

**Hardware Specification**

MPC850ABEC/D  
Rev. 1, 10/2002

MPC850 (Rev. A/B/C) Family  
Communications Controller  
Hardware Specifications



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This document contains detailed information on power considerations, AC/DC electrical characteristics, and AC timing specifications for revision A,B, and C of the MPC850 Family.

This document contains the following topics:

| Topic                                               | Page |
|-----------------------------------------------------|------|
| Part I, "Overview"                                  | 1    |
| Part II, "Features"                                 | 3    |
| Part III, "Electrical and Thermal Characteristics"  | 7    |
| Part IV, "Thermal Characteristics"                  | 9    |
| Part V, "Power Considerations"                      | 10   |
| Part VI, "Bus Signal Timing"                        | 12   |
| Part VII, "IEEE 1149.1 Electrical Specifications"   | 42   |
| Part VIII, "CPM Electrical Characteristics"         | 43   |
| Part IX, "Mechanical Data and Ordering Information" | 66   |
| Part X, "Document Revision History"                 | 72   |

## Part I Overview

The MPC850 is a versatile, one-chip integrated microprocessor and peripheral combination that can be used in a variety of controller applications, excelling particularly in communications and networking products. The MPC850, which includes support for Ethernet, is specifically designed for cost-sensitive, remote-access, and telecommunications applications. It provides functions similar to the MPC860, with system enhancements such as universal serial bus (USB) support and a larger (8-Kbyte) dual-port RAM.

In addition to a high-performance embedded MPC8xx core, the MPC850 integrates system functions, such as a versatile memory controller and a communications processor module (CPM) that incorporates a specialized, independent RISC communications processor (referred to as the CP). This separate processor off-loads peripheral tasks from the embedded MPC8xx core.

**For More Information On This Product,  
Go to: [www.freescale.com](http://www.freescale.com)**

The CPM of the MPC850 supports up to seven serial channels, as follows:

- One or two serial communications controllers (SCCs). The SCCs support Ethernet, ATM (MPC850SR and MPC850DSL), HDLC and a number of other protocols, along with a transparent mode of operation.
- One USB channel
- Two serial management controllers (SMCs)
- One I<sup>2</sup>C port
- One serial peripheral interface (SPI).

Table 1-1 shows the functionality supported by the members of the MPC850 family.

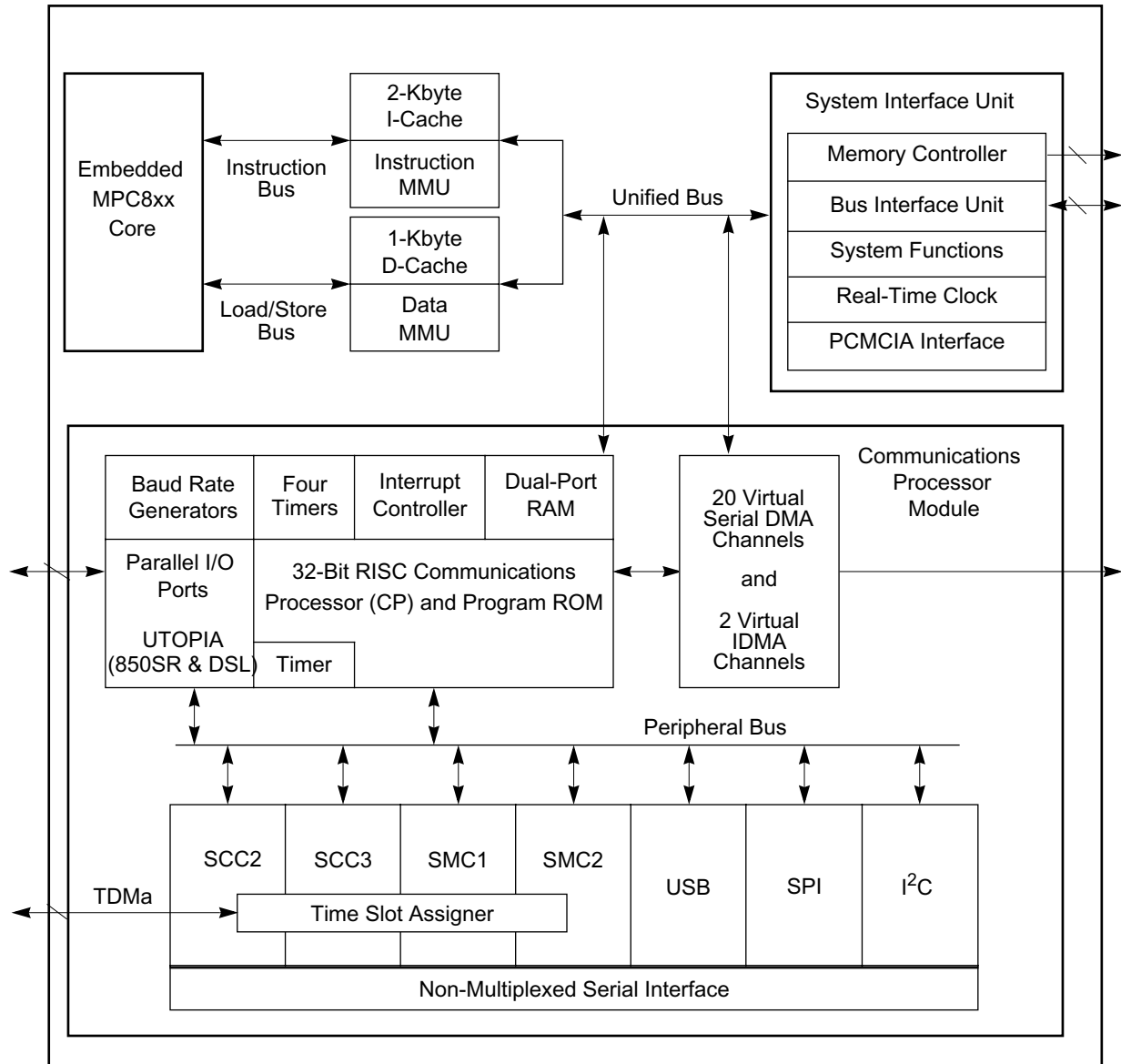
**Table 1-1. MPC850 Functionality Matrix**

| Part      | Number of SCCs Supported | Ethernet Support | ATM Support | USB Support | Multi-channel HDLC Support | Number of PCMCIA Slots Supported |
|-----------|--------------------------|------------------|-------------|-------------|----------------------------|----------------------------------|
| MPC850    | 1                        | Yes              | -           | Yes         | -                          | 1                                |
| MPC850DE  | 2                        | Yes              | -           | Yes         | -                          | 1                                |
| MPC850SR  | 2                        | Yes              | Yes         | Yes         | Yes                        | 1                                |
| MPC850DSL | 2                        | Yes              | Yes         | Yes         | No                         | 1                                |

Additional documentation may be provided for parts listed in Table 1-1.

## Part II Features

Figure 2-1 is a block diagram of the MPC850, showing its major components and the relationships among those components:



**Figure 2-1. MPC850 Microprocessor Block Diagram**

The following list summarizes the main features of the MPC850:

- Embedded single-issue, 32-bit MPC8xx core (implementing the PowerPC architecture) with thirty-two 32-bit general-purpose registers (GPRs)
  - Performs branch folding and branch prediction with conditional prefetch, but without conditional execution

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- 2-Kbyte instruction cache and 1-Kbyte data cache (Harvard architecture)
  - Caches are two-way, set-associative
  - Physically addressed
  - Cache blocks can be updated with a 4-word line burst
  - Least-recently used (LRU) replacement algorithm
  - Lockable one-line granularity
- Memory management units (MMUs) with 8-entry translation lookaside buffers (TLBs) and fully-associative instruction and data TLBs
- MMUs support multiple page sizes of 4 Kbytes, 16 Kbytes, 256 Kbytes, 512 Kbytes, and 8 Mbytes; 16 virtual address spaces and eight protection groups
- Advanced on-chip emulation debug mode
- Data bus dynamic bus sizing for 8, 16, and 32-bit buses
  - Supports traditional 68000 big-endian, traditional x86 little-endian and modified little-endian memory systems
  - Twenty-six external address lines
- Completely static design (0–80 MHz operation)
- System integration unit (SIU)
  - Hardware bus monitor
  - Spurious interrupt monitor
  - Software watchdog
  - Periodic interrupt timer
  - Low-power stop mode
  - Clock synthesizer
  - Decrementer, time base, and real-time clock (RTC) from the PowerPC architecture
  - Reset controller
  - IEEE 1149.1 test access port (JTAG)
- Memory controller (eight banks)
  - Glueless interface to DRAM single in-line memory modules (SIMMs), synchronous DRAM (SDRAM), static random-access memory (SRAM), electrically programmable read-only memory (EPROM), flash EPROM, etc.
  - Memory controller programmable to support most size and speed memory interfaces
  - Boot chip-select available at reset (options for 8, 16, or 32-bit memory)
  - Variable block sizes, 32 Kbytes to 256 Mbytes

- Selectable write protection
- On-chip bus arbiter supports one external bus master
- Special features for burst mode support
- General-purpose timers
  - Four 16-bit timers or two 32-bit timers
  - Gate mode can enable/disable counting
  - Interrupt can be masked on reference match and event capture
- Interrupts
  - Eight external interrupt request (IRQ) lines
  - Twelve port pins with interrupt capability
  - Fifteen internal interrupt sources
  - Programmable priority among SCCs and USB
  - Programmable highest-priority request
- Single socket PCMCIA-ATA interface
  - Master (socket) interface, release 2.1 compliant
  - Single PCMCIA socket
  - Supports eight memory or I/O windows
- Communications processor module (CPM)
  - 32-bit, Harvard architecture, scalar RISC communications processor (CP)
  - Protocol-specific command sets (for example, GRACEFUL STOP TRANSMIT stops transmission after the current frame is finished or immediately if no frame is being sent and CLOSE RXBD closes the receive buffer descriptor)
  - Supports continuous mode transmission and reception on all serial channels
  - Up to 8 Kbytes of dual-port RAM
  - Twenty serial DMA (SDMA) channels for the serial controllers, including eight for the four USB endpoints
  - Three parallel I/O registers with open-drain capability
- Four independent baud-rate generators (BRGs)
  - Can be connected to any SCC, SMC, or USB
  - Allow changes during operation
  - Autobaud support option
- Two SCCs (serial communications controllers)
  - Ethernet/IEEE 802.3, supporting full 10-Mbps operation
  - HDLC/SDLC™ (all channels supported at 2 Mbps)
  - HDLC bus (implements an HDLC-based local area network (LAN))

- Asynchronous HDLC to support PPP (point-to-point protocol)
- AppleTalk<sup>®</sup>
- Universal asynchronous receiver transmitter (UART)
- Synchronous UART
- Serial infrared (IrDA)
- Totally transparent (bit streams)
- Totally transparent (frame based with optional cyclic redundancy check (CRC))
- QUICC multichannel controller (QMC) microcode features
  - Up to 64 independent communication channels on a single SCC
  - Arbitrary mapping of 0–31 channels to any of 0–31 TDM time slots
  - Supports either transparent or HDLC protocols for each channel
  - Independent TxBDs/Rx and event/interrupt reporting for each channel
- One universal serial bus controller (USB)
  - Supports host controller and slave modes at 1.5 Mbps and 12 Mbps
- Two serial management controllers (SMCs)
  - UART
  - Transparent
  - General circuit interface (GCI) controller
  - Can be connected to the time-division-multiplexed (TDM) channel
- One serial peripheral interface (SPI)
  - Supports master and slave modes
  - Supports multimaster operation on the same bus
- One I<sup>2</sup>C<sup>®</sup> (interprocessor-integrated circuit) port
  - Supports master and slave modes
  - Supports multimaster environment
- Time slot assigner
  - Allows SCCs and SMCs to run in multiplexed operation
  - Supports T1, CEPT, PCM highway, ISDN basic rate, ISDN primary rate, user-defined
  - 1- or 8-bit resolution
  - Allows independent transmit and receive routing, frame syncs, clocking
  - Allows dynamic changes
  - Can be internally connected to four serial channels (two SCCs and two SMCs)
- Low-power support

- Full high: all units fully powered at high clock frequency
- Full low: all units fully powered at low clock frequency
- Doze: core functional units disabled except time base, decrements, PLL, memory controller, real-time clock, and CPM in low-power standby
- Sleep: all units disabled except real-time clock and periodic interrupt timer. PLL is active for fast wake-up
- Deep sleep: all units disabled including PLL, except the real-time clock and periodic interrupt timer
- Low-power stop: to provide lower power dissipation
- Separate power supply input to operate internal logic at 2.2 V when operating at or below 25 MHz
- Can be dynamically shifted between high frequency (3.3 V internal) and low frequency (2.2 V internal) operation
- Debug interface
  - Eight comparators: four operate on instruction address, two operate on data address, and two operate on data
  - The MPC850 can compare using the =, ≠, <, and > conditions to generate watchpoints
  - Each watchpoint can generate a breakpoint internally
- 3.3-V operation with 5-V TTL compatibility on all general purpose I/O pins.

## Part III Electrical and Thermal Characteristics

This section provides the AC and DC electrical specifications and thermal characteristics for the MPC850. Table 3-2 provides the maximum ratings.

**Table 3-2. Maximum Ratings**

(GND = 0V)

| Rating                            | Symbol           | Value                                      | Unit |
|-----------------------------------|------------------|--------------------------------------------|------|
| Supply voltage                    | VDDH             | -0.3 to 4.0                                | V    |
|                                   | VDDL             | -0.3 to 4.0                                | V    |
|                                   | KAPWR            | -0.3 to 4.0                                | V    |
|                                   | VDDSYN           | -0.3 to 4.0                                | V    |
| Input voltage <sup>1</sup>        | V <sub>in</sub>  | GND-0.3 to VDDH + 2.5 V                    | V    |
| Junction temperature <sup>2</sup> | T <sub>j</sub>   | 0 to 95 (standard)<br>-40 to 95 (extended) | °C   |
| Storage temperature range         | T <sub>stg</sub> | -55 to +150                                | °C   |

<sup>1</sup> Functional operating conditions are provided with the DC electrical specifications in Table 4-5. Absolute maximum ratings are stress ratings only; functional operation at the maxima is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage to the device.

CAUTION: All inputs that tolerate 5 V cannot be more than 2.5 V greater than the supply voltage. This restriction applies to power-up and normal operation (that is, if the MPC850 is unpowered, voltage greater than 2.5 V must not be applied to its inputs).

<sup>2</sup> The MPC850, a high-frequency device in a BGA package, does not provide a guaranteed maximum ambient temperature. Only maximum junction temperature is guaranteed. It is the responsibility of the user to consider power dissipation and thermal management. Junction temperature ratings are the same regardless of frequency rating of the device.

This device contains circuitry protecting against damage due to high-static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for example, either GND or V<sub>CC</sub>). Table 4-3 provides the package thermal characteristics for the MPC850.



# Part IV Thermal Characteristics

Table 4-3 shows the thermal characteristics for the MPC850.

**Table 4-3. Thermal Characteristics**

| Characteristic                                | Symbol        | Value           | Unit |
|-----------------------------------------------|---------------|-----------------|------|
| Thermal resistance for BGA <sup>1</sup>       | $\theta_{JA}$ | 40 <sup>2</sup> | °C/W |
|                                               | $\theta_{JA}$ | 31 <sup>3</sup> | °C/W |
|                                               | $\theta_{JA}$ | 24 <sup>4</sup> | °C/W |
| Thermal Resistance for BGA (junction-to-case) | $\theta_{JC}$ | 8               | °C/W |

<sup>1</sup> For more information on the design of thermal vias on multilayer boards and BGA layout considerations in general, refer to AN-1231/D, Plastic Ball Grid Array Application Note available from your local Motorola sales office.

<sup>2</sup> Assumes natural convection and a single layer board (no thermal vias).

<sup>3</sup> Assumes natural convection, a multilayer board with thermal vias<sup>4</sup>, 1 watt MPC850 dissipation, and a board temperature rise of 20°C above ambient.

<sup>4</sup> Assumes natural convection, a multilayer board with thermal vias<sup>4</sup>, 1 watt MPC850 dissipation, and a board temperature rise of 13°C above ambient.

$$T_J = T_A + (P_D \bullet \theta_{JA})$$

$$P_D = (V_{DD} \bullet I_{DD}) + P_{I/O}$$

where:

$P_{I/O}$  is the power dissipation on pins

Table 4-4 provides power dissipation information.

**Table 4-4. Power Dissipation ( $P_D$ )**

| Characteristic                                   | Frequency (MHz) | Typical <sup>1</sup> | Maximum <sup>2</sup> | Unit |
|--------------------------------------------------|-----------------|----------------------|----------------------|------|
| Power Dissipation<br>All Revisions<br>(1:1) Mode | 33              | TBD                  | 515                  | mW   |
|                                                  | 40              | TBD                  | 590                  | mW   |
|                                                  | 50              | TBD                  | 725                  | mW   |

<sup>1</sup> Typical power dissipation is measured at 3.3V

<sup>2</sup> Maximum power dissipation is measured at 3.65 V

Table 4-5 provides the DC electrical characteristics for the MPC850.

**Table 4-5. DC Electrical Specifications**

| Characteristic                                                                                   | Symbol                       | Min   | Max   | Unit |
|--------------------------------------------------------------------------------------------------|------------------------------|-------|-------|------|
| Operating voltage at 40 MHz or less                                                              | VDDH, VDDL,<br>KAPWR, VDDSYN | 3.0   | 3.6   | V    |
| Operating voltage at 40 MHz or higher                                                            | VDDH, VDDL,<br>KAPWR, VDDSYN | 3.135 | 3.465 | V    |
| Input high voltage (address bus, data bus, EXTAL, EXTCLK,<br>and all bus control/status signals) | VIH                          | 2.0   | 3.6   | V    |
| Input high voltage (all general purpose I/O and peripheral pins)                                 | VIH                          | 2.0   | 5.5   | V    |

Table 4-5. DC Electrical Specifications (continued)

| Characteristic                                                                                                                                                                                                                                                                                                                                                                                                                        | Symbol           | Min                    | Max                  | Unit |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------|------------------------|----------------------|------|
| Input low voltage                                                                                                                                                                                                                                                                                                                                                                                                                     | V <sub>IL</sub>  | GND                    | 0.8                  | V    |
| EXTAL, EXTCLK input high voltage                                                                                                                                                                                                                                                                                                                                                                                                      | V <sub>IHC</sub> | 0.7*(V <sub>CC</sub> ) | V <sub>CC</sub> +0.3 | V    |
| Input leakage current, V <sub>in</sub> = 5.5 V (Except TMS, $\overline{\text{TRST}}$ , DSCK and DSDI pins)                                                                                                                                                                                                                                                                                                                            | I <sub>in</sub>  | —                      | 100                  | μA   |
| Input leakage current, V <sub>in</sub> = 3.6V (Except TMS, $\overline{\text{TRST}}$ , DSCK and DSDI pins)                                                                                                                                                                                                                                                                                                                             | I <sub>in</sub>  | —                      | 10                   | μA   |
| Input leakage current, V <sub>in</sub> = 0V (Except TMS, $\overline{\text{TRST}}$ , DSCK and DSDI pins)                                                                                                                                                                                                                                                                                                                               | I <sub>in</sub>  | —                      | 10                   | μA   |
| Input capacitance                                                                                                                                                                                                                                                                                                                                                                                                                     | C <sub>in</sub>  | —                      | 20                   | pF   |
| Output high voltage, I <sub>OH</sub> = -2.0 mA, V <sub>DDH</sub> = 3.0V except XTAL, XFC, and open-drain pins                                                                                                                                                                                                                                                                                                                         | V <sub>OH</sub>  | 2.4                    | —                    | V    |
| Output low voltage<br>I <sub>OL</sub> = 2.0 mA CLKOUT<br>I <sub>OL</sub> = 3.2 mA <sup>1</sup><br>I <sub>OL</sub> = 5.3 mA <sup>2</sup><br>I <sub>OL</sub> = 7.0 mA PA[14]/ $\overline{\text{USBOE}}$ , PA[12]/TXD2<br>I <sub>OL</sub> = 8.9 mA $\overline{\text{TS}}$ , $\overline{\text{TA}}$ , $\overline{\text{TEA}}$ , $\overline{\text{BI}}$ , $\overline{\text{BB}}$ , $\overline{\text{HRESET}}$ , $\overline{\text{SRESET}}$ | V <sub>OL</sub>  | —                      | 0.5                  | V    |

<sup>1</sup> A[6:31], TSIZ0/ $\overline{\text{REG}}$ , TSIZ1, D[0:31], DP[0:3]/IRQ[3:6], RD/ $\overline{\text{WR}}$ , BURST, RSV/IRQ2, IP\_B[0:1]/IWP[0:1]/VFLS[0:1], IP\_B2/ $\overline{\text{IOIS16\_B/AT2}}$ , IP\_B3/IWP2/VF2, IP\_B4/LWP0/VF0, IP\_B5/LWP1/VF1, IP\_B6/DSDI/AT0, IP\_B7/PTR/AT3, PA[15]/USBRXD, PA[13]/RXD2, PA[9]/L1TXDA/SMRXD2, PA[8]/L1RXDA/SMTXD2, PA[7]/CLK1/TIN1/L1RCLKA/BRGO1, PA[6]/CLK2/TOUT1/TIN3, PA[5]/CLK3/TIN2/L1TCLKA/BRGO2, PA[4]/CLK4/TOUT2/TIN4, PB[31]/SPISEL, PB[30]/SPICLK/TXD3, PB[29]/SPIMOSI /RXD3, PB[28]/SPIMISO/BRGO3, PB[27]/I2CSDA/BRGO1, PB[26]/I2CSCL/BRGO2, PB[25]/SMTXD1/TXD3, PB[24]/SMRXD1/RXD3, PB[23]/SMSYN1/SDACK1, PB[22]/SMSYN2/SDACK2, PB[19]/L1ST1, PB[18]/RTS2/L1ST2, PB[17]/L1ST3, PB[16]/L1RQa/L1ST4, PC[15]/DREQ0/L1ST5, PC[14]/DREQ1/RTS2/L1ST6, PC[13]/L1ST7/RTS3, PC[12]/L1RQa/L1ST8, PC[11]/USBRXP, PC[10]/TGATE1/USBRXN, PC[9]/CTS2, PC[8]/CD2/TGATE1, PC[7]/USBTXP, PC[6]/USBTXN, PC[5]/CTS3/L1TSYNCA/SDACK1, PC[4]/CD3/L1RSYNCA, PD[15], PD[14], PD[13], PD[12], PD[11], PD[10], PD[9], PD[8], PD[7], PD[6], PD[5], PD[4], PD[3]

<sup>2</sup> BDIP/GPL\_B5, BR, BG, FRZ/IRQ6, CS[0:5], CS6/CE1\_B, CS7/CE2\_B, WE0/BS\_AB0/IORD, WE1/BS\_AB1/IOWR, WE2/BS\_AB2/PCOE, WE3/BS\_AB3/PCWE, GPL\_A0/GPL\_B0, OE/GPL\_A1/GPL\_B1, GPL\_A[2:3]/GPL\_B[2:3]/CS[2:3], UPWAITA/GPL\_A4/AS, UPWAITB/GPL\_B4, GPL\_A5, ALE\_B/DSCK/AT1, OP2/MODCK1/STS, OP3/MODCK2/DSDO

## Part V Power Considerations

The average chip-junction temperature, T<sub>J</sub>, in °C can be obtained from the equation:

$$T_J = T_A + (P_D \cdot \theta_{JA}) \quad (1)$$

where

T<sub>A</sub> = Ambient temperature, °C

θ<sub>JA</sub> = Package thermal resistance, junction to ambient, °C/W

$$P_D = P_{INT} + P_{I/O}$$

$$P_{INT} = I_{DD} \times V_{DD}, \text{ watts—chip internal power}$$

$$P_{I/O} = \text{Power dissipation on input and output pins—user determined}$$

For most applications  $P_{I/O} < 0.3 \cdot P_{INT}$  and can be neglected. If  $P_{I/O}$  is neglected, an approximate relationship between  $P_D$  and  $T_J$  is:

$$P_D = K \div (T_J + 273^\circ\text{C}) \quad (2)$$

Solving equations (1) and (2) for K gives:

$$K = P_D \cdot (T_A + 273^\circ\text{C}) + \theta_{JA} \cdot P_D^2 \quad (3)$$

where K is a constant pertaining to the particular part. K can be determined from equation (3) by measuring  $P_D$  (at equilibrium) for a known  $T_A$ . Using this value of K, the values of  $P_D$  and  $T_J$  can be obtained by solving equations (1) and (2) iteratively for any value of  $T_A$ .

## 5.1 Layout Practices

Each  $V_{CC}$  pin on the MPC850 should be provided with a low-impedance path to the board's supply. Each GND pin should likewise be provided with a low-impedance path to ground. The power supply pins drive distinct groups of logic on chip. The  $V_{CC}$  power supply should be bypassed to ground using at least four 0.1  $\mu\text{F}$  by-pass capacitors located as close as possible to the four sides of the package. The capacitor leads and associated printed circuit traces connecting to chip  $V_{CC}$  and GND should be kept to less than half an inch per capacitor lead. A four-layer board is recommended, employing two inner layers as  $V_{CC}$  and GND planes.

All output pins on the MPC850 have fast rise and fall times. Printed circuit (PC) trace interconnection length should be minimized in order to minimize undershoot and reflections caused by these fast output switching times. This recommendation particularly applies to the address and data busses. Maximum PC trace lengths of six inches are recommended. Capacitance calculations should consider all device loads as well as parasitic capacitances due to the PC traces. Attention to proper PCB layout and bypassing becomes especially critical in systems with higher capacitive loads because these loads create higher transient currents in the  $V_{CC}$  and GND circuits. Pull up all unused inputs or signals that will be inputs during reset. Special care should be taken to minimize the noise levels on the PLL supply pins.

## Part VI Bus Signal Timing

Table 6-6 provides the bus operation timing for the MPC850 at 50 MHz, 66 MHz, and 80 MHz. Timing information for other bus speeds can be interpolated by equation using the MPC850 Electrical Specifications Spreadsheet found at <http://www.mot.com/netcomm>.

The maximum bus speed supported by the MPC850 is 50 MHz. Higher-speed parts must be operated in half-speed bus mode (for example, an MPC850 used at 66 MHz must be configured for a 33 MHz bus).

The timing for the MPC850 bus shown assumes a 50-pF load. This timing can be derated by 1 ns per 10 pF. Derating calculations can also be performed using the MPC850 Electrical Specifications Spreadsheet.

**Table 6-6. Bus Operation Timing <sup>1</sup>**

| Num | Characteristic                                                | 50 MHz |      | 66 MHz |      | 80 MHz |      | FFACT | Cap Load<br>(default<br>50 pF) | Unit |
|-----|---------------------------------------------------------------|--------|------|--------|------|--------|------|-------|--------------------------------|------|
|     |                                                               | Min    | Max  | Min    | Max  | Min    | Max  |       |                                |      |
| B1  | CLKOUT period                                                 | 20     | —    | 30.30  | —    | 25     | —    | —     | —                              | ns   |
| B1a | EXTCLK to CLKOUT phase skew (EXTCLK > 15 MHz and MF ≤ 2)      | -0.90  | 0.90 | -0.90  | 0.90 | -0.90  | 0.90 | —     | 50.00                          | ns   |
| B1b | EXTCLK to CLKOUT phase skew (EXTCLK > 10 MHz and MF < 10)     | -2.30  | 2.30 | -2.30  | 2.30 | -2.30  | 2.30 | —     | 50.00                          | ns   |
| B1c | CLKOUT phase jitter (EXTCLK > 15 MHz and MF ≤ 2) <sup>2</sup> | -0.60  | 0.60 | -0.60  | 0.60 | -0.60  | 0.60 | —     | 50.00                          | ns   |
| B1d | CLKOUT phase jitter <sup>2</sup>                              | -2.00  | 2.00 | -2.00  | 2.00 | -2.00  | 2.00 | —     | 50.00                          | ns   |
| B1e | CLKOUT frequency jitter (MF < 10) <sup>2</sup>                | —      | 0.50 | —      | 0.50 | —      | 0.50 | —     | 50.00                          | %    |
| B1f | CLKOUT frequency jitter (10 < MF < 500) <sup>2</sup>          | —      | 2.00 | —      | 2.00 | —      | 2.00 | —     | 50.00                          | %    |
| B1g | CLKOUT frequency jitter (MF > 500) <sup>2</sup>               | —      | 3.00 | —      | 3.00 | —      | 3.00 | —     | 50.00                          | %    |
| B1h | Frequency jitter on EXTCLK <sup>3</sup>                       | —      | 0.50 | —      | 0.50 | —      | 0.50 | —     | 50.00                          | %    |
| B2  | CLKOUT pulse width low                                        | 8.00   | —    | 12.12  | —    | 10.00  | —    | —     | 50.00                          | ns   |
| B3  | CLKOUT width high                                             | 8.00   | —    | 12.12  | —    | 10.00  | —    | —     | 50.00                          | ns   |
| B4  | CLKOUT rise time                                              | —      | 4.00 | —      | 4.00 | —      | 4.00 | —     | 50.00                          | ns   |
| B5  | CLKOUT fall time                                              | —      | 4.00 | —      | 4.00 | —      | 4.00 | —     | 50.00                          | ns   |
| B7  | CLKOUT to A[6–31], RD/WR, BURST, D[0–31], DP[0–3] invalid     | 5.00   | —    | 7.58   | —    | 6.25   | —    | 0.250 | 50.00                          | ns   |
| B7a | CLKOUT to TSIZ[0–1], REG, RSV, AT[0–3], BDIP, PTR invalid     | 5.00   | —    | 7.58   | —    | 6.25   | —    | 0.250 | 50.00                          | ns   |

Table 6-6. Bus Operation Timing <sup>1</sup> (continued)

| Num  | Characteristic                                                                                                                                          | 50 MHz |       | 66 MHz |       | 80 MHz |       | FFACT | Cap Load<br>(default<br>50 pF) | Unit |
|------|---------------------------------------------------------------------------------------------------------------------------------------------------------|--------|-------|--------|-------|--------|-------|-------|--------------------------------|------|
|      |                                                                                                                                                         | Min    | Max   | Min    | Max   | Min    | Max   |       |                                |      |
| B7b  | CLKOUT to $\overline{BR}$ , $\overline{BG}$ , FRZ,<br>VFLS[0–1], VF[0–2] IWP[0–2],<br>LWP[0–1], $\overline{STS}$ invalid <sup>4</sup>                   | 5.00   | —     | 7.58   | —     | 6.25   | —     | 0.250 | 50.00                          | ns   |
| B8   | CLKOUT to A[6–31],<br>RD/ $\overline{WR}$ , BURST, D[0–31],<br>DP[0–3] valid                                                                            | 5.00   | 11.75 | 7.58   | 14.33 | 6.25   | 13.00 | 0.250 | 50.00                          | ns   |
| B8a  | CLKOUT to TSIZ[0–1], $\overline{REG}$ ,<br>RSV, AT[0–3] BDIP, PTR valid                                                                                 | 5.00   | 11.75 | 7.58   | 14.33 | 6.25   | 13.00 | 0.250 | 50.00                          | ns   |
| B8b  | CLKOUT to $\overline{BR}$ , $\overline{BG}$ , VFLS[0–1],<br>VF[0–2], IWP[0–2], FRZ,<br>LWP[0–1], $\overline{STS}$ valid <sup>4</sup>                    | 5.00   | 11.74 | 7.58   | 14.33 | 6.25   | 13.00 | 0.250 | 50.00                          | ns   |
| B9   | CLKOUT to A[6–31] RD/ $\overline{WR}$ ,<br>BURST, D[0–31], DP[0–3],<br>TSIZ[0–1], $\overline{REG}$ , RSV, AT[0–3],<br>PTR high-Z                        | 5.00   | 11.75 | 7.58   | 14.33 | 6.25   | 13.00 | 0.250 | 50.00                          | ns   |
| B11  | CLKOUT to $\overline{TS}$ , $\overline{BB}$ assertion                                                                                                   | 5.00   | 11.00 | 7.58   | 13.58 | 6.25   | 12.25 | 0.250 | 50.00                          | ns   |
| B11a | CLKOUT to $\overline{TA}$ , $\overline{BI}$ assertion,<br>(When driven by the memory<br>controller or PCMCIA interface)                                 | 2.50   | 9.25  | 2.50   | 9.25  | 2.50   | 9.25  | —     | 50.00                          | ns   |
| B12  | CLKOUT to $\overline{TS}$ , $\overline{BB}$ negation                                                                                                    | 5.00   | 11.75 | 7.58   | 14.33 | 6.25   | 13.00 | 0.250 | 50.00                          | ns   |
| B12a | CLKOUT to $\overline{TA}$ , $\overline{BI}$ negation<br>(when driven by the memory<br>controller or PCMCIA interface)                                   | 2.50   | 11.00 | 2.50   | 11.00 | 2.50   | 11.00 | —     | 50.00                          | ns   |
| B13  | CLKOUT to $\overline{TS}$ , $\overline{BB}$ high-Z                                                                                                      | 5.00   | 19.00 | 7.58   | 21.58 | 6.25   | 20.25 | 0.250 | 50.00                          | ns   |
| B13a | CLKOUT to $\overline{TA}$ , $\overline{BI}$ high-Z, (when<br>driven by the memory controller<br>or PCMCIA interface)                                    | 2.50   | 15.00 | 2.50   | 15.00 | 2.50   | 15.00 | —     | 50.00                          | ns   |
| B14  | CLKOUT to $\overline{TEA}$ assertion                                                                                                                    | 2.50   | 10.00 | 2.50   | 10.00 | 2.50   | 10.00 | —     | 50.00                          | ns   |
| B15  | CLKOUT to $\overline{TEA}$ high-Z                                                                                                                       | 2.50   | 15.00 | 2.50   | 15.00 | 2.50   | 15.00 | —     | 50.00                          | ns   |
| B16  | $\overline{TA}$ , $\overline{BI}$ valid to CLKOUT (setup<br>time) <sup>5</sup>                                                                          | 9.75   | —     | 9.75   | —     | 9.75   | —     | —     | 50.00                          | ns   |
| B16a | $\overline{TEA}$ , $\overline{KR}$ , $\overline{RETRY}$ , valid to<br>CLKOUT (setup time) <sup>5</sup>                                                  | 10.00  | —     | 10.00  | —     | 10.00  | —     | —     | 50.00                          | ns   |
| B16b | $\overline{BB}$ , $\overline{BG}$ , $\overline{BR}$ valid to CLKOUT<br>(setup time) <sup>6</sup>                                                        | 8.50   | —     | 8.50   | —     | 8.50   | —     | —     | 50.00                          | ns   |
| B17  | CLKOUT to $\overline{TA}$ , $\overline{TEA}$ , $\overline{BI}$ , $\overline{BB}$ , $\overline{BG}$ ,<br>$\overline{BR}$ valid (Hold time). <sup>5</sup> | 1.00   | —     | 1.00   | —     | 1.00   | —     | —     | 50.00                          | ns   |
| B17a | CLKOUT to $\overline{KR}$ , $\overline{RETRY}$ , except<br>$\overline{TEA}$ valid (hold time)                                                           | 2.00   | —     | 2.00   | —     | 2.00   | —     | —     | 50.00                          | ns   |
| B18  | D[0–31], DP[0–3] valid to<br>CLKOUT rising edge (setup<br>time) <sup>7</sup>                                                                            | 6.00   | —     | 6.00   | —     | 6.00   | —     | —     | 50.00                          | ns   |

### Table 6-6. Bus Operation Timing <sup>1</sup> (continued)

| Num  | Characteristic                                                                                                  | 50 MHz |       | 66 MHz |       | 80 MHz |       | FFACT | Cap Load<br>(default<br>50 pF) | Unit |
|------|-----------------------------------------------------------------------------------------------------------------|--------|-------|--------|-------|--------|-------|-------|--------------------------------|------|
|      |                                                                                                                 | Min    | Max   | Min    | Max   | Min    | Max   |       |                                |      |
| B19  | CLKOUT rising edge to D[0–31], DP[0–3] valid (hold time) <sup>7</sup>                                           | 1.00   | —     | 1.00   | —     | 1.00   | —     | —     | 50.00                          | ns   |
| B20  | D[0–31], DP[0–3] valid to CLKOUT falling edge (setup time) <sup>8</sup>                                         | 4.00   | —     | 4.00   | —     | 4.00   | —     | —     | 50.00                          | ns   |
| B21  | CLKOUT falling edge to D[0–31], DP[0–3] valid (hold time) <sup>8</sup>                                          | 2.00   | —     | 2.00   | —     | 2.00   | —     | —     | —                              | —    |
| B22  | CLKOUT rising edge to $\overline{CS}$ asserted GPCM ACS = 00                                                    | 5.00   | 11.75 | 7.58   | 14.33 | 6.25   | 13.00 | 0.250 | 50.00                          | ns   |
| B22a | CLKOUT falling edge to $\overline{CS}$ asserted GPCM ACS = 10, TRLX = 0,1                                       | —      | 8.00  | —      | 8.00  | —      | 8.00  | —     | 50.00                          | ns   |
| B22b | CLKOUT falling edge to $\overline{CS}$ asserted GPCM ACS = 11, TRLX = 0, EBDF = 0                               | 5.00   | 11.75 | 7.58   | 14.33 | 6.25   | 13.00 | 0.250 | 50.00                          | ns   |
| B22c | CLKOUT falling edge to $\overline{CS}$ asserted GPCM ACS = 11, TRLX = 0, EBDF = 1                               | 7.00   | 14.00 | 11.00  | 18.00 | 9.00   | 16.00 | 0.375 | 50.00                          | ns   |
| B23  | CLKOUT rising edge to $\overline{CS}$ negated GPCM read access, GPCM write access ACS = 00, TRLX = 0 & CSNT = 0 | 2.00   | 8.00  | 2.00   | 8.00  | 2.00   | 8.00  | —     | 50.00                          | ns   |
| B24  | A[6–31] to $\overline{CS}$ asserted GPCM ACS = 10, TRLX = 0.                                                    | 3.00   | —     | 6.00   | —     | 4.00   | —     | 0.250 | 50.00                          | ns   |
| B24a | A[6–31] to $\overline{CS}$ asserted GPCM ACS = 11, TRLX = 0                                                     | 8.00   | —     | 13.00  | —     | 11.00  | —     | 0.500 | 50.00                          | ns   |
| B25  | CLKOUT rising edge to $\overline{OE}$ , $\overline{WE}$ [0–3] asserted                                          | —      | 9.00  | —      | 9.00  | —      | 9.00  | —     | 50.00                          | ns   |
| B26  | CLKOUT rising edge to $\overline{OE}$ negated                                                                   | 2.00   | 9.00  | 2.00   | 9.00  | 2.00   | 9.00  | —     | 50.00                          | ns   |
| B27  | A[6–31] to $\overline{CS}$ asserted GPCM ACS = 10, TRLX = 1                                                     | 23.00  | —     | 36.00  | —     | 29.00  | —     | 1.250 | 50.00                          | ns   |
| B27a | A[6–31] to $\overline{CS}$ asserted GPCM ACS = 11, TRLX = 1                                                     | 28.00  | —     | 43.00  | —     | 36.00  | —     | 1.500 | 50.00                          | ns   |
| B28  | CLKOUT rising edge to $\overline{WE}$ [0–3] negated GPCM write access CSNT = 0                                  | —      | 9.00  | —      | 9.00  | —      | 9.00  | —     | 50.00                          | ns   |
| B28a | CLKOUT falling edge to $\overline{WE}$ [0–3] negated GPCM write access TRLX = 0,1 CSNT = 1, EBDF = 0            | 5.00   | 12.00 | 8.00   | 14.00 | 6.00   | 13.00 | 0.250 | 50.00                          | ns   |

Table 6-6. Bus Operation Timing <sup>1</sup> (continued)

| Num  | Characteristic                                                                                                                            | 50 MHz |       | 66 MHz |       | 80 MHz |       | FFACT | Cap Load<br>(default<br>50 pF) | Unit |
|------|-------------------------------------------------------------------------------------------------------------------------------------------|--------|-------|--------|-------|--------|-------|-------|--------------------------------|------|
|      |                                                                                                                                           | Min    | Max   | Min    | Max   | Min    | Max   |       |                                |      |
| B28b | CLKOUT falling edge to $\overline{CS}$ negated GPCM write access<br>TRLX = 0,1 CSNT = 1, ACS = 10<br>or ACS = 11, EBDF = 0                | —      | 12.00 | —      | 14.00 | —      | 13.00 | 0.250 | 50.00                          | ns   |
| B28c | CLKOUT falling edge to $\overline{WE}[0-3]$ negated GPCM write access<br>TRLX = 0,1 CSNT = 1<br>write access TRLX = 0, CSNT = 1, EBDF = 1 | 7.00   | 14.00 | 11.00  | 18.00 | 9.00   | 16.00 | 0.375 | 50.00                          | ns   |
| B28d | CLKOUT falling edge to $\overline{CS}$ negated GPCM write access<br>TRLX = 0,1 CSNT = 1, ACS = 10<br>or ACS = 11, EBDF = 1                | —      | 14.00 | —      | 18.00 | —      | 16.00 | 0.375 | 50.00                          | ns   |
| B29  | $\overline{WE}[0-3]$ negated to D[0-31],<br>DP[0-3] high-Z GPCM write access, CSNT = 0                                                    | 3.00   | —     | 6.00   | —     | 4.00   | —     | 0.250 | 50.00                          | ns   |
| B29a | $\overline{WE}[0-3]$ negated to D[0-31],<br>DP[0-3] high-Z GPCM write access, TRLX = 0 CSNT = 1,<br>EBDF = 0                              | 8.00   | —     | 13.00  | —     | 11.00  | —     | 0.500 | 50.00                          | ns   |
| B29b | $\overline{CS}$ negated to D[0-31],<br>DP[0-3], high-Z GPCM write access, ACS = 00, TRLX = 0 &<br>CSNT = 0                                | 3.00   | —     | 6.00   | —     | 4.00   | —     | 0.250 | 50.00                          | ns   |
| B29c | $\overline{CS}$ negated to D[0-31], DP[0-3] high-Z GPCM write access,<br>TRLX = 0, CSNT = 1, ACS = 10<br>or ACS = 11, EBDF = 0            | 8.00   | —     | 13.00  | —     | 11.00  | —     | 0.500 | 50.00                          | ns   |
| B29d | $\overline{WE}[0-3]$ negated to D[0-31],<br>DP[0-3] high-Z GPCM write access, TRLX = 1, CSNT = 1,<br>EBDF = 0                             | 28.00  | —     | 43.00  | —     | 36.00  | —     | 1.500 | 50.00                          | ns   |
| B29e | $\overline{CS}$ negated to D[0-31], DP[0-3] high-Z GPCM write access,<br>TRLX = 1, CSNT = 1, ACS = 10<br>or ACS = 11, EBDF = 0            | 28.00  | —     | 43.00  | —     | 36.00  | —     | 1.500 | 50.00                          | ns   |
| B29f | $\overline{WE}[0-3]$ negated to D[0-31],<br>DP[0-3] high-Z GPCM write access TRLX = 0, CSNT = 1,<br>EBDF = 1                              | 5.00   | —     | 9.00   | —     | 7.00   | —     | 0.375 | 50.00                          | ns   |
| B29g | $\overline{CS}$ negated to D[0-31], DP[0-3] high-Z GPCM write access<br>TRLX = 0, CSNT = 1, ACS = 10<br>or ACS = 11, EBDF = 1             | 5.00   | —     | 9.00   | —     | 7.00   | —     | 0.375 | 50.00                          | ns   |

**Table 6-6. Bus Operation Timing <sup>1</sup> (continued)**

| Num  | Characteristic                                                                                                                                                                                          | 50 MHz |      | 66 MHz |      | 80 MHz |      | FFACT | Cap Load<br>(default<br>50 pF) | Unit |
|------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------|------|--------|------|--------|------|-------|--------------------------------|------|
|      |                                                                                                                                                                                                         | Min    | Max  | Min    | Max  | Min    | Max  |       |                                |      |
| B29h | $\overline{WE}[0-3]$ negated to D[0-31], DP[0-3] high-Z GPCM write access TRLX = 0, CSNT = 1, EBDF = 1                                                                                                  | 25.00  | —    | 39.00  | —    | 31.00  | —    | 1.375 | 50.00                          | ns   |
| B29i | $\overline{CS}$ negated to D[0-31], DP[0-3] high-Z GPCM write access, TRLX = 1, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1                                                                                | 25.00  | —    | 39.00  | —    | 31.00  | —    | 1.375 | 50.00                          | ns   |
| B30  | $\overline{CS}$ , $\overline{WE}[0-3]$ negated to A[6-31] invalid GPCM write access <sup>9</sup>                                                                                                        | 3.00   | —    | 6.00   | —    | 4.00   | —    | 0.250 | 50.00                          | ns   |
| B30a | $\overline{WE}[0-3]$ negated to A[6-31] invalid GPCM write access, TRLX = 0, CSNT = 1, $\overline{CS}$ negated to A[6-31] invalid GPCM write access TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0  | 8.00   | —    | 13.00  | —    | 11.00  | —    | 0.500 | 50.00                          | ns   |
| B30b | $\overline{WE}[0-3]$ negated to A[6-31] invalid GPCM write access, TRLX = 1, CSNT = 1. $\overline{CS}$ negated to A[6-31] Invalid GPCM write access TRLX = 1, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 0  | 28.00  | —    | 43.00  | —    | 36.00  | —    | 1.500 | 50.00                          | ns   |
| B30c | $\overline{WE}[0-3]$ negated to A[6-31] invalid GPCM write access, TRLX = 0, CSNT = 1. $\overline{CS}$ negated to A[6-31] invalid GPCM write access, TRLX = 0, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1 | 5.00   | —    | 8.00   | —    | 6.00   | —    | 0.375 | 50.00                          | ns   |
| B30d | $\overline{WE}[0-3]$ negated to A[6-31] invalid GPCM write access TRLX = 1, CSNT = 1, $\overline{CS}$ negated to A[6-31] invalid GPCM write access TRLX = 1, CSNT = 1, ACS = 10 or ACS = 11, EBDF = 1   | 25.00  | —    | 39.00  | —    | 31.00  | —    | 1.375 | 50.00                          | ns   |
| B31  | CLKOUT falling edge to $\overline{CS}$ valid - as requested by control bit CST4 in the corresponding word in the UPM                                                                                    | 1.50   | 6.00 | 1.50   | 6.00 | 1.50   | 6.00 | —     | 50.00                          | ns   |



Table 6-6. Bus Operation Timing <sup>1</sup> (continued)

| Num  | Characteristic                                                                                                                          | 50 MHz |       | 66 MHz |       | 80 MHz |       | FFACT | Cap Load<br>(default<br>50 pF) | Unit |
|------|-----------------------------------------------------------------------------------------------------------------------------------------|--------|-------|--------|-------|--------|-------|-------|--------------------------------|------|
|      |                                                                                                                                         | Min    | Max   | Min    | Max   | Min    | Max   |       |                                |      |
| B31a | CLKOUT falling edge to $\overline{CS}$ valid<br>- as requested by control bit<br>CST1 in the corresponding word<br>in the UPM           | 5.00   | 12.00 | 8.00   | 14.00 | 6.00   | 13.00 | 0.250 | 50.00                          | ns   |
| B31b | CLKOUT rising edge to $\overline{CS}$ valid<br>- as requested by control bit<br>CST2 in the corresponding word<br>in the UPM            | 1.50   | 8.00  | 1.50   | 8.00  | 1.50   | 8.00  | —     | 50.00                          | ns   |
| B31c | CLKOUT rising edge to $\overline{CS}$ valid<br>- as requested by control bit<br>CST3 in the corresponding word<br>in the UPM            | 5.00   | 12.00 | 8.00   | 14.00 | 6.00   | 13.00 | 0.250 | 50.00                          | ns   |
| B31d | CLKOUT falling edge to $\overline{CS}$ valid<br>- as requested by control bit<br>CST1 in the corresponding word<br>in the UPM EBDF = 1  | 9.00   | 14.00 | 13.00  | 18.00 | 11.00  | 16.00 | 0.375 | 50.00                          | ns   |
| B32  | CLKOUT falling edge to $\overline{BS}$ valid<br>- as requested by control bit<br>BST4 in the corresponding word<br>in the UPM           | 1.50   | 6.00  | 1.50   | 6.00  | 1.50   | 6.00  | —     | 50.00                          | ns   |
| B32a | CLKOUT falling edge to $\overline{BS}$ valid<br>- as requested by control bit<br>BST1 in the corresponding word<br>in the UPM, EBDF = 0 | 5.00   | 12.00 | 8.00   | 14.00 | 6.00   | 13.00 | 0.250 | 50.00                          | ns   |
| B32b | CLKOUT rising edge to $\overline{BS}$ valid<br>- as requested by control bit<br>BST2 in the corresponding word<br>in the UPM            | 1.50   | 8.00  | 1.50   | 8.00  | 1.50   | 8.00  | —     | 50.00                          | ns   |
| B32c | CLKOUT rising edge to $\overline{BS}$ valid<br>- as requested by control bit<br>BST3 in the corresponding word<br>in the UPM            | 5.00   | 12.00 | 8.00   | 14.00 | 6.00   | 13.00 | 0.250 | 50.00                          | ns   |
| B32d | CLKOUT falling edge to $\overline{BS}$ valid<br>- as requested by control bit<br>BST1 in the corresponding word<br>in the UPM, EBDF = 1 | 9.00   | 14.00 | 13.00  | 18.00 | 11.00  | 16.00 | 0.375 | 50.00                          | ns   |
| B33  | CLKOUT falling edge to GPL<br>valid - as requested by control<br>bit GxT4 in the corresponding<br>word in the UPM                       | 1.50   | 6.00  | 1.50   | 6.00  | 1.50   | 6.00  | —     | 50.00                          | ns   |
| B33a | CLKOUT rising edge to GPL<br>valid - as requested by control<br>bit GxT3 in the corresponding<br>word in the UPM                        | 5.00   | 12.00 | 8.00   | 14.00 | 6.00   | 13.00 | 0.250 | 50.00                          | ns   |

**Table 6-6. Bus Operation Timing <sup>1</sup> (continued)**

| Num  | Characteristic                                                                                                                | 50 MHz |     | 66 MHz |     | 80 MHz |     | FFACT | Cap Load<br>(default<br>50 pF) | Unit |
|------|-------------------------------------------------------------------------------------------------------------------------------|--------|-----|--------|-----|--------|-----|-------|--------------------------------|------|
|      |                                                                                                                               | Min    | Max | Min    | Max | Min    | Max |       |                                |      |
| B34  | A[6–31] and D[0–31] to $\overline{CS}$ valid<br>- as requested by control bit<br>CST4 in the corresponding word<br>in the UPM | 3.00   | —   | 6.00   | —   | 4.00   | —   | 0.250 | 50.00                          | ns   |
| B34a | A[6–31] and D[0–31] to $\overline{CS}$ valid<br>- as requested by control bit<br>CST1 in the corresponding word<br>in the UPM | 8.00   | —   | 13.00  | —   | 11.00  | —   | 0.500 | 50.00                          | ns   |
| B34b | A[6–31] and D[0–31] to $\overline{CS}$ valid<br>- as requested by CST2 in the<br>corresponding word in UPM                    | 13.00  | —   | 21.00  | —   | 17.00  | —   | 0.750 | 50.00                          | ns   |
| B35  | A[6–31] to $\overline{CS}$ valid - as<br>requested by control bit BST4 in<br>the corresponding word in UPM                    | 3.00   | —   | 6.00   | —   | 4.00   | —   | 0.250 | 50.00                          | ns   |
| B35a | A[6–31] and D[0–31] to $\overline{BS}$ valid<br>- as requested by BST1 in the<br>corresponding word in the UPM                | 8.00   | —   | 13.00  | —   | 11.00  | —   | 0.500 | 50.00                          | ns   |
| B35b | A[6–31] and D[0–31] to $\overline{BS}$ valid<br>- as requested by control bit<br>BST2 in the corresponding word<br>in the UPM | 13.00  | —   | 21.00  | —   | 17.00  | —   | 0.750 | 50.00                          | ns   |
| B36  | A[6–31] and D[0–31] to GPL<br>valid - as requested by control<br>bit GxT4 in the corresponding<br>word in the UPM             | 3.00   | —   | 6.00   | —   | 4.00   | —   | 0.250 | 50.00                          | ns   |
| B37  | UPWAIT valid to CLKOUT falling<br>edge <sup>10</sup>                                                                          | 6.00   | —   | 6.00   | —   | 6.00   | —   | —     | 50.00                          | ns   |
| B38  | CLKOUT falling edge to<br>UPWAIT valid <sup>10</sup>                                                                          | 1.00   | —   | 1.00   | —   | 1.00   | —   | —     | 50.00                          | ns   |
| B39  | $\overline{AS}$ valid to CLKOUT rising edge<br><sup>11</sup>                                                                  | 7.00   | —   | 7.00   | —   | 7.00   | —   | —     | 50.00                          | ns   |
| B40  | A[6–31], TSIZ[0–1], RD/ $\overline{WR}$ ,<br>BURST, valid to CLKOUT rising<br>edge.                                           | 7.00   | —   | 7.00   | —   | 7.00   | —   | —     | 50.00                          | ns   |
| B41  | $\overline{TS}$ valid to CLKOUT rising edge<br>(setup time)                                                                   | 7.00   | —   | 7.00   | —   | 7.00   | —   | —     | 50.00                          | ns   |
| B42  | CLKOUT rising edge to $\overline{TS}$ valid<br>(hold time)                                                                    | 2.00   | —   | 2.00   | —   | 2.00   | —   | —     | 50.00                          | ns   |
| B43  | $\overline{AS}$ negation to memory<br>controller signals negation                                                             | —      | TBD | —      | TBD | TBD    | —   | —     | 50.00                          | ns   |

- <sup>1</sup> The minima provided assume a 0 pF load, whereas maxima assume a 50pF load. For frequencies not marked on the part, new bus timing must be calculated for all frequency-dependent AC parameters. Frequency-dependent AC parameters are those with an entry in the FFactor column. AC parameters without an FFactor entry do not need to be calculated and can be taken directly from the frequency column corresponding to the frequency marked on the part. The following equations should be used in these calculations.

For a frequency F, the following equations should be applied to each one of the above parameters:

For minima:

$$D = \frac{\text{FFACTOR} \times 1000}{F} + (D_{50} - 20 \times \text{FFACTOR})$$

For maxima:

$$D = \frac{\text{FFACTOR} \times 1000}{F} + (D_{50} - 20 \times \text{FFACTOR}) + 1\text{ns}(\text{CAP LOAD} - 50) / 10$$

where:

D is the parameter value to the frequency required in ns

F is the operation frequency in MHz

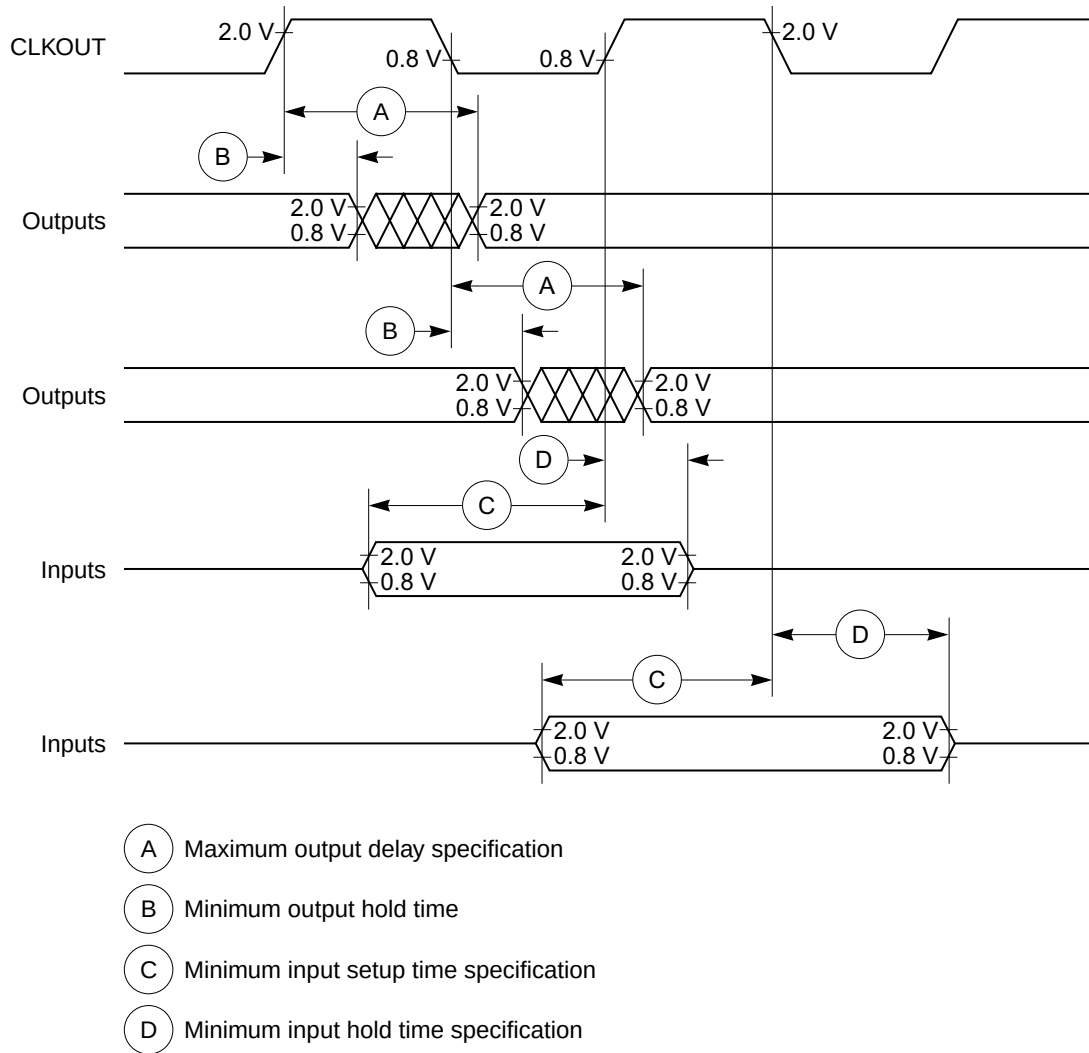
D<sub>50</sub> is the parameter value defined for 50 MHz

CAP LOAD is the capacitance load on the signal in question.

FFACTOR is the one defined for each of the parameters in the table.

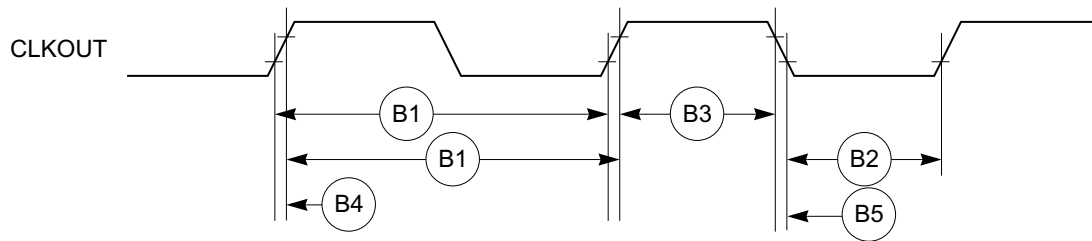
- <sup>2</sup> Phase and frequency jitter performance results are valid only if the input jitter is less than the prescribed value.
- <sup>3</sup> If the rate of change of the frequency of EXTAL is slow (i.e. it does not jump between the minimum and maximum values in one cycle) or the frequency of the jitter is fast (i.e., it does not stay at an extreme value for a long time) then the maximum allowed jitter on EXTAL can be up to 2%.
- <sup>4</sup> The timing for  $\overline{\text{BR}}$  output is relevant when the MPC850 is selected to work with external bus arbiter. The timing for  $\overline{\text{BG}}$  output is relevant when the MPC850 is selected to work with internal bus arbiter.
- <sup>5</sup> The setup times required for  $\overline{\text{TA}}$ ,  $\overline{\text{TEA}}$ , and  $\overline{\text{BI}}$  are relevant only when they are supplied by an external device (and not when the memory controller or the PCMCIA interface drives them).
- <sup>6</sup> The timing required for  $\overline{\text{BR}}$  input is relevant when the MPC850 is selected to work with the internal bus arbiter. The timing for  $\overline{\text{BG}}$  input is relevant when the MPC850 is selected to work with the external bus arbiter.
- <sup>7</sup> The D[0–31] and DP[0–3] input timings B20 and B21 refer to the rising edge of the CLKOUT in which the  $\overline{\text{TA}}$  input signal is asserted.
- <sup>8</sup> The D[0:31] and DP[0:3] input timings B20 and B21 refer to the falling edge of CLKOUT. This timing is valid only for read accesses controlled by chip-selects controlled by the UPM in the memory controller, for data beats where DLT3 = 1 in the UPM RAM words. (This is only the case where data is latched on the falling edge of CLKOUT.
- <sup>9</sup> The timing B30 refers to  $\overline{\text{CS}}$  when ACS = '00' and to  $\overline{\text{WE}}[0:3]$  when CSNT = '0'.
- <sup>10</sup> The signal UPWAIT is considered asynchronous to CLKOUT and synchronized internally. The timings specified in B37 and B38 are specified to enable the freeze of the UPM output signals.
- <sup>11</sup> The  $\overline{\text{AS}}$  signal is considered asynchronous to CLKOUT.

Figure 6-2 is the control timing diagram.



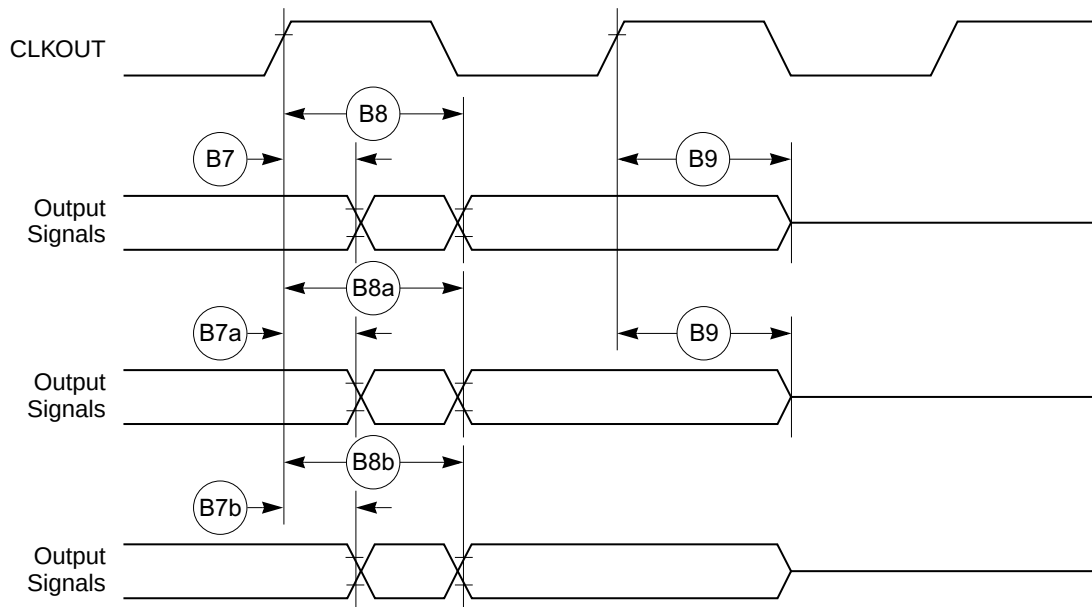
**Figure 6-2. Control Timing**

Figure 6-3 provides the timing for the external clock.



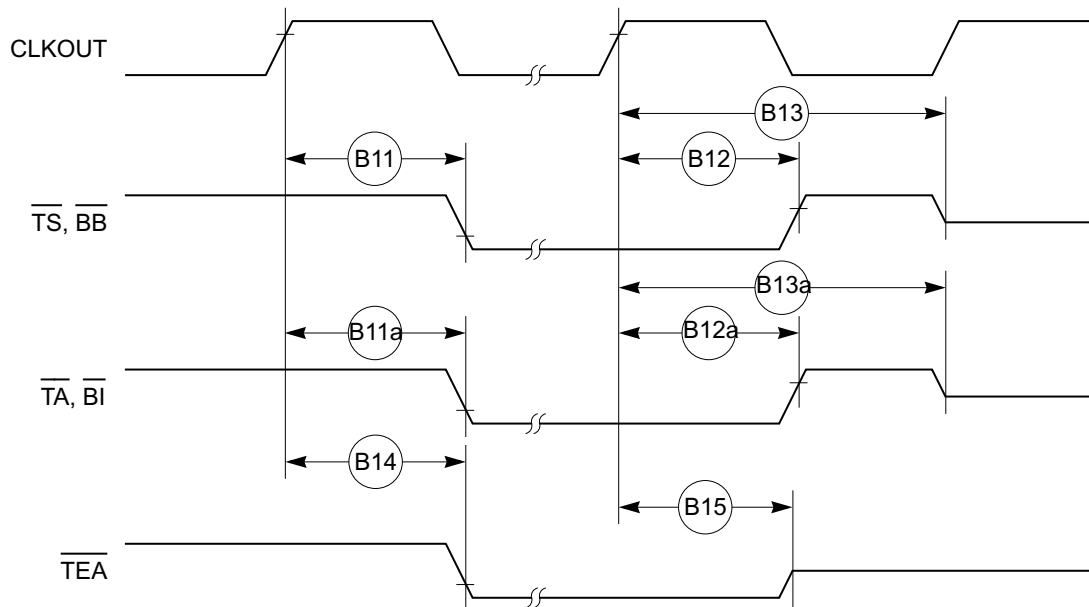
**Figure 6-3. External Clock Timing**

Figure 6-4 provides the timing for the synchronous output signals.



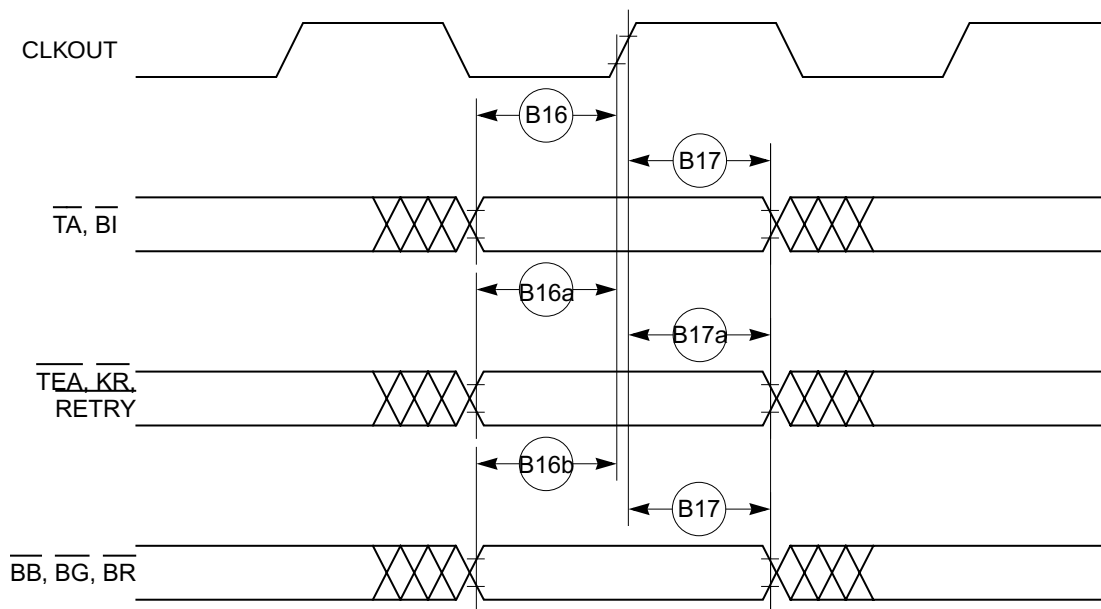
**Figure 6-4. Synchronous Output Signals Timing**

Figure 6-5 provides the timing for the synchronous active pull-up and open-drain output signals.



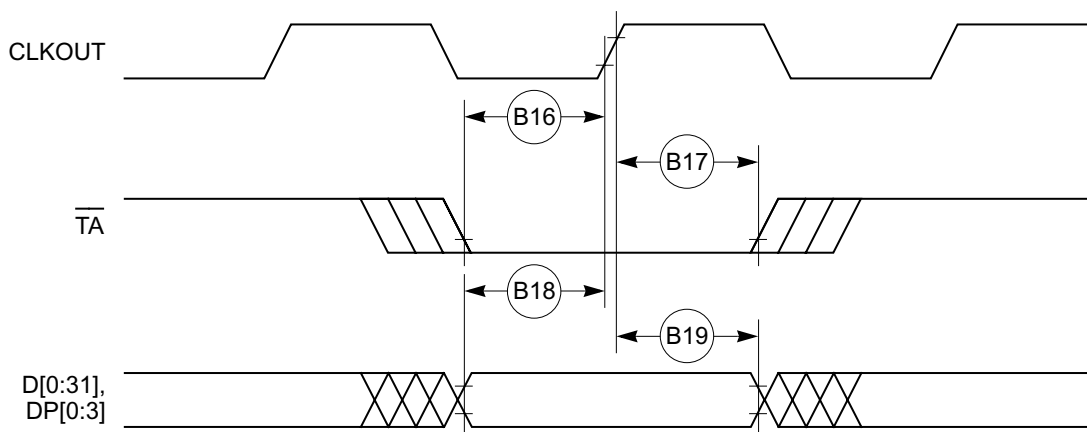
**Figure 6-5. Synchronous Active Pullup and Open-Drain Outputs Signals Timing**

Figure 6-6 provides the timing for the synchronous input signals.



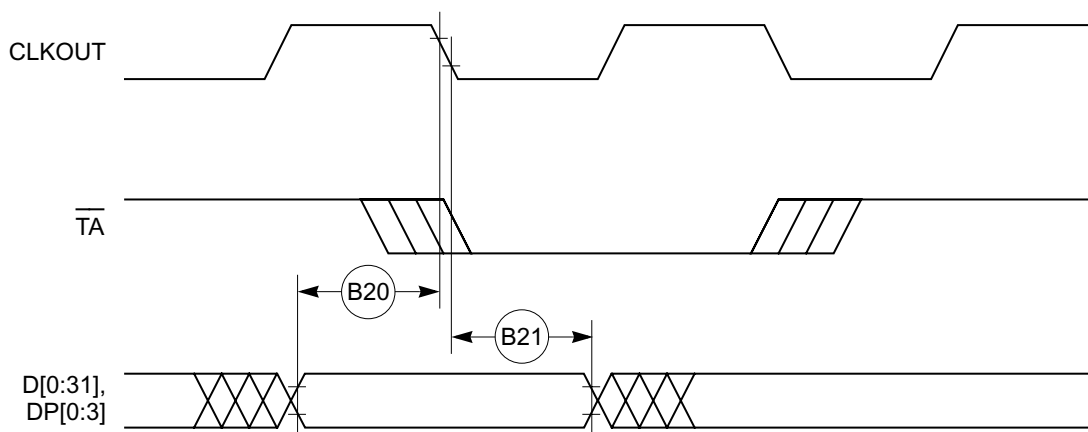
**Figure 6-6. Synchronous Input Signals Timing**

Figure 6-7 provides normal case timing for input data.



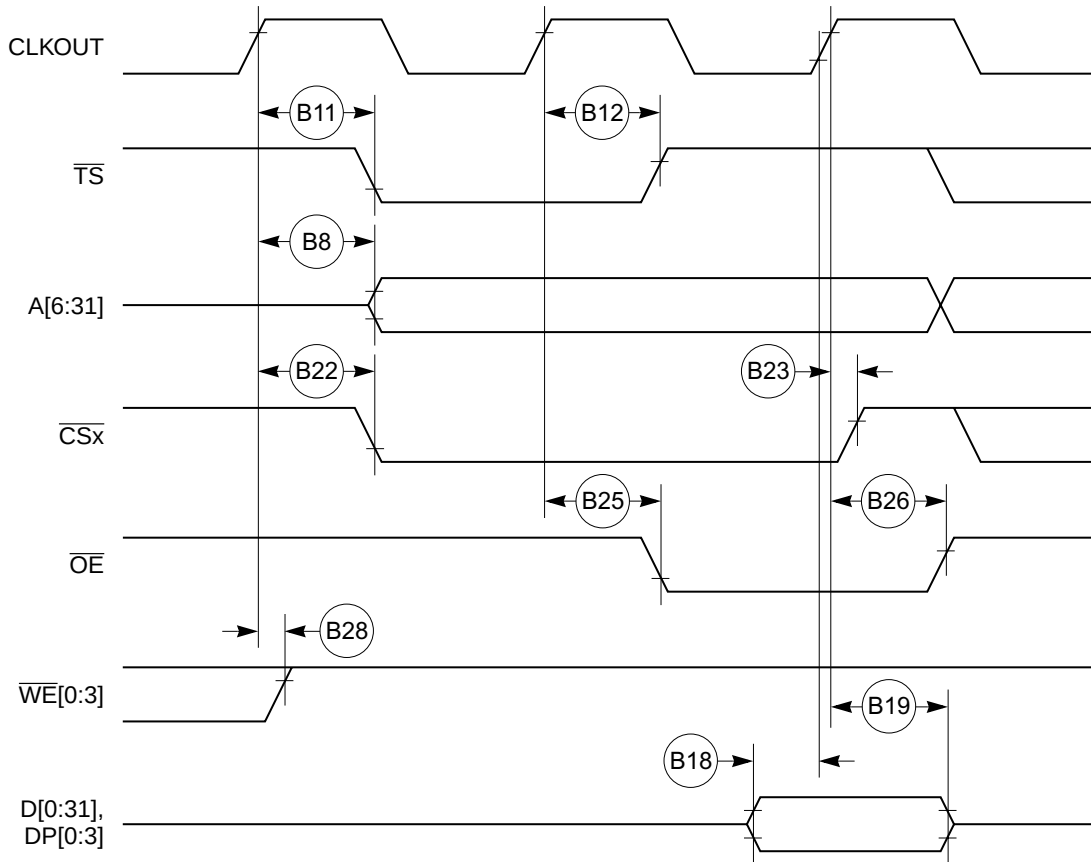
**Figure 6-7. Input Data Timing in Normal Case**

Figure 6-8 provides the timing for the input data controlled by the UPM in the memory controller.



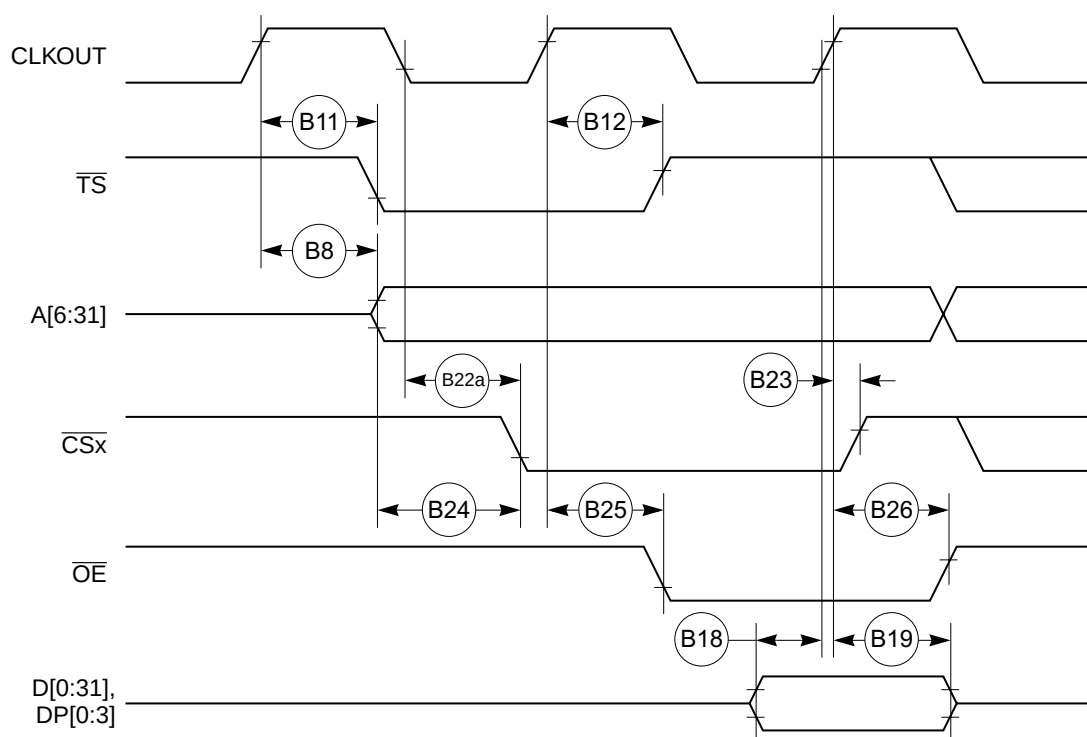
**Figure 6-8. Input Data Timing when Controlled by UPM in the Memory Controller**

Figure 6-9 through Figure 6-12 provide the timing for the external bus read controlled by various GPCM factors.

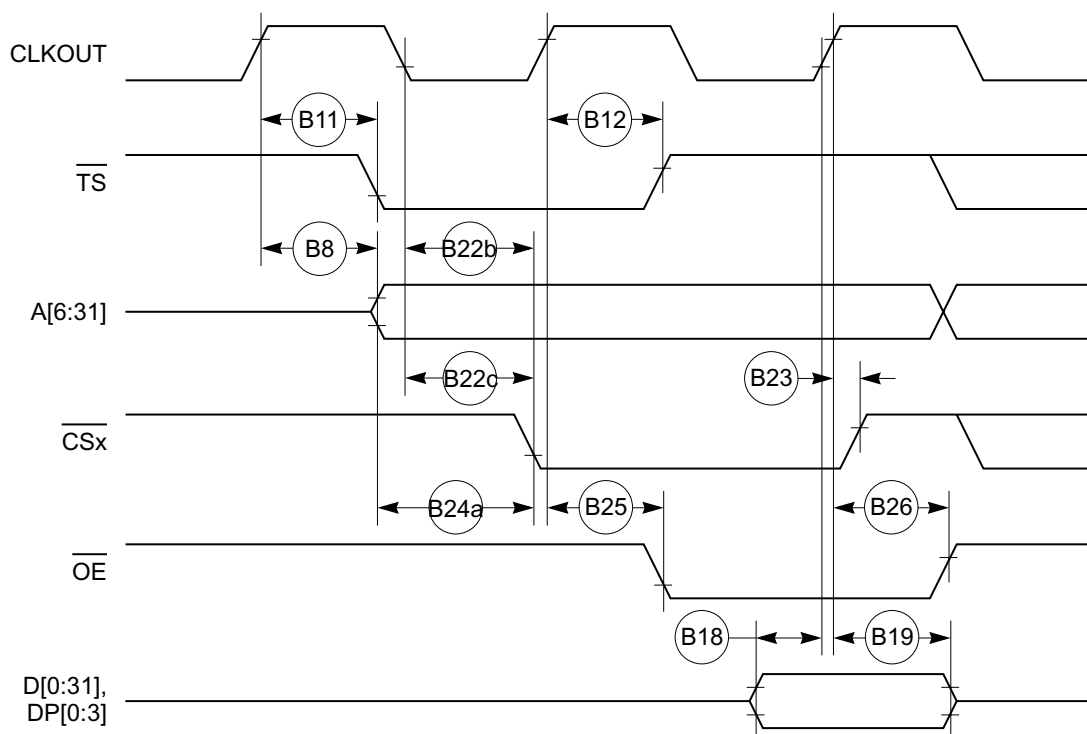


**Figure 6-9. External Bus Read Timing (GPCM Controlled—ACS = 00)**

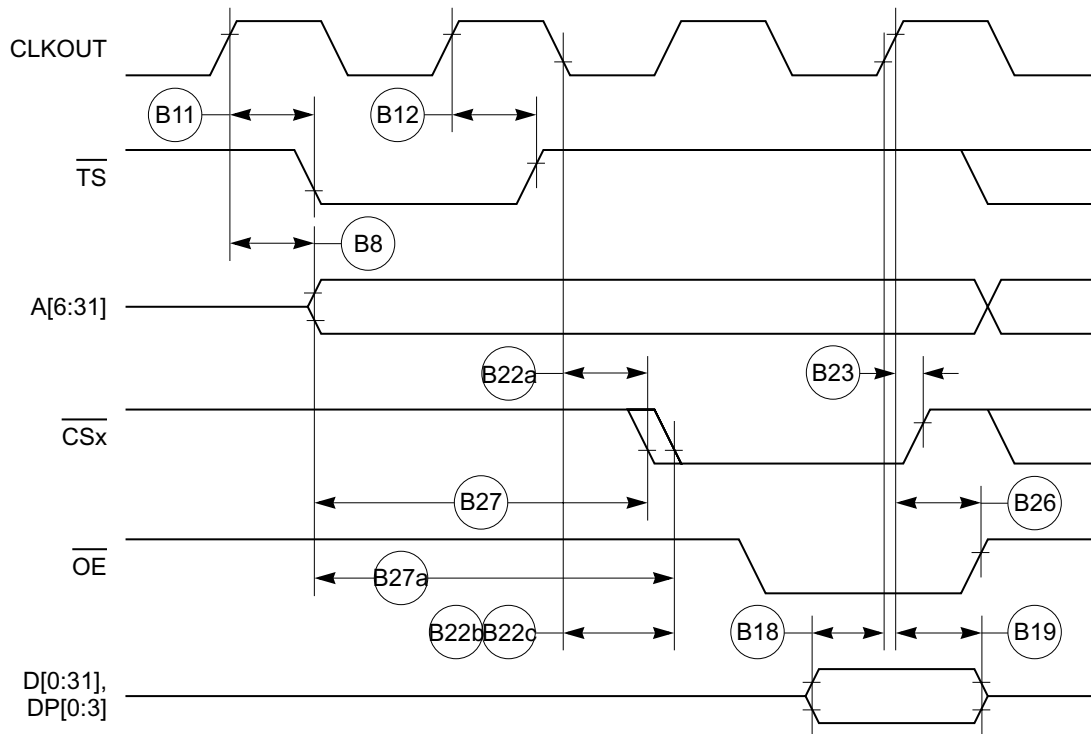




**Figure 6-10. External Bus Read Timing (GPCM Controlled—TRLX = 0, ACS = 10)**



**Figure 6-11. External Bus Read Timing (GPCM Controlled—TRLX = 0, ACS = 11)**



**Figure 6-12. External Bus Read Timing (GPCM Controlled—TRLX = 1, ACS = 10, ACS = 11)**

Figure 6-13 through Figure 6-15 provide the timing for the external bus write controlled by various GPCM factors.

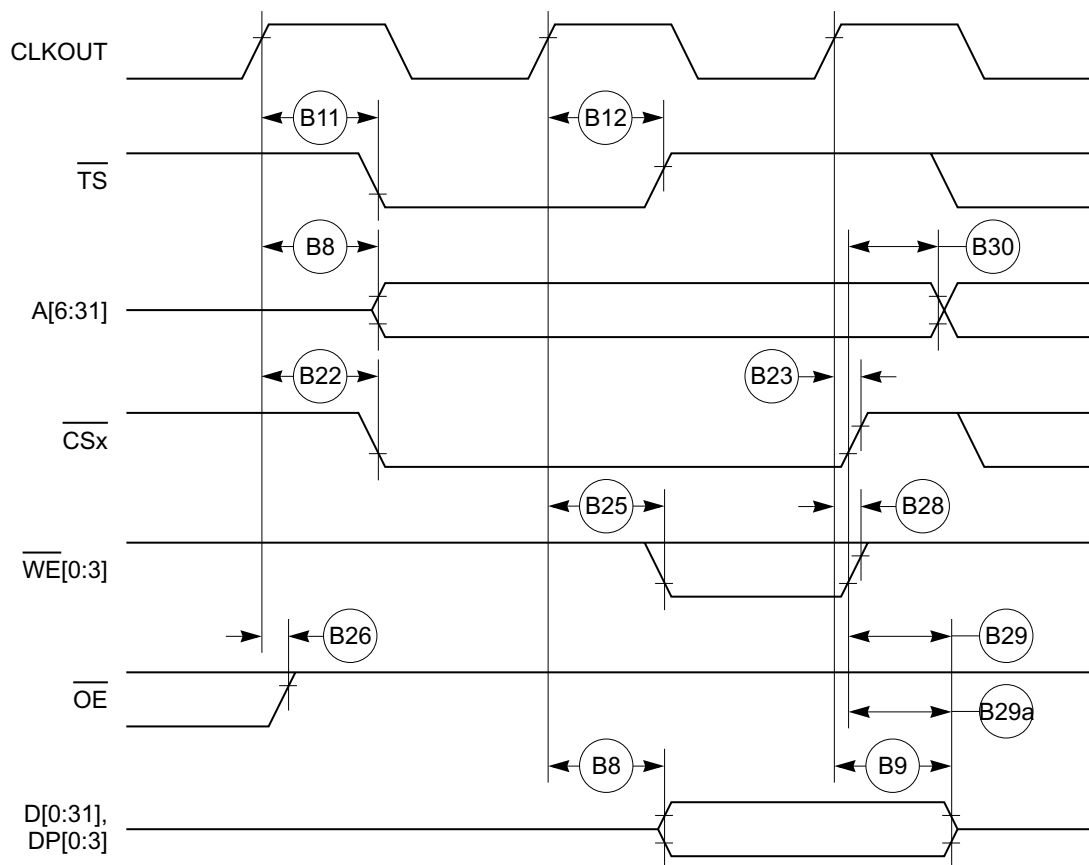
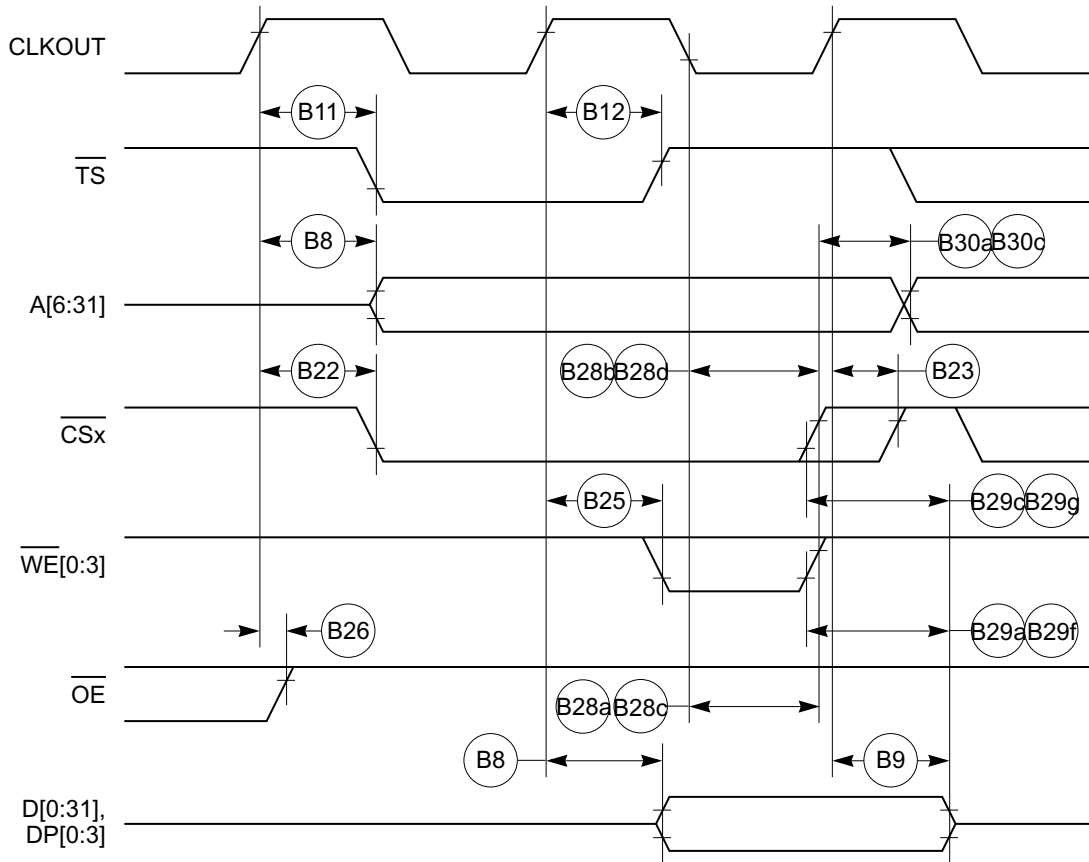
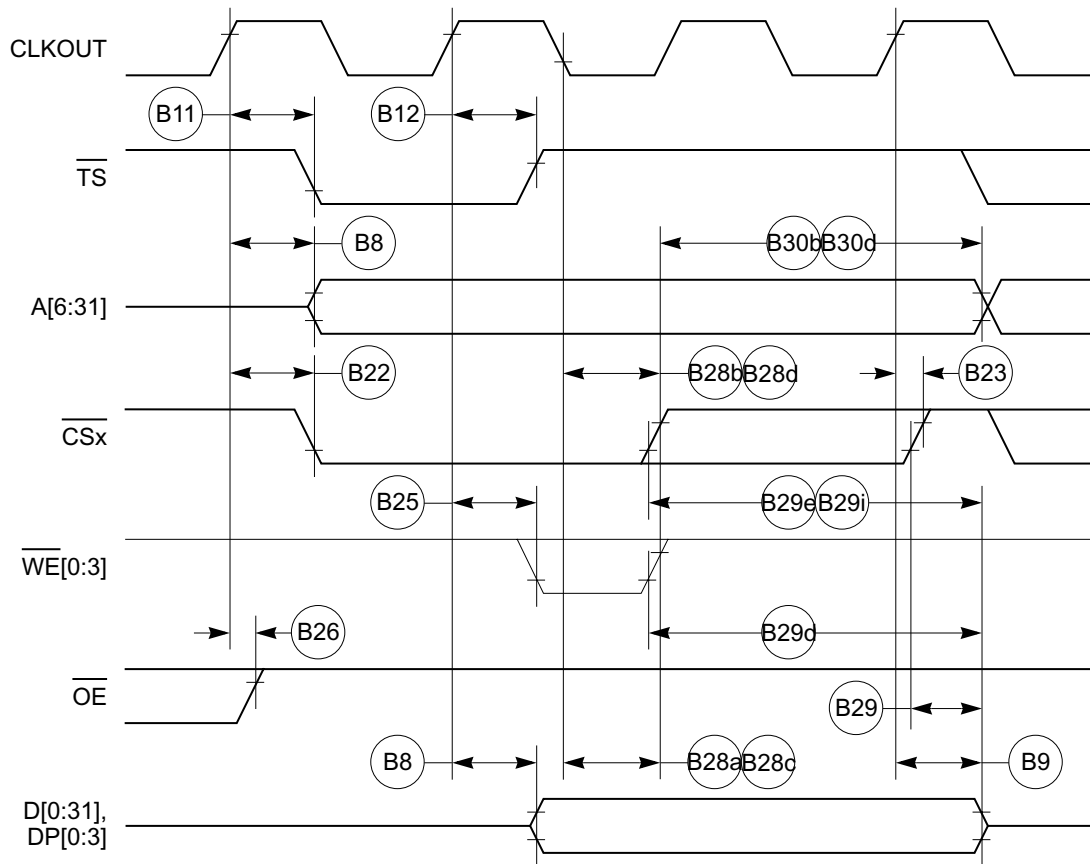


Figure 6-13. External Bus Write Timing (GPCM Controlled—TRLX = 0, CSNT = 0)

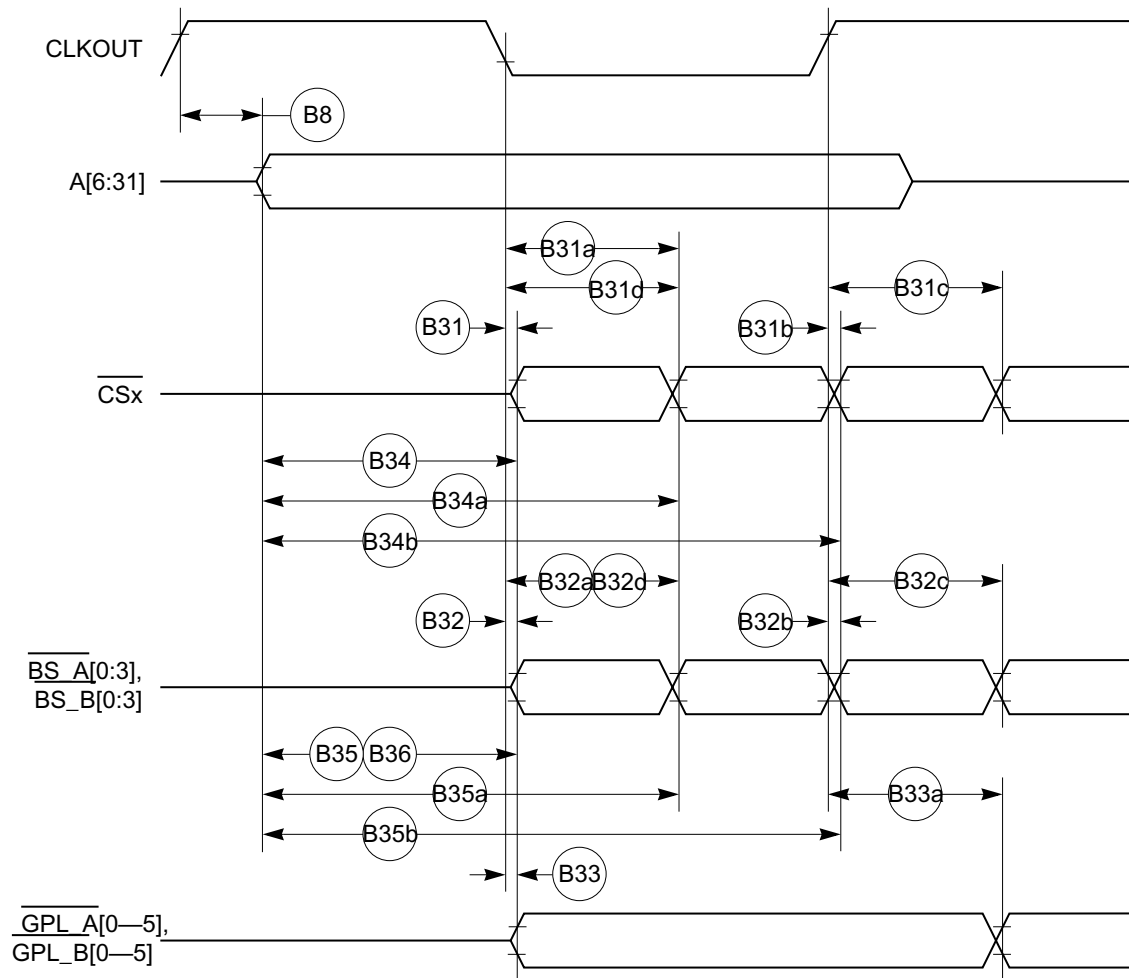


**Figure 6-14. External Bus Write Timing (GPCM Controlled—TRLX = 0, CSNT = 1)**



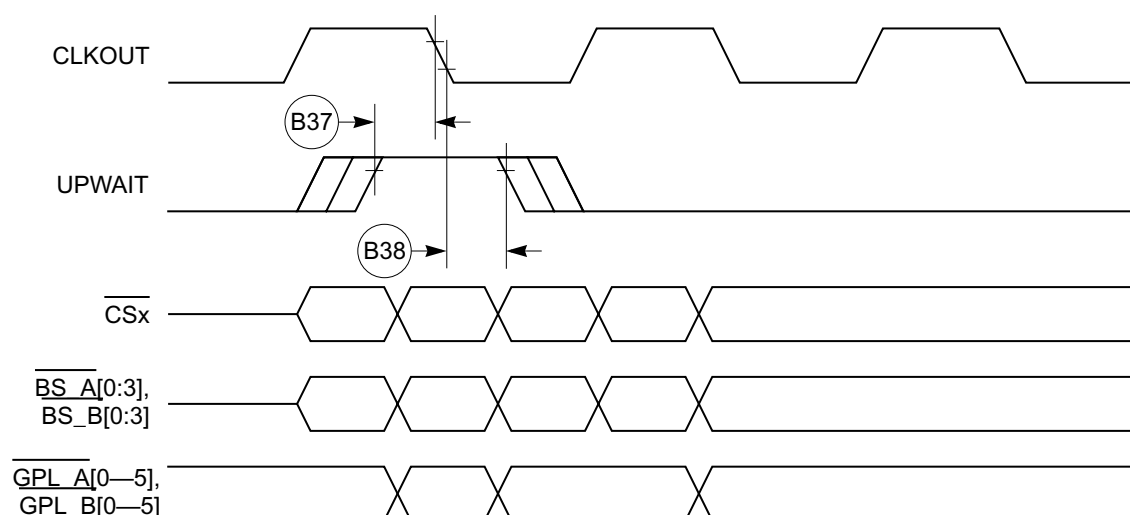
**Figure 6-15. External Bus Write Timing (GPCM Controlled—TRLX = 1, CSNT = 1)**

Figure 6-16 provides the timing for the external bus controlled by the UPM.



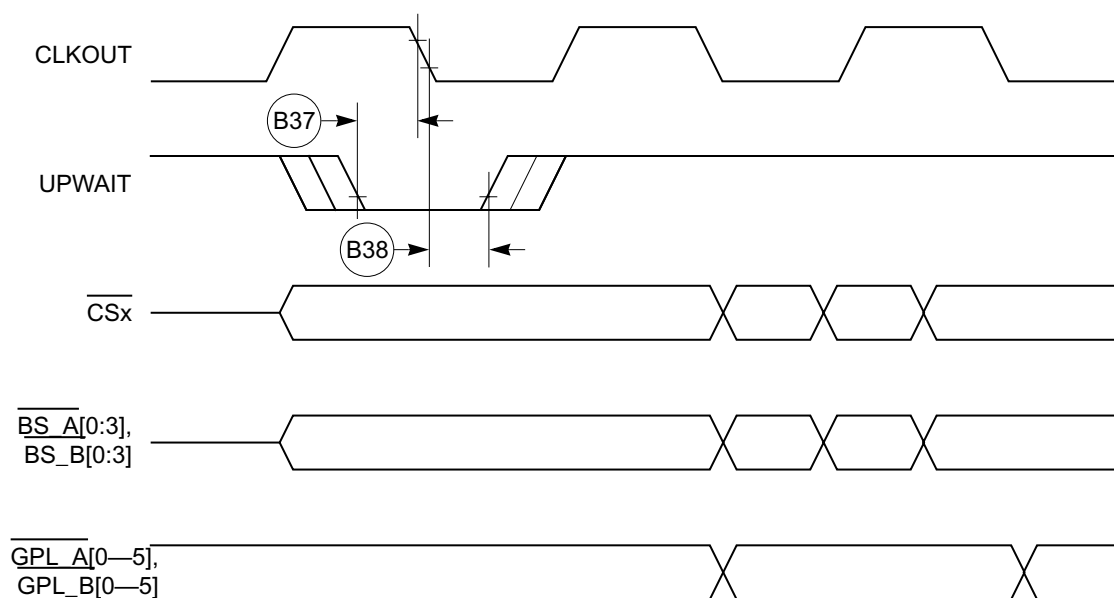
**Figure 6-16. External Bus Timing (UPM Controlled Signals)**

Figure 6-17 provides the timing for the asynchronous asserted UPWAIT signal controlled by the UPM.



**Figure 6-17. Asynchronous UPWAIT Asserted Detection in UPM Handled Cycles Timing**

Figure 6-18 provides the timing for the asynchronous negated UPWAIT signal controlled by the UPM.



**Figure 6-18. Asynchronous  $\overline{\text{UPWAIT}}$  Negated Detection in UPM Handled Cycles Timing**

Figure 6-19 provides the timing for the synchronous external master access controlled by the GPCM.

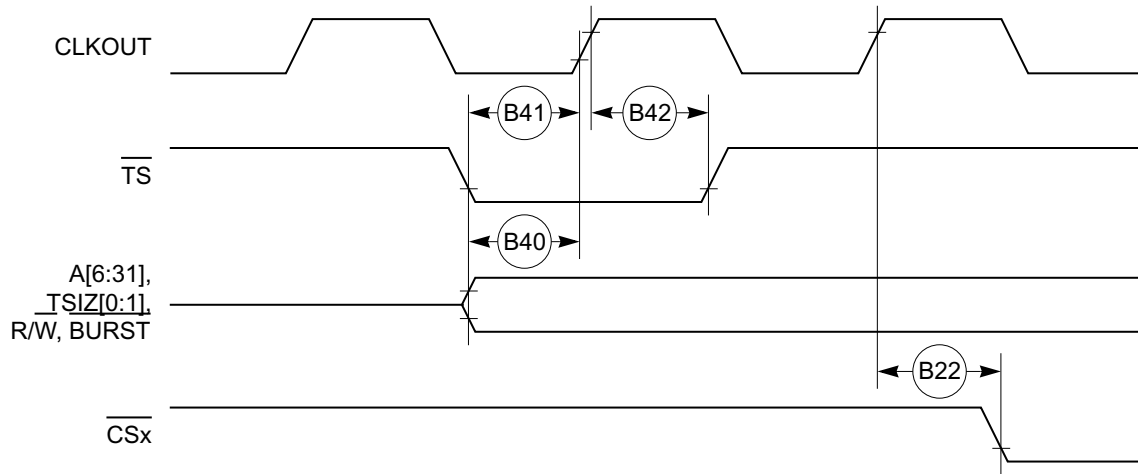
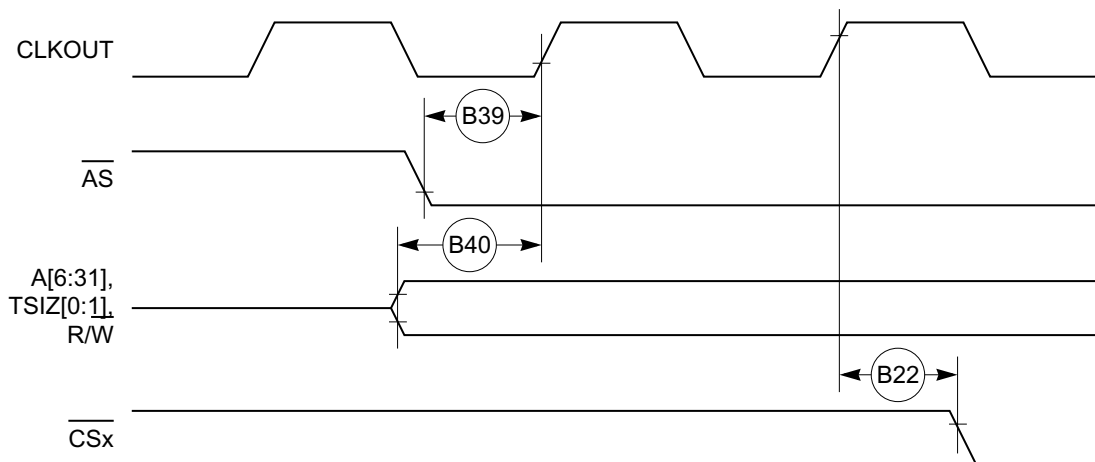


Figure 6-19. Synchronous External Master Access Timing (GPCM Handled ACS = 00)

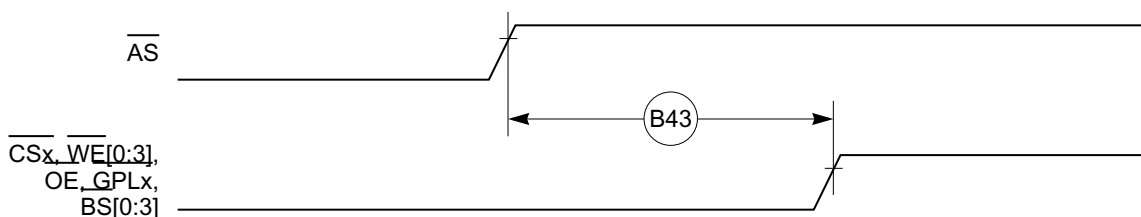


Figure 6-20 provides the timing for the asynchronous external master memory access controlled by the GPCM.



**Figure 6-20. Asynchronous External Master Memory Access Timing (GPCM Controlled—ACS = 00)**

Figure 6-21 provides the timing for the asynchronous external master control signals negation.



**Figure 6-21. Asynchronous External Master—Control Signals Negation Timing**

Table 6-7 provides interrupt timing for the MPC850.

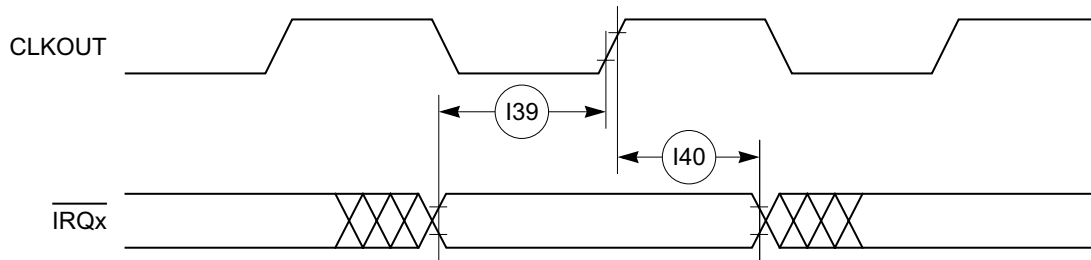
**Table 6-7. Interrupt Timing**

| Num | Characteristic <sup>1</sup>                                 | 50 MHz |     | 66MHz |     | 80 MHz |     | Unit |
|-----|-------------------------------------------------------------|--------|-----|-------|-----|--------|-----|------|
|     |                                                             | Min    | Max | Min   | Max | Min    | Max |      |
| I39 | $\overline{IRQx}$ valid to CLKOUT rising edge (set up time) | 6.00   | —   | 6.00  | —   | 6.00   | —   | ns   |
| I40 | $\overline{IRQx}$ hold time after CLKOUT.                   | 2.00   | —   | 2.00  | —   | 2.00   | —   | ns   |
| I41 | $\overline{IRQx}$ pulse width low                           | 3.00   | —   | 3.00  | —   | 3.00   | —   | ns   |
| I42 | $\overline{IRQx}$ pulse width high                          | 3.00   | —   | 3.00  | —   | 3.00   | —   | ns   |
| I43 | $\overline{IRQx}$ edge-to-edge time                         | 80.00  | —   | 121.0 | —   | 100.0  | —   | ns   |

<sup>1</sup> The timings I39 and I40 describe the testing conditions under which the  $\overline{\text{IRQ}}$  lines are tested when being defined as level sensitive. The  $\overline{\text{IRQ}}$  lines are synchronized internally and do not have to be asserted or negated with reference to the CLKOUT.

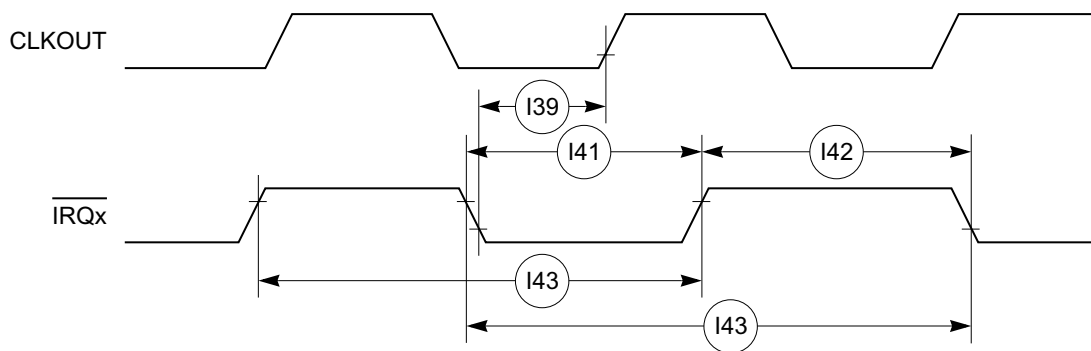
The timings I41, I42, and I43 are specified to allow the correct function of the  $\overline{\text{IRQ}}$  lines detection circuitry, and has no direct relation with the total system interrupt latency that the MPC850 is able to support

Figure 6-22 provides the interrupt detection timing for the external level-sensitive lines.



**Figure 6-22. Interrupt Detection Timing for External Level Sensitive Lines**

Figure 6-23 provides the interrupt detection timing for the external edge-sensitive lines.



**Figure 6-23. Interrupt Detection Timing for External Edge Sensitive Lines**

Table 6-8 shows the PCMCIA timing for the MPC850.

**Table 6-8. PCMCIA Timing**

| Num | Characteristic                                                                                                                   | 50MHz |       | 66MHz |       | 80 MHz |       | FFACTOR | Unit |
|-----|----------------------------------------------------------------------------------------------------------------------------------|-------|-------|-------|-------|--------|-------|---------|------|
|     |                                                                                                                                  | Min   | Max   | Min   | Max   | Min    | Max   |         |      |
| P44 | A[6–31], $\overline{\text{REG}}$ valid to PCMCIA strobe asserted. <sup>1</sup>                                                   | 13.00 | —     | 21.00 | —     | 17.00  | —     | 0.750   | ns   |
| P45 | A[6–31], $\overline{\text{REG}}$ valid to ALE negation. <sup>1</sup>                                                             | 18.00 | —     | 28.00 | —     | 23.00  | —     | 1.000   | ns   |
| P46 | CLKOUT to $\overline{\text{REG}}$ valid                                                                                          | 5.00  | 13.00 | 8.00  | 16.00 | 6.00   | 14.00 | 0.250   | ns   |
| P47 | CLKOUT to $\overline{\text{REG}}$ Invalid.                                                                                       | 6.00  | —     | 9.00  | —     | 7.00   | —     | 0.250   | ns   |
| P48 | CLKOUT to $\overline{\text{CE1}}$ , $\overline{\text{CE2}}$ asserted.                                                            | 5.00  | 13.00 | 8.00  | 16.00 | 6.00   | 14.00 | 0.250   |      |
| P49 | CLKOUT to $\overline{\text{CE1}}$ , $\overline{\text{CE2}}$ negated.                                                             | 5.00  | 13.00 | 8.00  | 16.00 | 6.00   | 14.00 | 0.250   | ns   |
| P50 | CLKOUT to $\overline{\text{PCOE}}$ , $\overline{\text{IORD}}$ , $\overline{\text{PCWE}}$ , $\overline{\text{IOWR}}$ assert time. | —     | 11.00 | —     | 11.00 | —      | 11.00 | —       | ns   |
| P51 | CLKOUT to $\overline{\text{PCOE}}$ , $\overline{\text{IORD}}$ , $\overline{\text{PCWE}}$ , $\overline{\text{IOWR}}$ negate time. | 2.00  | 11.00 | 2.00  | 11.00 | 2.00   | 11.00 | —       | ns   |
| P52 | CLKOUT to ALE assert time                                                                                                        | 5.00  | 13.00 | 8.00  | 16.00 | 6.00   | 14.00 | 0.250   | ns   |

Table 6-8. PCMCIA Timing (continued)

| Num | Characteristic                                                          | 50MHz |       | 66MHz |       | 80 MHz |       | FFACTOR | Unit |
|-----|-------------------------------------------------------------------------|-------|-------|-------|-------|--------|-------|---------|------|
|     |                                                                         | Min   | Max   | Min   | Max   | Min    | Max   |         |      |
| P53 | CLKOUT to ALE negate time                                               | —     | 13.00 | —     | 16.00 | —      | 14.00 | 0.250   | ns   |
| P54 | PCWE, $\overline{\text{IOWR}}$ negated to D[0–31] invalid. <sup>1</sup> | 3.00  | —     | 6.00  | —     | 4.00   | —     | 0.250   | ns   |
| P55 | $\overline{\text{WAIT\_B}}$ valid to CLKOUT rising edge. <sup>1</sup>   | 8.00  | —     | 8.00  | —     | 8.00   | —     | —       | ns   |
| P56 | CLKOUT rising edge to $\overline{\text{WAIT\_B}}$ invalid. <sup>1</sup> | 2.00  | —     | 2.00  | —     | 2.00   | —     | —       | ns   |

<sup>1</sup> PSST = 1. Otherwise add PSST times cycle time.  
 PSHT = 0. Otherwise add PSHT times cycle time.

These synchronous timings define when the  $\overline{\text{WAIT\_B}}$  signal is detected in order to freeze (or relieve) the PCMCIA current cycle. The  $\overline{\text{WAIT\_B}}$  assertion will be effective only if it is detected 2 cycles before the PSL timer expiration. See PCMCIA Interface in the MPC850 PowerQUICC User's Manual.

Figure 6-24 provides the PCMCIA access cycle timing for the external bus read.

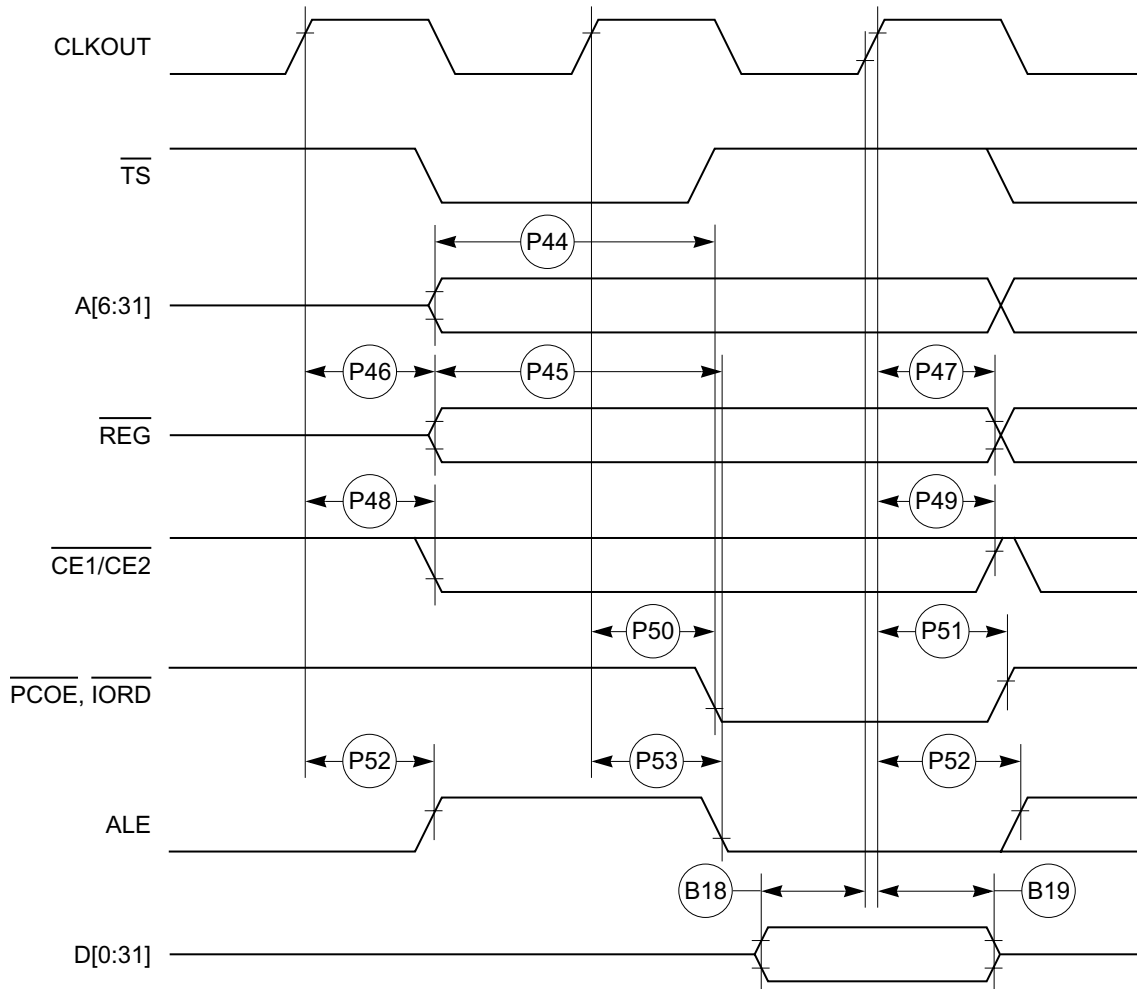


Figure 6-24. PCMCIA Access Cycles Timing External Bus Read

Figure 6-25 provides the PCMCIA access cycle timing for the external bus write.

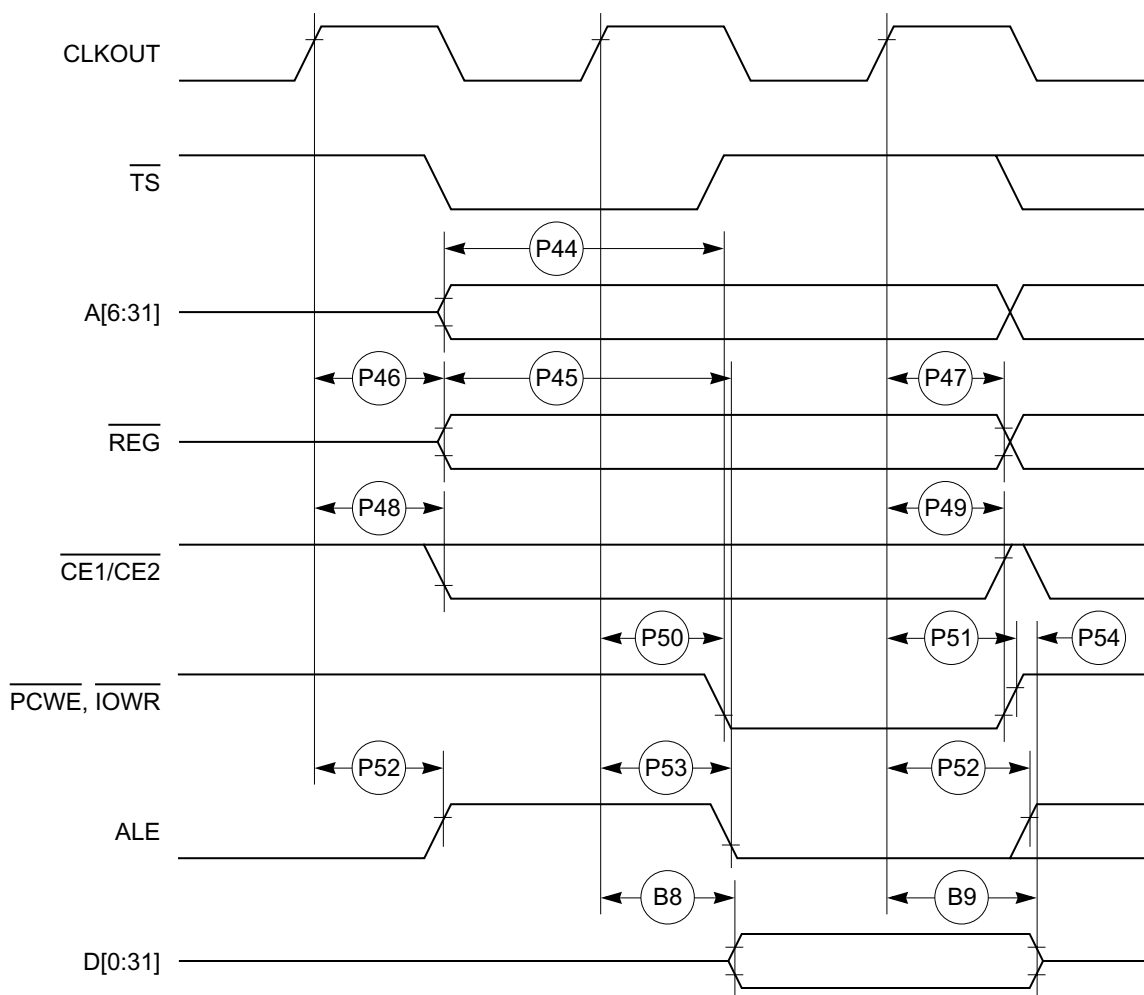


Figure 6-25. PCMCIA Access Cycles Timing External Bus Write

Figure 6-26 provides the PCMCIA WAIT signals detection timing.

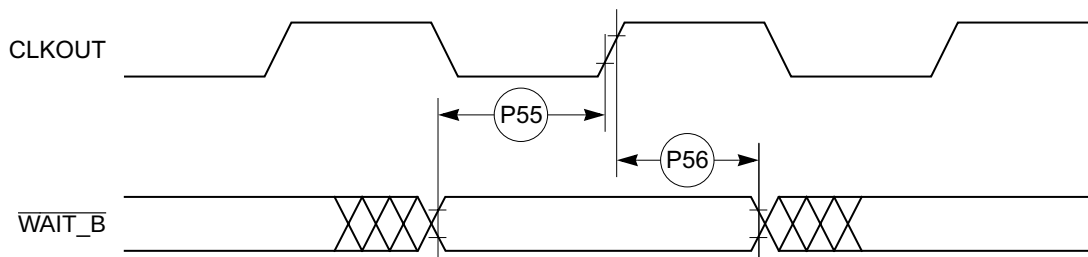


Figure 6-26. PCMCIA WAIT Signal Detection Timing

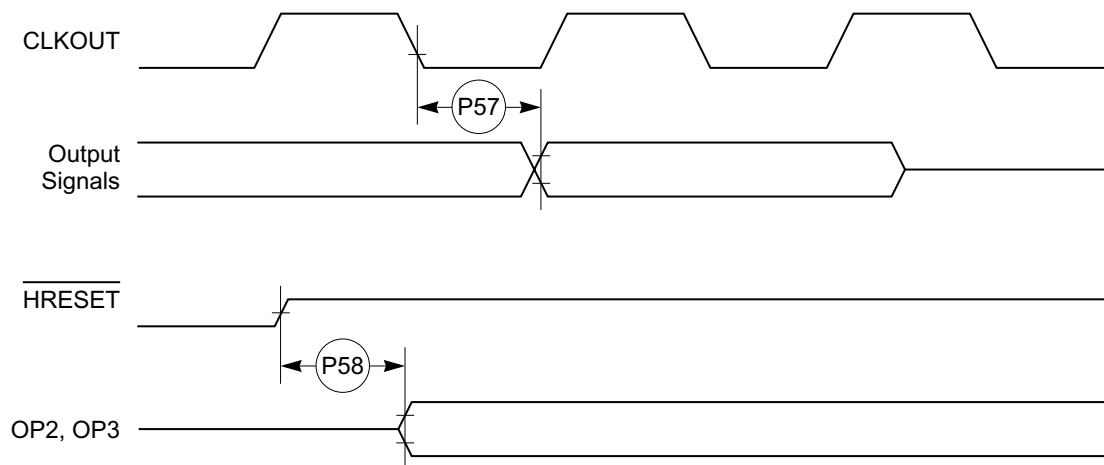
Table 6-9 shows the PCMCIA port timing for the MPC850.

**Table 6-9. PCMCIA Port Timing**

| Num | Characteristic                           | 50 MHz |       | 66 MHz |       | 80 MHz |       | Unit |
|-----|------------------------------------------|--------|-------|--------|-------|--------|-------|------|
|     |                                          | Min    | Max   | Min    | Max   | Min    | Max   |      |
| P57 | CLKOUT to OPx valid                      | —      | 19.00 | —      | 19.00 | —      | 19.00 | ns   |
| P58 | HRESET negated to OPx drive <sup>1</sup> | 18.00  | —     | 26.00  | —     | 22.00  | —     | ns   |
| P59 | IP_Xx valid to CLKOUT rising edge        | 5.00   | —     | 5.00   | —     | 5.00   | —     | ns   |
| P60 | CLKOUT rising edge to IP_Xx invalid      | 1.00   | —     | 1.00   | —     | 1.00   | —     | ns   |

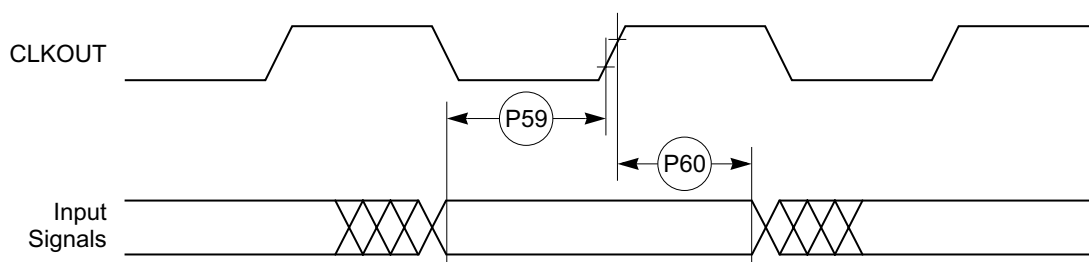
<sup>1</sup> OP2 and OP3 only.

Figure 6-27 provides the PCMCIA output port timing for the MPC850.



**Figure 6-27. PCMCIA Output Port Timing**

Figure 6-28 provides the PCMCIA output port timing for the MPC850.



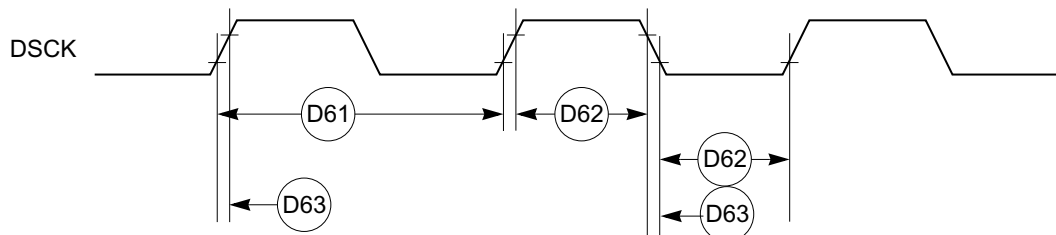
**Figure 6-28. PCMCIA Input Port Timing**

Table 6-10 shows the debug port timing for the MPC850.

**Table 6-10. Debug Port Timing**

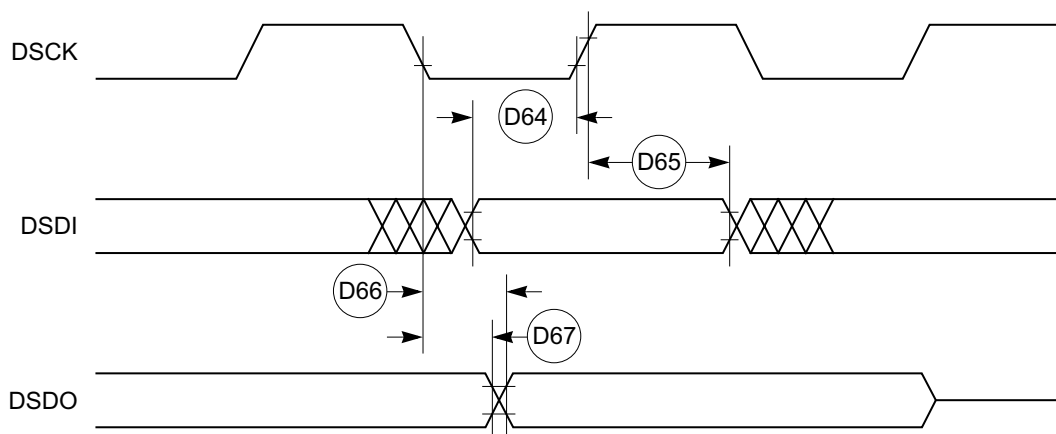
| Num | Characteristic              | 50 MHz |       | 66 MHz |       | 80 MHz |       | Unit |
|-----|-----------------------------|--------|-------|--------|-------|--------|-------|------|
|     |                             | Min    | Max   | Min    | Max   | Min    | Max   |      |
| D61 | DSCK cycle time             | 60.00  | —     | 91.00  | —     | 75.00  | —     | ns   |
| D62 | DSCK clock pulse width      | 25.00  | —     | 38.00  | —     | 31.00  | —     | ns   |
| D63 | DSCK rise and fall times    | 0.00   | 3.00  | 0.00   | 3.00  | 0.00   | 3.00  | ns   |
| D64 | DSDI input data setup time  | 8.00   | —     | 8.00   | —     | 8.00   | —     | ns   |
| D65 | DSDI data hold time         | 5.00   | —     | 5.00   | —     | 5.00   | —     | ns   |
| D66 | DSCK low to DSDO data valid | 0.00   | 15.00 | 0.00   | 15.00 | 0.00   | 15.00 | ns   |
| D67 | DSCK low to DSDO invalid    | 0.00   | 2.00  | 0.00   | 2.00  | 0.00   | 2.00  | ns   |

Figure 6-29 provides the input timing for the debug port clock.



**Figure 6-29. Debug Port Clock Input Timing**

Figure 6-30 provides the timing for the debug port.



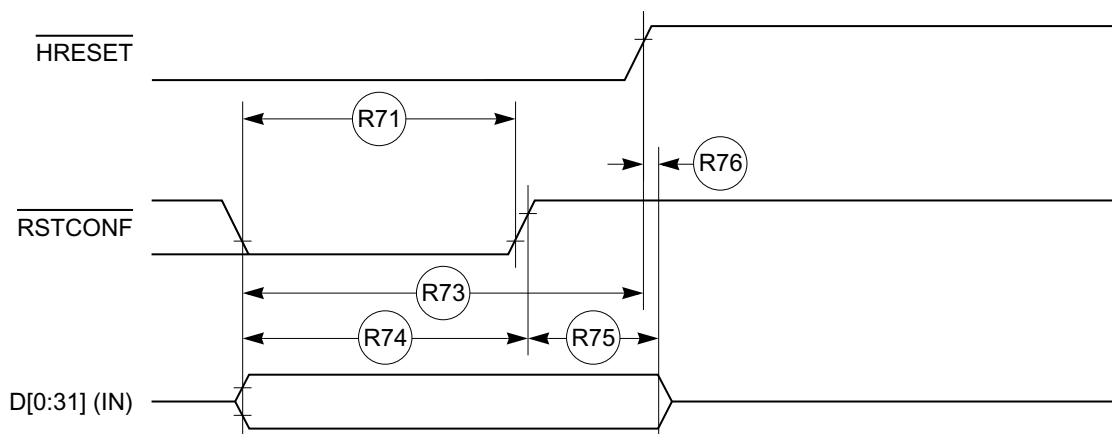
**Figure 6-30. Debug Port Timings**

Table 6-11 shows the reset timing for the MPC850.

**Table 6-11. Reset Timing**

| Num | Characteristic                                                                      | 50 MHz |       | 66MHz  |       | 80 MHz |       | FFACTOR | Unit |
|-----|-------------------------------------------------------------------------------------|--------|-------|--------|-------|--------|-------|---------|------|
|     |                                                                                     | Min    | Max   | Min    | Max   | Min    | Max   |         |      |
| R69 | CLKOUT to HRESET high impedance                                                     | —      | 20.00 | —      | 20.00 | —      | 20.00 | —       | ns   |
| R70 | CLKOUT to SRESET high impedance                                                     | —      | 20.00 | —      | 20.00 | —      | 20.00 | —       | ns   |
| R71 | RSTCONF pulse width                                                                 | 340.00 | —     | 515.00 | —     | 425.00 | —     | 17.000  | ns   |
| R72 |                                                                                     | —      | —     | —      | —     | —      | —     | —       |      |
| R73 | Configuration data to HRESET rising edge set up time                                | 350.00 | —     | 505.00 | —     | 425.00 | —     | 15.000  | ns   |
| R74 | Configuration data to RSTCONF rising edge set up time                               | 350.00 | —     | 350.00 | —     | 350.00 | —     | —       | ns   |
| R75 | Configuration data hold time after RSTCONF negation                                 | 0.00   | —     | 0.00   | —     | 0.00   | —     | —       | ns   |
| R76 | Configuration data hold time after HRESET negation                                  | 0.00   | —     | 0.00   | —     | 0.00   | —     | —       | ns   |
| R77 | HRESET and RSTCONF asserted to data out drive                                       | —      | 25.00 | —      | 25.00 | —      | 25.00 | —       | ns   |
| R78 | RSTCONF negated to data out high impedance.                                         | —      | 25.00 | —      | 25.00 | —      | 25.00 | —       | ns   |
| R79 | CLKOUT of last rising edge before chip tristates HRESET to data out high impedance. | —      | 25.00 | —      | 25.00 | —      | 25.00 | —       | ns   |
| R80 | DSDI, DSCK set up                                                                   | 60.00  | —     | 90.00  | —     | 75.00  | —     | 3.000   | ns   |
| R81 | DSDI, DSCK hold time                                                                | 0.00   | —     | 0.00   | —     | 0.00   | —     | —       | ns   |
| R82 | SRESET negated to CLKOUT rising edge for DSDI and DSCK sample                       | 160.00 | —     | 242.00 | —     | 200.00 | —     | 8.000   | ns   |

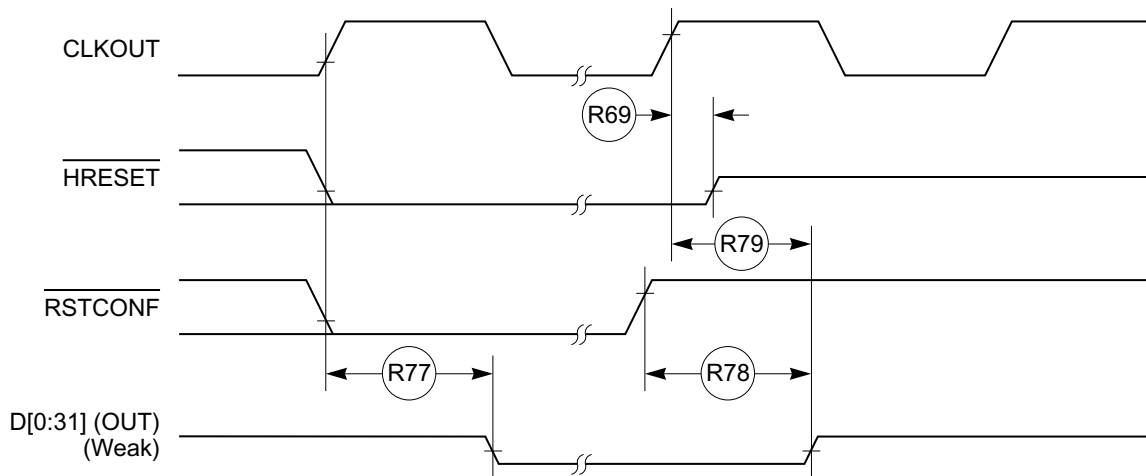
Figure 6-31 shows the reset timing for the data bus configuration.



**Figure 6-31. Reset Timing—Configuration from Data Bus**

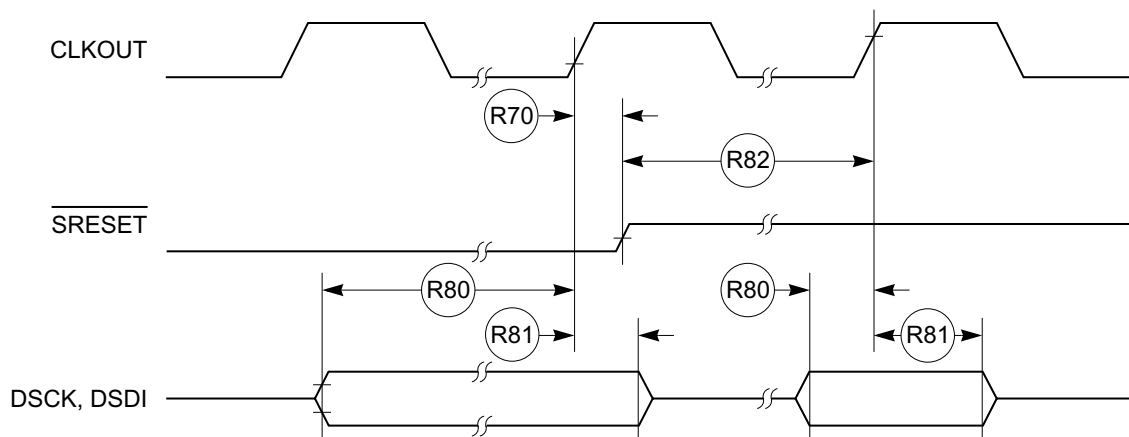


Figure 6-32 provides the reset timing for the data bus weak drive during configuration.



**Figure 6-32. Reset Timing—Data Bus Weak Drive during Configuration**

Figure 6-33 provides the reset timing for the debug port configuration.



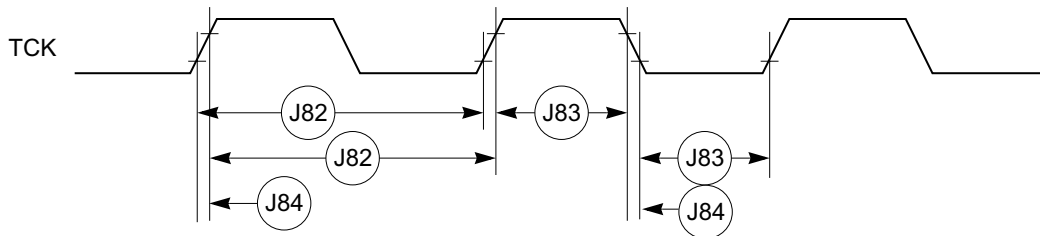
**Figure 6-33. Reset Timing—Debug Port Configuration**

# Part VII IEEE 1149.1 Electrical Specifications

Table 7-12 provides the JTAG timings for the MPC850 as shown in Figure 7-34 to Figure 7-37.

**Table 7-12. JTAG Timing**

| Num | Characteristic                                         | 50 MHz |       | 66MHz  |       | 80 MHz |       | Unit |
|-----|--------------------------------------------------------|--------|-------|--------|-------|--------|-------|------|
|     |                                                        | Min    | Max   | Min    | Max   | Min    | Max   |      |
| J82 | TCK cycle time                                         | 100.00 | —     | 100.00 | —     | 100.00 | —     | ns   |
| J83 | TCK clock pulse width measured at 1.5 V                | 40.00  | —     | 40.00  | —     | 40.00  | —     | ns   |
| J84 | TCK rise and fall times                                | 0.00   | 10.00 | 0.00   | 10.00 | 0.00   | 10.00 | ns   |
| J85 | TMS, TDI data setup time                               | 5.00   | —     | 5.00   | —     | 5.00   | —     | ns   |
| J86 | TMS, TDI data hold time                                | 25.00  | —     | 25.00  | —     | 25.00  | —     | ns   |
| J87 | TCK low to TDO data valid                              | —      | 27.00 | —      | 27.00 | —      | 27.00 | ns   |
| J88 | TCK low to TDO data invalid                            | 0.00   | —     | 0.00   | —     | 0.00   | —     | ns   |
| J89 | TCK low to TDO high impedance                          | —      | 20.00 | —      | 20.00 | —      | 20.00 | ns   |
| J90 | $\overline{\text{TRST}}$ assert time                   | 100.00 | —     | 100.00 | —     | 100.00 | —     | ns   |
| J91 | $\overline{\text{TRST}}$ setup time to TCK low         | 40.00  | —     | 40.00  | —     | 40.00  | —     | ns   |
| J92 | TCK falling edge to output valid                       | —      | 50.00 | —      | 50.00 | —      | 50.00 | ns   |
| J93 | TCK falling edge to output valid out of high impedance | —      | 50.00 | —      | 50.00 | —      | 50.00 | ns   |
| J94 | TCK falling edge to output high impedance              | —      | 50.00 | —      | 50.00 | —      | 50.00 | ns   |
| J95 | Boundary scan input valid to TCK rising edge           | 50.00  | —     | 50.00  | —     | 50.00  | —     | ns   |
| J96 | TCK rising edge to boundary scan input invalid         | 50.00  | —     | 50.00  | —     | 50.00  | —     | ns   |



**Figure 7-34. JTAG Test Clock Input Timing**

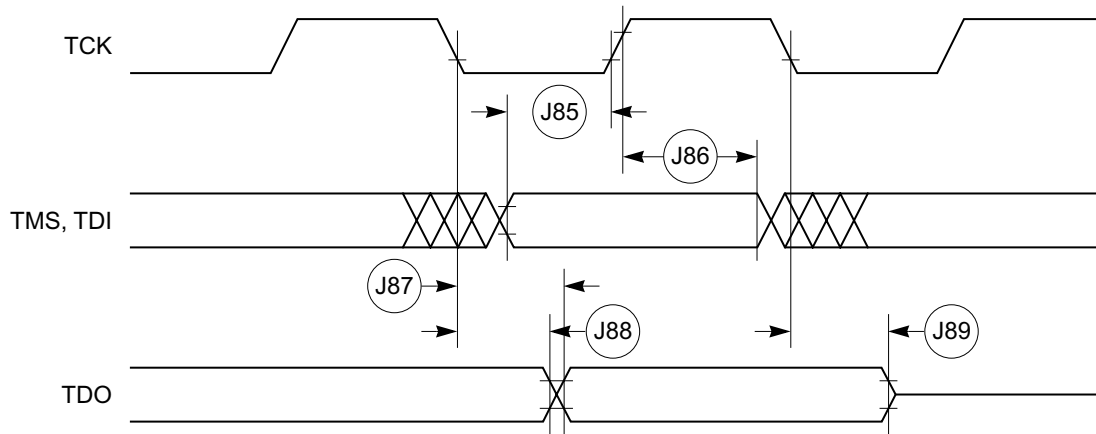


Figure 7-35. JTAG Test Access Port Timing Diagram

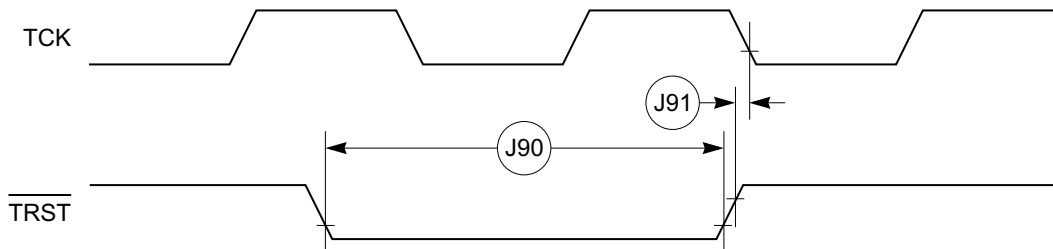
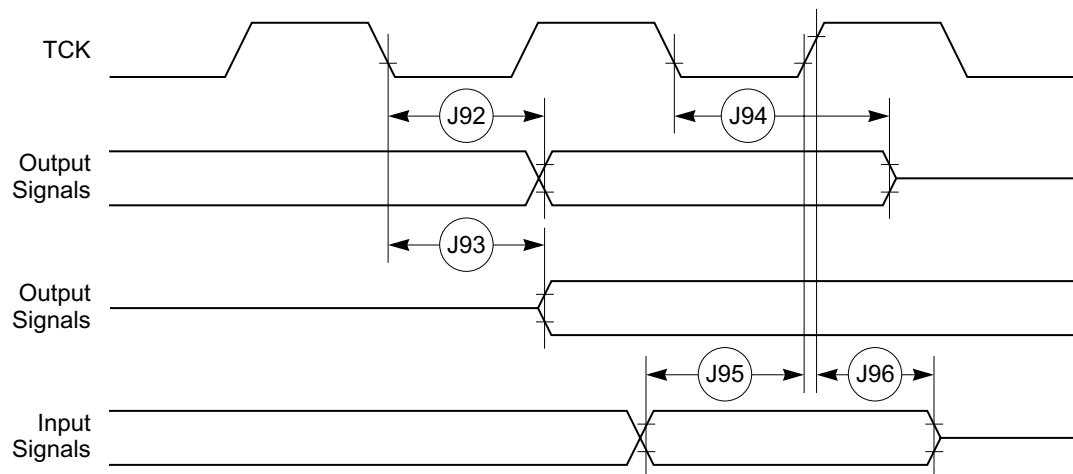
Figure 7-36. JTAG  $\overline{\text{TRST}}$  Timing Diagram

Figure 7-37. Boundary Scan (JTAG) Timing Diagram

## Part VIII CPM Electrical Characteristics

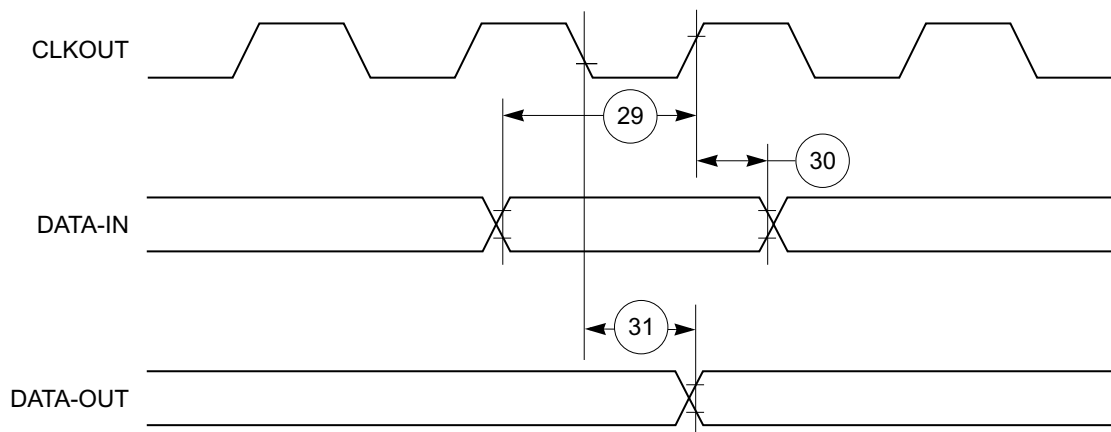
This section provides the AC and DC electrical specifications for the communications processor module (CPM) of the MPC850.

## 8.1 PIO AC Electrical Specifications

Table 8-13 provides the parallel I/O timings for the MPC850 as shown in Figure 8-38.

**Table 8-13. Parallel I/O Timing**

| Num | Characteristic                                                       | All Frequencies |     | Unit |
|-----|----------------------------------------------------------------------|-----------------|-----|------|
|     |                                                                      | Min             | Max |      |
| 29  | Data-in setup time to clock high                                     | 15              | —   | ns   |
| 30  | Data-in hold time from clock high                                    | 7.5             | —   | ns   |
| 31  | Clock low to data-out valid (CPU writes data, control, or direction) | —               | 25  | ns   |



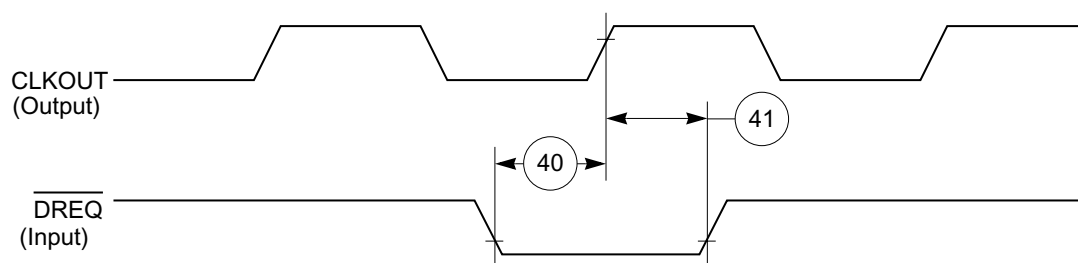
**Figure 8-38. Parallel I/O Data-In/Data-Out Timing Diagram**

## 8.2 IDMA Controller AC Electrical Specifications

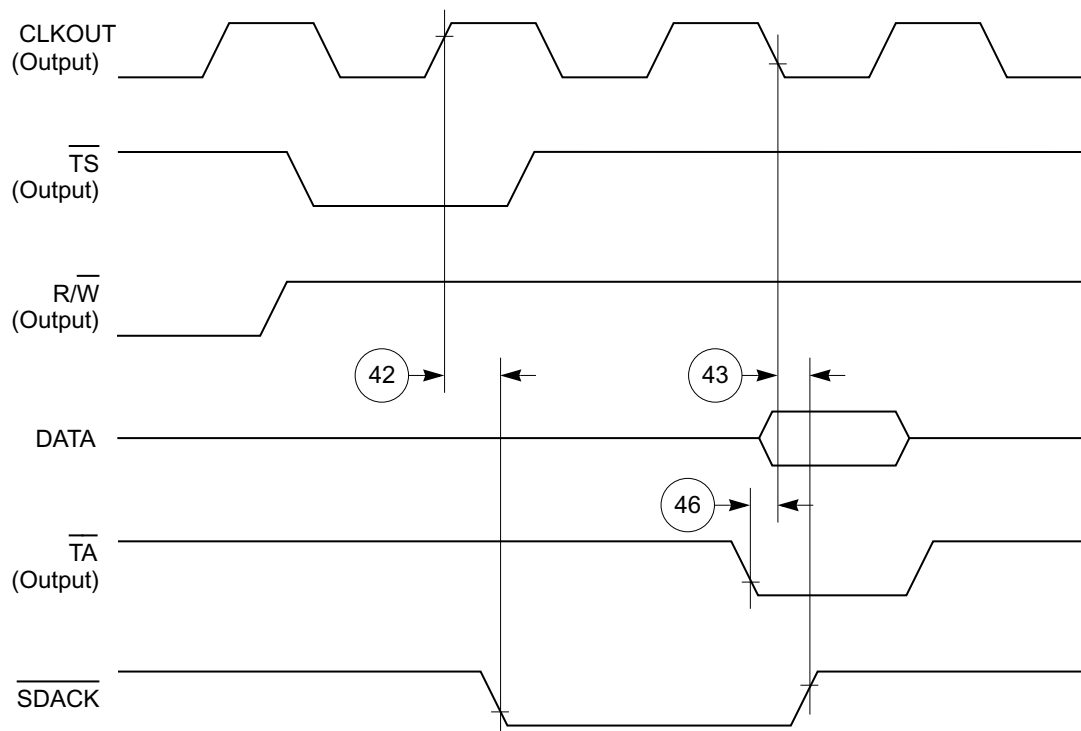
Table 8-14 provides the IDMA controller timings as shown in Figure 8-39 to Figure 8-42.

**Table 8-14. IDMA Controller Timing**

| Num | Characteristic                                                                                           | All Frequencies |       | Unit |
|-----|----------------------------------------------------------------------------------------------------------|-----------------|-------|------|
|     |                                                                                                          | Min             | Max   |      |
| 40  | DREQ setup time to clock high                                                                            | 7.00            | —     | ns   |
| 41  | DREQ hold time from clock high                                                                           | 3.00            | —     | ns   |
| 42  | SDACK assertion delay from clock high                                                                    | —               | 12.00 | ns   |
| 43  | SDACK negation delay from clock low                                                                      | —               | 12.00 | ns   |
| 44  | SDACK negation delay from $\overline{TA}$ low                                                            | —               | 20.00 | ns   |
| 45  | SDACK negation delay from clock high                                                                     | —               | 15.00 | ns   |
| 46  | $\overline{TA}$ assertion to falling edge of the clock setup time (applies to external $\overline{TA}$ ) | 7.00            | —     | ns   |

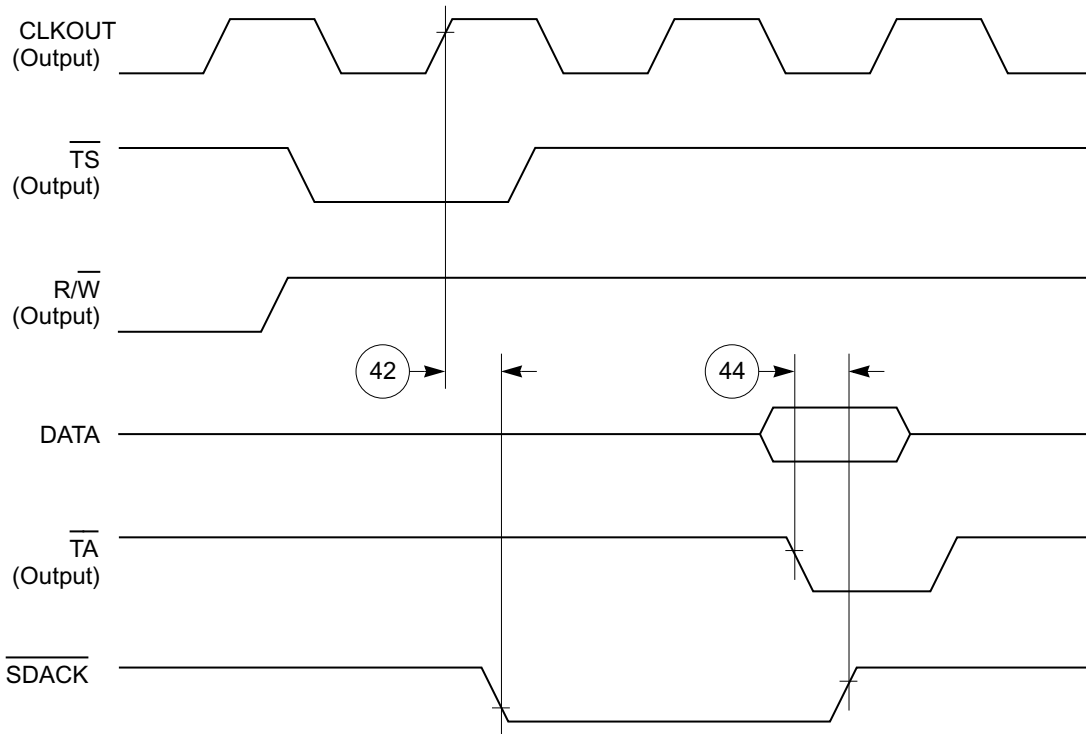


**Figure 8-39. IDMA External Requests Timing Diagram**



**Figure 8-40.  $\overline{\text{SDACK}}$  Timing Diagram—Peripheral Write,  $\overline{\text{TA}}$  Sampled Low at the Falling Edge of the Clock**

# **Freescale Semiconductor, Inc.** **IDMA Controller AC Electrical Specifications**



**Figure 8-41.  $\overline{SDACK}$  Timing Diagram—Peripheral Write,  $\overline{TA}$  Sampled High at the Falling Edge of the Clock**

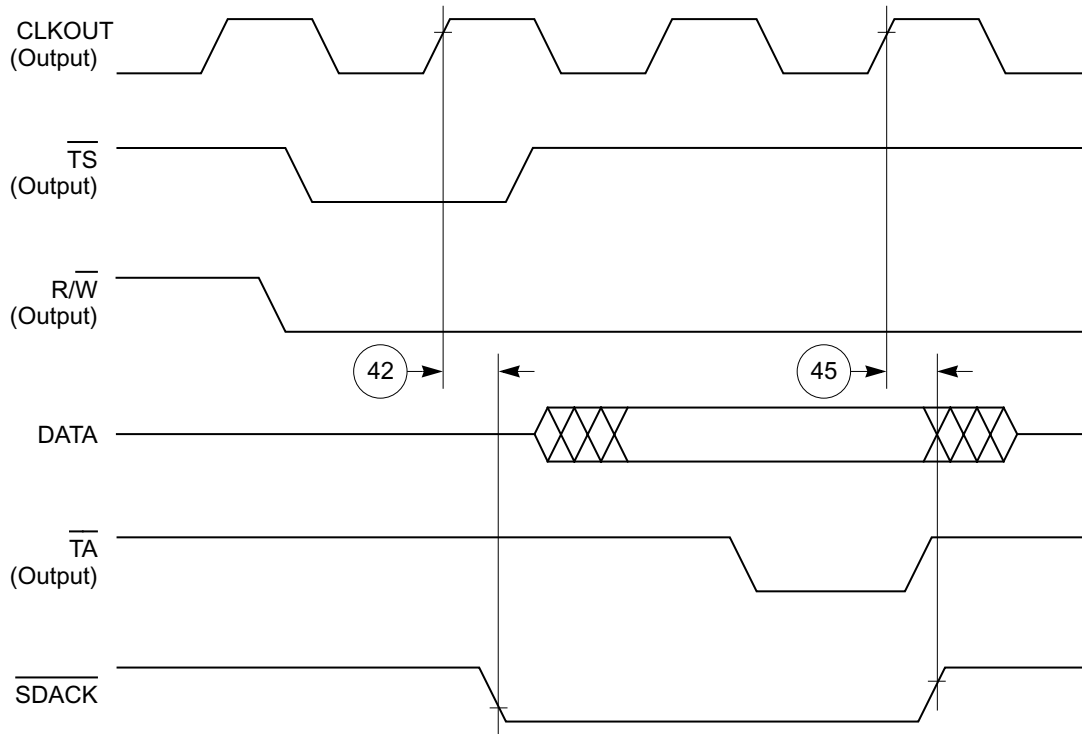


Figure 8-42.  $\overline{\text{SDACK}}$  Timing Diagram—Peripheral Read

## 8.3 Baud Rate Generator AC Electrical Specifications

Table 8-15 provides the baud rate generator timings as shown in Figure 8-43.

Table 8-15. Baud Rate Generator Timing

| Num | Characteristic          | All Frequencies |       | Unit |
|-----|-------------------------|-----------------|-------|------|
|     |                         | Min             | Max   |      |
| 50  | BRGO rise and fall time | —               | 10.00 | ns   |
| 51  | BRGO duty cycle         | 40.00           | 60.00 | %    |
| 52  | BRGO cycle              | 40.00           | —     | ns   |

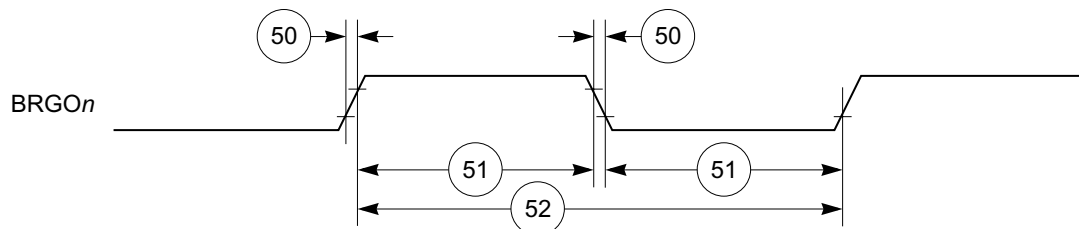


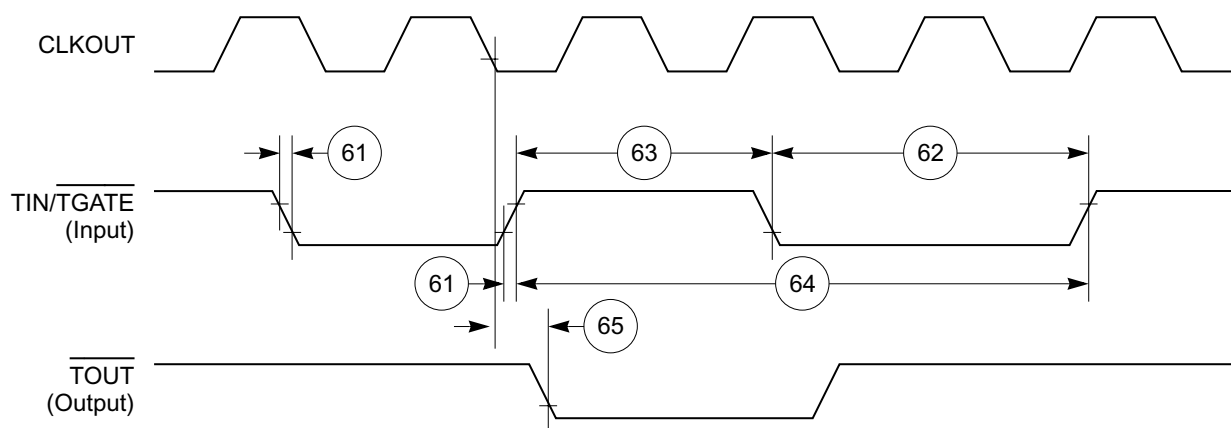
Figure 8-43. Baud Rate Generator Timing Diagram

## 8.4 Timer AC Electrical Specifications

Table 8-16 provides the baud rate generator timings as shown in Figure 8-44.

**Table 8-16. Timer Timing**

| Num | Characteristic               | All Frequencies |       | Unit |
|-----|------------------------------|-----------------|-------|------|
|     |                              | Min             | Max   |      |
| 61  | TIN/TGATE rise and fall time | 10.00           | —     | ns   |
| 62  | TIN/TGATE low time           | 1.00            | —     | clk  |
| 63  | TIN/TGATE high time          | 2.00            | —     | clk  |
| 64  | TIN/TGATE cycle time         | 3.00            | —     | clk  |
| 65  | CLKO high to TOUT valid      | 3.00            | 25.00 | ns   |



**Figure 8-44. CPM General-Purpose Timers Timing Diagram**

## 8.5 Serial Interface AC Electrical Specifications

Table 8-17 provides the serial interface timings as shown in Figure 8-45 to Figure 8-49.

**Table 8-17. SI Timing**

| Num | Characteristic                                               | All Frequencies |             | Unit |
|-----|--------------------------------------------------------------|-----------------|-------------|------|
|     |                                                              | Min             | Max         |      |
| 70  | L1RCLK, L1TCLK frequency (DSC = 0) <sup>1, 2</sup>           | —               | SYNCCLK/2.5 | MHz  |
| 71  | L1RCLK, L1TCLK width low (DSC = 0) <sup>2</sup>              | P + 10          | —           | ns   |
| 71a | L1RCLK, L1TCLK width high (DSC = 0) <sup>3</sup>             | P + 10          | —           | ns   |
| 72  | L1TXD, L1STn, L1RQ, L1xCLKO rise/fall time                   | —               | 15.00       | ns   |
| 73  | L1RSYNC, L1TSYNC valid to L1xCLK edge Edge (SYNC setup time) | 20.00           | —           | ns   |



**Table 8-17. SI Timing (continued)**

| Num | Characteristic                                                       | All Frequencies |                    | Unit   |
|-----|----------------------------------------------------------------------|-----------------|--------------------|--------|
|     |                                                                      | Min             | Max                |        |
| 74  | L1xCLK edge to L1RSYNC, L1TSYNC, invalid (SYNC hold time)            | 35.00           | —                  | ns     |
| 75  | L1RSYNC, L1TSYNC rise/fall time                                      | —               | 15.00              | ns     |
| 76  | L1RXD valid to L1xCLK edge (L1RXD setup time)                        | 17.00           | —                  | ns     |
| 77  | L1xCLK edge to L1RXD invalid (L1RXD hold time)                       | 13.00           | —                  | ns     |
| 78  | L1xCLK edge to L1ST $n$ valid <sup>4</sup>                           | 10.00           | 45.00              | ns     |
| 78A | L1SYNC valid to L1ST $n$ valid                                       | 10.00           | 45.00              | ns     |
| 79  | L1xCLK edge to L1ST $n$ invalid                                      | 10.00           | 45.00              | ns     |
| 80  | L1xCLK edge to L1TXD valid                                           | 10.00           | 55.00              | ns     |
| 80A | L1TSYNC valid to L1TXD valid <sup>4</sup>                            | 10.00           | 55.00              | ns     |
| 81  | L1xCLK edge to L1TXD high impedance                                  | 0.00            | 42.00              | ns     |
| 82  | L1RCLK, L1TCLK frequency (DSC =1)                                    | —               | 16.00 or SYNCCLK/2 | MHz    |
| 83  | L1RCLK, L1TCLK width low (DSC =1)                                    | P + 10          | —                  | ns     |
| 83A | L1RCLK, L1TCLK width high (DSC = 1) <sup>3</sup>                     | P + 10          | —                  | ns     |
| 84  | L1CLK edge to L1CLKO valid (DSC = 1)                                 | —               | 30.00              | ns     |
| 85  | L1RQ valid before falling edge of L1TSYNC <sup>4</sup>               | 1.00            | —                  | L1TCLK |
| 86  | L1GR setup time <sup>2</sup>                                         | 42.00           | —                  | ns     |
| 87  | L1GR hold time                                                       | 42.00           | —                  | ns     |
| 88  | L1xCLK edge to L1SYNC valid (FSD = 00) CNT = 0000, BYT = 0, DSC = 0) | —               | 0.00               | ns     |

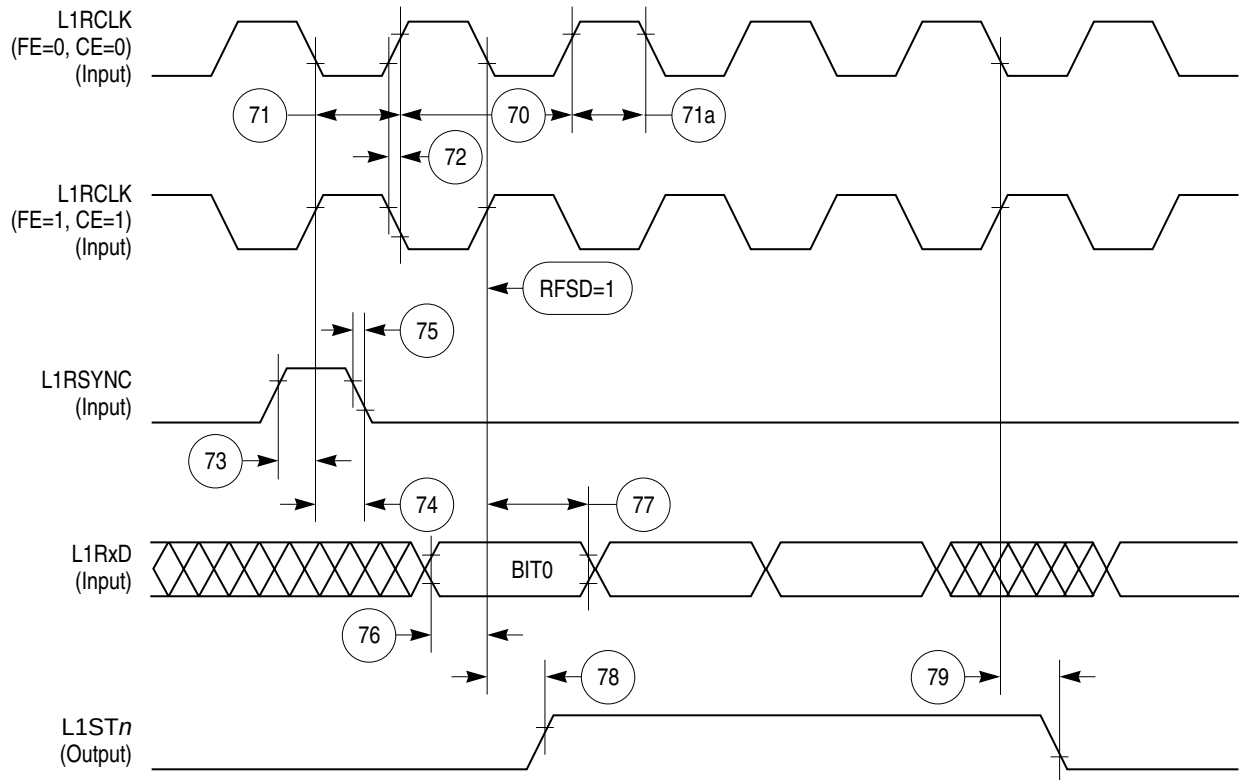
<sup>1</sup> The ratio SyncCLK/L1RCLK must be greater than 2.5/1.

<sup>2</sup> These specs are valid for IDL mode only.

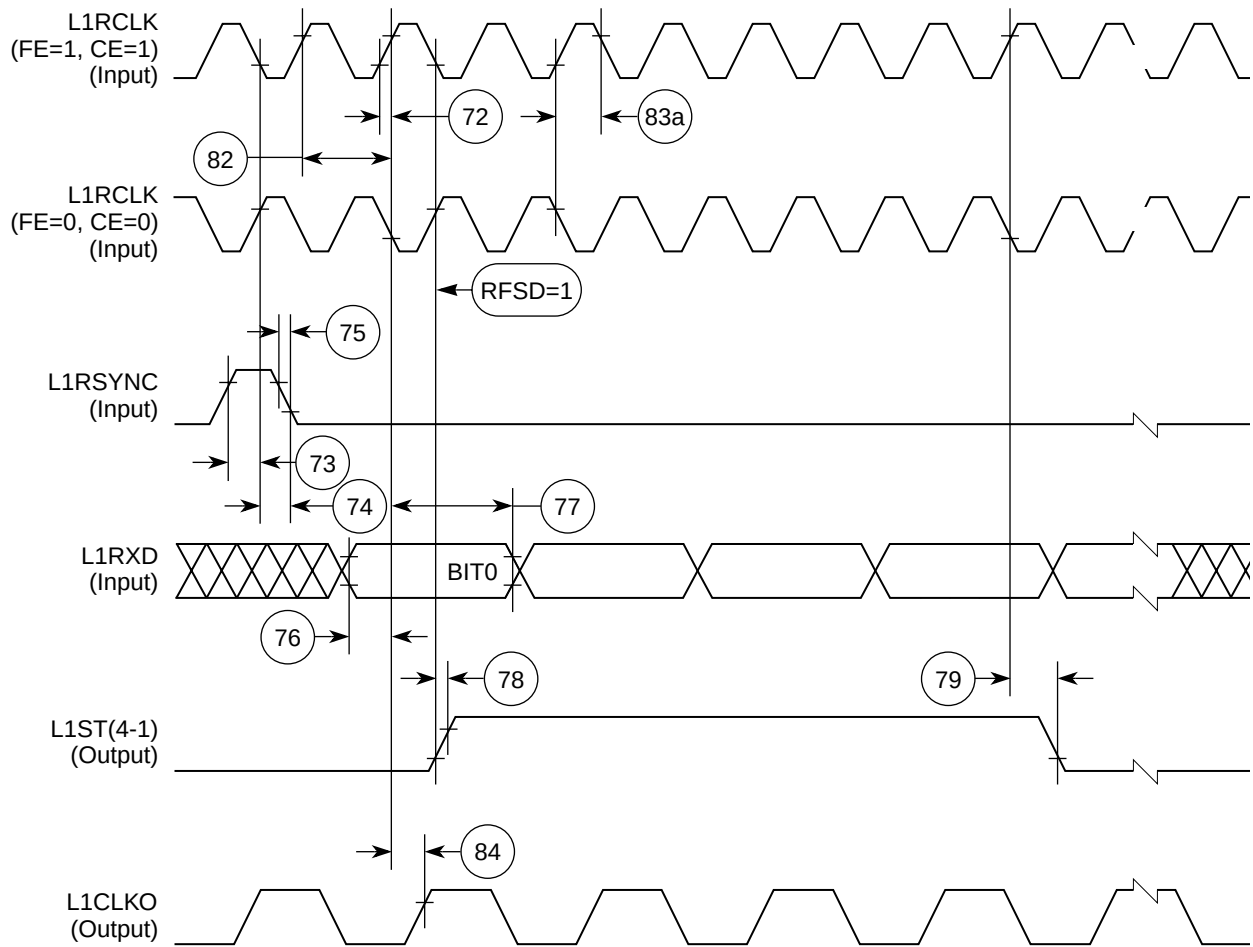
<sup>3</sup> Where P = 1/CLKOUT. Thus for a 25-MHz CLKOUT rate, P = 40 ns.

<sup>4</sup> These strobes and TxD on the first bit of the frame become valid after L1CLK edge or L1SYNC, whichever is later.

# **Freescale Semiconductor, Inc.** **Serial Interface AC Electrical Specifications**

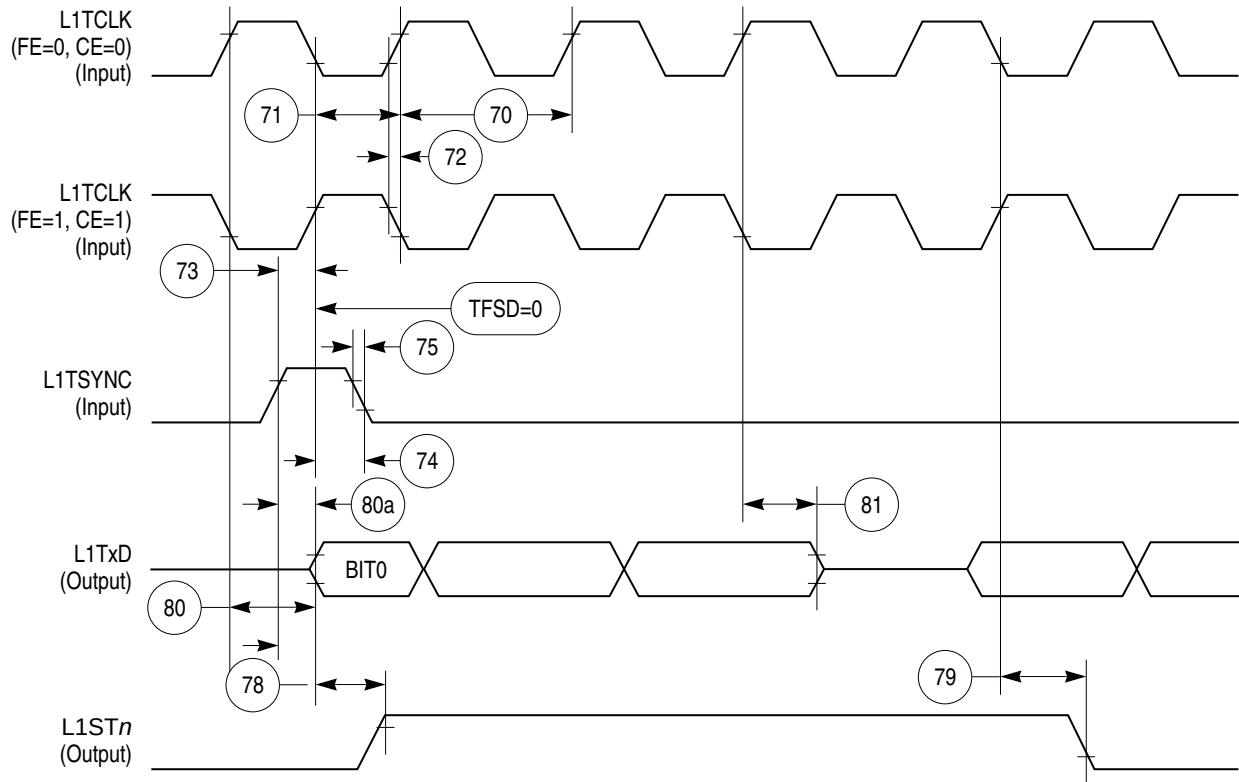


**Figure 8-45. SI Receive Timing Diagram with Normal Clocking (DSC = 0)**

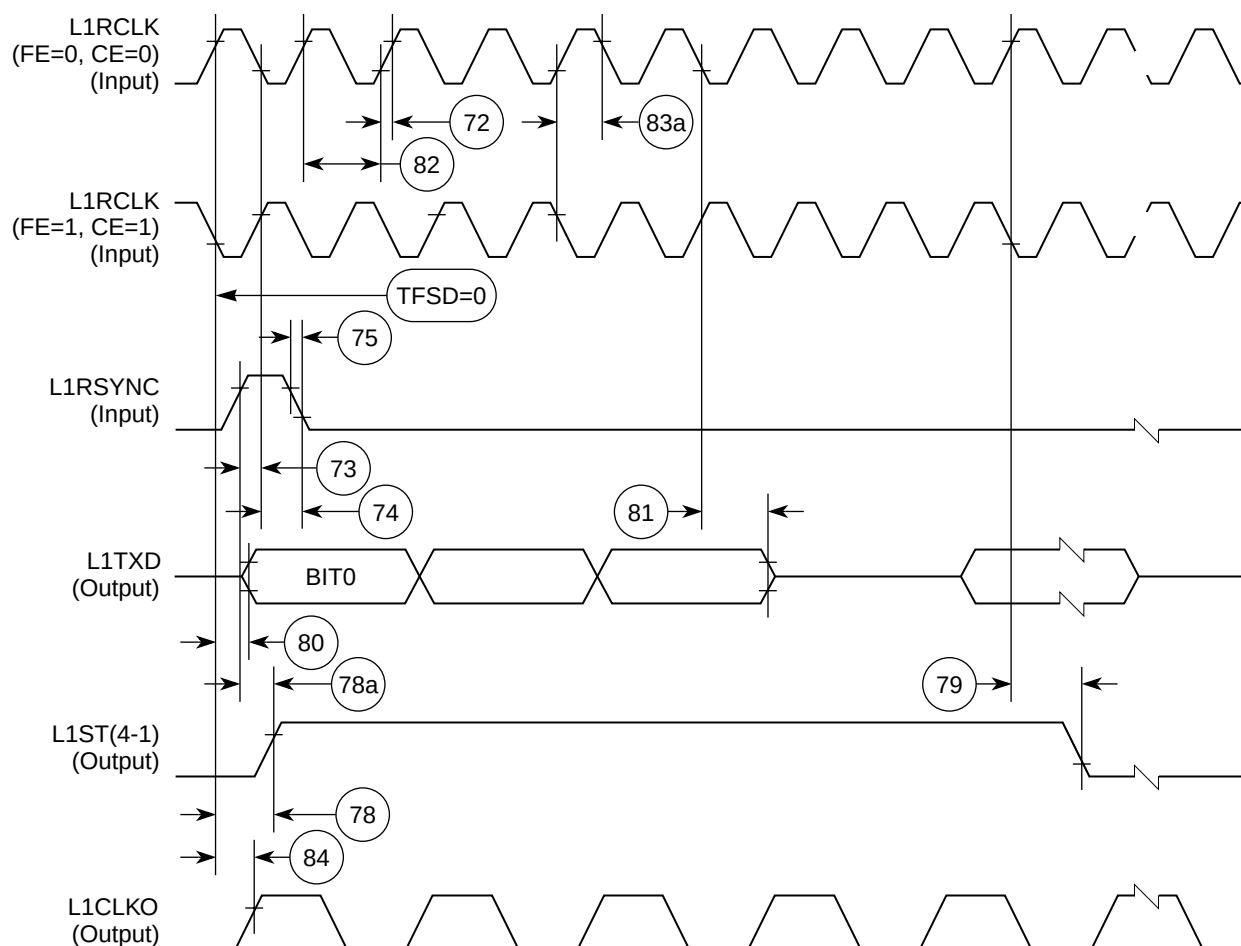


**Figure 8-46. SI Receive Timing with Double-Speed Clocking (DSC = 1)**

# **Freescale Semiconductor, Inc.** **Serial Interface AC Electrical Specifications**

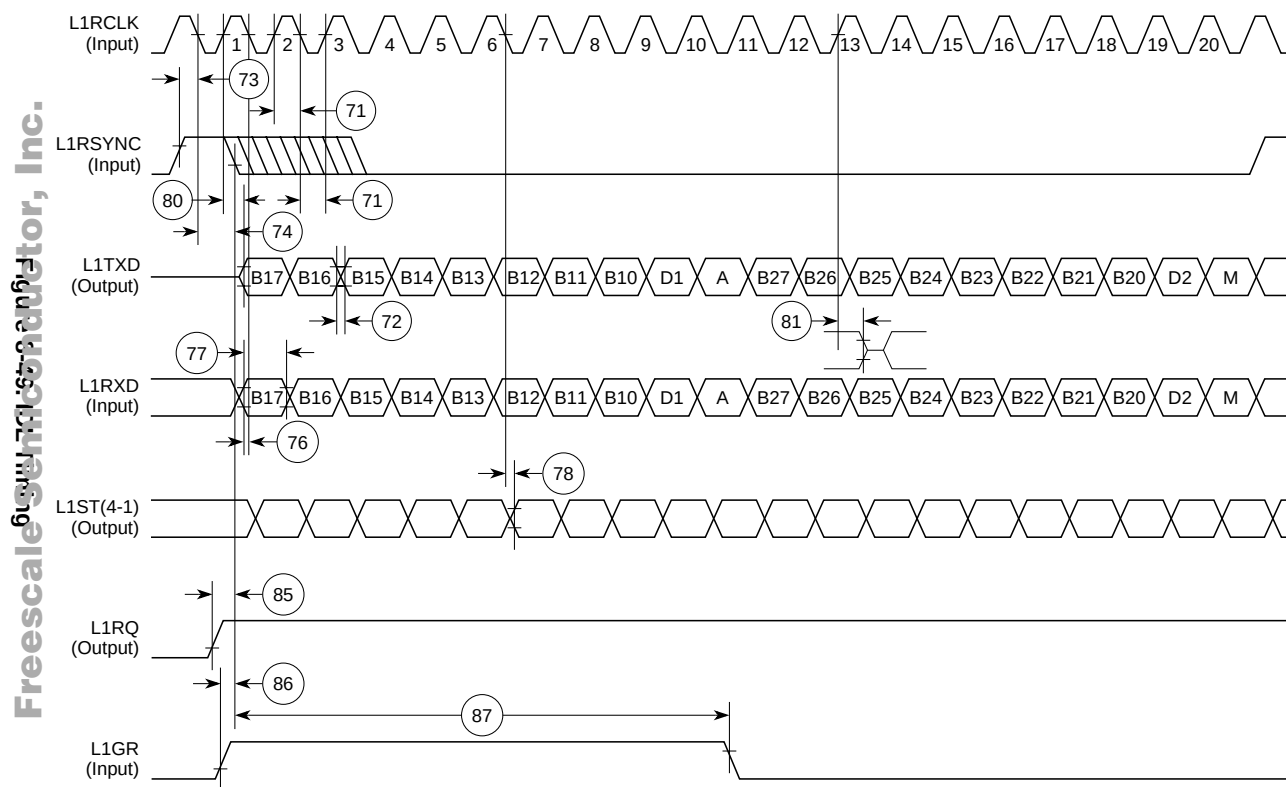


**Figure 8-47. SI Transmit Timing Diagram**



**Figure 8-48. SI Transmit Timing with Double Speed Clocking (DSC = 1)**

# Freescale Semiconductor, Inc.



Freescale Semiconductor, Inc.

## 8.6 SCC in NMSI Mode Electrical Specifications

Table 8-18 provides the NMSI external clock timing.

**Table 8-18. NMSI External Clock Timing**

| Num | Characteristic                                                                | All Frequencies |       | Unit |
|-----|-------------------------------------------------------------------------------|-----------------|-------|------|
|     |                                                                               | Min             | Max   |      |
| 100 | RCLKx and TCLKx frequency <sup>1</sup> (x = 2, 3 for all specs in this table) | 1/SYNCCLK       | —     | ns   |
| 101 | RCLKx and TCLKx width low                                                     | 1/SYNCCLK +5    | —     | ns   |
| 102 | RCLKx and TCLKx rise/fall time                                                | —               | 15.00 | ns   |
| 103 | TXDx active delay (from TCLKx falling edge)                                   | 0.00            | 50.00 | ns   |
| 104 | RTSx active/inactive delay (from TCLKx falling edge)                          | 0.00            | 50.00 | ns   |
| 105 | CTSx setup time to TCLKx rising edge                                          | 5.00            | —     | ns   |
| 106 | RXDx setup time to RCLKx rising edge                                          | 5.00            | —     | ns   |
| 107 | RXDx hold time from RCLKx rising edge <sup>2</sup>                            | 5.00            | —     | ns   |
| 108 | CDx setup time to RCLKx rising edge                                           | 5.00            | —     | ns   |

<sup>1</sup> The ratios SyncCLK/RCLKx and SyncCLK/TCLKx must be greater than or equal to 2.25/1.

<sup>2</sup> Also applies to  $\overline{CD}$  and  $\overline{CTS}$  hold time when they are used as an external sync signal.

Table 8-19 provides the NMSI internal clock timing.

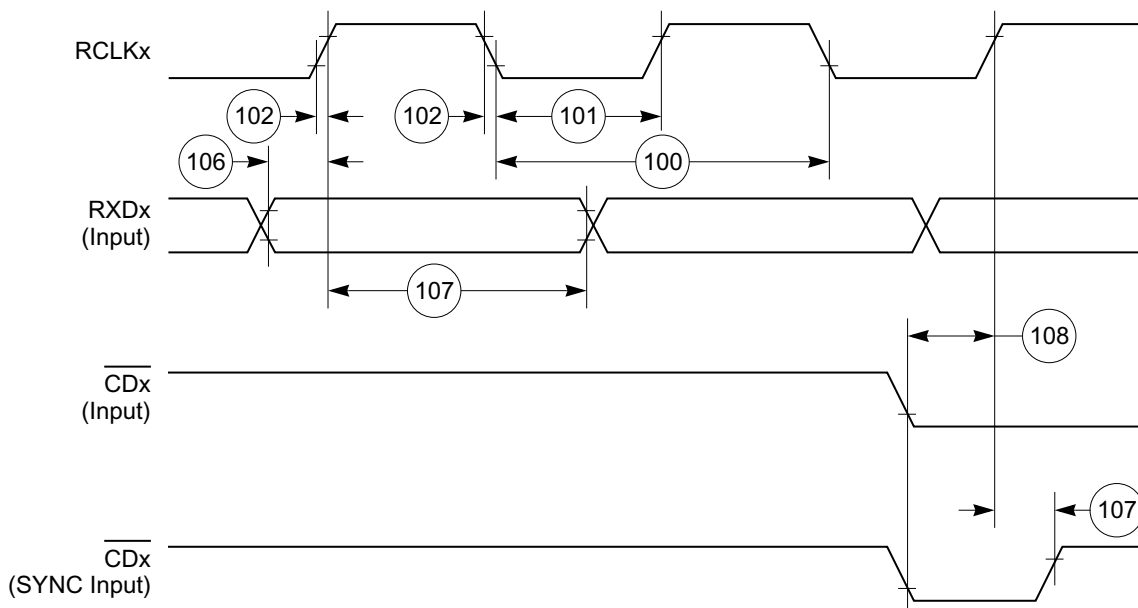
**Table 8-19. NMSI Internal Clock Timing**

| Num | Characteristic                                                                | All Frequencies |           | Unit |
|-----|-------------------------------------------------------------------------------|-----------------|-----------|------|
|     |                                                                               | Min             | Max       |      |
| 100 | RCLKx and TCLKx frequency <sup>1</sup> (x = 2, 3 for all specs in this table) | 0.00            | SYNCCLK/3 | MHz  |
| 102 | RCLKx and TCLKx rise/fall time                                                | —               | —         | ns   |
| 103 | TXDx active delay (from TCLKx falling edge)                                   | 0.00            | 30.00     | ns   |
| 104 | RTSx active/inactive delay (from TCLKx falling edge)                          | 0.00            | 30.00     | ns   |
| 105 | CTSx setup time to TCLKx rising edge                                          | 40.00           | —         | ns   |
| 106 | RXDx setup time to RCLKx rising edge                                          | 40.00           | —         | ns   |
| 107 | RXDx hold time from RCLKx rising edge <sup>2</sup>                            | 0.00            | —         | ns   |
| 108 | CDx setup time to RCLKx rising edge                                           | 40.00           | —         | ns   |

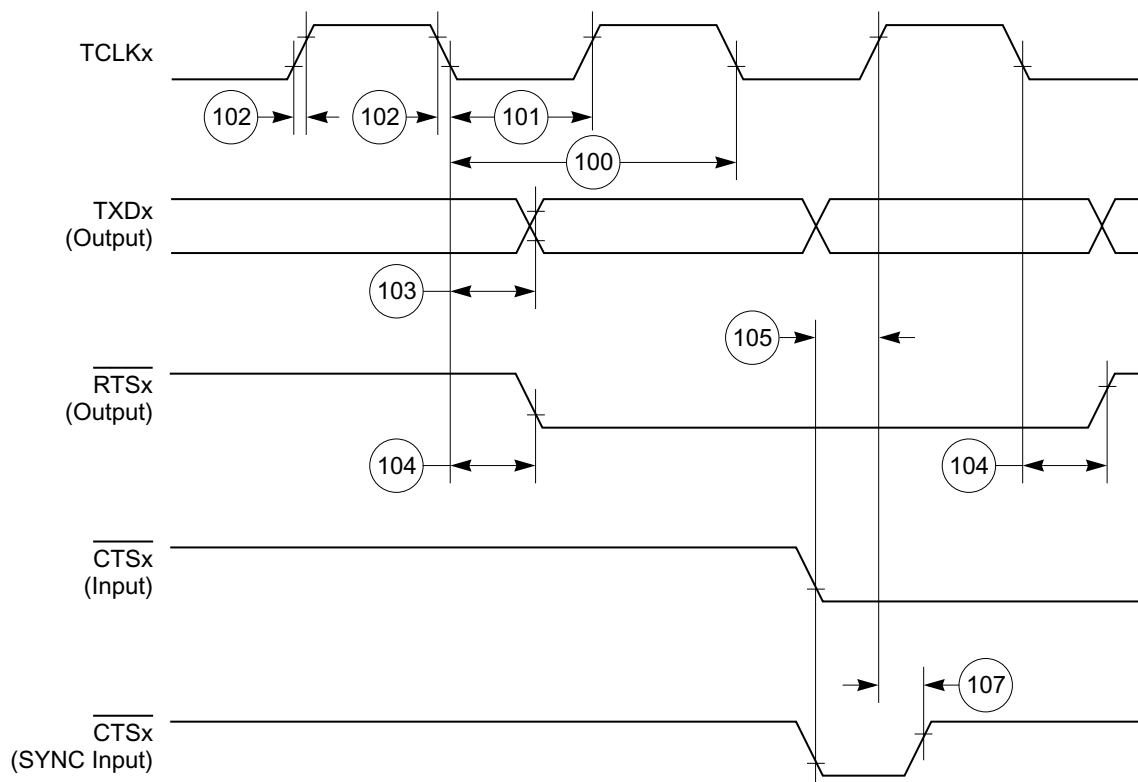
<sup>1</sup> The ratios SyncCLK/RCLKx and SyncCLK/TCLK1x must be greater or equal to 3/1.

<sup>2</sup> Also applies to  $\overline{CD}$  and  $\overline{CTS}$  hold time when they are used as an external sync signals.

Figure 8-50 through Figure 8-52 show the NMSI timings.



**Figure 8-50. SCC NMSI Receive Timing Diagram**



**Figure 8-51. SCC NMSI Transmit Timing Diagram**



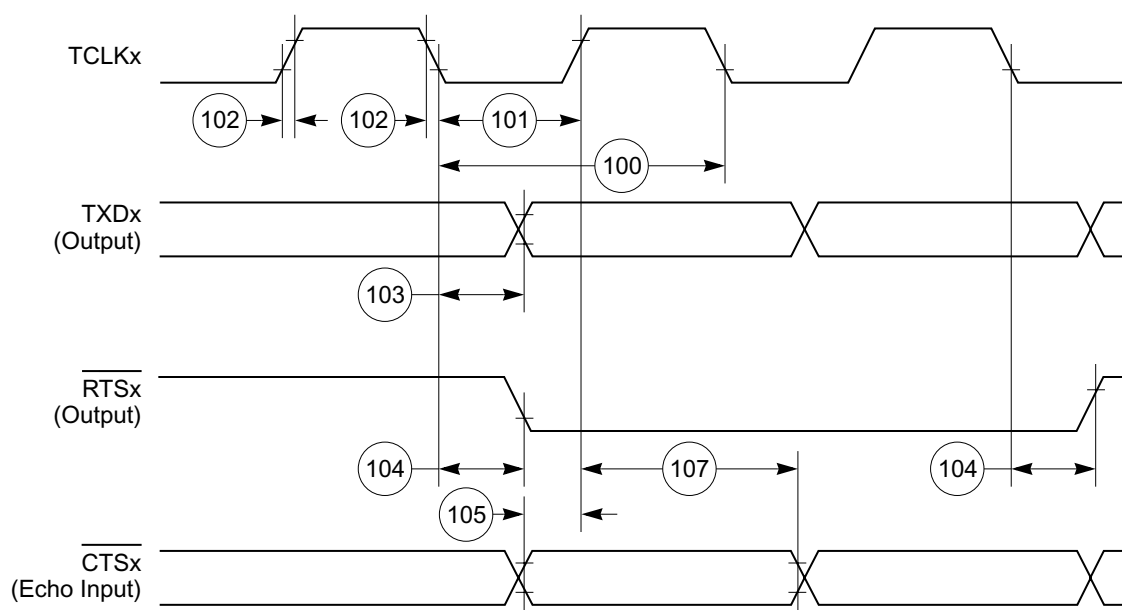


Figure 8-52. HDLC Bus Timing Diagram

## 8.7 Ethernet Electrical Specifications

Table 8-20 provides the Ethernet timings as shown in Figure 8-53 to Figure 8-55.

Table 8-20. Ethernet Timing

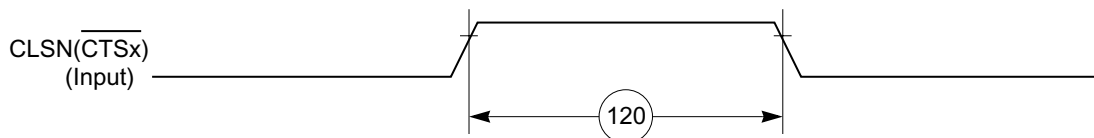
| Num | Characteristic                                                  | All Frequencies |        | Unit |
|-----|-----------------------------------------------------------------|-----------------|--------|------|
|     |                                                                 | Min             | Max    |      |
| 120 | CLSN width high                                                 | 40.00           | —      | ns   |
| 121 | RCLKx rise/fall time (x = 2, 3 for all specs in this table)     | —               | 15.00  | ns   |
| 122 | RCLKx width low                                                 | 40.00           | —      | ns   |
| 123 | RCLKx clock period <sup>1</sup>                                 | 80.00           | 120.00 | ns   |
| 124 | RXDx setup time                                                 | 20.00           | —      | ns   |
| 125 | RXDx hold time                                                  | 5.00            | —      | ns   |
| 126 | RENA active delay (from RCLKx rising edge of the last data bit) | 10.00           | —      | ns   |
| 127 | RENA width low                                                  | 100.00          | —      | ns   |
| 128 | TCLKx rise/fall time                                            | —               | 15.00  | ns   |
| 129 | TCLKx width low                                                 | 40.00           | —      | ns   |
| 130 | TCLKx clock period <sup>1</sup>                                 | 99.00           | 101.00 | ns   |
| 131 | TXDx active delay (from TCLKx rising edge)                      | 10.00           | 50.00  | ns   |
| 132 | TXDx inactive delay (from TCLKx rising edge)                    | 10.00           | 50.00  | ns   |

**Table 8-20. Ethernet Timing (continued)**

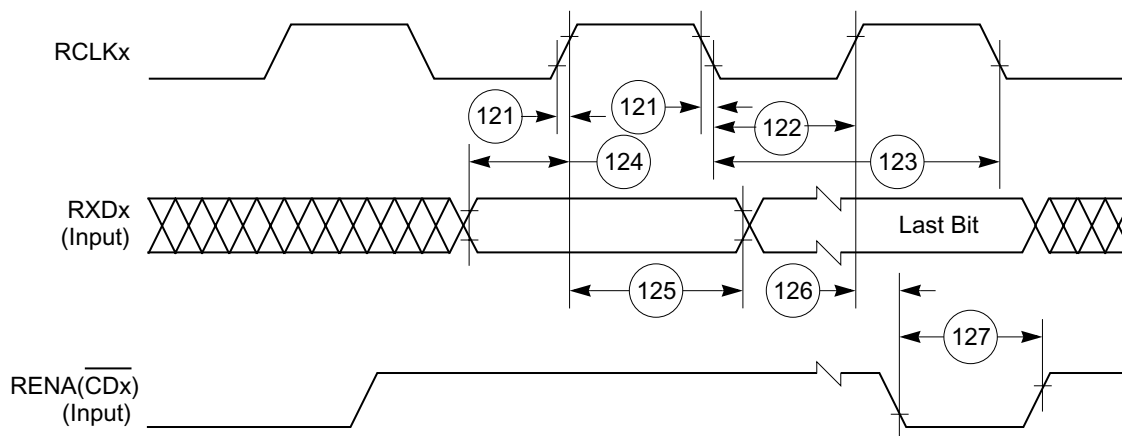
| Num | Characteristic                                                | All Frequencies |       | Unit |
|-----|---------------------------------------------------------------|-----------------|-------|------|
|     |                                                               | Min             | Max   |      |
| 133 | TENA active delay (from TCLKx rising edge)                    | 10.00           | 50.00 | ns   |
| 134 | TENA inactive delay (from TCLKx rising edge)                  | 10.00           | 50.00 | ns   |
| 138 | CLKOUT low to $\overline{\text{SDACK}}$ asserted <sup>2</sup> | —               | 20.00 | ns   |
| 139 | CLKOUT low to $\overline{\text{SDACK}}$ negated <sup>2</sup>  | —               | 20.00 | ns   |

<sup>1</sup> The ratios SyncCLK/RCLKx and SyncCLK/TCLKx must be greater or equal to 2/1.

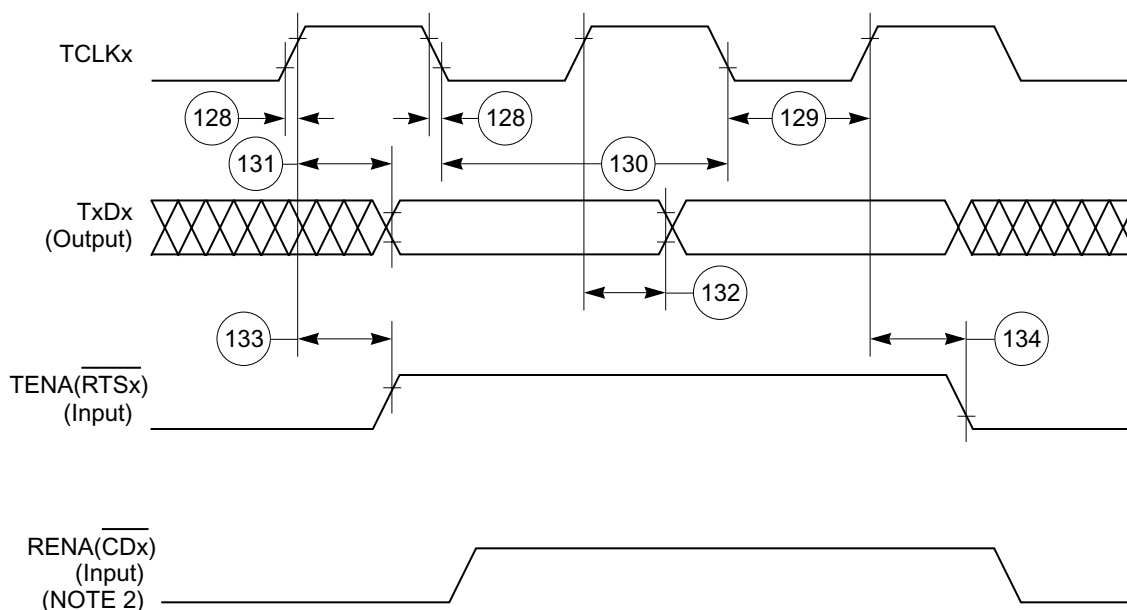
<sup>2</sup>  $\overline{\text{SDACK}}$  is asserted whenever the SDMA writes the incoming frame destination address into memory.



**Figure 8-53. Ethernet Collision Timing Diagram**



**Figure 8-54. Ethernet Receive Timing Diagram**



NOTES:

1. Transmit clock invert (TCI) bit in GSMR is set.
2. If RENA is deasserted before TENA, or RENA is not asserted at all during transmit, then the CSL bit is set in the buffer descriptor at the end of the frame transmission.

**Figure 8-55. Ethernet Transmit Timing Diagram**

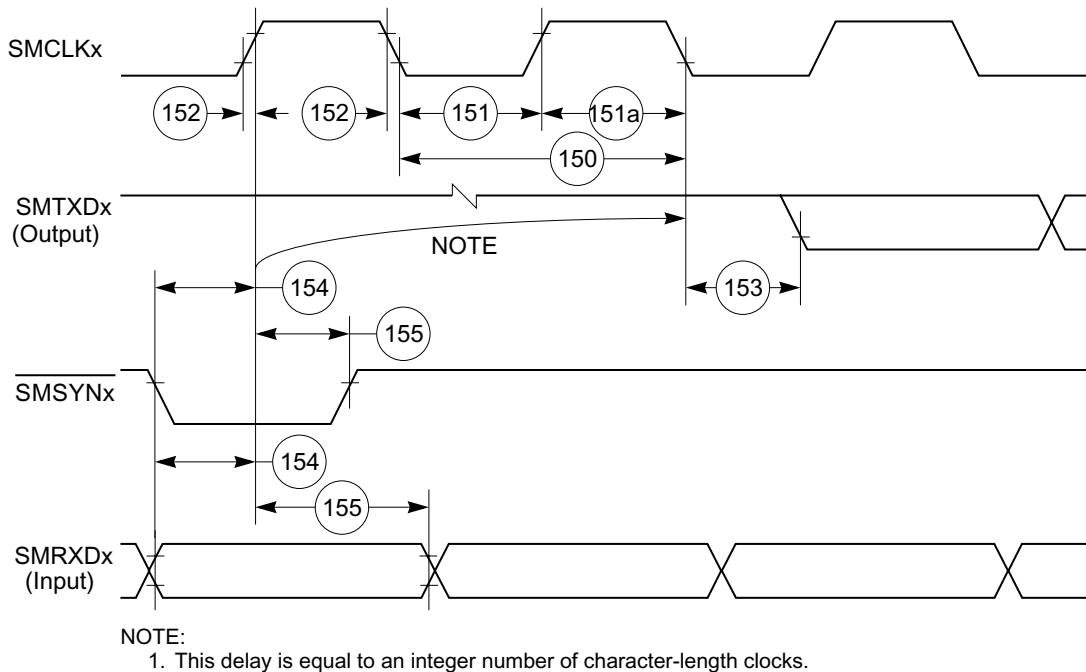
## 8.8 SMC Transparent AC Electrical Specifications

Figure 8-21 provides the SMC transparent timings as shown in Figure 8-56.

**Table 8-21. Serial Management Controller Timing**

| Num  | Characteristic                                 | All Frequencies |       | Unit |
|------|------------------------------------------------|-----------------|-------|------|
|      |                                                | Min             | Max   |      |
| 150  | SMCLKx clock period <sup>1</sup>               | 100.00          | —     | ns   |
| 151  | SMCLKx width low                               | 50.00           | —     | ns   |
| 151a | SMCLKx width high                              | 50.00           | —     | ns   |
| 152  | SMCLKx rise/fall time                          | —               | 15.00 | ns   |
| 153  | SMTXDx active delay (from SMCLKx falling edge) | 10.00           | 50.00 | ns   |
| 154  | SMRXDx/SMSYNx setup time                       | 20.00           | —     | ns   |
| 155  | SMRXDx/SMSYNx hold time                        | 5.00            | —     | ns   |

<sup>1</sup> The ratio SyncCLK/SMCLKx must be greater or equal to 2/1.



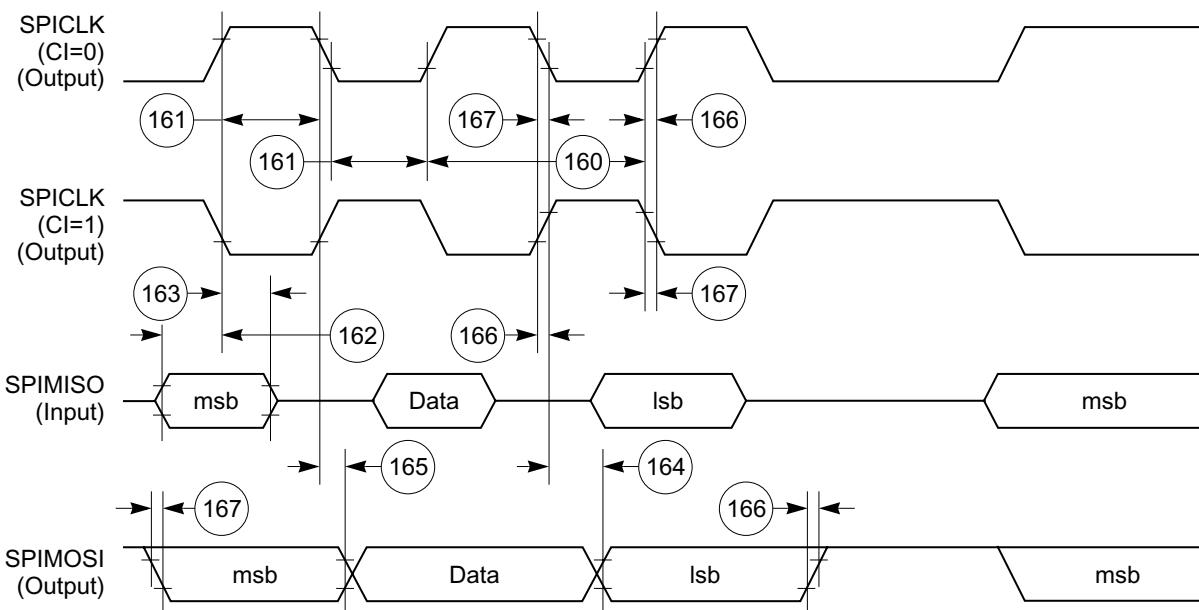
**Figure 8-56. SMC Transparent Timing Diagram**

## 8.9 SPI Master AC Electrical Specifications

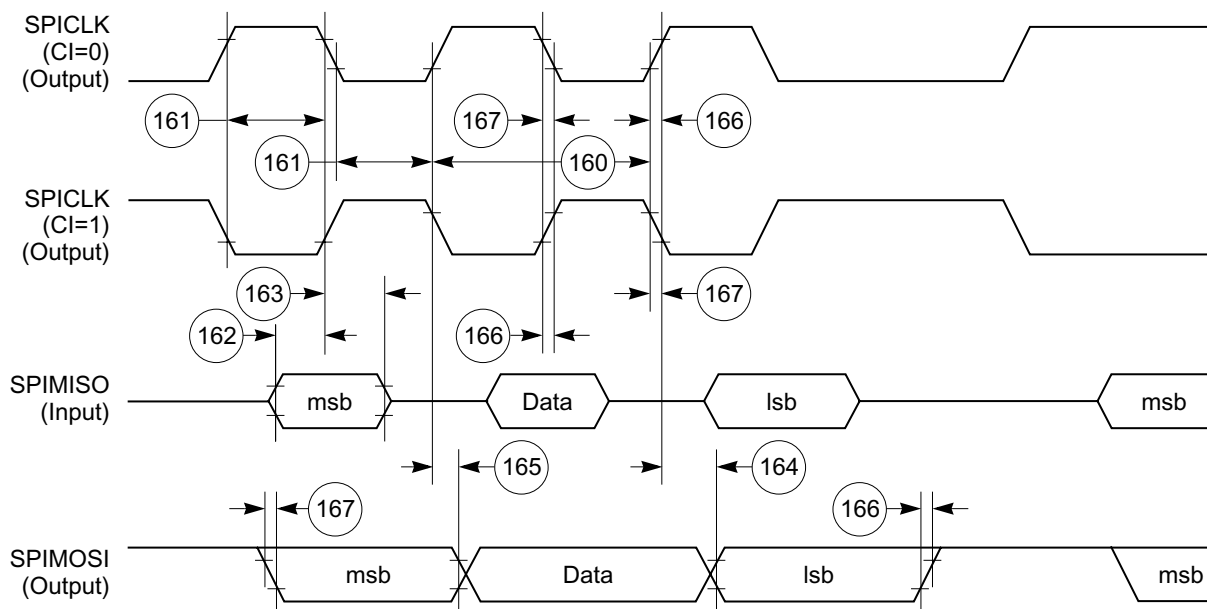
Table 8-22 provides the SPI master timings as shown in Figure 8-57 and Figure 8-58.

**Table 8-22. SPI Master Timing**

| Num | Characteristic                      | All Frequencies |       | Unit      |
|-----|-------------------------------------|-----------------|-------|-----------|
|     |                                     | Min             | Max   |           |
| 160 | MASTER cycle time                   | 4               | 1024  | $t_{cyc}$ |
| 161 | MASTER clock (SCK) high or low time | 2               | 512   | $t_{cyc}$ |
| 162 | MASTER data setup time (inputs)     | 50.00           | —     | ns        |
| 163 | Master data hold time (inputs)      | 0.00            | —     | ns        |
| 164 | Master data valid (after SCK edge)  | —               | 20.00 | ns        |
| 165 | Master data hold time (outputs)     | 0.00            | —     | ns        |
| 166 | Rise time output                    | —               | 15.00 | ns        |
| 167 | Fall time output                    | —               | 15.00 | ns        |



**Figure 8-57. SPI Master (CP = 0) Timing Diagram**



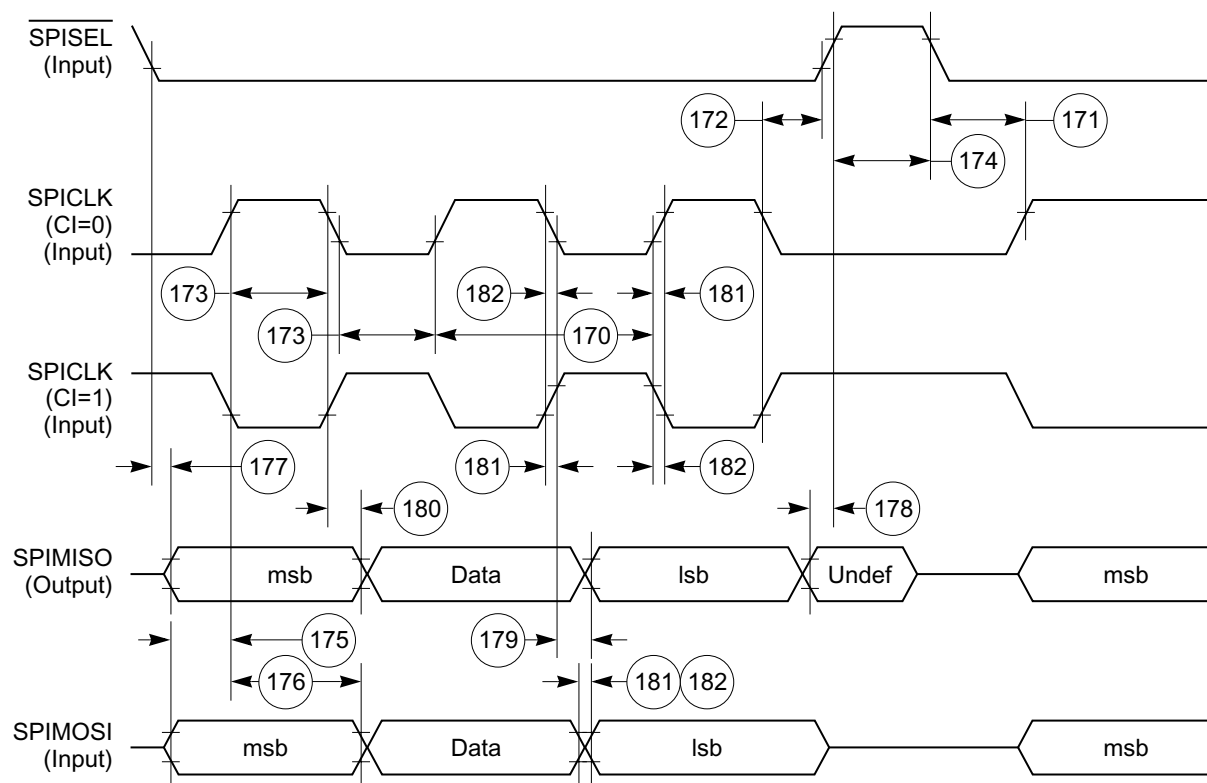
**Figure 8-58. SPI Master (CP = 1) Timing Diagram**

## 8.10 SPI Slave AC Electrical Specifications

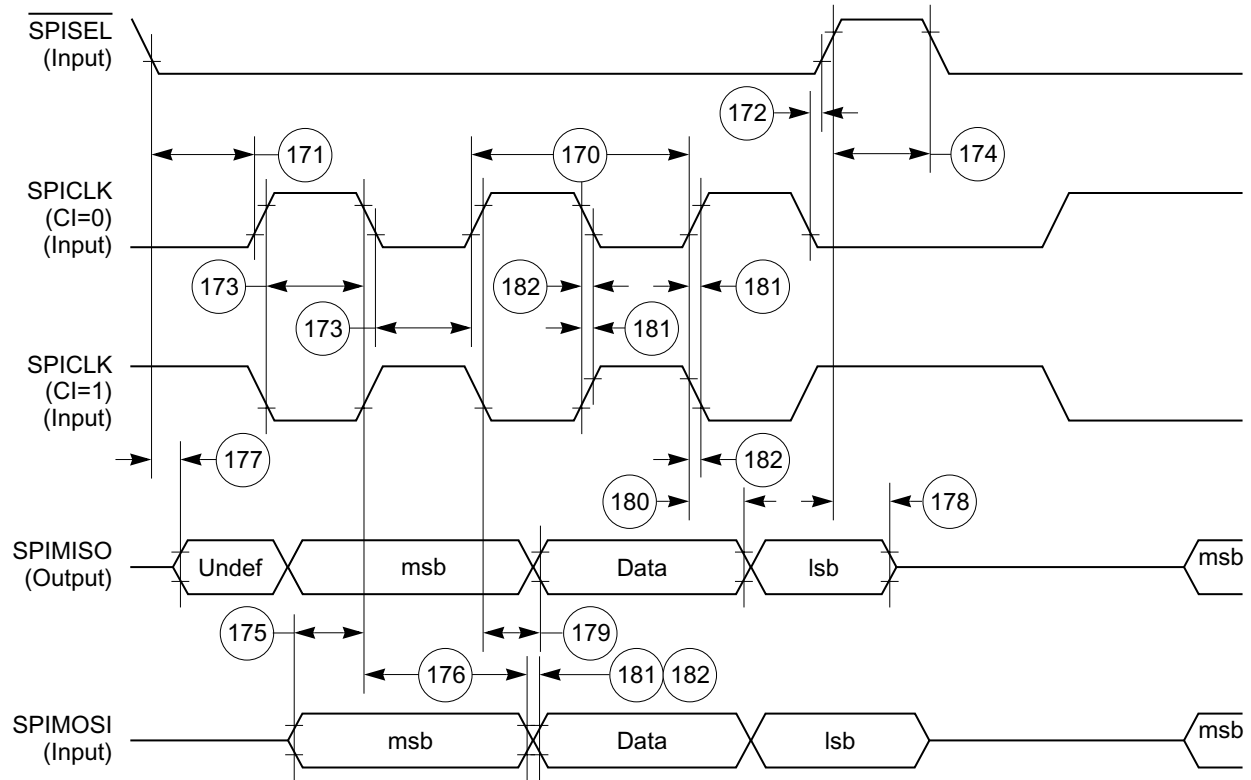
Table 8-23 provides the SPI slave timings as shown in Figure 8-59 and Figure 8-60.

**Table 8-23. SPI Slave Timing**

| Num | Characteristic                                              | All Frequencies |       | Unit             |
|-----|-------------------------------------------------------------|-----------------|-------|------------------|
|     |                                                             | Min             | Max   |                  |
| 170 | Slave cycle time                                            | 2               | —     | t <sub>cyc</sub> |
| 171 | Slave enable lead time                                      | 15.00           | —     | ns               |
| 172 | Slave enable lag time                                       | 15.00           | —     | ns               |
| 173 | Slave clock (SPICLK) high or low time                       | 1               | —     | t <sub>cyc</sub> |
| 174 | Slave sequential transfer delay (does not require deselect) | 1               | —     | t <sub>cyc</sub> |
| 175 | Slave data setup time (inputs)                              | 20.00           | —     | ns               |
| 176 | Slave data hold time (inputs)                               | 20.00           | —     | ns               |
| 177 | Slave access time                                           | —               | 50.00 | ns               |
| 178 | Slave SPI MISO disable time                                 | —               | 50.00 | ns               |
| 179 | Slave data valid (after SPICLK edge)                        | —               | 50.00 | ns               |
| 180 | Slave data hold time (outputs)                              | 0.00            | —     | ns               |
| 181 | Rise time (input)                                           | —               | 15.00 | ns               |
| 182 | Fall time (input)                                           | —               | 15.00 | ns               |



**Figure 8-59. SPI Slave (CP = 0) Timing Diagram**



**Figure 8-60. SPI Slave (CP = 1) Timing Diagram**

## 8.11 I<sup>2</sup>C AC Electrical Specifications

Table 8-24 provides the I<sup>2</sup>C (SCL < 100 KHz) timings.

**Table 8-24. I<sup>2</sup>C Timing (SCL < 100 KHz)**

| Num | Characteristic                            | All Frequencies |        | Unit |
|-----|-------------------------------------------|-----------------|--------|------|
|     |                                           | Min             | Max    |      |
| 200 | SCL clock frequency (slave)               | 0.00            | 100.00 | KHz  |
| 200 | SCL clock frequency (master) <sup>1</sup> | 1.50            | 100.00 | KHz  |
| 202 | Bus free time between transmissions       | 4.70            | —      | μs   |
| 203 | Low period of SCL                         | 4.70            | —      | μs   |
| 204 | High period of SCL                        | 4.00            | —      | μs   |
| 205 | Start condition setup time                | 4.70            | —      | μs   |
| 206 | Start condition hold time                 | 4.00            | —      | μs   |
| 207 | Data hold time                            | 0.00            | —      | μs   |



**Table 8-24. I<sup>2</sup>C Timing (SCL < 100 KHz) (CONTINUED)**

| Num | Characteristic            | All Frequencies |        | Unit |
|-----|---------------------------|-----------------|--------|------|
|     |                           | Min             | Max    |      |
| 208 | Data setup time           | 250.00          | —      | ns   |
| 209 | SDL/SCL rise time         | —               | 1.00   | μs   |
| 210 | SDL/SCL fall time         | —               | 300.00 | ns   |
| 211 | Stop condition setup time | 4.70            | —      | μs   |

<sup>1</sup> SCL frequency is given by  $SCL = BRGCLK\_frequency / ((BRG\ register + 3) * pre\_scaler * 2)$ .  
The ratio SyncClk/(BRGCLK/pre\_scaler) must be greater or equal to 4/1.

Table 8-25 provides the I<sup>2</sup>C (SCL > 100 KHz) timings.

**Table 8-25. I<sup>2</sup>C Timing (SCL > 100 KHz)**

| Num | Characteristic                            | Expression | All Frequencies |               | Unit |
|-----|-------------------------------------------|------------|-----------------|---------------|------|
|     |                                           |            | Min             | Max           |      |
| 200 | SCL clock frequency (slave)               | fSCL       | 0               | BRGCLK/48     | Hz   |
| 200 | SCL clock frequency (master) <sup>1</sup> | fSCL       | BRGCLK/16512    | BRGCLK/48     | Hz   |
| 202 | Bus free time between transmissions       |            | 1/(2.2 * fSCL)  | —             | s    |
| 203 | Low period of SCL                         |            | 1/(2.2 * fSCL)  | —             | s    |
| 204 | High period of SCL                        |            | 1/(2.2 * fSCL)  | —             | s    |
| 205 | Start condition setup time                |            | 1/(2.2 * fSCL)  | —             | s    |
| 206 | Start condition hold time                 |            | 1/(2.2 * fSCL)  | —             | s    |
| 207 | Data hold time                            |            | 0               | —             | s    |
| 208 | Data setup time                           |            | 1/(40 * fSCL)   | —             | s    |
| 209 | SDL/SCL rise time                         |            | —               | 1/(10 * fSCL) | s    |
| 210 | SDL/SCL fall time                         |            | —               | 1/(33 * fSCL) | s    |
| 211 | Stop condition setup time                 |            | 1/2(2.2 * fSCL) | —             | s    |

<sup>1</sup> SCL frequency is given by  $SCL = BrgClk\_frequency / ((BRG\ register + 3) * pre\_scaler * 2)$ .  
The ratio SyncClk/(Brg\_Clk/pre\_scaler) must be greater or equal to 4/1.

Figure 8-61 shows the I<sup>2</sup>C bus timing.

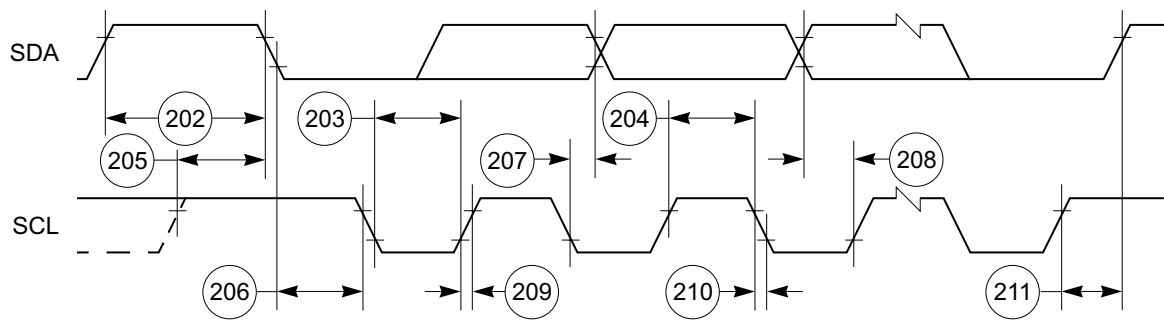


Figure 8-61. I<sup>2</sup>C Bus Timing Diagram

## Part IX Mechanical Data and Ordering Information

Table 9-26 provides information on the MPC850 derivative devices.

Table 9-26. MPC850 Family Derivatives

| Device    | Ethernet Support | Number of SCCs <sup>1</sup> | 32-Channel HDLC Support | 64-Channel HDLC Support <sup>2</sup> |
|-----------|------------------|-----------------------------|-------------------------|--------------------------------------|
| MPC850    | N/A              | One                         | N/A                     | N/A                                  |
| MPC850DE  | Yes              | Two                         | N/A                     | N/A                                  |
| MPC850SR  | Yes              | Two                         | N/A                     | Yes                                  |
| MPC850DSL | Yes              | Two                         | No                      | No                                   |

<sup>1</sup> Serial Communication Controller (SCC)

<sup>2</sup> 50 MHz version supports 64 time slots on a time division multiplexed line using one SCC

Table 9-27 identifies the packages and operating frequencies available for the MPC850.

**Table 9-27. MPC850 Package/Frequency/Availability**

| Package Type                                     | Frequency (MHz) | Temperature (Tj) | Order Number                                                            |
|--------------------------------------------------|-----------------|------------------|-------------------------------------------------------------------------|
| 256-Lead Plastic Ball Grid Array<br>(ZT suffix)  | 50              | 0°C to 95°C      | XPC850ZT50BU<br>XPC850DEZT50BU<br>XPC850SRZT50BU<br>XPC850DSLZT50BU     |
|                                                  | 66              | 0°C to 95°C      | XPC850ZT66BU<br>XPC850DEZT66BU<br>XPC850SRZT66BU                        |
|                                                  | 80              | 0°C to 95°C      | XPC850ZT80BU<br>XPC850DEZT80BU<br>XPC850SRZT80BU                        |
| 256-Lead Plastic Ball Grid Array<br>(CZT suffix) | 50              | -40°C to 95°C    | XPC850CZT50BU<br>XPC850DECZT50BU<br>XPC850SRCZT50BU<br>XPC850DCLCZT50BU |
|                                                  | 66              |                  | XPC850CZT66BU<br>XPC850DECZT66BU<br>XPC850SRCZT66BU                     |
|                                                  | 80              |                  | XPC850CZT80B<br>XPC850DECZT80B<br>XPC850SRCZT80B                        |

## 9.1 Pin Assignments and Mechanical Dimensions of the PBGA

The original pin numbering of the MPC850 conformed to a Motorola proprietary pin numbering scheme that has since been replaced by the JEDEC pin numbering standard for this package type. To support customers that are currently using the non-JEDEC pin numbering scheme, two sets of pinouts, JEDEC and non-JEDEC, are presented in this document.

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## Pin Assignments and Mechanical Dimensions of the PBGA

Figure 9-62 shows the non-JEDEC pinout of the PBGA package as viewed from the top surface.

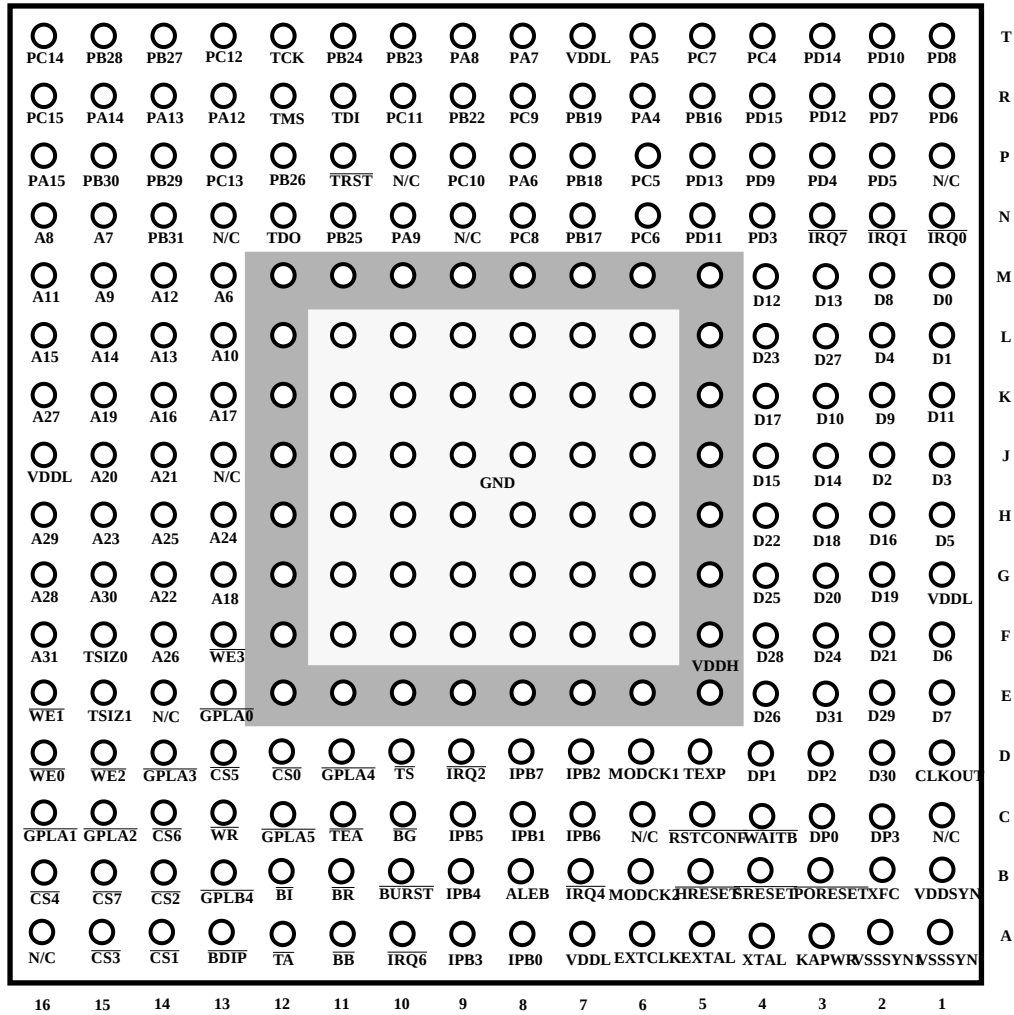
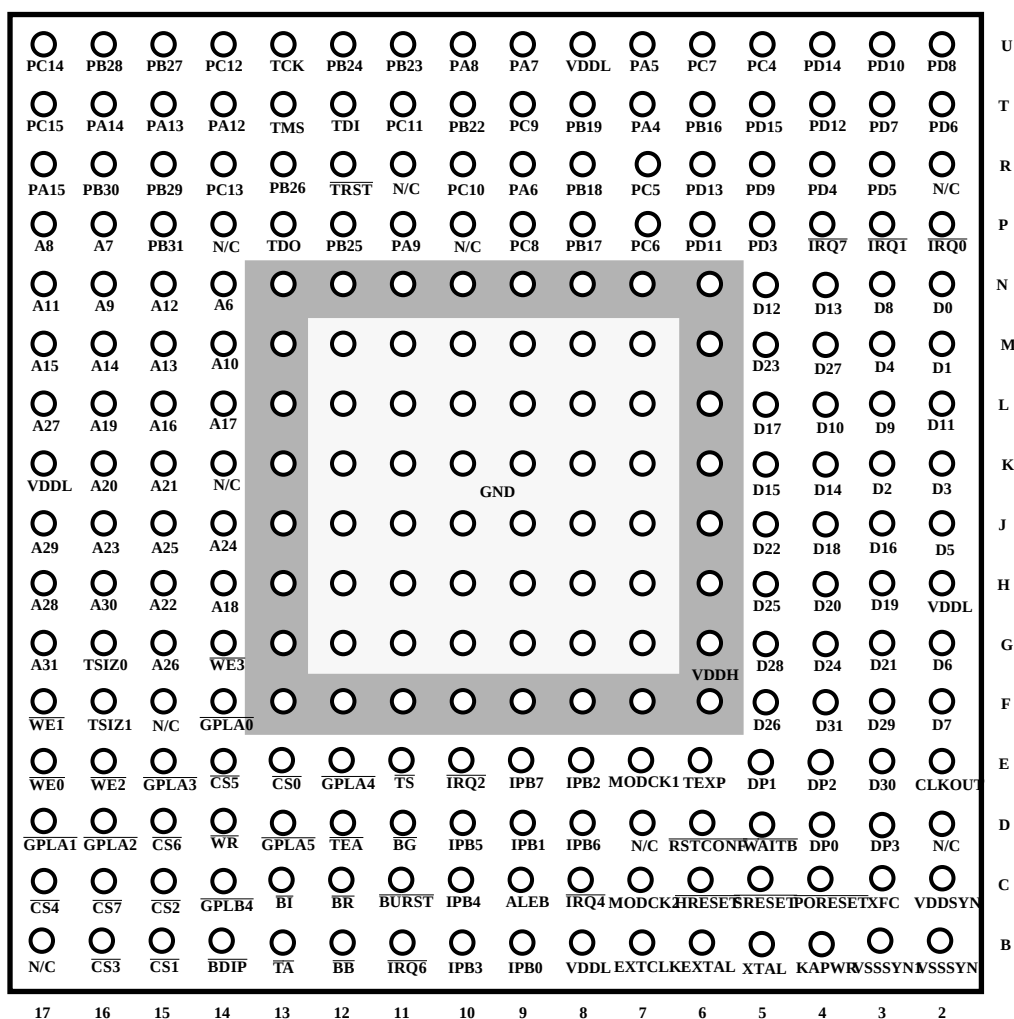


Figure 9-62. Pin Assignments for the PBGA (Top View)—non-JEDEC Standard

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## Pin Assignments and Mechanical Dimensions of the PBGA

Figure 9-63 shows the JEDEC pinout of the PBGA package as viewed from the top surface.



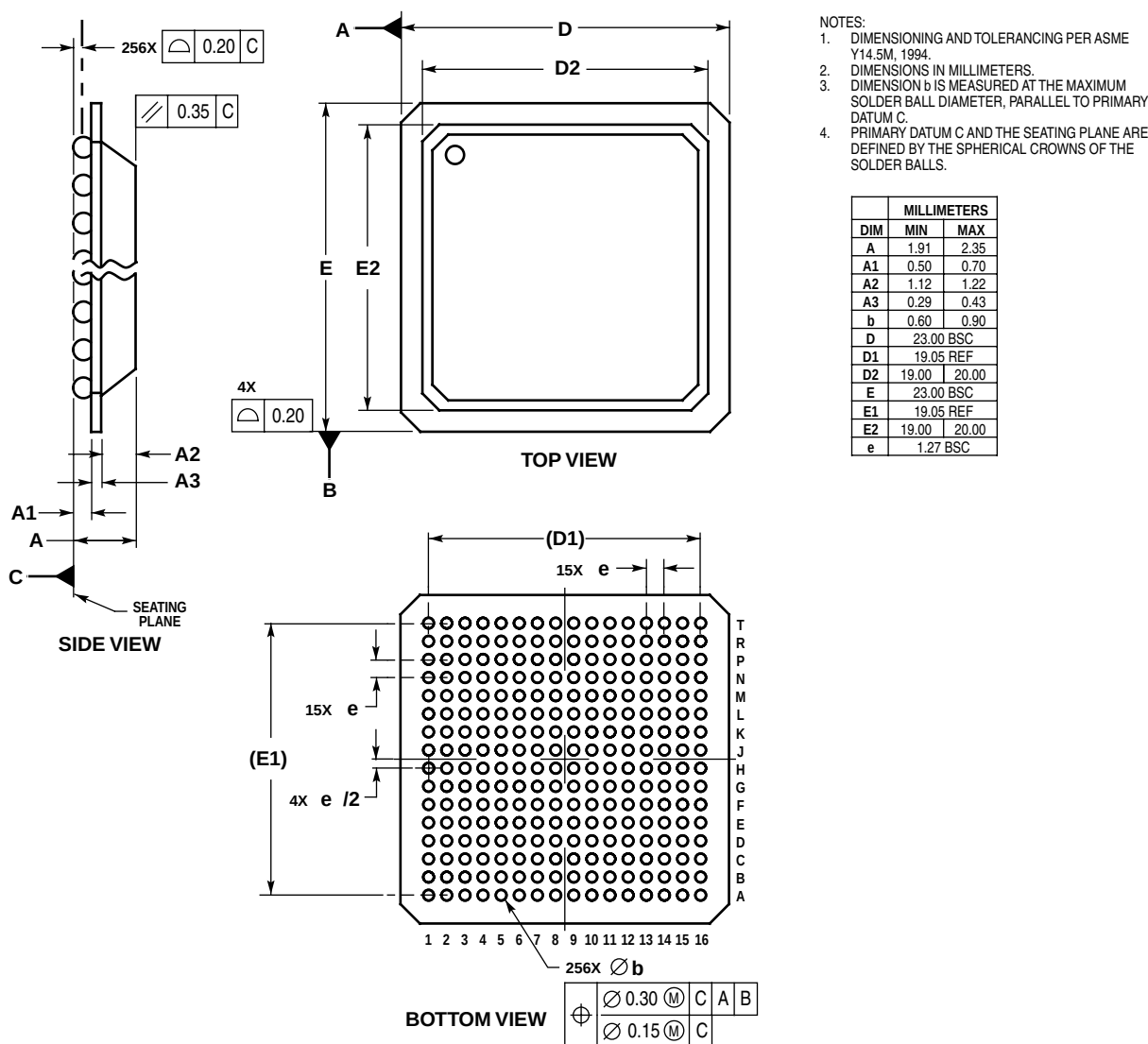
**Figure 9-63. Pin Assignments for the PBGA (Top View)—JEDEC Standard**

For more information on the printed circuit board layout of the PBGA package, including thermal via design and suggested pad layout, please refer to AN-1231/D, Plastic Ball Grid Array Application Note available from your local Motorola sales office.

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## Pin Assignments and Mechanical Dimensions of the PBGA

Figure 9-64 shows the non-JEDEC package dimensions of the PBGA.

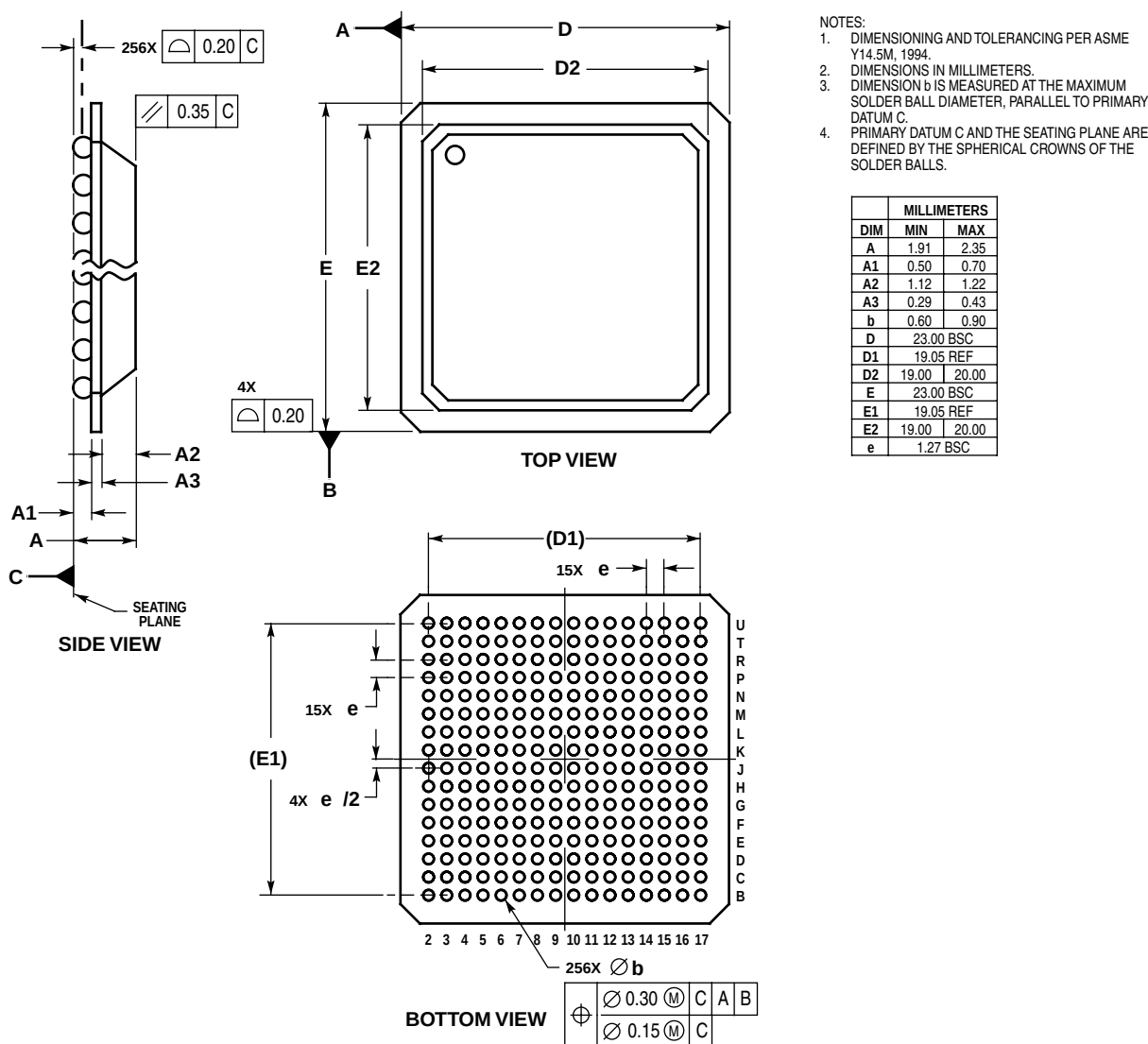


**Figure 9-64. Package Dimensions for the Plastic Ball Grid Array (PBGA)—non-JEDEC Standard**

# Freescale Semiconductor, Inc.

## Pin Assignments and Mechanical Dimensions of the PBGA

Figure 9-65 shows the JEDEC package dimensions of the PBGA.



CASE 1130-01  
ISSUE B

Figure 9-65. Package Dimensions for the Plastic Ball Grid Array (PBGA)—JEDEC Standard

## Part X Document Revision History

Table 10-28 lists significant changes between revisions of this document.

**Table 10-28. Document Revision History**

| Revision | Date    | Change                                                                                                                                                                                     |
|----------|---------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 0.1      | 11/2001 | Removed reference to 5 Volt tolerance capability on peripheral interface pins. Replaced SI and IDL timing diagrams with better images. Updated to new template, added this revision table. |
| 0.2      | 04/2002 | Updated power numbers and added Rev. C                                                                                                                                                     |
| 1        | 10/2002 | Added MPC850DSL. Corrected Figure 6-25 on page 37.                                                                                                                                         |



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