuration Register controls how the memory is mapped.

## **BLOCK/SECTOR ADDRESSES**

Table 1. Block/Sector Addresses of IS25WD020/040

Memory Den	Memory Density		Block Size (Kbytes)	Sector No.	Sector Size (Kbytes)	Address Range
				Sector 0	4	000000h – 000FFFh
		Block 0	64	Sector 1	4	001000h – 001FFFh
		DIOCK U	04	:	:	:
				Sector 15	4	00F000h - 00FFFFh
	2 Mbit			Sector 16	4	010000h – 010FFFh
	Z WIDIL	Block 1	64	Sector 17	4 011000h – 011Fi	011000h – 011FFFh
		DIUCK I	64 : Secto	:	:	:
4 Mbit				Sector 31	4	01F000h – 01FFFFh
		••	:	:	:	:
		Block 3	64	:	4	030000h - 03FFFFh
		Block 4	64	:	4	040000h – 04FFFFh
		:	:	:	:	:
		:	:	:	:	:
		Block 7	64	:	4	070000h – 07FFFFh



## **REGISTERS (CONTINUED)**

#### STATUS REGISTER

Refer to Tables 5 and 6 for Status Register Format and Status Register Bit Definitions.

The BP0, BP1, BP2, and SRWD are volatile memory cells that can be written by a Write Status Register (WRSR) instruction. The default value of the BP2, BP1. BP0 were set to "0" and SRWD bits was set to "0" at factory. Once a "0" or "1" is written, it will not be changed by device power-up or power-down, and can only be altered by the next WRSR instruction. The Status Register can be read by the Read Status Register (RDSR). Refer to Table 10 for Instruction Set.

The function of Status Register bits are described as follows:

**WIP bit**: The Write In Progress (WIP) bit is read-only. and can be used to detect the progress or completion of a program or erase operation. When the WIP bit is "0", the device is ready for a write status register. program or erase operation. When the WIP bit is "1", the device is busy.

WEL bit: The Write Enable Latch (WEL) bit indicates the status of the internal write enable latch. When the WEL is "0", the write enable latch is disabled, and all write operations, including write status register, page program, sector erase, block and chip erase operations are inhibited. When the WEL bit is "1", write operations

are allowed. The WEL bit is set by a Write Enable (WREN) instruction. Each write register, program and erase instruction must be preceded by a WREN instruction. The WEL bit can be reset by a Write Disable (WRDI) instruction. It will automatically be the reset after the completion of a write instruction.

BP2, BP1, BP0 bits: The Block Protection (BP2, BP1, BP0) bits are used to define the portion of the memory area to be protected. Refer to Tables 7, 8 and 9 for the Block Write Protection bit settings. When a defined combination of BP2, BP1 and BP0 bits are set, the corresponding memory area is protected. Any program or erase operation to that area will be inhibited. Note: a Chip Erase (CHIP ER) instruction is executed successfully only if all the Block Protection Bits are set as "0"s.

**SRWD bit**: The Status Register Write Disable (SRWD) bit operates in conjunction with the Write Protection (WP#) signal to provide a Hardware Protection Mode. When the SRWD is set to "0", the Status Register is not write-protected. When the SRWD is set to "1" and the WP# is pulled low (VIL), the volatile bits of Status Register (SRWD, BP2, BP1, BP0) become read-only, and a WRSR instruction will be ignored. If the SRWD is set to "1" and WP# is pulled high (VIH), the Status Register can be changed by a WRSR instruction.

Table 5. Status Register Format

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
	SRWD1	Rese	rved	BP2	BP1	BP0	WEL	WIP
Default (flash bit)	0	C	)	0	0	0	0	0



# **REGISTERS (CONTINUED)**

**Table 6. Status Register Bit Definition** 

Bit	Name	Definition	Read- /Write	Non-Volatile bit
Bit 0	WIP	Write In Progress Bit: "0" indicates the device is ready "1" indicates a write cycle is in progress and the device is busy	R	No
Bit 1	WEL	Write Enable Latch: "0" indicates the device is not write enabled "1" indicates the device is write enabled (default)	R/W	No
Bit 2	BP0	Block Protection Bit: (See Table 7 and Table 8 for details)		
Bit 3	BP1	"0" indicates the specific blocks are not write-protected (default)	R/W	Yes
Bit 4	BP2	"1" indicates the specific blocks are write-protected		
Bits 5 – 6	N/A	Reserved: Always "0"s	N/A	
Bit 7	SRWD	Status Register Write Disable: (See Table 9 for details) "0" indicates the Status Register is not write-protected (default) "1" indicates the Status Register is write-protected	R/W	Yes

Table 8. Block Write Protect Bits for IS25WD020

Status Register Bits		Bits	Protected Memory Area
BP2	BP1 BP0		2 Mbit
Not used	0	0	None
Not used	0	1	Upper eight (block : 3): 030000h – 03FFFFh
Not used	1	0	Upper quarter (two blocks :2 and 3): 020000h - 03FFFFh
Not used	1	1	Upper half (four blocks :0 to 3): 000000h – 03FFFFh

Table 8-1. Block Write Protect Bits for IS25WD040

Sta	Status Register Bits		Protected Memory Area	
BP2	BP1	BP0	4 Mbit	
0	0	0	None	
0	0	1	Upper eight (block : 7): 070000h – 07FFFFh	
0	1	0	Upper quarter (two blocks :6 and 7): 060000h - 07FFFFh	
0	1	1	Upper half (four blocks :4 to 7): 040000h – 07FFFFh	
1	0	0		
1	0	1	All Blocks (Block 0 to 7):	
1	1	0	000000h – 07FFFFh	
1	1	1		



## REGISTERS (CONTINUED)

### **PROTECTION MODE**

The IS25WD020/040 have two types of write-protection mechanisms: hardware and software. These are used to prevent irrelevant operation in a possibly noisy environment and protect the data integrity.

#### HARDWARE WRITE-PROTECTION

The devices provide two hardware write-protection features:

- a. When inputting a program, erase or write status register instruction, the number of clock pulse is checked to determine whether it is a multiple of eight before the executing. Any incomplete instruction command sequence will be ignored.
- The Write Protection (WP#) pin provides a hardware write protection method for BP2, BP1, BP0 and SRWD in the Status Register. Refer to the STATUS REGISTER description.
- c. Write inhibit is 1.5 V, all write sequence will be ignored when Vcc drop to 1.5 V and lower

#### **SOFTWARE WRITE PROTECTION**

The IS25WD020/040 also provides two software write protection features:

- a. Before the execution of any program, erase or write status register instruction, the Write Enable Latch (WEL) bit must be enabled by executing a Write Enable (WREN) instruction. If the WEL bit is not enabled first, the program, erase or write register instruction will be ignored.
- b. The Block Protection (BP2, BP1, BP0) bits allow part or the whole memory area to be write-protected.

Table 9. Hardware Write Protection on Status Register

SRWD	WP#	Status Register
0	Low	Writable
1	Low	Protected
0	High	Writable
1	High	Writable



# IS25WD020/040

#### **DEVICE OPERATION**

The IS25WD020/040 utilize an 8-bit instruction register. Refer to Table 10 Instruction Set for details of the Instructions and Instruction Codes. All instructions, addresses, and data are shifted in with the most significant bit (MSB) first on Serial Data Input (SI). The input data on SI is latched on the rising edge of Serial Clock (SCK) after Chip Enable (CE#) is driven low (VIL). Every instruction sequence starts with a one-byte

instruction code and is followed by address bytes, data bytes, or both address bytes and data bytes, depending on the type of instruction. CE# must be driven high ( $V_{IH}$ ) after the last bit of the instruction sequence has been shifted in.

The timing for each instruction is illustrated in the following operational descriptions.

**Table 10. Instruction Set** 

Instruction Name	Hex Code	Operation	Command Cycle	Maximum Frequency
RDID	Abh	Read Manufacturer and Product ID	4 Bytes	80 MHz
JEDEC ID READ	9Fh	Read Manufacturer and Product ID by JEDEC ID Command	1 Byte	80 MHz
RDMDID	90h	Read Manufacturer and Device ID	4 Bytes	80 MHz
WREN	06h	Write Enable	1 Byte	80 MHz
WRDI	04h	Write Disable	1 Byte	80 MHz
RDSR	05h	Read Status Register	1 Byte	80 MHz
WRSR	01h	Write Status Register	2 Bytes	80 MHz
READ	03h	Read Data Bytes from Memory at Normal Read Mode	4 Bytes	30 MHz
FAST_READ	0Bh	Read Data Bytes from Memory at Fast Read Mode	5 Bytes	80 MHz
FRDO	3Bh	Fast Read Dual Output	5 Bytes	80 MHz
PAGE_ PROG	02h	Page Program Data Bytes Into Memory	4 Bytes + 256B	80 MHz
SECTOR_ER	D7h/ 20h	Sector Erase	4 Bytes	80 MHz
BLOCK_ER	D8h	Block Erase	4 Bytes	80 MHz
CHIP_ER	C7h/ 60h	Chip Erase	1 Byte	80 MHz

#### **HOLD OPERATION**

HOLD# is used in conjunction with CE# to select the IS25WD020/040. When the devices are selected and a serial sequence is underway, HOLD# can be used to pause the serial communication with the master device without resetting the serial sequence. To pause, HOLD# is brought low while the SCK signal is low. To resume serial communication, HOLD# is brought high while the SCK signal is low (SCK may still toggle during HOLD). Inputs to SI will be ignored while SO is in the high impedance state.



# RDID COMMAND (READ PRODUCT IDENTIFICATION) OPERATION

The Read Product Identification (RDID) instruction is for reading out the old style of 8-bit Electronic Signature, whose values are shown as table of ID Definitions. This is not same as RDID or JEDEC ID instruction. It's not recommended to use for new design. For new design, please use RDID or JEDEC ID instruction.

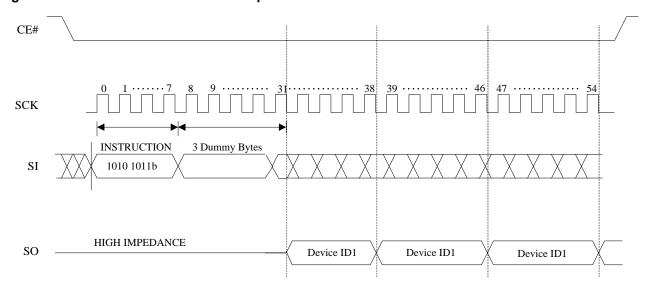
The RDES instruction code is followed by three dummy bytes, each bit being latched-in on SI during the rising edge of SCK. Then the Device ID is shifted out on SO with the MSB first, each bit been shifted out during the falling edge of SCK. The RDES instruction is ended by

CE# goes high. The Device ID outputs repeatedly if continuously send the additional clock cycles on SCK while CE# is at low.

**Table 11. Product Identification** 

Product Identifica	Data	
Manufacturer ID	First Byte	9Dh
Manuacturer ID	Second Byte	7Fh
Device ID:	Device ID 1	Device ID 2
IS25WD020	11h	32h
IS25WD040	12h	33h

Figure 3. Read Product Identification Sequence



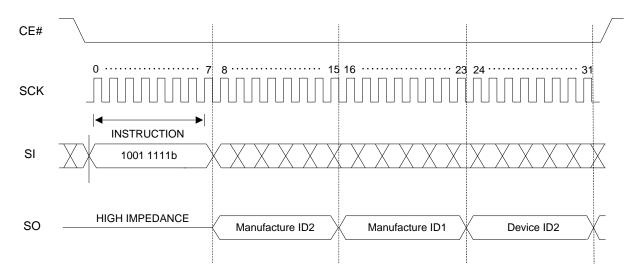


# JEDEC ID READ COMMAND (READ PRODUCT IDENTIFICATION BY JEDEC ID) OPERATION

The JEDEC ID READ instruction allows the user to read the manufacturer and product ID of devices. Refer to Table 11 Product Identification for pFlash Manufacturer ID and Device ID. After the JEDEC ID READ command is input, the second Manufacturer ID (7Fh) is shifted out on SO with the MSB first, followed

by the first Manufacturer ID (9Dh) and the Device ID (32h, in the case of the IS25WD020), each bit shifted out during the falling edge of SCK. If CE# stays low after the last bit of the Device ID is shifted out, the Manufacturer ID and Device ID will loop until CE# is pulled high.

Figure 4. Read Product Identification by JEDEC ID READ Sequence



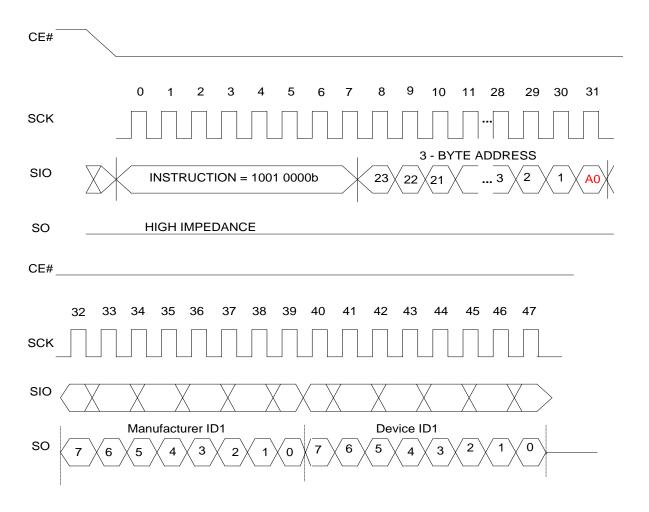


# RDMDID COMMAND (READ DEVICE MANUFACTURER AND DEVICE ID) OPERATION

The RDMDID instruction allows the user to read the manufacturer and product ID of devices. Refer to Table 11 Product Identification for pFlash Manufacturer ID and Device ID. The RDMDID command is input, followed by a 24-bit address pointing to an ID table. The table contains the first Manufacturer ID (9Dh) and

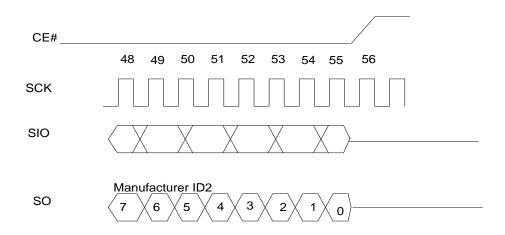
the Device ID (32h, in the case of the IS25WD020), and is shifted out on SO with the MSB first, each bit shifted out during the falling edge of SCK. If CE# stays low after the last bit of the Device ID is shifted out, the Manufacturer ID and Device ID will loop until CE# is pulled high.

Figure 5. Read Product Identification by RDMDID READ Sequence









#### Note:

0. ADDRESS A0 = 0, will output the 1<sup>st</sup> manufacture ID (9Dh) first -> device ID1 -> 2<sup>nd</sup> manufacture ID (7Fh) ADDRESS A0 = 1, will output the device ID1 -> 1<sup>st</sup> manufacture ID (9D) -> 2<sup>nd</sup> manufacture ID (7Fh)

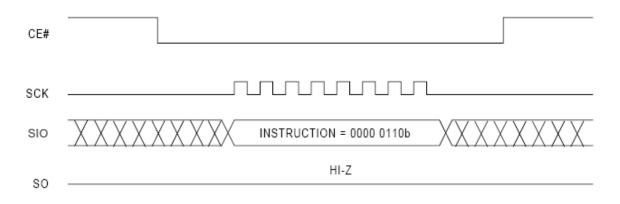


#### WRITE ENABLE OPERATION

The Write Enable (WREN) instruction is used to set the erase, chip erase, page program and write status Write Enable Latch (WEL) bit. The WEL bit of the IS25WD020/040 is reset to the write -protected state after power-up. The WEL bit must be write enabled before any write operation, including sector, block

register operations. The WEL bit will be reset to the write-protect state automatically upon completion of a write operation. The WREN instruction is required before any above operation is executed.

Figure 6. Write Enable Sequence

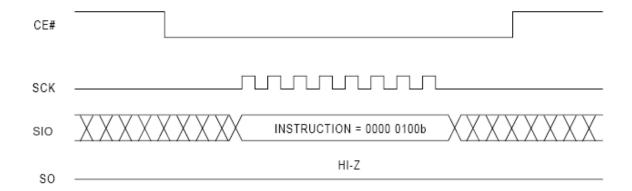


#### WRDI COMMAND (WRITE DISABLE) OPERATION

The Write Disable (WRDI) instruction resets the WEL bit and disables all write instructions. The WRDI

instruction is not required after the execution of a write instruction, since the WEL bit is automatically reset.

Figure 7. Write Disable Sequence



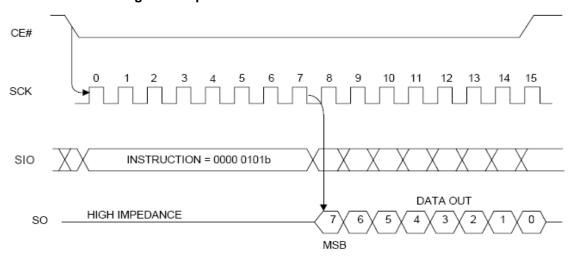


#### **RDSR COMMAND (READ STATUS REGISTER) OPERATION**

The Read Status Register (RDSR) instruction provides access to the Status Register. During the execution of a program, erase or write status register operation, all other instructions will be ignored except the RDSR

instruction, which can be used to check the progress or completion of an operation by reading the WIP bit of Status Register.

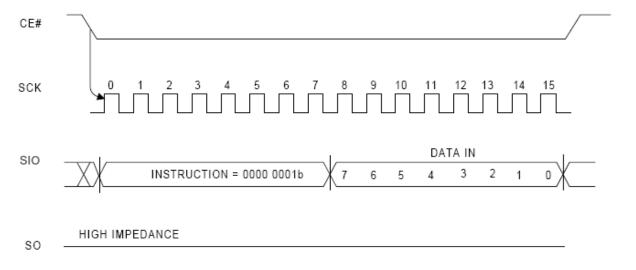
Figure 8. Read Status Register Sequence



#### WRSR COMMAND (WRITE STATUS REGISTER) OPERATION

The Write Status Register (WRSR) instruction allows the user to enable or disable the block protection and status register write protection features by writing "0"s or "1" s into the volatile BP2, BP1, BP0 and SRWD bits.

Figure 9. Write Status Register Sequence





#### **READ COMMAND (READ DATA) OPERATION**

The Read Data (READ) instruction is used to read memory data of a IS25WD020/040 under normal mode running up to 30 MHz.

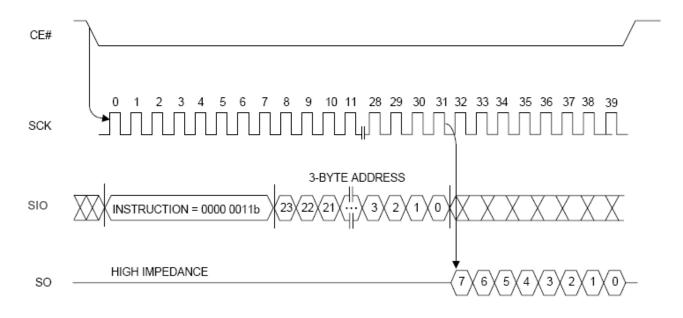
The READ instruction code is transmitted via the SI line, followed by three address bytes (A23 – A0) of the first memory location to be read. A total of 24 address bits are shifted in, but only  $A_{\rm MS}$  (most significant address) – A0 are decoded. The remaining bits (A23 –  $A_{\rm MS}$ ) are ignored. The first byte addressed can be at any memory location. Upon completion, any data on the SI will be ignored. Refer to Table 12 for the related Address Key.

The first byte data (D7 – D0) addressed is then shifted out on the SO line, MSb first. A single byte of data, or up to the whole memory array, can be read out in one READ instruction. The address is automatically incremented after each byte of data is shifted out. The read operation can be terminated at any time by driving CE# high ( $V_{IH}$ ) after the data comes out. When the highest address of the devices is reached, the address counter will roll over to the 000000h address, allowing the entire memory to be read in one continuous READ instruction.

Table 12. Address Key

Address	IS25WD020	IS25WD040
$A_N (A_{MS} - A_0)$	A17 – A0	A18 – A0
Don't Care Bits	A23 – A18	A23 – A19

Figure 12. Read Data Sequence





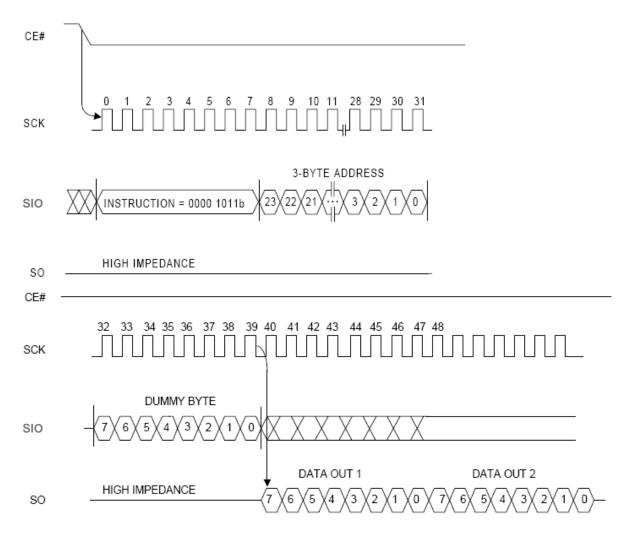
#### FAST\_READ COMMAND (FAST READ DATA) OPERATION

The FAST READ instruction is used to read memory data at up to a 80 MHz clock.

The FAST\_READ instruction code is followed by three address bytes (A23 - A0) and a dummy byte (8 clocks), transmitted via the SI line, with each bit latched-in during the rising edge of SCK. Then the first data byte addressed is shifted out on the SO line, with each bit shifted out at a maximum frequency fct, during the falling edge of SCK.

The first byte addressed can be at any memory location. The address is automatically incremented after each byte of data is shifted out. When the highest address is reached, the address counter will roll over to the 000000h address, allowing the entire memory to be read with a single FAST\_READ instruction. The FAST\_READ instruction is terminated by driving CE# high (V<sub>IH</sub>).

Figure 13. Fast Read Data Sequence





#### FRDO COMMAND (FAST READ DUAL OUTPUT) OPERATION

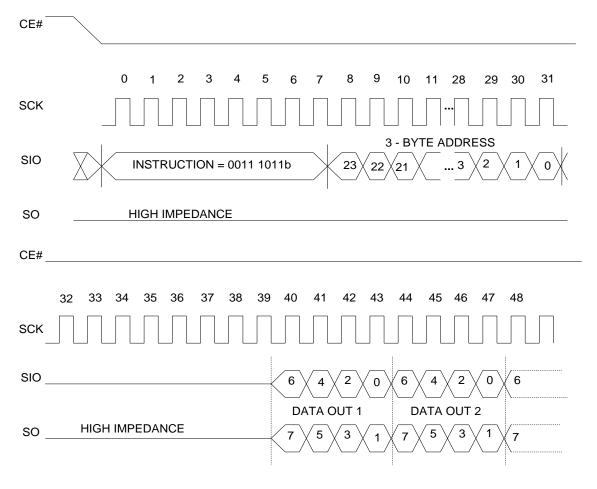
The FRDO instruction is used to read memory data on two output pins each at up to a 80 MHz clock.

The FRDO instruction code is followed by three address bytes (A23 – A0) and a dummy byte (8 clocks), transmitted via the SI line, with each bit latched-in during the rising edge of SCK. Then the first data byte addressed is shifted out on the SO and SIO lines, with each pair of bits shifted out at a maximum frequency fct, during the falling edge of SCK. The first

bit (MSb) is output on SO, while simultaneously the second bit is output on SIO.

The first byte addressed can be at any memory location. The address is automatically incremented after each byte of data is shifted out. When the highest address is reached, the address counter will roll over to the 000000h address, allowing the entire memory to be read with a single FRDO instruction. FRDO instruction is terminated by driving CE# high ( $V_{\rm IH}$ ).

Figure 14. Fast Read Dual-Output Sequence





#### PAGE\_PROG COMMAND (PAGE PROGRAM) OPERATION

The Page Program (PAGE\_PROG) instruction allows up to 256 bytes data to be programmed into memory in a single operation. The destination of the memory to be programmed must be outside the protected memory area set by the Block Protection (BP2, BP1, BP0) bits. A PAGE\_PROG instruction which attempts to program into a page that is write-protected will be ignored. Before the execution of PAGE\_PROG instruction, the Write Enable Latch (WEL) must be enabled through a Write Enable (WREN) instruction.

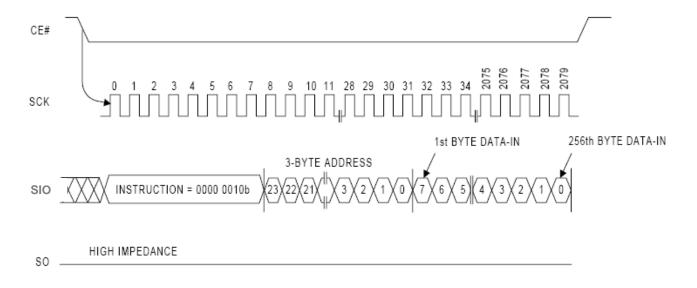
The PAGE\_PROG instruction code, three address bytes and program data (1 to 256 bytes) are input via the SI line. Program operation will start immediately after the CE# is brought high, otherwise the PAGE\_PROG instruction will not be executed. The internal control logic automatically handles the programming voltages and timing. During a program operation, all instructions will be ignored except the RDSR instruction. The progress or completion of the program operation can be determined by reading the

WIP bit in Status Register via a RDSR instruction. If the WIP bit is "1", the program operation is still in progress. If WIP bit is "0", the program operation has completed.

If more than 256 bytes data are sent to a device, the address counter rolls over within the same page, the previously latched data are discarded, and the last 256 bytes data are kept to be programmed into the page. The starting byte can be anywhere within the page. When the end of the page is reached, the address will wrap around to the beginning of the same page. If the data to be programmed are less than a full page, the data of all other bytes on the same page will remain unchanged.

Note: A program operation can alter "1"s into "0"s, but an erase operation is required to change "0"s back to "1"s. A byte cannot be reprogrammed without first erasing the whole sector or block.

Figure 15. Page Program Sequence







#### **ERASE OPERATION**

The memory array of the IS25WD020/040 is organized into uniform 4 Kbyte sectors or 64 Kbyte uniform blocks (a block consists of sixteen adjacent sectors). Before a byte can be reprogrammed, the sector or block that contains the byte must be erased (erasing sets bits to "1"). In order to erase the devices, there are three erase instructions available: Sector Erase (SECTOR\_ER), Block Erase (BLOCK\_ER) and Chip Erase (CHIP\_ER). A sector erase operation allows any individual sector to be erased without affecting the data in other sectors. A block erase operation erases any individual block. A chip erase operation erases the whole memory array of a device. A sector erase, block erase or chip erase operation can be executed prior to any programming operation.

#### SECTOR\_ER COMMAND (SECTOR ERASE) **OPERATION**

A SECTOR\_ER instruction erases a 4 Kbyte sector. Before the execution of a SECTOR ER instruction, the Write Enable Latch (WEL) must be set via a Write Enable (WREN) instruction. The WEL bit is reset automatically after the completion of sector an erase operation.

A SECTOR\_ER instruction is entered, after CE# is pulled low to select the device and stays low during the entire instruction sequence The SECTOR ER instruction code, and three address bytes are input via SI. Erase operation will start immediately after CE# is pulled high. The internal control logic automatically handles the erase voltage and timing. Refer to Figure 14 for Sector Erase Sequence.

During an erase operation, all instruction will be ignored except the Read Status Register (RDSR) instruction. The progress or completion of the erase operation can be determined by reading the WIP bit in the Status Register using a RDSR instruction. If the WIP bit is "1", the erase operation is still in progress. If the WIP bit is "0", the erase operation has been completed.

#### **BLOCK ER COMMAND (BLOCK ERASE) OPERATION**

A Block Erase (BLOCK\_ER) instruction erases a 64 Kbyte block of the IS25WD020/040. Before the execution of a BLOCK ER instruction, the Write Enable Latch (WEL) must be set via a Write Enable (WREN) instruction. The WEL is reset automatically after the completion of a block erase operation.

The BLOCK\_ER instruction code and three address bytes are input via SI. Erase operation will start immediately after the CE# is pulled high, otherwise the BLOCK\_ER instruction will not be executed. The internal control logic automatically handles the erase voltage and timing. Refer to Figure 15 for Block Erase Sequence.

## **CHIP ER COMMAND (CHIP ERASE) OPERATION**

A Chip Erase (CHIP ER) instruction erases the entire memory array of a IS25WD020/040. Before the execution of CHIP\_ER instruction, the Write Enable Latch (WEL) must be set via a Write Enable (WREN) instruction. The WEL is reset automatically after completion of a chip erase operation.

The CHIP\_ER instruction code is input via the SI. Erase operation will start immediately after CE# is pulled high, otherwise the CHIP ER instruction will not be executed. The internal control logic automatically handles the erase voltage and timing. Refer to Figure 16 for Chip Erase Sequence.



Figure 16. Sector Erase Sequence

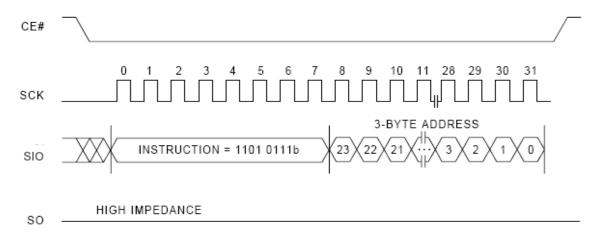


Figure 17. Block Erase Sequence

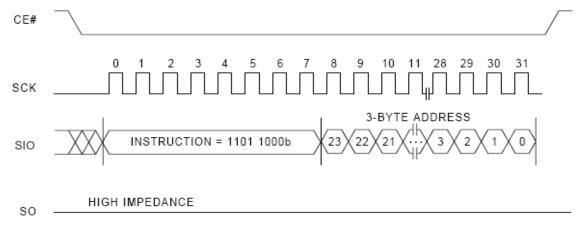
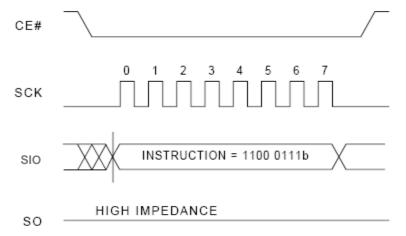


Figure 18. Chip Erase Sequence







# ABSOLUTE MAXIMUM RATINGS (1)

Temperature Under Bias	-65°C to +125°C	
Storage Temperature	-65°C to +125°C	
Surface Mount Lead Soldering Temperature	Halogen-free Package	260°C 10 Seconds
Surface Mount Lead Soldering Temperature	Lead-free Package	260°C 10 Seconds
Input Voltage with Respect to Ground on All F	-0.5 V to VCC + 0.5 V	
All Output Voltage with Respect to Ground	-0.5 V to VCC + 0.5 V	
VCC (2)	-0.5 V to +4.0 V	

#### Notes:

- 1. Applied conditions greater than those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only. The functional operation of the device conditions that exceed those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating condition for extended periods may affect device reliability.
- 2. Maximum DC voltage on input or I/O pins is Vcc + 0.5 V. During voltage transitions, input or I/O pins may overshoot Vcc by + 2.0 V for a period of time not to exceed 20 ns. Minimum DC voltage on input or I/O pins is -0.5 V. During voltage transitions, input or I/O pins may undershoot GND by -2.0 V for a period of time not to exceed 20 ns.

## **DC AND AC OPERATING RANGE**

Part Number	IS25WD020/040
Operating Temperature (Extended Grade)	-40°C to 105°C
Operating Temperature (Automotive, A1 Grade)	-40°C to 85°C
Operating Temperature (Automotive, A2 Grade)	-40°C to 105°C
Vcc Power Supply	1.65 V – 1.95 V





# **DC CHARACTERISTICS**

Applicable over recommended operating range from: Vcc = 1.65 V to 1.95 V (unless otherwise noted).

Symbol	Parameter	Condition	Min	Тур	Max	Units	
I <sub>CC1</sub>	Vcc Active Read Current	V <sub>CC</sub> = 1.95Vat 30 MH	z, SO = Open		2	5	mA
I <sub>CC2</sub>	Vcc Program/Erase Current	V <sub>CC</sub> = 1.95Vat 30 MH	z, SO = Open		6	10	mA
I <sub>SB1</sub>	Vcc Standby Current CMOS	$V_{CC} = 1.95V, CE# = V$	/cc			10	μΑ
I <sub>SB2</sub>	Vcc Standby Current TTL	$V_{CC} = 1.95V, CE# = V$			2	mA	
I <sub>LI</sub>	Input Leakage Current	$V_{IN} = 0V \text{ to } V_{CC}$			1	μΑ	
I <sub>LO</sub>	Output Leakage Current	$V_{IN} = 0V$ to $V_{CC}$ , $T_{AC} =$			1	μΑ	
V <sub>IL</sub>	Input Low Voltage			-0.5		0.3	V
V <sub>IH</sub>	Input High Voltage			0.7V <sub>CC</sub>		V <sub>CC</sub> + 0.3	V
V <sub>OL</sub>	Output Low Voltage		$I_{OL} = 2.1 \text{ mA}$			0.2	V
V <sub>OH</sub>	Output High Voltage	$1.65V < V_{CC} < 1.95V$	I <sub>OH</sub> = -100 μA	V <sub>CC</sub> – 0.2			V





# **AC CHARACTERISTICS**

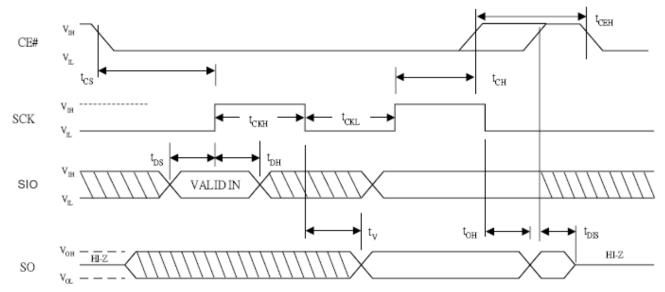
Applicable over recommended operating range from Vcc = 1.65 V to 1.95 V  $C_L$  = 1 TTL Gate and 10 pF (unless otherwise noted).

Symbol	Parameter	Min	Тур	Max	Units
fст	Clock Frequency for fast read mode	0		80	MHz
fc	Clock Frequency for read mode	0		30	MHz
trı	Input Rise Time			8	ns
tFI	Input Fall Time			8	ns
tскн	SCK High Time	4			ns
tckl	SCK Low Time	4			ns
tceh	CE# High Time	25			ns
tcs	CE# Setup Time	10			ns
tсн	CE# Hold Time	5			ns
tos	Data In Setup Time	2			ns
tDH	Data in Hold Time	2			ns
ths	Hold Setup Time	15			ns
thd	Hold Time	15			ns
tv	Output Valid			8	ns
tон	Output Hold Time Normal Mode	0			ns
tLZ	Hold to Output Low Z			20	ns
tHZ	Hold to Output High Z			20	ns
tois	Output Disable Time			20	ns
tec	Sector/Block/Chip Erase Time		1.7	2	ms
tpp	Page Program Time		2	3	ms
tvcs	Vcc Set-up Time	50			μS
t <sub>w</sub>	Write Status Register time			2	ms



# **AC CHARACTERISTICS (CONTINUED)**

# SERIAL INPUT/OUTPUT TIMING (1)

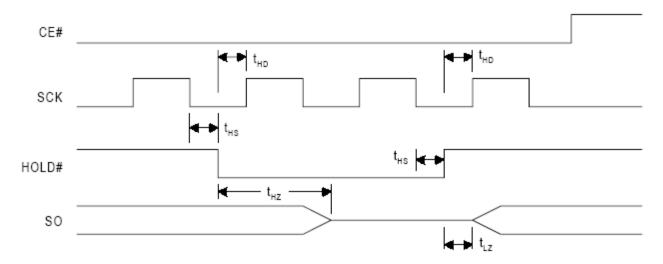


Note: 1. For SPI Mode 0 (0,0)



# **AC CHARACTERISTICS (CONTINUED)**

#### **HOLD TIMING**

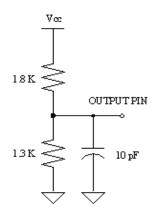


#### **PIN CAPACITANCE** ( $f = 1 \text{ MHz}, T = 25^{\circ}\text{C}$ )

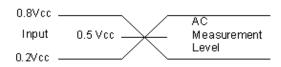
	Тур	Max	Units	Conditions
Cin	4	6	pF	Vin = 0 V
Соит	8	12	pF	Vout = 0 V

Note: These parameters are characterized but not 100% tested.

#### **OUTPUT TEST LOAD**



# INPUT TEST WAVEFORMS AND MEASUREMENT LEVEL



Note: 1. Input Pulse Voltage: 0.2Vcc to 0.8Vcc.

- 2. Input Timing Reference Voltages :
  - 0.3Vcc to 0.7Vcc.
- 3. Output Timing Reference Voltage: Vcc/2.





#### POWER-UP AND POWER-DOWN

At Power-up and Power-down, the device must not be selected (CE# must follow the voltage applied on Vcc) until Vcc reaches the correct value:

- Vcc(min) at Power-up, and then for a further delay of tVCF
- 0. Vss at Power-down

Usually a simple pull-up resistor on CE# can be used to insure safe and proper Power-up and Power-down. To avoid data corruption and inadvertent write operations during power up, a Power On Reset (POR) circuit is included. The logic inside the device is held reset while Vcc is less than the POR threshold value (Vwi) during power up, the device does not respond to any instruction until a time delay of tPUW has elapsed after the moment that Vcc rised above the Vwi threshold. However, the correct operation of the device is not guaranteed if, by this time, Vcc is still below Vcc(min). No Write Status Register, Program or Erase instructions should be sent until the later of:

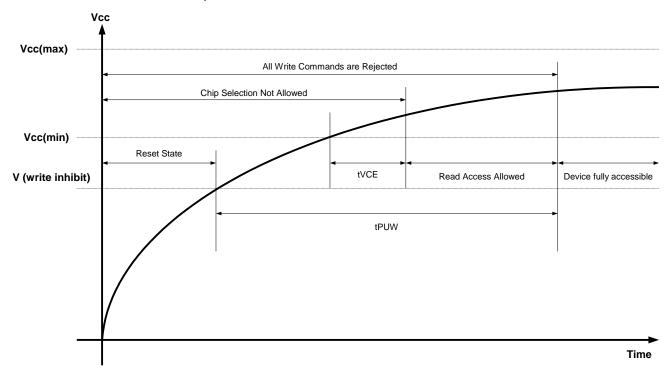
- tPUW after Vcc passed the VWI threshold
- tVCE after Vcc passed the Vcc(min) level

At Power-up, the device is in the following state:

- The device is in the Standby mode
- The Write Enable Latch (WEL) bit is reset

At Power-down, when Vcc drops from the operating voltage, to below the Vwi, all write operations are disabled

and the device does not respond to any write instruction.



Symbol	Parameter	Min.	Max.	Unit
t <sub>VCE</sub> *1	Vcc(min) to CE# Low	10		us
t <sub>PUW</sub> *1	Power-Up time delay to Write instruction	1	10	ms

Note: \*1. These parameters are characterized only.





## PROGRAM/ERASE PERFORMANCE

Parameter	Unit	Тур	Max	Remarks
Sector Erase Time	ms	1.7 2		From writing erase command to erase completion
Block Erase Time	ms	1.7	2	From writing erase command to erase completion
Chip Erase Time	ms	1.7	2	From writing erase command to erase completion
Page Programming Time	ms	2	3	From writing program command to program completion

Note: These parameters are characterized and are not 100% tested.

# **RELIABILITY CHARACTERISTICS**

Parameter	Min	Unit	Test Method
Endurance	200,000	Cycles	JEDEC Standard A117
Data Retention	20	Years	JEDEC Standard A103
ESD – Human Body Model	2,000	Volts	JEDEC Standard A114
ESD – Machine Model	200	Volts	JEDEC Standard A115
Latch-Up	100 + Icc1	mA	JEDEC Standard 78

Note: These parameters are characterized and are not 100% tested.



## **PACKAGE TYPE INFORMATION**

# JN 8-Pin SOIC 150mil Broad Small Outline Integrated Circuit Package (Unit: millimeters)

Top View Side View  $\frac{4.00}{3.80} + \frac{0.25}{0.10}$ End View  $\frac{6.20}{5.80} + \frac{0.25}{0.19}$ 

Note: Package dimensions are shown in mm

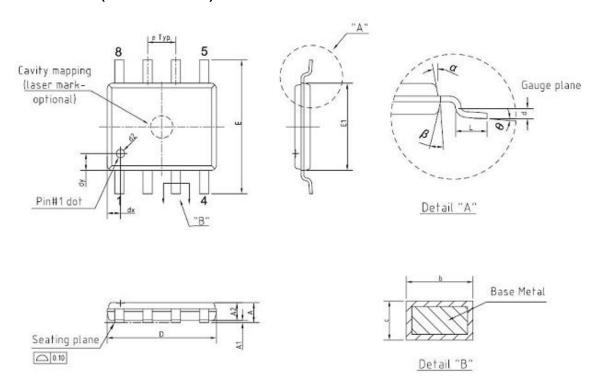
 $\frac{1.27}{0.40}$ 





# PACKAGE TYPE INFORMATION (CONTINUED)

JV 8-Pin VVSOP 150mil (Unit: millimeters)



Note: Package dimensions are shown in mm

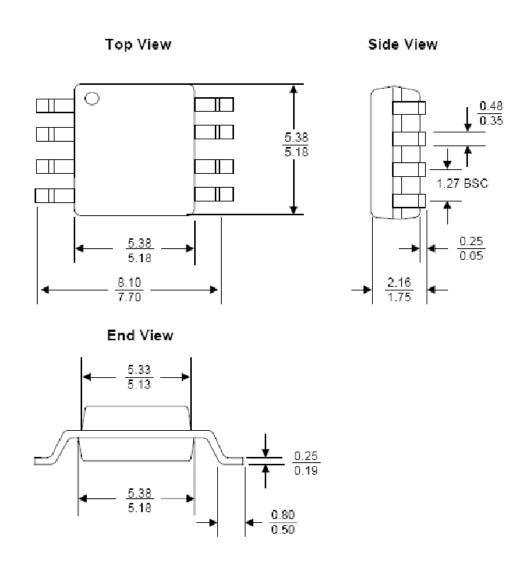


SYMBOL		OIMENSIO (MM)	N	DIMENSION (MIL)			
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	
А			0.88			34.6	
Α1	0.05		0.14	2.0		5.5	
Α2	0.63		0.74	24.8		29.1	
Ь	0.33	0.41	0.51	13.0	16.1	20.1	
C	0.13		0.18	5.1		7.1	
D	4.80	4.90	5.00	189.0	192.9	196.9	
Д		0.25			10.0		
d1		0.50typ			19.7typ		
dx		0.60typ			23.6typ		
dy		0.76typ			29.9†yp		
E	5.80	6.00	6.20	228.3	236.2	244.1	
E1	3.80	3.90	4.00	149.6	153.5	157.5	
е		1.27			50.0		
L	0.41	0.71	1.27	16.1	28.0	50.0	
α		10°			10°		
β		10°			10°		
θ	0°		10°	0°		10°	



# **PACKAGE TYPE INFORMATION (CONTINUED)**

# JB 8-Pin SOIC 208mil Broad Small Outline Integrated Circuit Package (Unit: millimeters)



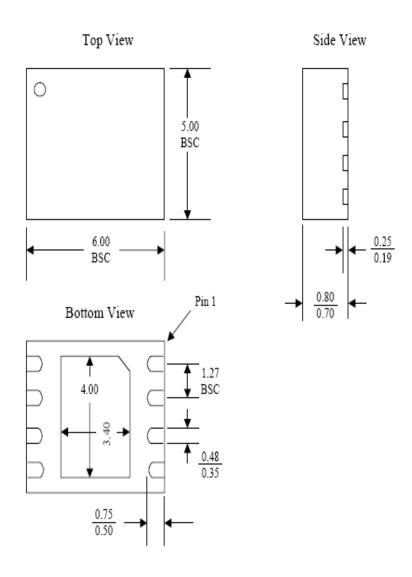
Note: Package dimensions are shown in mm



# PACKAGE TYPE INFORMATION (CONTINUED)

# JK

8-pin WSON Ultra-Thin Small Outline No-Lead Package (Unit: millimeters)



Note: Package dimensions are shown in mm





## ORDERING INFORMATION:

Density	Frequency (MHz)	Order Part Number	Package
		IS25WD020-JBLE	8-pin SOIC 208mil
		IS25WD020-JNLE	8-pin SOIC 150mil
		IS25WD020-JVLE	8-pin VVSOP 150mil
		IS25WD020-JKLE	8-pin WSON (5x6mm)
2M	80	IS25WD020-JBLA*	8-pin SOIC 208mil (Call Factory)
		IS25WD020-JNLA*	8-pin SOIC 150mil (Call Factory)
		IS25WD020-JVLA*	8-pin VVSOP 150mil (Call Factory)
		IS25WD020-JKLA*	8-pin WSON (5x6mm) (Call Factory)
		IS25WD020-JWLE	KGD (Call Factory)
		IS25WD040-JNLE	8-pin SOIC 150mil
		IS25WD040-JBLE	8-pin SOIC 208mil
		IS25WD040-JVLE	8-pin VVSOP 150mil
		IS25WD040-JKLE	8-pin WSON (5x6mm)
4M	80	IS25WD040-JNLA*	8-pin SOIC 150mil (Call Factory)
		IS25WD040-JBLA*	8-pin SOIC 208mil (Call Factory)
		IS25WD040-JVLA*	8-pin VVSOP 150mil (Call Factory)
		IS25WD040-JKLA*	8-pin WSON (5x6mm) (Call Factory)
		IS25WD020-JWLE	KGD (Call Factory)

A\* = A1, A2 Automotive Temperature Ranges

# **Mouser Electronics**

**Authorized Distributor** 

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# ISSI:

IS25WD020-JBLE-TR IS25WD020-JNLE IS25WD020-JBLE IS25WD040-JVLE-TR IS25WD040-JKLE-TR IS25WD040-JKLE-TR IS25WD020-JKLE-TR IS25WD020-JVLE-TR IS25WD020-JVLE-TR IS25WD020-JVLE-TR IS25WD040-JNLE