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Jameco Part Number 2057094

# LM5116

## Wide Range Synchronous Buck Controller

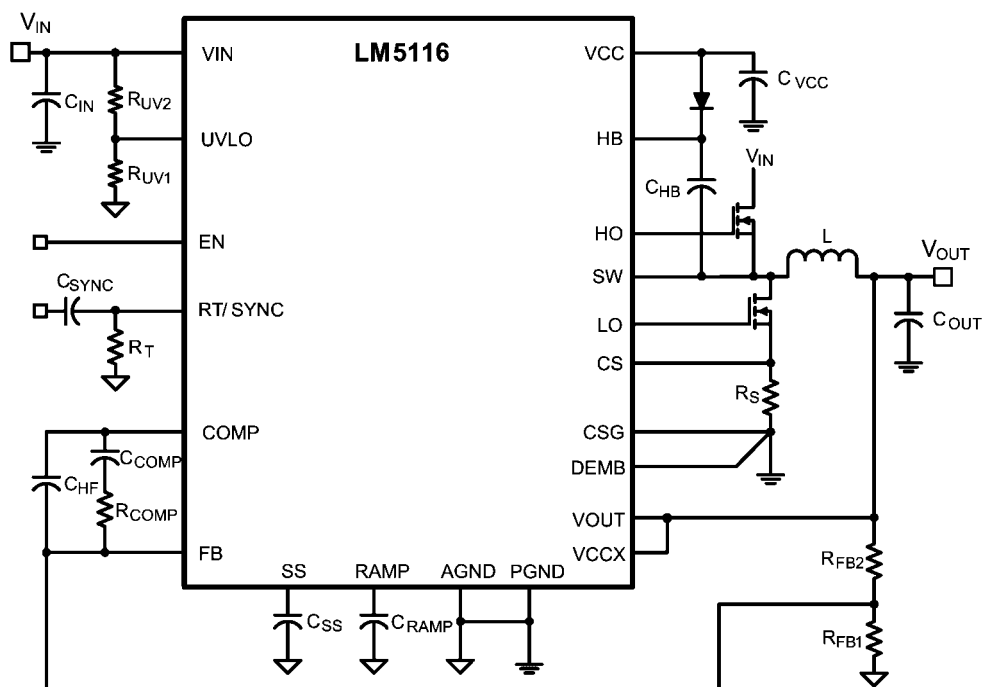
### General Description

The LM5116 is a synchronous buck controller intended for step-down regulator applications from a high voltage or widely varying input supply. The control method is based upon current mode control utilizing an emulated current ramp. Current mode control provides inherent line feed-forward, cycle by cycle current limiting and ease of loop compensation. The use of an emulated control ramp reduces noise sensitivity of the pulse-width modulation circuit, allowing reliable control of very small duty cycles necessary in high input voltage applications. The operating frequency is programmable from 50kHz to 1MHz. The LM5116 drives external high-side and low-side NMOS power switches with adaptive dead-time control. A user-selectable diode emulation mode enables discontinuous mode operation for improved efficiency at light load conditions. A low quiescent current shutdown disables the controller and consumes less than 10 $\mu$ A of total input current. Additional features include a high voltage bias regulator, automatic switch-over to external bias for improved efficiency, thermal shutdown, frequency synchronization, cycle by cycle current limit and adjustable line under-voltage lockout. The device is available in a power enhanced TSSOP-20 package featuring an exposed die attach pad to aid thermal dissipation.

### Features

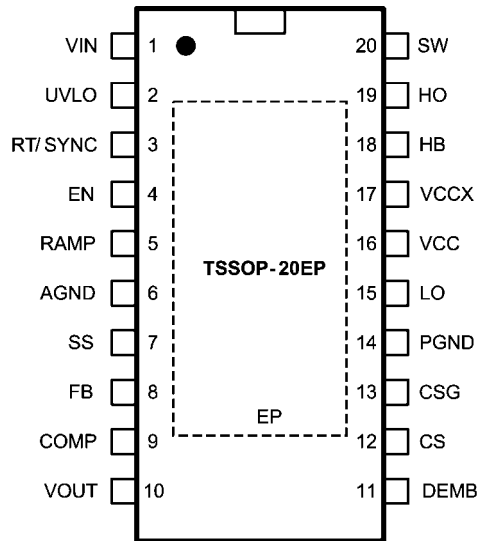
- Emulated peak current mode
- Wide operating range up to 100V
- Low  $I_Q$  shutdown (<10 $\mu$ A)
- Drives standard or logic level MOSFETs
- Robust 3.5A peak gate drive
- Free-run or synchronous operation to 1MHz
- Optional diode emulation mode
- Programmable output from 1.215V to 80V
- Precision 1.5% voltage reference
- Programmable current limit
- Programmable soft-start
- Programmable line under-voltage lockout
- Automatic switch to external bias supply
- TSSOP-20EP exposed pad
- Thermal shutdown

### Typical Application



30007501

## Connection Diagram



30007502

Top View  
See NS Package Numbers MXA20A

## Ordering Information

Ordering Number	Package Type	NSC Package Drawing	Supplied As
LM5116MH	TSSOP-20EP	MXA20A	73 Units Per Anti-Static Tube
LM5116MHX	TSSOP-20EP	MXA20A	2500 units shipped as Tape & Reel

## Pin Descriptions

Pin	Name	Description
1	VIN	Chip supply voltage, input voltage monitor and input to the VCC regulator.
2	UVLO	If the UVLO pin is below 1.215V, the regulator will be in standby mode (VCC regulator running, switching regulator disabled). If the UVLO pin voltage is above 1.215V, the regulator is operational. An external voltage divider can be used to set an under-voltage shutdown threshold. There is a fixed 5 $\mu$ A pull up current on this pin when EN is high. UVLO is pulled to ground in the event a current limit condition exists for 256 clock cycles.
3	RT/ SYNC	The internal oscillator is set with a single resistor between this pin and the AGND pin. The recommended frequency range is 50kHz to 1MHz. The internal oscillator can be synchronized to an external clock by AC coupling a positive edge onto this node.
4	EN	If the EN pin is below 0.5V, the regulator will be in a low power state drawing less than 10 $\mu$ A from VIN. EN must be pulled above 3.3V for normal operation.
5	RAMP	Ramp control signal. An external capacitor connected between this pin and the AGND pin sets the ramp slope used for current mode control.
6	AGND	Analog ground.
7	SS	An external capacitor and an internal 10 $\mu$ A current source set the soft start time constant for the rise of the error amp reference. The SS pin is held low during VCC < 4.5V, UVLO < 1.215V, EN input low or thermal shutdown.
8	FB	Feedback signal from the regulated output. This pin is connected to the inverting input of the internal error amplifier. The regulation threshold is 1.215V.
9	COMP	Output of the internal error amplifier. The loop compensation network should be connected between this pin and the FB pin.
10	VOUT	Output monitor. Connect directly to the output voltage.
11	DEMB	Low-side MOSFET source voltage monitor for diode emulation. For start-up into a pre-biased load, tie this pin to ground at the CSG connection. For fully synchronous operation, use an external series resistor between DEMB and ground to raise the diode emulation threshold above the low-side SW on-voltage.

Pin	Name	Description
12	CS	Current sense amplifier input. Connect to the top of the current sense resistor or the drain of the low-sided MOSFET if $R_{DS(ON)}$ current sensing is used.
13	CSG	Current sense amplifier input. Connect to the bottom of the sense resistor or the source of the low-side MOSFET if $R_{DS(ON)}$ current sensing is used.
14	PGND	Power ground.
15	LO	Connect to the gate of the low-side synchronous MOSFET through a short, low inductance path.
16	VCC	Locally decouple to PGND using a low ESR/ESL capacitor located as close to the controller as possible.
17	VCCX	Optional input for an externally supplied VCC. If $VCCX > 4.5V$ , VCCX is internally connected to VCC and the internal VCC regulator is disabled. If VCCX is unused, it should be connected to ground.
18	HB	High-side driver supply for bootstrap gate drive. Connect to the cathode of the bootstrap diode and the positive terminal of the bootstrap capacitor. The bootstrap capacitor supplies current to charge the high-side MOSFET gate and should be placed as close to the controller as possible.
19	HO	Connect to the gate of the high-side synchronous MOSFET through a short, low inductance path
20	SW	Switch node. Connect to the negative terminal of the bootstrap capacitor and the source terminal of the high-side MOSFET.
EP	EP	Exposed pad. Solder to ground plane.

## Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

VIN to GND	-0.3V to 100V
VCC, VCCX, UVLO to GND (Note 3)	-0.3 to 16V
SW, CS to GND	-3.0 to 100V
HB to SW	-0.3 to 16V
HO to SW	-0.3 to HB+0.3V
VOOUT to GND	-0.3 to 100V
CSG to GND	-1V to 1V
LO to GND	-0.3 to VCC+0.3V
SS to GND	-0.3 to 7V
FB to GND	-0.3 to 7V
DEMB to GND	-0.3 to VCC

RT to GND	-0.3 to 7V
EN to GND	-0.3 to 100V
ESD Rating	
HBM (Note 2)	2 kV
Storage Temperature Range	-55°C to +150°C
Junction Temperature	+150°C

## Operating Ratings (Note 1)

VIN	6V to 100V
VCC, VCCX	4.75V to 15V
HB to SW	4.75V to 15V
DEMB to GND	-0.3V to 2V
Junction Temperature	-40°C to +125°C

Note: RAMP, COMP are output pins. As such they are not specified to have an external voltage applied.

**Electrical Characteristics** Limits in standard type are for  $T_J = 25^\circ\text{C}$  only; limits in boldface type apply over the junction temperature range of  $-40^\circ\text{C}$  to  $+125^\circ\text{C}$  and are provided for reference only. Unless otherwise specified, the following conditions apply: VIN = 48V, VCC = 7.4V, VCCX = 0V, EN = 5V,  $R_T = 16\text{k}\Omega$ , no load on LO and HO.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
<b>VIN Supply</b>						
$I_{\text{BIAS}}$	VIN Operating Current	VCCX = 0V, VIN = 48V		5	<b>7</b>	mA
		VCCX = 0V, VIN = 100V		5.9	<b>8</b>	mA
$I_{\text{BIASX}}$	VIN Operating Current	VCCX = 5V, VIN = 48V		1.2	<b>1.7</b>	mA
		VCCX = 5V, VIN = 100V		1.6	<b>2.3</b>	mA
$I_{\text{STDBY}}$	VIN Shutdown Current	EN = 0V, VIN = 48V		1	<b>10</b>	$\mu\text{A}$
		EN = 0V, VIN = 100V		1		$\mu\text{A}$
<b>VCC Regulator</b>						
$V_{\text{CC(REG)}}$	VCC Regulation		<b>7.1</b>	7.4	<b>7.7</b>	V
	VCC LDO Mode Turn-off			10.6		V
	VCC Regulation	VIN = 6V	<b>5.0</b>	5.9	<b>6.0</b>	V
	VCC Sourcing Current Limit	VCC = 0V	<b>15</b>	26		mA
	VCCX Switch Threshold	VCCX Rising	<b>4.3</b>	4.5	<b>4.7</b>	V
	VCCX Switch Hysteresis			0.25		V
	VCCX Switch $R_{\text{DS(ON)}}$	ICCX = 10mA		3.8	<b>6.2</b>	$\Omega$
	VCCX Leakage	VCCX = 0V		-200		nA
	VCCX Pull-down Resistance	VCCX = 3V		100		$\text{k}\Omega$
	VCC Under-voltage Threshold	VCC Rising	<b>4.3</b>	4.5	<b>4.7</b>	V
	VCC Under-voltage Hysteresis			0.2		V
	HB DC Bias Current	HB-SW = 15V		125	<b>200</b>	$\mu\text{A}$
<b>EN Input</b>						
VIL max	EN Input Low Threshold				<b>0.5</b>	V
VIH min	EN Input High Threshold		<b>3.3</b>			V
	EN Input Bias Current	VEN = 3V	<b>-7.5</b>	-3	<b>1</b>	$\mu\text{A}$
	EN Input Bias Current	VEN = 0.5V	<b>-1</b>	0	<b>1</b>	$\mu\text{A}$
	EN Input Bias Current	VEN = 100V		20	<b>90</b>	$\mu\text{A}$
<b>UVLO Thresholds</b>						
	UVLO Standby Threshold	UVLO Rising	<b>1.170</b>	1.215	<b>1.262</b>	V
	UVLO Threshold Hysteresis			0.1		V
	UVLO Pull-up Current Source	UVLO = 0V		5.4		$\mu\text{A}$
	UVLO Pull-down $R_{\text{DS(ON)}}$			80	<b>210</b>	$\Omega$

Symbol	Parameter	Conditions	Min	Typ	Max	Units
<b>Soft Start</b>						
	SS Current Source	SS = 0V	<b>8</b>	11	<b>14</b>	$\mu\text{A}$
	SS Diode Emulation Ramp Disable Threshold	SS Rising		3		V
	SS to FB Offset	FB = 1.25V		160		mV
	SS Output Low Voltage	Sinking 100 $\mu\text{A}$ , UVLO = 0V		45		mV
<b>Error Amplifier</b>						
$V_{\text{REF}}$	FB Reference Voltage	Measured at FB pin, FB = COMP	<b>1.195</b>	1.215	<b>1.231</b>	V
	FB Input Bias Current	FB = 2V		15	<b>500</b>	nA
	COMP Sink/Source Current		<b>3</b>			mA
$A_{\text{OL}}$	DC Gain			80		dB
$f_{\text{BW}}$	Unity Gain Bandwidth			3		MHz
<b>PWM Comparators</b>						
$t_{\text{HO(OFF)}}$	Forced HO Off-time		<b>320</b>	450	<b>580</b>	ns
$t_{\text{ON(min)}}$	Minimum HO On-time	VIN = 80V, $C_{\text{RAMP}} = 50\text{pF}$		100		ns
<b>Oscillator</b>						
$f_{\text{SW1}}$	Frequency 1	RT = 16k $\Omega$	<b>180</b>	200	<b>220</b>	kHz
$f_{\text{SW2}}$	Frequency 2	RT = 5k $\Omega$	<b>480</b>	535	<b>590</b>	kHz
	RT output voltage		<b>1.191</b>	1.215	<b>1.239</b>	V
	RT sync positive threshold		<b>3.0</b>	3.5	<b>4.0</b>	V
<b>Current Limit</b>						
$V_{\text{CS(TH)}}$	Cycle-by-cycle Sense Voltage Threshold (CSG-CS)	VCCX = 0V, RAMP = 0V	<b>94</b>	110	<b>126</b>	mV
$V_{\text{CS(THX)}}$	Cycle-by-cycle Sense Voltage Threshold (CSG-CS)	VCCX = 5V, RAMP = 0V	<b>105</b>	122	<b>139</b>	mV
	CS Bias Current	CS = 100V	<b>-1</b>		1	$\mu\text{A}$
	CS Bias Current	CS = 0V		90	<b>125</b>	$\mu\text{A}$
	CSG Bias Current	CSG = 0V		90	<b>125</b>	$\mu\text{A}$
	Current Limit Fault Timer	$R_{\text{T}} = 16\text{k}\Omega$ , (200kHz), (256 clock cycles)		1.28		ms
<b>RAMP Generator</b>						
$I_{\text{R1}}$	RAMP Current 1	VIN = 60V, VOUT=10V	<b>235</b>	285	<b>335</b>	$\mu\text{A}$
$I_{\text{R2}}$	RAMP Current 2	VIN = 10V, VOUT = 10V	<b>21</b>	28	<b>35</b>	$\mu\text{A}$
	VOUT Bias Current	VOUT = 36V		200		$\mu\text{A}$
	RAMP Output Low Voltage	VIN = 60V, VOUT = 10V		265		mV
<b>Diode Emulation</b>						
	SW Zero Cross Threshold			-6		mV
	DEMB Output Current	DEMB = 0V, SS = 1.25V	<b>1.6</b>	2.7	<b>3.8</b>	$\mu\text{A}$
	DEMB Output Current	DEMB = 0V, SS = 2.8V	<b>28</b>	38	<b>48</b>	$\mu\text{A}$
	DEMB Output Current	DEMB = 0V, SS = Regulated by FB	<b>45</b>	65	<b>85</b>	$\mu\text{A}$
<b>LO Gate Driver</b>						
$V_{\text{OLL}}$	LO Low-state Output Voltage	$I_{\text{LO}} = 100\text{mA}$		0.08	<b>0.17</b>	V
$V_{\text{OHL}}$	LO High-state Output Voltage	$I_{\text{LO}} = -100\text{mA}$ , $V_{\text{OHL}} = V_{\text{CC}} - V_{\text{LO}}$		0.25		V
	LO Rise Time	C-load = 1000pF		18		ns
	LO Fall Time	C-load = 1000pF		12		ns
$I_{\text{OHL}}$	Peak LO Source Current	$V_{\text{LO}} = 0\text{V}$		1.8		A
$I_{\text{OLL}}$	Peak LO Sink Current	$V_{\text{LO}} = V_{\text{CC}}$		3.5		A

Symbol	Parameter	Conditions	Min	Typ	Max	Units
<b>HO Gate Driver</b>						
$V_{OLH}$	HO Low-state Output Voltage	$I_{HO} = 100\text{mA}$		0.17	<b>0.27</b>	V
$V_{OHH}$	HO High-state Output Voltage	$I_{HO} = -100\text{mA}$ , $V_{OHH} = V_{HB} - V_{HO}$		0.45		V
	HO Rise Time	C-load = 1000pF		19		ns
	HO High-side Fall Time	C-load = 1000pF		13		ns
$I_{OHH}$	Peak HO Source Current	$V_{HO} = 0\text{V}$		1		A
$I_{OLH}$	Peak HO Sink Current	$V_{HO} = V_{CC}$		2.2		A
	HB to SW under-voltage			3		V
<b>Switching Characteristics</b>						
	LO Fall to HO Rise Delay	C-load = 0		75		ns
	HO Fall to LO Rise Delay	C-load = 0		70		ns
<b>Thermal</b>						
$T_{SD}$	Thermal Shutdown	Rising		170		°C
	Thermal Shutdown Hysteresis			15		°C
$\theta_{JA}$	Junction to Ambient			40		°C/W
$\theta_{JC}$	Junction to Case			4		°C/W

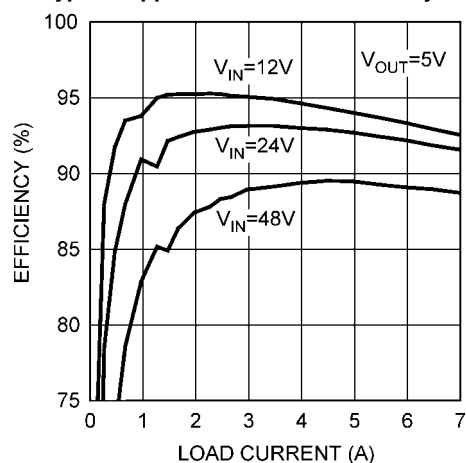
**Note 1:** Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is guaranteed. Operating Ratings do not imply guaranteed performance limits. For guaranteed performance limits and associated test conditions, see the Electrical Characteristics tables.

**Note 2:** The human body model is a 100pF capacitor discharged through a 1.5kΩ resistor into each pin. LO, HO and HB are rated at 1kV. 2kV rating for all pins except VIN which is rated for 1.5kV.

**Note 3:** These pins must not exceed VIN.

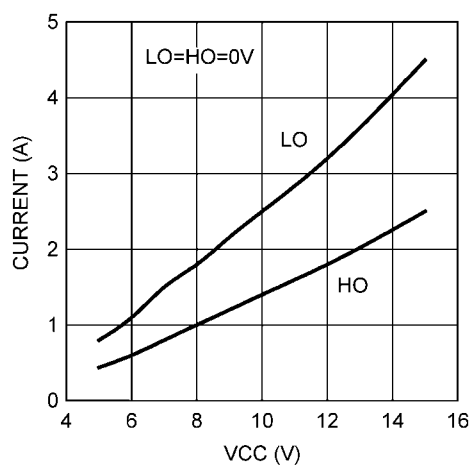
# Typical Performance Characteristics

## Typical Application Circuit Efficiency



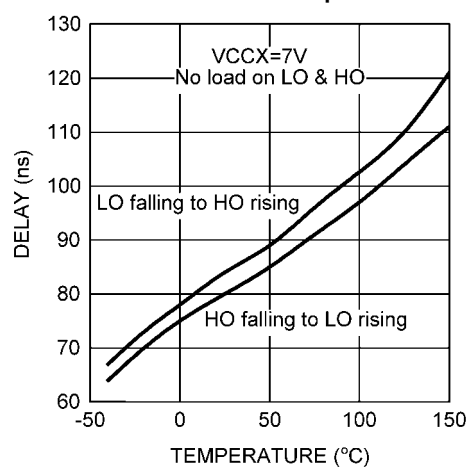
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## Driver Source Current vs VCC



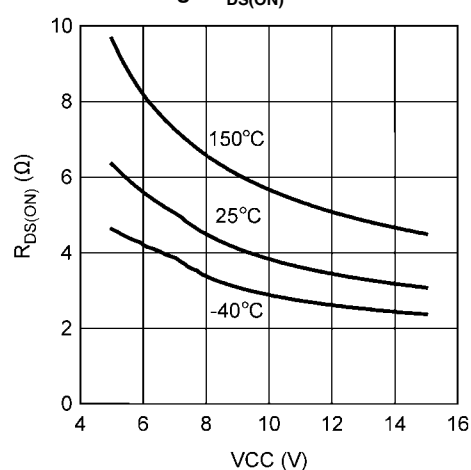
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## Driver Dead-time vs Temperature



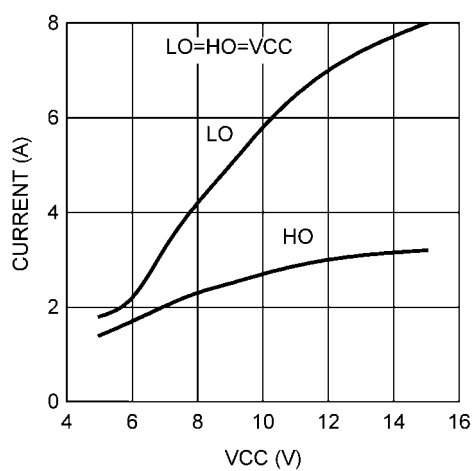
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## HO High $R_{DS(ON)}$ vs VCC



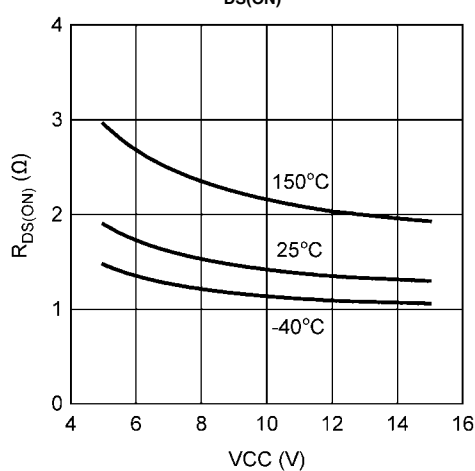
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## Driver Sink Current vs VCC



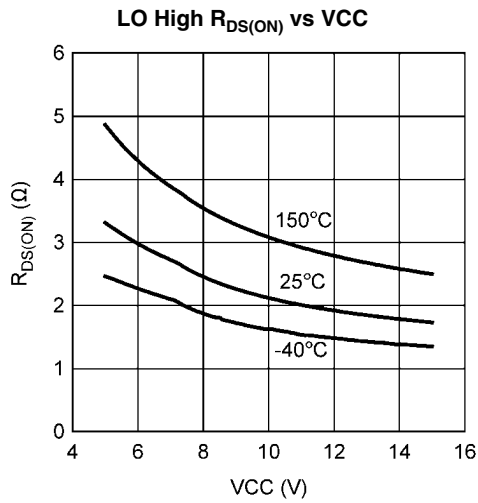
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## HO Low $R_{DS(ON)}$ vs VCC

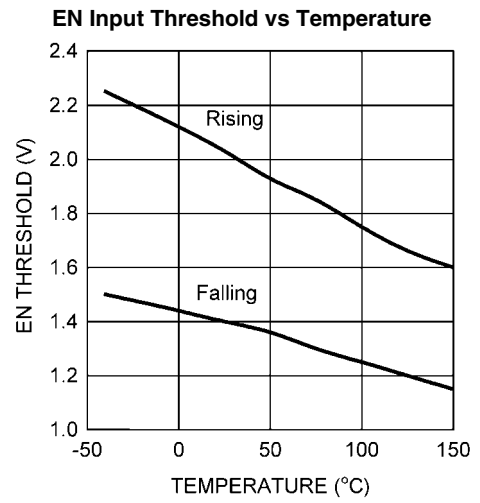


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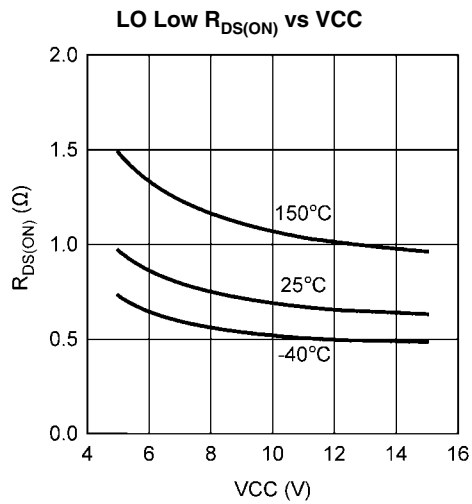




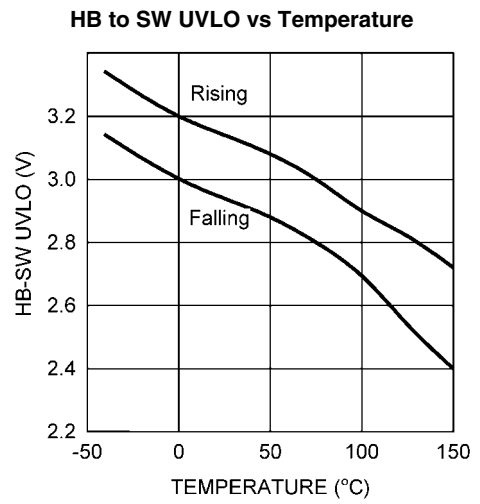
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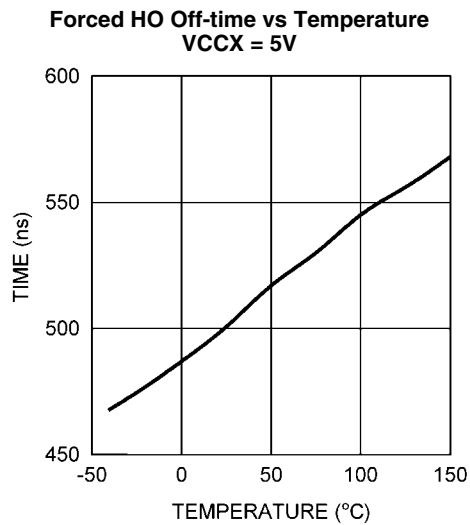
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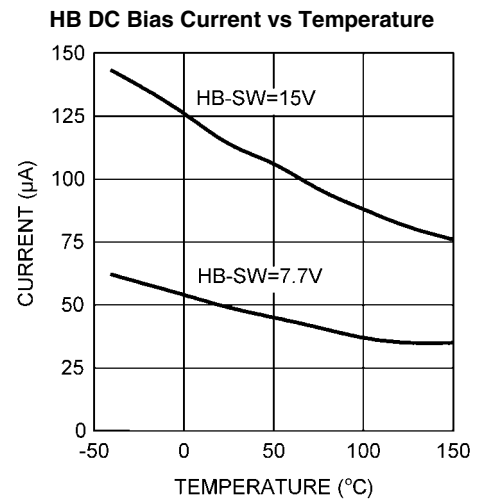
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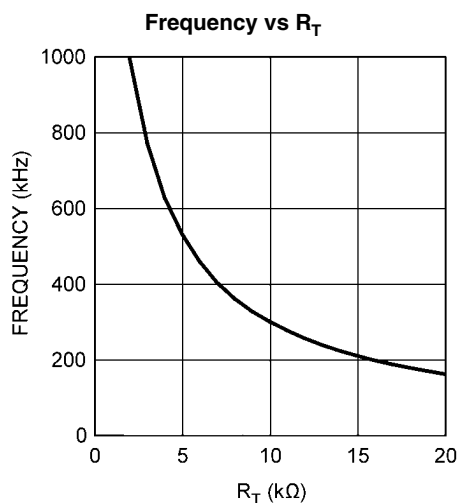
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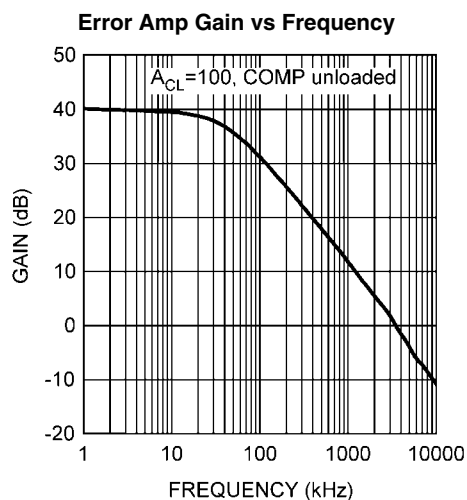
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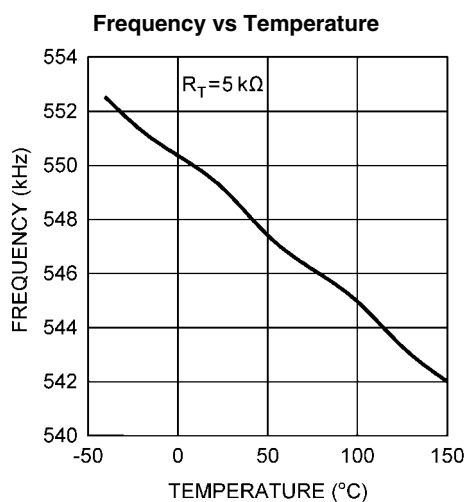
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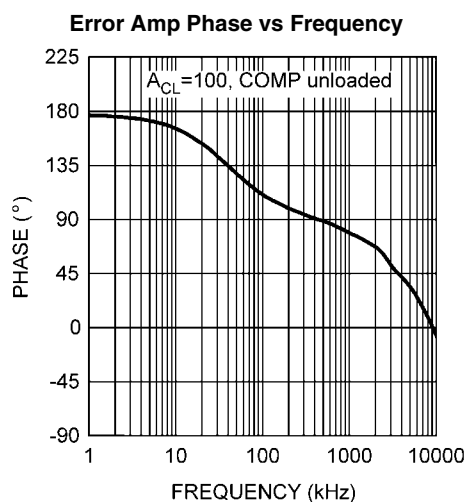
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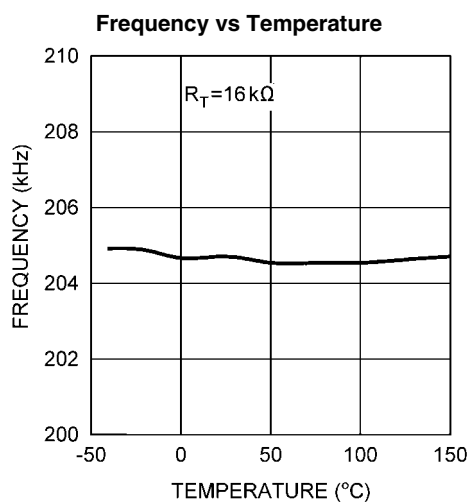
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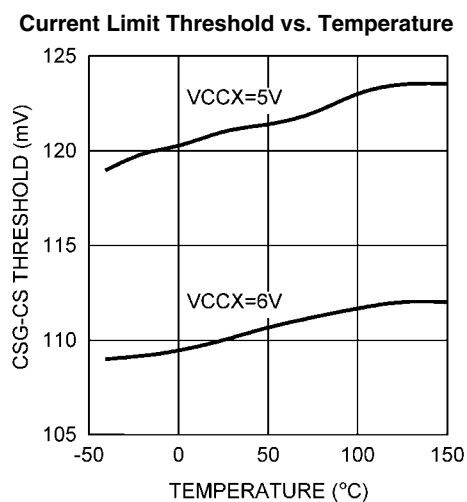
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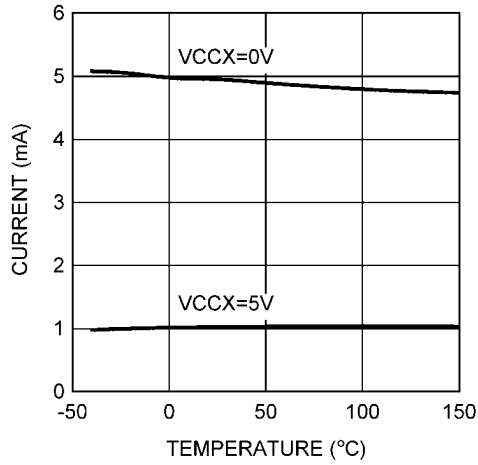


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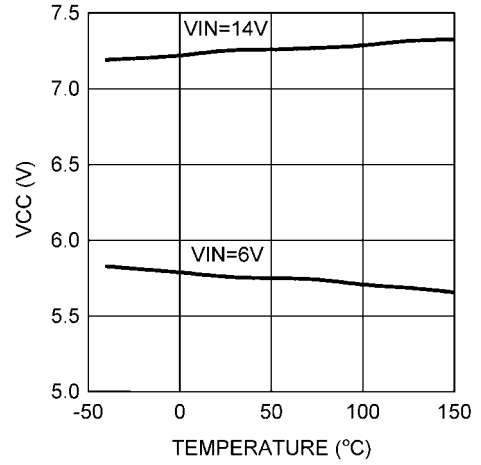
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VIN Operating Current vs Temperature



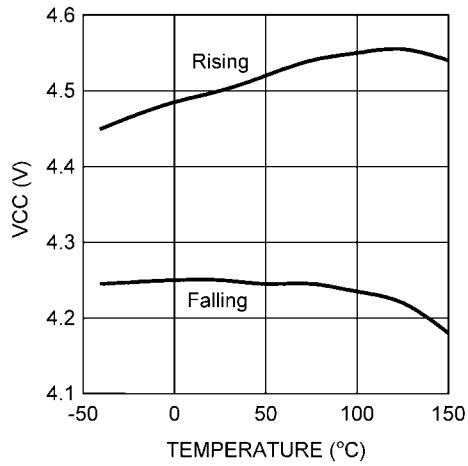
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VCC vs Temperature



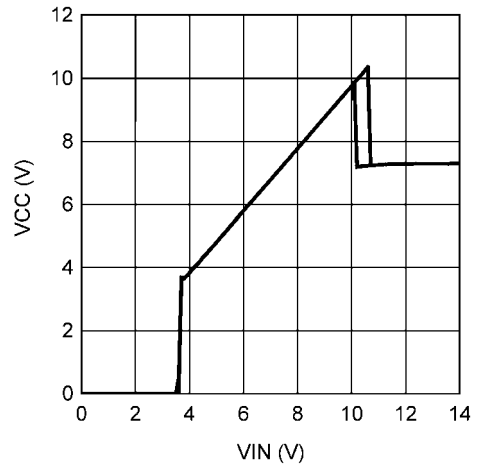
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VCC UVLO vs Temperature



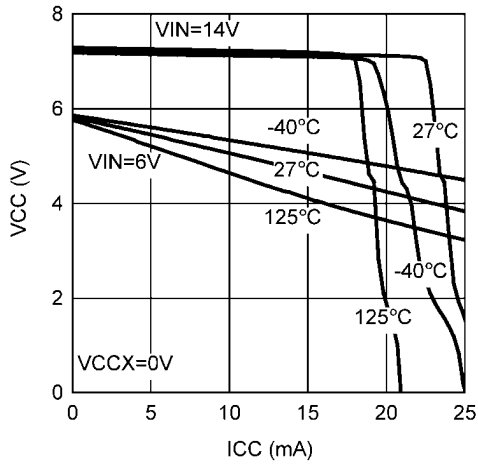
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VCC vs VIN

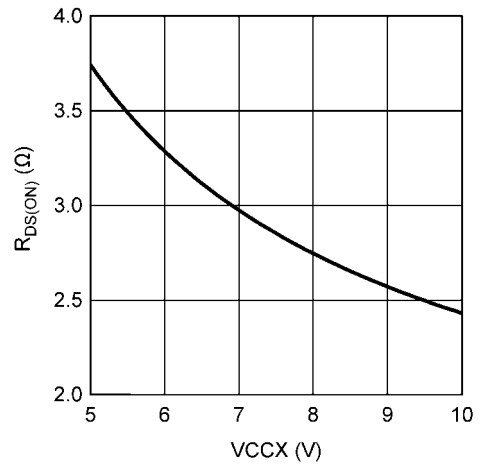


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VCC vs ICC



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VCCX Switch  $R_{DS(ON)}$  vs VCCX

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# Block Diagram and Typical Application Circuit

LM5116

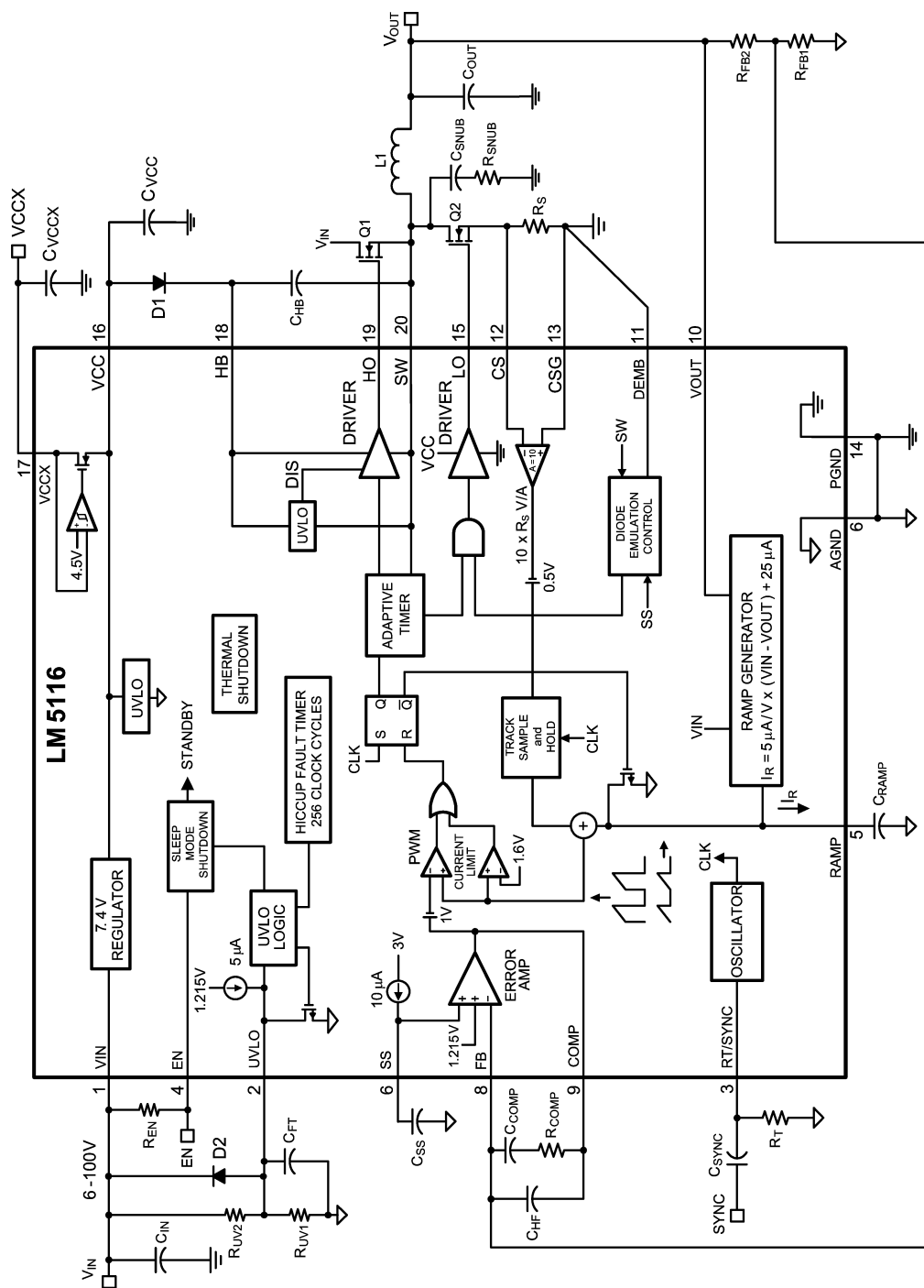


FIGURE 1.

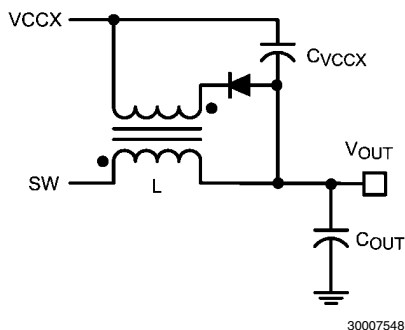
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## Detailed Operating Description

The LM5116 high voltage switching regulator features all of the functions necessary to implement an efficient high voltage buck regulator using a minimum of external components. This easy to use regulator integrates high-side and low-side MOSFET drivers capable of supplying peak currents of 2 Amps. The regulator control method is based on current mode control utilizing an emulated current ramp. Emulated peak current mode control provides inherent line feed-forward, cycle by cycle current limiting and ease of loop compensation. The use of an emulated control ramp reduces noise sensitivity of the pulse-width modulation circuit, allowing reliable processing of the very small duty cycles necessary in high input voltage applications. The operating frequency is user programmable from 50kHz to 1MHz. An oscillator/synchronization pin allows the operating frequency to be set by a single resistor or synchronized to an external clock. Fault protection features include current limiting, thermal shutdown and remote shutdown capability. An under-voltage lockout input allows regulator shutdown when the input voltage is below a user selected threshold, and an enable function will put the regulator into an extremely low current shutdown via the enable input. The TSSOP-20EP package features an exposed pad to aid in thermal dissipation.

## High Voltage Start-Up Regulator

The LM5116 contains a dual mode internal high voltage start-up regulator that provides the VCC bias supply for the PWM controller and a boot-strap gate drive for the high-side buck MOSFET. The input pin (VIN) can be connected directly to an input voltage source as high as 100 volts. For input voltages below 10.6V, a low dropout switch connects VCC directly to VIN. In this supply range, VCC is approximately equal to VIN. For VIN voltages greater than 10.6V, the low dropout switch is disabled and the VCC regulator is enabled to maintain VCC at approximately 7.4V. The wide operating range of 6V to 100V is achieved through the use of this dual mode regulator. The output of the VCC regulator is current limited to 26mA (typical). Upon power-up, the regulator sources current into the capacitor connected to the VCC pin. When the voltage at the VCC pin exceeds 4.5V and the UVLO pin is greater than 1.215V, the output switch is enabled and a soft-start sequence begins. The output switch remains enabled until VCC falls below 4.5V, EN is pulled low, the UVLO pin falls below 1.215V or the die temperature exceeds the thermal limit threshold.



**FIGURE 2. VCCX Bias Supply with Additional Inductor Winding**

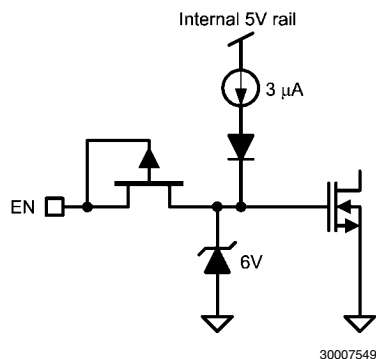
An output voltage derived bias supply can be applied to the VCCX pin to reduce the IC power dissipation. If the bias sup-

ply voltage is greater than 4.5V, the internal regulator will essentially shut off, reducing the IC power dissipation. The VCC regulator series pass transistor includes a diode between VCC and VIN that should not be forward biased in normal operation. For an output voltage between 5V and 15V, VOUT can be connected directly to VCCX. For  $V_{OUT} < 5V$ , a bias winding on the output inductor can be added to VOUT. If the bias winding can supply VCCX greater than VIN, an external blocking diode is required from the input power supply to the VIN pin to prevent VCC from discharging into the input supply.

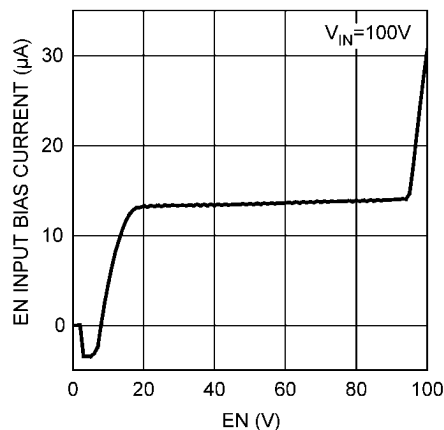
In high voltage applications extra care should be taken to ensure the VIN pin does not exceed the absolute maximum voltage rating of 100V. During line or load transients, voltage ringing on the VIN line that exceeds the Absolute Maximum Ratings can damage the IC. Both careful PC board layout and the use of quality bypass capacitors located close to the VIN and GND pins are essential.

## Enable

The LM5116 contains an enable function allowing a very low input current shutdown. If the enable pin is pulled below 0.5V, the regulator enters shutdown, drawing less than 10μA from the VIN pin. Raising the EN input above 3.3V returns the regulator to normal operation. The EN pin can be tied directly to VIN if this function is not needed. It must not be left floating. A 1MΩ pull-up resistor to VIN can be used to interface with an open collector control signal.



**FIGURE 3. Enable Circuit**



**FIGURE 4. EN Bias Current vs Voltage**

## UVLO

An under-voltage lockout pin is provided to disable the regulator without entering shutdown. If the UVLO pin is pulled below 1.215V, the regulator enters a standby mode of operation with the soft-start capacitor discharged and outputs disabled, but with the VCC regulator running. If the UVLO input is pulled above 1.215V, the controller will resume normal operation. A voltage divider from input to ground can be used to set a VIN threshold to disable the supply in brown-out conditions or for low input faults. The UVLO pin has a 5μA internal pull up current that allows this pin to left open if the input under-voltage lockout function is not needed.

The UVLO pin can also be used to implement a “hiccup” current limit. If a current limit fault exists for more than 256 consecutive clock cycles, the UVLO pin will be internally pulled down to 200mV and then released. A capacitor to ground connected to the UVLO pin will set the timing for hiccup mode current limit. When this feature is used in conjunction with the voltage divider, a diode across the top resistor may be used to discharge the capacitor in the event of an input under-voltage condition.

## Oscillator and Sync Capability

The LM5116 oscillator frequency is set by a single external resistor connected between the RT/SYNC pin and the AGND pin. The resistor should be located very close to the device and connected directly to the pins of the IC (RT/SYNC and AGND). To set a desired oscillator frequency ( $f_{SW}$ ), the necessary value for the resistor can be calculated from the following equation:

$$R_T = \frac{T - 450 \text{ ns}}{284 \text{ pF}}$$

Where  $T = 1 / f_{SW}$  and  $R_T$  is in ohms. 450ns represents the fixed minimum off time.

The RT/SYNC pin can be used to synchronize the internal oscillator to an external clock. The external clock must be a higher frequency than the free-running frequency set by the RT resistor. The internal oscillator can be synchronized to an external clock by AC coupling a positive edge into the RT/SYNC pin. The voltage at the RT/SYNC pin is nominally

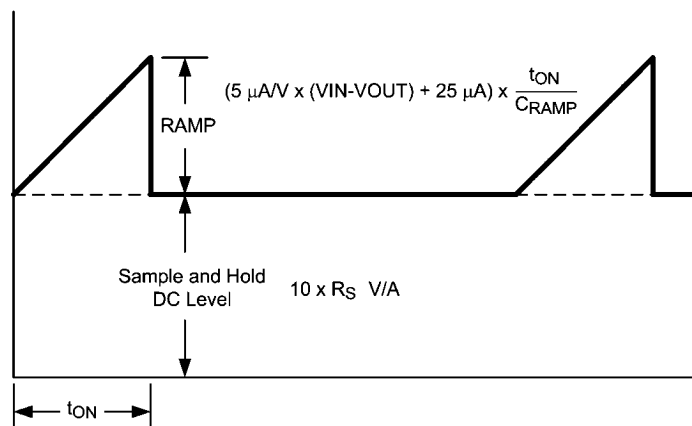
1.215V and must exceed 4V to trip the internal synchronization pulse detection. A 5V amplitude signal and 100pF coupling capacitor are recommended. The free-running frequency should be set nominally 15% below the external clock. Synchronizing above twice the free-running frequency may result in abnormal behavior of the pulse width modulator.

## Error Amplifier and PWM Comparator

The internal high-gain error amplifier generates an error signal proportional to the difference between the regulated output voltage and an internal precision reference (1.215V). The output of the error amplifier is connected to the COMP pin allowing the user to provide loop compensation components, generally a type II network. This network creates a pole at very low frequency, a mid-band zero, and a noise reducing high frequency pole. The PWM comparator compares the emulated current sense signal from the RAMP generator to the error amplifier output voltage at the COMP pin.

## Ramp Generator

The ramp signal used in the pulse width modulator for current mode control is typically derived directly from the buck switch current. This switch current corresponds to the positive slope portion of the inductor current. Using this signal for the PWM ramp simplifies the control loop transfer function to a single pole response and provides inherent input voltage feed-forward compensation. The disadvantage of using the buck switch current signal for PWM control is the large leading edge spike due to circuit parasitics that must be filtered or blanked. Also, the current measurement may introduce significant propagation delays. The filtering, blanking time and propagation delay limit the minimal achievable pulse width. In applications where the input voltage may be relatively large in comparison to the output voltage, controlling small pulse widths and duty cycles is necessary for regulation. The LM5116 utilizes a unique ramp generator which does not actually measure the buck switch current but rather reconstructs the signal. Representing or emulating the inductor current provides a ramp signal to the PWM comparator that is free of leading edge spikes and measurement or filtering delays. The current reconstruction is comprised of two elements, a sample-and-hold DC level and an emulated current ramp.



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FIGURE 5. Composition of Current Sense Signal

The sample-and-hold DC level is derived from a measurement of the recirculating current through either the low-side MOSFET or current sense resistor. The voltage level across the MOSFET or sense resistor is sampled and held just prior to the onset of the next conduction interval of the buck switch. The current sensing and sample-and-hold provide the DC level of the reconstructed current signal. The positive slope inductor current ramp is emulated by an external capacitor connected from the RAMP pin to the AGND and an internal voltage controlled current source. The ramp current source that emulates the inductor current is a function of the VIN and VOUT voltages per the following equation:

$$I_R = 5\mu A/V \times (V_{IN} - V_{OUT}) + 25\mu A$$

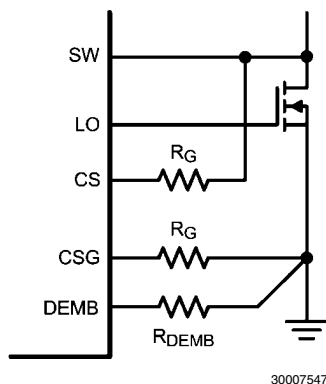
Proper selection of the RAMP capacitor ( $C_{RAMP}$ ) depends upon the value of the output inductor (L) and the current sense resistor ( $R_S$ ). For proper current emulation, the DC sample and hold value and the ramp amplitude must have the same dependence on the load current. That is:

$$R_S \times A = \frac{g_m \times L}{C_{RAMP}}, \text{ so}$$

$$C_{RAMP} = \frac{g_m \times L}{A \times R_S}$$

Where  $g_m$  is the ramp generator transconductance ( $5\mu A/V$ ) and A is the current sense amplifier gain ( $10V/V$ ). The ramp capacitor should be located very close to the device and connected directly to the pins of the IC (RAMP and AGND).

The difference between the average inductor current and the DC value of the sampled inductor current can cause instability for certain operating conditions. This instability is known as sub-harmonic oscillation, which occurs when the inductor ripple current does not return to its initial value by the start of next switching cycle. Sub-harmonic oscillation is normally characterized by observing alternating wide and narrow pulses at the switch node. Adding a fixed slope voltage ramp (slope compensation) to the current sense signal prevents this oscillation. The  $25\mu A$  of offset current provided from the emulated current source adds the optimal slope compensation to the ramp signal for a 5V output. For higher output voltages, additional slope compensation may be required. In these applications, the ramp capacitor can be decreased from its nominal value to increase the ramp slope compensation.



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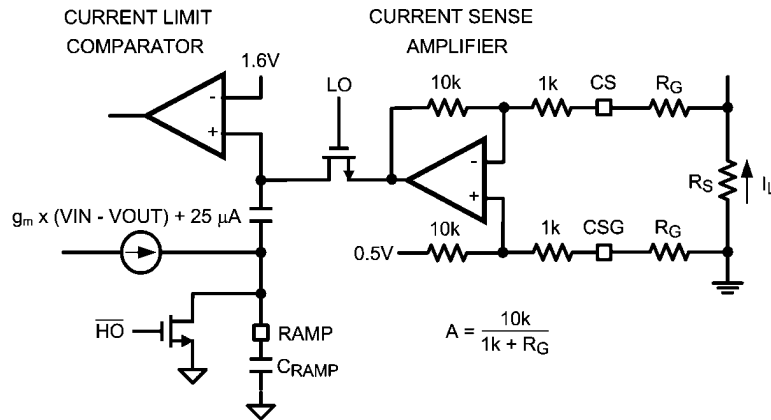
FIGURE 6.  $R_{DS(ON)}$  Current Sensing without Diode Emulation

The DC current sample is obtained using the CS and CSG pins connected to either a source sense resistor ( $R_S$ ) or the  $R_{DS(ON)}$  of the low-side MOSFET. For  $R_{DS(ON)}$  sensing,  $R_S = R_{DS(ON)}$  of the low-side MOSFET. In this case it is sometimes helpful to adjust the current sense amplifier gain (A) to a lower value in order to obtain the desired current limit. Adding external resistors  $R_G$  in series with CS and CSG, the current sense amplifier gain A becomes:

$$A \approx \frac{10k}{1k + R_G}$$

## Current Limit

The LM5116 contains a current limit monitoring scheme to protect the circuit from possible over-current conditions. When set correctly, the emulated current sense signal is proportional to the buck switch current with a scale factor determined by the current limit sense resistor. The emulated ramp signal is applied to the current limit comparator. If the emulated ramp signal exceeds 1.6V, the current cycle is terminated (cycle-by-cycle current limiting). Since the ramp amplitude is proportional to  $V_{IN} - V_{OUT}$ , if  $V_{OUT}$  is shorted, there is an immediate reduction in duty cycle. To further protect the external switches during prolonged current limit conditions, an internal counter counts clock pulses when in current limit. When the counter detects 256 consecutive clock cycles, the regulator enters a low power dissipation hiccup mode of current limit. The regulator is shut down by momentarily pulling UVLO low, and the soft-start capacitor discharged. The regulator is restarted with a full soft-start cycle once UVLO charges back to 1.215V. This process is repeated until the fault is removed. The hiccup off-time can be controlled by a capacitor to ground on the UVLO pin. In applications with low output inductance and high input voltage, the switch current may overshoot due to the propagation delay of the current limit comparator. If an overshoot should occur, the sample-and-hold circuit will detect the excess recirculating current. If the sample-and-hold DC level exceeds the internal current limit threshold, the buck switch will be disabled and skip pulses until the current has decayed below the current limit threshold. This approach prevents current runaway conditions due to propagation delays or inductor saturation since the inductor current is forced to decay following any current overshoot.



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FIGURE 7. Current Limit and Ramp Circuit

Using a current sense resistor in the source of the low-side MOSFET provides superior current limit accuracy compared to  $R_{DS(ON)}$  sensing.  $R_{DS(ON)}$  sensing is far less accurate due to the large variation of MOSFET  $R_{DS(ON)}$  with temperature and part-to-part variation. The CS and CSG pins should be Kelvin connected to the current sense resistor or MOSFET drain and source.

The peak current which triggers the current limit comparator is:

$$I_{PEAK} = \frac{1.1V - \frac{25 \mu A \times t_{ON}}{C_{RAMP}}}{A \times R_S} \approx \frac{1.1V}{A \times R_S}$$

Where  $t_{ON}$  is the on-time of the high-side MOSFET. The 1.1V threshold is the difference between the 1.6V reference at the current limit comparator and the 0.5V offset at the current sense amplifier. This offset at the current sense amplifier allows the inductor ripple current to go negative by  $0.5V / (A \times R_S)$  when running full synchronous operation.

Current limit hysteresis prevents chatter around the threshold when VCCX is powered from VOUT. When  $4.5V < VCC < 5.8V$ , the 1.6V reference is increased to 1.72V. The peak current which triggers the current limit comparator becomes:

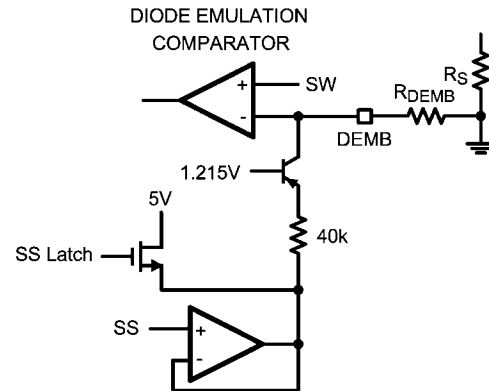
$$I_{PEAK} = \frac{1.22V - \frac{25 \mu A \times t_{ON}}{C_{RAMP}}}{A \times R_S} \approx \frac{1.22V}{A \times R_S}$$

This has the effect of a 10% fold-back of the peak current during a short circuit when VCCX is powered from a 5V output.

## Soft-Start and Diode Emulation

The soft-start feature allows the regulator to gradually reach the initial steady state operating point, thus reducing start-up stresses and surges. The LM5116 will regulate the FB pin to the SS pin voltage or the internal 1.215V reference, whichever is lower. At the beginning of the soft-start sequence when SS = 0V, the internal 10μA soft-start current source gradually increases the voltage of an external soft-start capacitor ( $C_{SS}$ )

connected to the SS pin resulting in a gradual rise of FB and the output voltage.



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FIGURE 8. Diode Emulation Control

During this initial charging of  $C_{SS}$  to the internal reference voltage, the LM5116 will force diode emulation. That is, the low-side MOSFET will turn off for the remainder of a cycle if the sensed inductor current becomes negative. The inductor current is sensed by monitoring the voltage between SW and DEMB. As the SS capacitor continues to charge beyond 1.215V to 3V, the DEMB bias current will increase from 0μA up to 40μA. With the use of an external DEMB resistor ( $R_{DEMB}$ ), the current sense threshold for diode emulation will increase resulting in the gradual transition to synchronous operation. Forcing diode emulation during soft-start allows the LM5116 to start up into a pre-biased output without unnecessarily discharging the output capacitor. Full synchronous operation is obtained if the DEMB pin is always biased to a higher potential than the SW pin when LO is high.  $R_{DEMB} = 10k\Omega$  will bias the DEMB pin to 0.45V minimum, which is adequate for most applications. The DEMB bias potential should always be kept below 2V. When  $R_{DEMB} = 0\Omega$ , the LM5116 will always run in diode emulation.

Once SS charges to 3V the SS latch is set, increasing the DEMB bias current to 65μA. An amplifier is enabled that regulates SS to 160mV above the FB voltage. This feature can prevent overshoot of the output voltage in the event the output



voltage momentarily dips out of regulation. When a fault is detected (VCC under-voltage, UVLO pin < 1.215, or EN = 0V) the soft-start capacitor is discharged. Once the fault condition is no longer present, a new soft-start sequence begins.

## HO Output

The LM5116 contains a high current, high-side driver and associated high voltage level shift. This gate driver circuit works in conjunction with an external diode and bootstrap capacitor. A 1µF ceramic capacitor, connected with short traces between the HB pin and SW pin, is recommended. During the off-time of the high-side MOSFET, the SW pin voltage is approximately -0.5V and the bootstrap capacitor charges from VCC through the external bootstrap diode. When operating with a high PWM duty cycle, the buck switch will be forced off each cycle for 450ns to ensure that the bootstrap capacitor is recharged.

The LO and HO outputs are controlled with an adaptive dead-time methodology which insures that both outputs are never enabled at the same time. When the controller commands HO to be enabled, the adaptive block first disables LO and waits for the LO voltage to drop below approximately 25% of VCC. HO is then enabled after a small delay. Similarly, LO is enabled once HO has discharged. This methodology insures adequate dead-time for any size MOSFET.

## Thermal Protection

Internal thermal shutdown circuitry is provided to protect the integrated circuit in the event the maximum junction temperature is exceeded. When activated, typically at 170°C, the controller is forced into a low power reset state, disabling the output driver and the bias regulator. This is designed to prevent catastrophic failures from accidental device overheating.

## Application Information

### EXTERNAL COMPONENTS

The procedure for calculating the external components is illustrated with the following design example. The Bill of Materials for this design is listed in Table 1. The circuit shown in Figure 15 is configured for the following specifications:

- Output voltage = 5V
- Input voltage = 7V to 60V
- Maximum load current = 7A
- Switching frequency = 250kHz

Simplified equations are used as a general guideline for the design method. Comprehensive equations are provided at the end of this section.

### TIMING RESISTOR

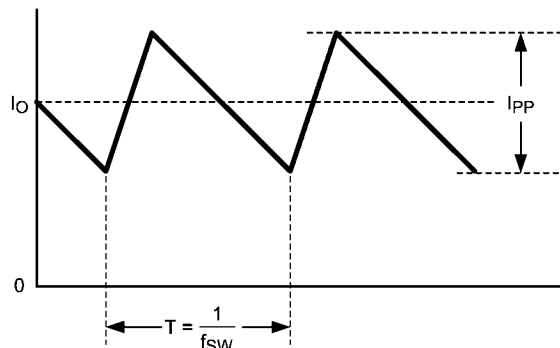
$R_T$  sets the oscillator switching frequency. Generally, higher frequency applications are smaller but have higher losses. Operation at 250kHz was selected for this example as a reasonable compromise for both small size and high efficiency. The value of  $R_T$  for 250kHz switching frequency can be calculated as follows:

$$R_T = \frac{\frac{1}{250 \text{ kHz}} - 450 \text{ ns}}{284 \text{ pF}} = 12.5 \text{ k}\Omega$$

The nearest standard value of 12.4kΩ was chosen for  $R_T$ .

### OUTPUT INDUCTOR

The inductor value is determined based on the operating frequency, load current, ripple current and the input and output voltages.



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FIGURE 9. Inductor Current

Knowing the switching frequency ( $f_{SW}$ ), maximum ripple current ( $I_{PP}$ ), maximum input voltage ( $V_{IN(MAX)}$ ) and the nominal output voltage ( $V_{OUT}$ ), the inductor value can be calculated:

$$L = \frac{V_{OUT}}{I_{PP} \times f_{SW}} \times \left(1 - \frac{V_{OUT}}{V_{IN(MAX)}}\right)$$

The maximum ripple current occurs at the maximum input voltage. Typically,  $I_{PP}$  is 20% to 40% of the full load current. When running diode emulation mode, the maximum ripple current should be less than twice the minimum load current. For full synchronous operation, higher ripple current is acceptable. Higher ripple current allows for a smaller inductor size, but places more of a burden on the output capacitor to smooth the ripple current for low output ripple voltage. For this example, 40% ripple current was chosen for a smaller sized inductor.

$$L = \frac{5V}{0.4 \times 7A \times 250kHz} \times \left(1 - \frac{5V}{60V}\right) = 6.5 \mu H$$

The nearest standard value of 6µH will be used. The inductor must be rated for the peak current to prevent saturation. During normal operation, the peak current occurs at maximum load current plus maximum ripple. During overload conditions with properly scaled component values, the peak current is limited to  $V_{CS(TH)} / R_S$  (See next section). At the maximum input voltage with a shorted output, the valley current must fall below  $V_{CS(TH)} / R_S$  before the high-side MOSFET is allowed to turn on. The peak current in steady state will increase to  $V_{IN(MAX)} \times t_{ON(min)} / L$  above this level. The chosen inductor must be evaluated for this condition, especially at elevated temperature where the saturation current rating may drop significantly.

### CURRENT SENSE RESISTOR

The current limit is set by the current sense resistor value ( $R_S$ ).

$$I_{LIM} = \frac{V_{CS(TH)}}{R_S}$$

For a 5V output, the maximum current sense signal occurs at the minimum input voltage, so  $R_S$  is calculated from:

$$R_S \leq \frac{V_{CS(TH)}}{I_O + \frac{V_{OUT}}{2 \times L \times f_{SW}}} \times \left(1 + \frac{V_{OUT}}{V_{IN(MIN)}}\right)$$

For this example  $V_{CCX} = 0V$ , so  $V_{CS(TH)} = 0.11V$ . The current sense resistor is calculated as:

$$R_S \leq \frac{0.11V}{7A + \frac{5V}{2 \times 6 \mu H \times 250 \text{ kHz}}} \times \left(1 + \frac{5V}{7V}\right) \leq 0.011\Omega$$

The next lowest standard value of  $10m\Omega$  was chosen for  $R_S$ .

#### RAMP CAPACITOR

With the inductor and sense resistor value selected, the value of the ramp capacitor ( $C_{RAMP}$ ) necessary for the emulation ramp circuit is:

$$C_{RAMP} \approx \frac{g_m \times L}{A \times R_S}$$

Where  $L$  is the value of the output inductor in Henrys,  $g_m$  is the ramp generator transconductance ( $5\mu A/V$ ), and  $A$  is the current sense amplifier gain ( $10V/V$ ). For the 5V output design example, the ramp capacitor is calculated as:

$$C_{RAMP} = \frac{5 \mu A/V \times 6 \mu H}{10V/V \times 10 m\Omega} = 300 \text{ pF}$$

The next lowest standard value of  $270pF$  was selected for  $C_{RAMP}$ . A COG type capacitor with 5% or better tolerance is recommended.

#### OUTPUT CAPACITORS

The output capacitors smooth the inductor ripple current and provide a source of charge for transient loading conditions. For this design example, five  $100\mu F$  ceramic capacitors were selected. Ceramic capacitors provide very low equivalent series resistance (ESR), but can exhibit a significant reduction in capacitance with DC bias. From the manufacturer's data, the ESR at  $250kHz$  is  $2m\Omega / 5 = 0.4m\Omega$ , with a 36% reduction in capacitance at 5V. This is verified by measuring the output ripple voltage and frequency response of the circuit. The fundamental component of the output ripple voltage is calculated as:

$$\Delta V_{OUT} = I_{PP} \times \sqrt{ESR^2 + \left(\frac{1}{8 \times f_{SW} \times C_{OUT}}\right)^2}$$

With typical values for the 5V design example:

$$\Delta V_{OUT} = 3A \times \sqrt{0.4 m\Omega^2 + \left(\frac{1}{8 \times 250 \text{ kHz} \times 320 \mu F}\right)^2}$$

$$\Delta V_{OUT} = 4.8 \text{ mV}$$

#### INPUT CAPACITORS

The regulator supply voltage has a large source impedance at the switching frequency. Good quality input capacitors are necessary to limit the ripple voltage at the VIN pin while supplying most of the switch current during the on-time. When the buck switch turns on, the current into the switch steps to the valley of the inductor current waveform, ramps up to the peak value, and then drops to zero at turn-off. The input capacitors should be selected for RMS current rating and minimum ripple voltage. A good approximation for the required ripple current rating is  $I_{RMS} > I_{OUT} / 2$ .

Quality ceramic capacitors with a low ESR were selected for the input filter. To allow for capacitor tolerances and voltage rating, four  $2.2\mu F$ ,  $100V$  ceramic capacitors were used for the typical application circuit. With ceramic capacitors, the input ripple voltage will be triangular and peak at 50% duty cycle. Taking into account the capacitance change with DC bias, the input ripple voltage is approximated as:

$$\Delta V_{IN} = \frac{I_{OUT}}{4 \times f_{SW} \times C_{IN}} = \frac{7A}{4 \times 250 \text{ kHz} \times 7 \mu F} = 1V$$

When the converter is connected to an input power source, a resonant circuit is formed by the line impedance and the input capacitors. If step input voltage transients are expected near the maximum rating of the LM5116, a careful evaluation of the ringing and possible overshoot at the device VIN pin should be completed. To minimize overshoot make  $C_{IN} > 10 \times L_{IN}$ . The characteristic source impedance and resonant frequency are:

$$Z_S = \sqrt{\frac{L_{IN}}{C_{IN}}} \quad f_S = \frac{1}{2\pi \sqrt{L_{IN} \times C_{IN}}}$$

The converter exhibits a negative input impedance which is lowest at the minimum input voltage:

$$Z_{IN} = -\frac{V_{IN}^2}{P_{OUT}}$$

The damping factor for the input filter is given by:

$$\delta = \frac{1}{2} \left( \frac{R_{IN} + ESR}{Z_S} + \frac{Z_S}{Z_{IN}} \right)$$

When  $\delta = 1$ , the input filter is critically damped. This may be difficult to achieve with practical component values. With  $\delta < 0.2$ , the input filter will exhibit significant ringing. If  $\delta$  is zero or negative, there is not enough resistance in the circuit and the input filter will sustain an oscillation. When operating near the minimum input voltage, an aluminum electrolytic capacitor across  $C_{IN}$  may be needed to damp the input for a typical bench test setup. Any parallel capacitor should be evaluated for its RMS current rating. The current will split between the ceramic and aluminum capacitors based on the relative impedance at the switching frequency.

#### VCC CAPACITOR

The primary purpose of the VCC capacitor ( $C_{VCC}$ ) is to supply the peak transient currents of the LO driver and bootstrap diode (D1) as well as provide stability for the VCC regulator.

These current peaks can be several amperes. The recommended value of  $C_{VCC}$  should be no smaller than  $0.47\mu\text{F}$ , and should be a good quality, low ESR, ceramic capacitor located at the pins of the IC to minimize potentially damaging voltage transients caused by trace inductance. A value of  $1\mu\text{F}$  was selected for this design.

### BOOTSTRAP CAPACITOR

The bootstrap capacitor ( $C_{HB}$ ) between the HB and SW pins supplies the gate current to charge the high-side MOSFET gate at each cycle's turn-on as well as supplying the recovery charge for the bootstrap diode (D1). These current peaks can be several amperes. The recommended value of the bootstrap capacitor is at least  $0.1\mu\text{F}$ , and should be a good quality, low ESR, ceramic capacitor located at the pins of the IC to minimize potentially damaging voltage transients caused by trace inductance. The absolute minimum value for the bootstrap capacitor is calculated as:

$$C_{HB} \geq \frac{Q_g}{\Delta V_{HB}}$$

Where  $Q_g$  is the high-side MOSFET gate charge and  $\Delta V_{HB}$  is the tolerable voltage droop on  $C_{HB}$ , which is typically less than 5% of VCC. A value of  $1\mu\text{F}$  was selected for this design.

### SOFT START CAPACITOR

The capacitor at the SS pin ( $C_{SS}$ ) determines the soft-start time, which is the time for the reference voltage and the output voltage to reach the final regulated value. The value of  $C_{SS}$  for a given time is determined from:

$$C_{SS} = \frac{t_{SS} \times 10 \mu\text{A}}{1.215\text{V}}$$

For this application, a value of  $0.01\mu\text{F}$  was chosen for a soft-start time of 1.2ms.

### OUTPUT VOLTAGE DIVIDER

$R_{FB1}$  and  $R_{FB2}$  set the output voltage level, the ratio of these resistors is calculated from:

$$\frac{R_{FB2}}{R_{FB1}} = \frac{V_{OUT}}{1.215\text{V}} - 1$$

$R_{FB1}$  is typically  $1.21\text{k}\Omega$  for a divider current of 1mA. The divider current can be reduced to  $100\mu\text{A}$  with  $R_{FB1}=12.1\text{k}\Omega$ . For the 5V output design example used here,  $R_{FB1} = 1.21\text{k}\Omega$  and  $R_{FB2} = 3.74\text{k}\Omega$ .

### UVLO DIVIDER

A voltage divider and filter can be connected to the UVLO pin to set a minimum operating voltage  $V_{IN(MIN)}$  for the regulator. If this feature is required, the following procedure can be used to determine appropriate resistor values for  $R_{UV2}$ ,  $R_{UV1}$  and  $C_{FT}$ .

1.  $R_{UV2}$  must be large enough such that in the event of a current limit, the internal UVLO switch can pull UVLO < 200mV. This can be guaranteed if:

$$R_{UV2} > 500 \times V_{IN(MAX)}$$

Where  $V_{IN(MAX)}$  is the maximum input voltage and  $R_{UV2}$  is in ohms.

2. With an appropriate value for  $R_{UV2}$ ,  $R_{UV1}$  can be selected using the following equation:

$$R_{UV1} = 1.215 \times \left( \frac{R_{UV2}}{V_{IN(MIN)} + (5 \mu\text{A} \times R_{UV2}) - 1.215} \right)$$

Where  $V_{IN(MIN)}$  is the desired shutdown voltage.

3. Capacitor  $C_{FT}$  provides filtering for the divider and determines the off-time of the "hiccup" duty cycle during current limit. When  $C_{FT}$  is used in conjunction with the voltage divider, a diode across the top resistor should be used to discharge  $C_{FT}$  in the event of an input under-voltage condition.

$$t_{OFF} = - \left( \frac{R_{UV1} \times R_{UV2}}{R_{UV1} + R_{UV2}} \right) \times C_{FT} \times \ln \left( 1 - \frac{1.215 \times (R_{UV1} + R_{UV2})}{V_{IN} \times R_{UV1}} \right)$$

If under-voltage shutdown is not required,  $R_{UV1}$  and  $R_{UV2}$  can be eliminated and the off-time becomes:

$$t_{OFF} = C_{FT} \times \frac{1.215\text{V}}{5 \mu\text{A}}$$

The voltage at the UVLO pin should never exceed 16V when using an external set-point divider. It may be necessary to clamp the UVLO pin at high input voltages. For the design example,  $R_{UV2} = 102\text{k}\Omega$  and  $R_{UV1} = 21\text{k}\Omega$  for a shut-down voltage of 6.6V. If sustained short circuit protection is required,  $C_{FT} \geq 1\mu\text{F}$  will limit the short circuit power dissipation. D2 may be installed when using  $C_{FT}$  with  $R_{UV1}$  and  $R_{UV2}$ .

### MOSFETS

Selection of the power MOSFETs is governed by the same tradeoffs as switching frequency. Breaking down the losses in the high-side and low-side MOSFETs is one way to determine relative efficiencies between different devices. When using discrete SO-8 MOSFETs the LM5116 is most efficient for output currents of 2A to 10A. Losses in the power MOSFETs can be broken down into conduction loss, gate charging loss, and switching loss. Conduction, or  $I^2R$  loss  $P_{DC}$ , is approximately:

$$P_{DC(HO-MOSFET)} = D \times (I_O^2 \times R_{DS(ON)}) \times 1.3$$

$$P_{DC(LO-MOSFET)} = (1 - D) \times (I_O^2 \times R_{DS(ON)}) \times 1.3$$

Where D is the duty cycle. The factor 1.3 accounts for the increase in MOSFET on-resistance due to heating. Alternatively, the factor of 1.3 can be ignored and the on-resistance of the MOSFET can be estimated using the  $R_{DS(ON)}$  vs Temperature curves in the MOSFET datasheet. Gate charging loss,  $P_{GC}$ , results from the current driving the gate capacitance of the power MOSFETs and is approximated as:

$$P_{GC} = n \times V_{CC} \times Q_g \times f_{SW}$$

$Q_g$  refer to the total gate charge of an individual MOSFET, and 'n' is the number of MOSFETs. If different types of MOSFETs are used, the 'n' term can be ignored and their gate charges summed to form a cumulative  $Q_g$ . Gate charge loss differs from conduction and switching losses in that the actual dissipation occurs in the LM5116 and not in the MOSFET itself. Further loss in the LM5116 is incurred as the gate driving current is supplied by the internal linear regulator. Switching loss occurs during the brief transition period as the MOSFET turns on and off. During the transition period both current and voltage are present in the channel of the MOSFET. The switching loss can be approximated as:

$$P_{SW} = 0.5 \times V_{IN} \times I_O \times (t_R + t_F) \times f_{SW}$$

Where  $t_R$  and  $t_F$  are the rise and fall times of the MOSFET. Switching loss is calculated for the high-side MOSFET only. Switching loss in the low-side MOSFET is negligible because the body diode of the low-side MOSFET turns on before the MOSFET itself, minimizing the voltage from drain to source before turn-on. For this example, the maximum drain-to-source voltage applied to either MOSFET is 60V. VCC provides the drive voltage at the gate of the MOSFETs. The selected MOSFETs must be able to withstand 60V plus any ringing from drain to source, and be able to handle at least VCC plus ringing from gate to source. A good choice of MOSFET for the 60V input design example is the Si7850DP. It has an  $R_{DS(ON)}$  of 20m $\Omega$ , total gate charge of 14nC, and rise and fall times of 10ns and 12ns respectively. In applications where a high step-down ratio is maintained for normal operation, efficiency may be optimized by choosing a high-side MOSFET with lower  $Q_g$ , and low-side MOSFET with lower  $R_{DS(ON)}$ .

For higher voltage MOSFETs which are not true logic level, it is important to use the UVLO feature. Choose a minimum operating voltage which is high enough for VCC and the bootstrap (HB) supply to fully enhance the MOSFET gates. This will prevent operation in the linear region during power-on or power-off which can result in MOSFET failure. Similar consideration must be made when powering VCCX from the output voltage.

### MOSFET SNUBBER

A resistor-capacitor snubber network across the low-side MOSFET reduces ringing and spikes at the switching node. Excessive ringing and spikes can cause erratic operation and couple spikes and noise to the output. Selecting the values for the snubber is best accomplished through empirical methods. First, make sure the lead lengths for the snubber connections are very short. Start with a resistor value between 5 $\Omega$  and 50 $\Omega$ . Increasing the value of the snubber capacitor results in more damping, but higher snubber losses. Select a minimum value for the snubber capacitor that provides adequate damping of the spikes on the switch waveform at high load.

### ERROR AMPLIFIER COMPENSATION

$R_{COMP}$ ,  $C_{COMP}$  and  $C_{HF}$  configure the error amplifier gain characteristics to accomplish a stable voltage loop gain. One advantage of current mode control is the ability to close the loop with only two feedback components,  $R_{COMP}$  and  $C_{COMP}$ . The voltage loop gain is the product of the modulator gain and the error amplifier gain. For the 5V output design example, the modulator is treated as an ideal voltage-to-current converter. The DC modulator gain of the LM5116 can be modeled as:

$$DC\ Gain_{(MOD)} = R_{LOAD} / (A \times R_S)$$

The dominant low frequency pole of the modulator is determined by the load resistance ( $R_{LOAD}$ ) and output capacitance ( $C_{OUT}$ ). The corner frequency of this pole is:

$$f_{P(MOD)} = 1 / (2\pi \times R_{LOAD} \times C_{OUT})$$

For  $R_{LOAD} = 5V / 7A = 0.714\Omega$  and  $C_{OUT} = 320\mu F$  (effective) then  $f_{P(MOD)} = 700Hz$

DC  $Gain_{(MOD)} = 0.714\Omega / (10 \times 10m\Omega) = 7.14 = 17dB$

For the 5V design example the modulator gain vs. frequency characteristic was measured as shown in Figure 10.

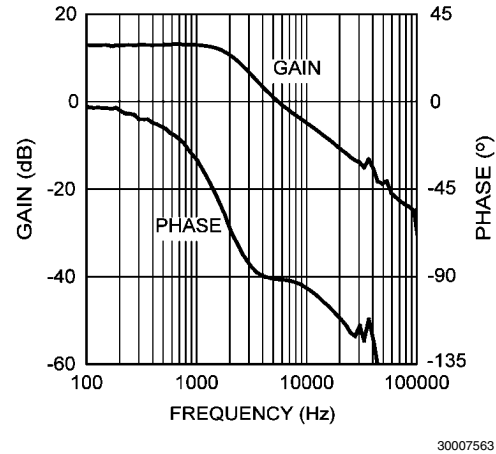


FIGURE 10. Modulator Gain and Phase

Components  $R_{COMP}$  and  $C_{COMP}$  configure the error amplifier as a type II configuration. The DC gain of the amplifier is 80dB which has a pole at low frequency and a zero at  $f_{ZEA} = 1 / (2\pi \times R_{COMP} \times C_{COMP})$ . The error amplifier zero cancels the modulator pole leaving a single pole response at the crossover frequency of the voltage loop. A single pole response at the crossover frequency yields a very stable loop with 90° of phase margin. For the design example, a target loop bandwidth (crossover frequency) of one-tenth the switching frequency or 25kHz was selected. The compensation network zero ( $f_{ZEA}$ ) should be selected at least an order of magnitude less than the target crossover frequency. This constrains the product of  $R_{COMP}$  and  $C_{COMP}$  for a desired compensation network zero  $1 / (2\pi \times R_{COMP} \times C_{COMP})$  to be 2.5kHz. Increasing  $R_{COMP}$ , while proportionally decreasing  $C_{COMP}$ , increases the error amp gain. Conversely, decreasing  $R_{COMP}$  while proportionally increasing  $C_{COMP}$ , decreases the error amp gain. For the design example  $C_{COMP}$  was selected as 3300pF and  $R_{COMP}$  was selected as 18k $\Omega$ . These values configure the compensation network zero at 2.7kHz. The error amp gain at frequencies greater than  $f_{ZEA}$  is:  $R_{COMP} / R_{FB2}$ , which is approximately 4.8 (13.6dB).

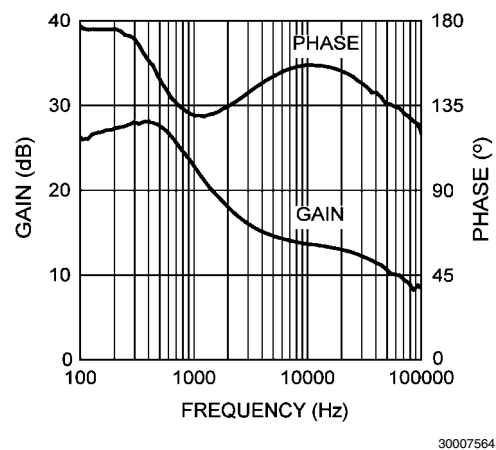
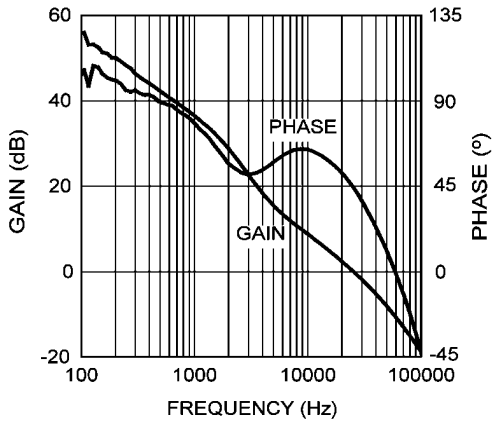


FIGURE 11. Error Amplifier Gain and Phase

The overall voltage loop gain can be predicted as the sum (in dB) of the modulator gain and the error amp gain.



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FIGURE 12. Overall Voltage Loop Gain and Phase

If a network analyzer is available, the modulator gain can be measured and the error amplifier gain can be configured for the desired loop transfer function. If a network analyzer is not available, the error amplifier compensation components can be designed with the guidelines given. Step load transient tests can be performed to verify acceptable performance. The step load goal is minimum overshoot with a damped response.  $C_{HF}$  can be added to the compensation network to decrease noise susceptibility of the error amplifier. The value of  $C_{HF}$  must be sufficiently small since the addition of this capacitor adds a pole in the error amplifier transfer function. This pole must be well beyond the loop crossover frequency. A good approximation of the location of the pole added by  $C_{HF}$  is:  $f_{P2} = f_{ZEA} \times C_{COMP} / C_{HF}$ . The value of  $C_{HF}$  was selected as 100pF for the design example.

#### PCB BOARD LAYOUT and THERMAL CONSIDERATIONS

In a buck regulator there are two loops where currents are switched very fast. The first loop starts from the input capacitors, through the high-side MOSFET, to the inductor then out to the load. The second loop starts from the output capacitor ground, to the regulator PGND pins, to the current sense resistor, through the low-side MOSFET, to the inductor and then out to the load. Minimizing the area of these two loops reduces the stray inductance and minimizes noise and possible erratic operation. A ground plane in the PC board is recommended as a means to connect the input filter capacitors to the output filter capacitors and the PGND pin of the regulator. Connect all of the low power ground connections ( $C_{SS}$ ,  $R_T$ ,  $C_{RAMP}$ ) directly to the regulator AGND pin. Connect the AGND and PGND pins together through to topside copper area covering the entire underside of the device. Place several vias in this underside copper area to the ground plane. The input capacitor ground connection should be as close as possible to the low-side source or current sense ground connection.

The highest power dissipating components are the two power MOSFETs. The easiest way to determine the power dissipated in the MOSFETs is to measure the total conversion losses ( $P_{IN} - P_{OUT}$ ), then subtract the power losses in the output inductor and any snubber resistors.

If a snubber is used, the power loss can be estimated with an oscilloscope by observation of the resistor voltage drop at both turn-on and turn-off transitions. Assuming that the RC time constant is  $\ll 1 / f_{SW}$ .

$$P = C \times V^2 \times f_{SW}$$

The regulator has an exposed thermal pad to aid power dissipation. Selecting MOSFETs with exposed pads will aid the power dissipation of these devices. The resulting power losses are primarily in the switching MOSFETs. Careful attention to  $R_{DS(ON)}$  at high temperature should be observed. Also, at 250 kHz, a MOSFET with low gate capacitance will result in lower switching losses.

## Comprehensive Equations

### CURRENT SENSE RESISTOR AND RAMP CAPACITOR

$T = 1 / f_{SW}$ ,  $g_m = 5\mu A/V$ ,  $A = 10V/V$ .  $I_{OUT}$  is the maximum output current at current limit.

General Method for  $V_{OUT} < 5V$ :

$$R_S = \frac{V_{CS(TH)}}{I_{OUT} - \frac{V_{OUT} \times T}{2 \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN(MIN)}}\right) + \frac{V_{OUT} \times T}{L} \times \left(1 + \frac{5 - V_{OUT}}{V_{IN(MIN)}}\right)}$$

$$C_{RAMP} = \frac{g_m \times L}{A \times R_S} \times \left(1 + \frac{5 - V_{OUT}}{V_{IN(MAX)}}$$

General Method for  $5V < V_{OUT} < 7.5V$ :

$$R_S = \frac{V_{CS(TH)}}{I_{OUT} - \frac{V_{OUT} \times T}{2 \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN(MIN)}}\right) + \frac{V_{OUT} \times T}{L}}$$

$$C_{RAMP} = \frac{g_m \times L}{A \times R_S} \times \left(1 + \frac{5 - V_{OUT}}{V_{IN(MIN)}}\right)$$

Best Performance Method:

This minimizes the current limit deviation due to changes in line voltage, while maintaining near optimal slope compensation.

Calculate optimal slope current,  $I_{OS} = (V_{OUT} / 3) \times 10\mu A/V$ . For example, at  $V_{OUT} = 7.5V$ ,  $I_{OS} = 25\mu A$ .

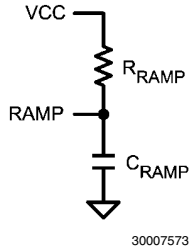
$$R_S = \frac{V_{CS(TH)}}{I_{OUT} + \frac{V_{OUT} \times T}{L}} \quad C_{RAMP} = \frac{I_{OS} \times L}{V_{OUT} \times A \times R_S}$$

Calculate  $V_{RAMP}$  at the nominal input voltage.

$$V_{RAMP} = \frac{V_{OUT}}{V_{IN}} \times \frac{((V_{IN} - V_{OUT}) \times g_m + I_{OS}) \times T}{C_{RAMP}}$$

For  $V_{OUT} > 7.5V$ , install a resistor from the RAMP pin to VCC.

$$R_{RAMP} = \frac{V_{CC} - V_{RAMP}}{I_{OS} - 25\mu A}$$

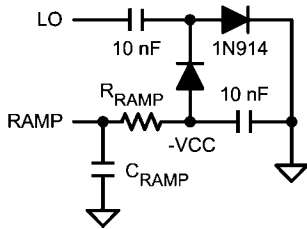


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**FIGURE 13.  $R_{RAMP}$  to VCC for  $V_{OUT} > 7.5V$** 

For  $V_{OUT} < 7.5V$ , a negative VCC is required. This can be made with a simple charge pump from the LO gate output. Install a resistor from the RAMP pin to the negative VCC.

$$R_{RAMP} = \frac{VCC - 0.5V + V_{RAMP}}{25 \mu A - I_{OS}}$$



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**FIGURE 14.  $R_{RAMP}$  to -VCC for  $V_{OUT} < 7.5V$** 

If a large variation is expected in VCC, say for  $V_{IN} < 11V$ , a Zener regulator may be added to supply a constant voltage for  $R_{RAMP}$ .

### MODULATOR TRANSFER FUNCTION

The following equations can be used to calculate the control-to-output transfer function:

$$\frac{\hat{V}_{OUT}}{\hat{V}_{COMP}} = \frac{R_{LOAD}}{A \times R_S} \times \frac{1}{1 + \frac{R_{LOAD}}{K_m \times A \times R_S}} \times \frac{1 + \frac{s}{\omega_Z}}{\left(1 + \frac{s}{\omega_P}\right) \times \left(1 + \frac{s}{\omega_n \times Q} + \frac{s^2}{\omega_n^2}\right)}$$

$$K_m = \frac{1}{\frac{(D - 0.5) \times A \times R_S \times T}{L} + (1 - 2 \times D) \times K_{SL} + \frac{V_{SL}}{V_{IN}}}$$

$$K_{SL} = \frac{g_m \times T}{C_{RAMP}} \quad V_{SL} = \frac{I_{OS} \times T}{C_{RAMP}}$$

$$\omega_Z = \frac{1}{C_{OUT} \times ESR} \quad \omega_P = \frac{1}{C_{OUT}} \times \left( \frac{1}{R_{LOAD}} + \frac{1}{K_m \times A \times R_S} \right) \quad \omega_n = \frac{\pi}{T}$$

$$S_e = \frac{(V_{IN} - V_{OUT}) \times K_{SL} + V_{SL}}{T} \quad S_n = \frac{V_{IN} \times A \times R_S}{L}$$

$$m_C = \frac{S_e}{S_n} \quad Q = \frac{1}{\pi \times (m_C - 0.5)}$$

$K_m$  is the effective DC gain of the modulating comparator. The duty cycle  $D = V_{OUT} / V_{IN}$ .  $K_{SL}$  is the proportional slope compensation term.  $V_{SL}$  is the fixed slope compensation term. Slope compensation is set by  $m_C$ , which is the ratio of the external ramp to the natural ramp. The switching frequency sampling gain is characterized by  $\omega_n$  and  $Q$ , which accounts for the high frequency inductor pole.

### ERROR AMPLIFIER TRANSFER FUNCTION

The following equations are used to calculate the error amplifier transfer function:

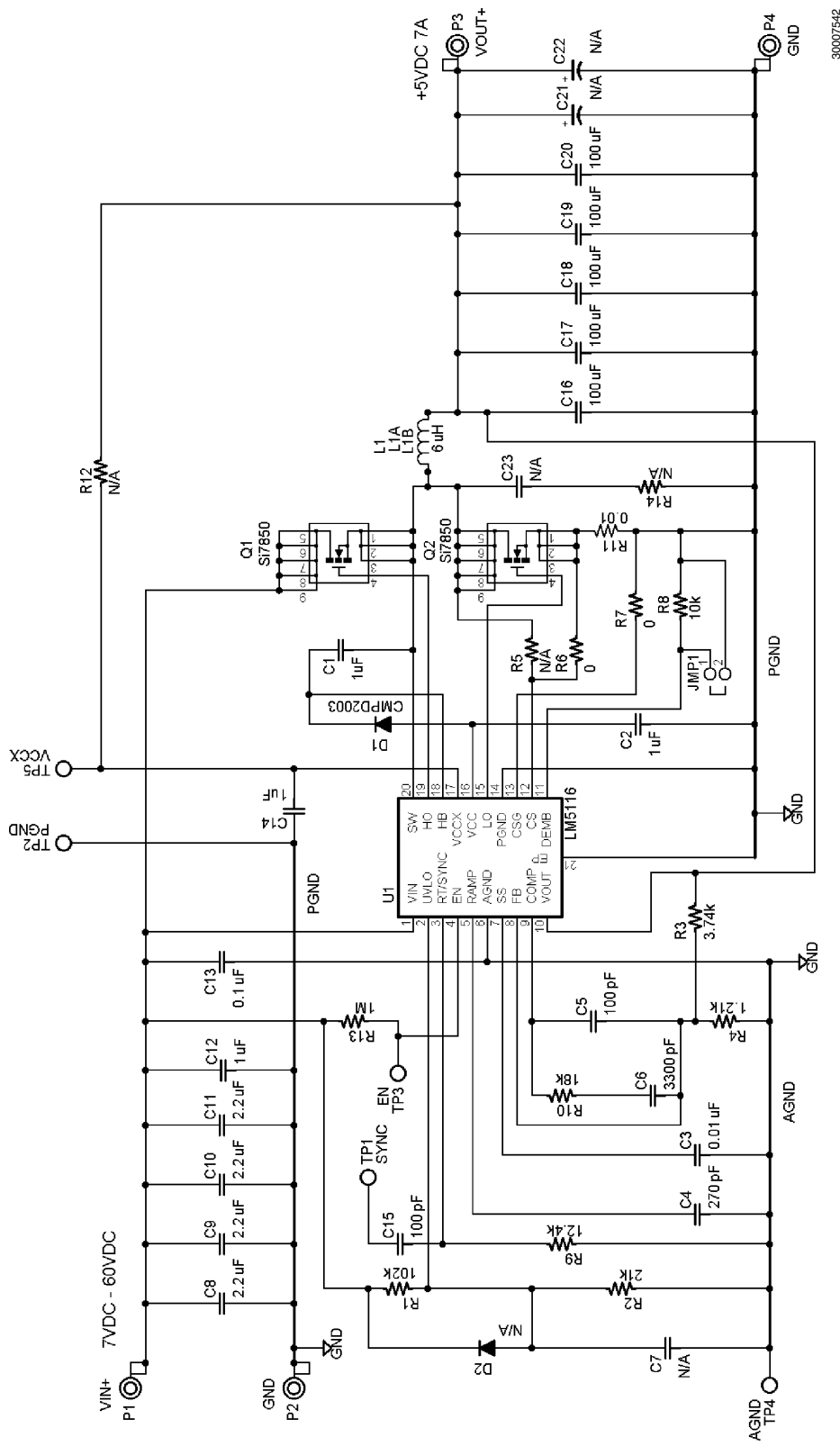
$$\frac{\hat{V}_{COMP}}{\hat{V}_{OUT(FB)}} = -G_{EA(S)} \times \frac{1}{1 + \left( \frac{1}{A_{OL}} + \frac{s}{\omega_{BW}} \right) \times \left( 1 + \frac{G_{EA(S)}}{K_{FB}} \right)}$$

$$G_{EA(S)} = \frac{1 + \frac{s}{\omega_{ZEA}}}{\frac{s}{\omega_O} \times \left( 1 + \frac{s}{\omega_{HF}} \right)} \quad K_{FB} = \frac{R_{FB1}}{R_{FB1} + R_{FB2}}$$

$$\omega_{ZEA} = \frac{1}{C_{COMP} \times R_{COMP}} \quad \omega_O = \frac{1}{(C_{HF} + C_{COMP}) \times R_{FB2}}$$

$$\omega_{HF} = \frac{(C_{HF} + C_{COMP})}{C_{HF} \times C_{COMP} \times R_{COMP}}$$

Where  $A_{OL} = 10,000$  (80dB) and  $\omega_{BW} = 2\pi \times f_{BW}$ .  $G_{EA(S)}$  is the ideal error amplifier gain, which is modified at DC and high frequency by the open loop gain of the amplifier and the feedback divider ratio.



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5V 7A Typical Application Schematic

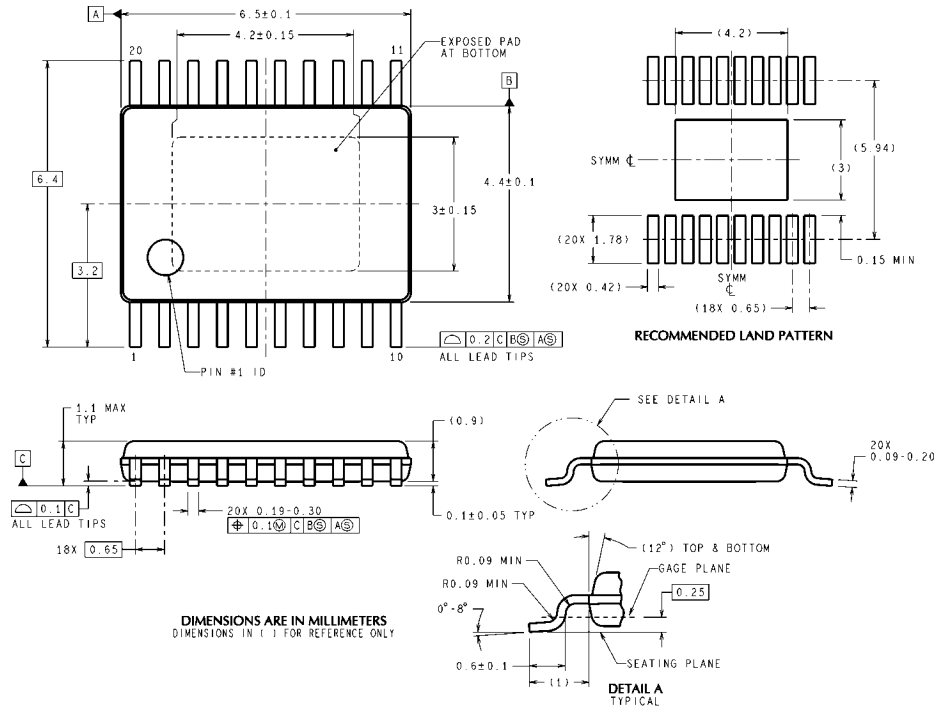
FIGURE 15.

TABLE 1. Bill of Materials for 7V-60V Input, 5V 7A Output, 250kHz

ID	Part Number	Type	Size	Parameters	Qty	Vendor
C1, C2, C14	C2012X7R1E105K	Capacitor, Ceramic	0805	1 $\mu$ F, 25V, X7R	3	TDK
C3	VJ0603Y103KXAAT	Capacitor, Ceramic	0603	0.01 $\mu$ F, 50V, X7R	1	Vishay
C4	VJ0603A271JXAAT	Capacitor, Ceramic	0603	270pF, 50V, COG, 5%	1	Vishay
C5, C15	VJ0603Y101KXAT W1BC	Capacitor, Ceramic	0603	100pF, 50V, X7R	2	Vishay
C6	VJ0603Y332KXXAT	Capacitor, Ceramic	0603	3300pF, 25V, X7R	1	Vishay
C7		Capacitor, Ceramic	0603	Not Used	0	
C8, C9, C10, C11	C4532X7R2A225M	Capacitor, Ceramic	1812	2.2 $\mu$ F, 100V X7R	4	TDK
C12	C3225X7R2A105M	Capacitor, Ceramic	1210	1 $\mu$ F, 100V X7R	1	TDK
C13	C2012X7R2A104M	Capacitor, Ceramic	0805	0.1 $\mu$ F, 100V X7R	1	TDK
C16, C17, C18, C19, C20	C4532X6S0J107M	Capacitor, Ceramic	1812	100 $\mu$ F, 6.3V, X6S, 105°C	5	TDK
C21, C22		Capacitor, Tantalum	D Case	Not Used	0	
C23		Capacitor, Ceramic	0805	Not Used	0	
D1	CMPD2003	Diode, Switching	SOT-23	200mA, 200V	1	Central Semi
D2	CMPD2003	Diode, Switching	SOT-23	Not Used	0	Central Semi
JMP1		Connector, Jumper		2 pin sq. post	1	
L1	HC2LP-6R0	Inductor		6 $\mu$ H, 16.5A	1	Cooper
P1-P4	1514-2	Turret Terminal	.090" dia.		4	Keystone
TP1-TP5	5012	Test Point	.040" dia.		5	Keystone
Q1, Q2	Si7850DP	N-CH MOSFET	SO-8 Power PAK	10.3A, 60V	2	Vishay Siliconix
R1	CRCW06031023F	Resistor	0603	102k $\Omega$ , 1%	1	Vishay
R2	CRCW06032102F	Resistor	0603	21.0k $\Omega$ , 1%	1	Vishay
R3	CRCW06033741F	Resistor	0603	3.74k $\Omega$ , 1%	1	Vishay
R4	CRCW06031211F	Resistor	0603	1.21k $\Omega$ , 1%	1	Vishay
R5		Resistor	0603	Not Used	0	
R6, R7	CRCW06030R0J	Resistor	0603	0 $\Omega$	2	Vishay
R8	CRCW0603103J	Resistor	0603	10k $\Omega$ , 5%	1	Vishay
R9	CRCW06031242F	Resistor	0603	12.4k $\Omega$ , 1%	1	Vishay
R10	CRCW0603183J	Resistor	0603	18k $\Omega$ , 5%	1	Vishay
R11	LRC-LRF2010-01- R010-F	Resistor	2010	0.010 $\Omega$ , 1%	1	IRC
R12		Resistor	0603	Not Used	0	
R13	CRCW0603105J	Resistor	0603	1M $\Omega$ , 5%	1	Vishay
R14		Resistor	1206	Not Used	0	
U1	LM5116MHX	Synchronous Buck Controller	TSSOP-20EP		1	NSC



# Physical Dimensions inches (millimeters) unless otherwise noted



**TSSOP-20EP Outline Drawing**  
**NS Package Number MXA20A**

MXA20A (Rev C)

## Notes

## Notes

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