

Description

The SL432 series are 3-terminal precision shunt regulators that are programmable over a wide voltage range of 1.24V to 16V with $\pm 0.5\%$, $\pm 1.0\%$, $\pm 2.0\%$ tolerance. The SL432 series have a low dynamic impedance of 0.25Ω . These features make the SL432 series an excellent replacement for zener diodes in numerous applications circuits that require a precision reference voltage.

Features

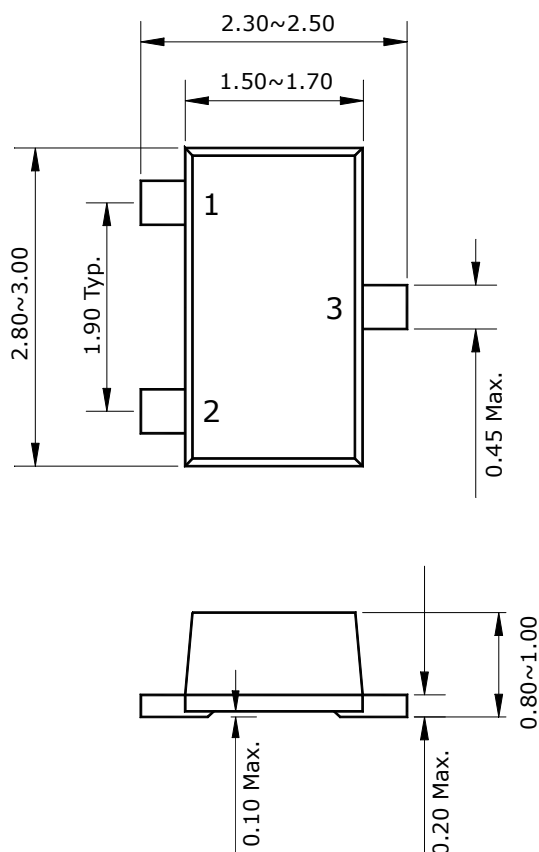
- Programmable output voltage from 1.24V to 16V
- Voltage reference tolerance : $\pm 0.5\%$, $\pm 1.0\%$, $\pm 2.0\%$
- Cathode current capability of $80\mu\text{A}$ to 30mA

Ordering Information

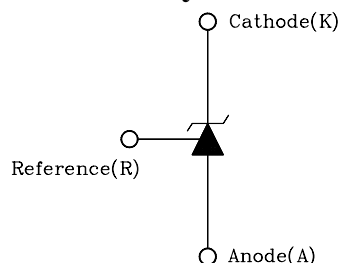
Type NO.	Marking	Package Code
SL432xSF	42□	SOT-23F

□: Grade => 3: $\pm 2\%$, A: $\pm 1\%$, B: $\pm 0.5\%$

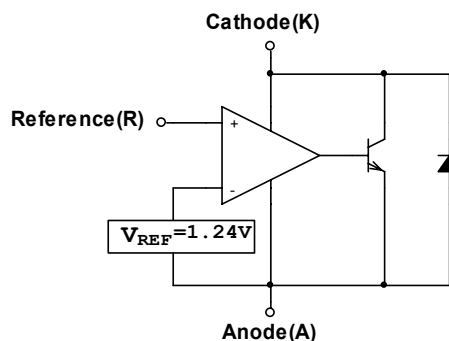
Outline Dimensions (Unit : mm)



Symbol



Functional block diagram



PIN Connections

1. Reference
2. Cathode
3. Anode

Absolute maximum ratings

[Ta=25℃]

Characteristic	Symbol	Rating	Unit
Cathode to Anode voltage	V_{KA}	18	V
Cathode current	I_K	30	mA
Reference input current	I_{ref}	3	mA
Power Dissipation	P_D^*	350	mW
Junction Temperature	T_J	150	℃
Operating temperature range	T_{opr}	-40 ~ +85	℃
Storage temperature range	T_{stg}	-55 ~ +150	℃

* With PCB(8×8mm copper area) at glass epoxy board(t=1.7mm, area : 20×20mm)

Recommended operating conditions

Characteristic	Symbol	Rating		Unit
		Min.	Max.	
Cathode to Anode voltage	V_{KA}	V_{ref}	16	V
Cathode current	I_K	0.1	25	mA

Electrical Characteristics (Ta=25℃, unless otherwise noted.)

Characteristic	Symbol	Condition		Min.	Typ.	Max.	Unit
Reference voltage (Fig.1)	V _{ref}	V _{KA} =V _{ref} , I _K =10mA	SL432BSF	1.234	1.240	1.246	V
			SL432ASF	1.228		1.252	
			SL432SF	1.215		1.265	
Reference input voltage deviation over temperature (Fig.1, Note1,2)	ΔV _{ref}	V _{KA} =V _{ref} , I _K =10mA @ -40°C ≤ Ta ≤ 85°C		-	10	20	mV
Ratio of delta reference input voltage to delta cathode voltage (Fig.2)	$\frac{\Delta V_{ref}}{\Delta V_{KA}}$	I _K =10mA V _{ref} ≤ V _{KA} ≤ 16V	ΔV _{ref} =V _{ref} (16V)-V _{ref}	-	-1.0	-2.7	mV/V
			ΔV _{KA} =V _{KA} (16V)-V _{ref}				
Reference current (Fig.2)	I _{ref}	I _K =10mA R1=10KΩ, R2=∞		-	1.0	1.5	μA
Reference input current deviation over temperature (Fig.2, Note 1,2)	ΔI _{ref}	I _K =10mA R1=10KΩ, R2=∞ @ -40°C ≤ Ta ≤ 85°C		-	0.04	0.08	μA
Minimum cathode current for regulation	I _{K(MIN)}	V _{KA} =V _{ref}		-	80	100	μA
Off-state cathode current (Fig.3)	I _{K(off)}	V _{KA} =16V, V _{ref} =0V		-	5	50	nA
Dynamic impedance (Fig.1, Note3)	Z _{KA}	V _{KA} =V _{ref} , f ≤ 1.0KHz 0.1mA ≤ I _K ≤ 25mA		-	0.25	0.4	Ω

Fig. 1 Test circuit for $V_{KA}=V_{ref}$

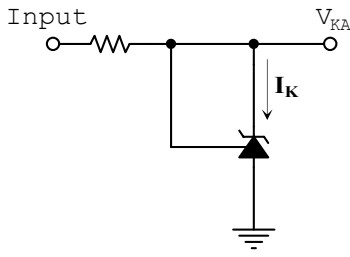
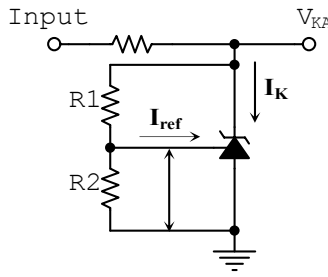
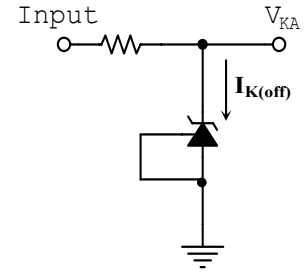


Fig. 2 Test circuit for $V_{KA}>V_{ref}$



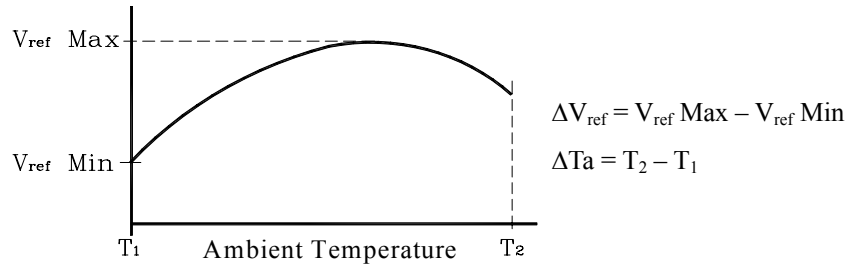
$$V_{KA} = V_{ref} \times \left(1 + \frac{R_1}{R_2}\right) + I_{ref} \times R_1$$

Fig. 3 Test circuit for $I_{K(off)}$



Note.

1. Ambient temperature range: $T_{LOW} = -40^{\circ}\text{C}$, $T_{High} = 85^{\circ}\text{C}$
2. The deviation parameters ΔV_{ref} and ΔI_{ref} are defined as the difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.



The average temperature coefficient of the reference input voltage, αV_{ref} is defined as:

$$\alpha V_{ref} \left(\frac{\text{ppm}}{^{\circ}\text{C}} \right) = \frac{\left(\frac{\Delta V_{ref}}{V_{ref}(T_a = 25^{\circ}\text{C})} \times 10^6 \right)}{T_a}$$

αV_{ref} can be positive or negative depending on whether $V_{ref} \text{ Min}$ or $V_{ref} \text{ Max}$ occurs at the lower ambient temperature, refer to Fig. 8

Example : $\Delta V_{ref} = 10\text{mV}$ and the slope is positive,

$$\Delta V_{ref} @ 25^{\circ}\text{C} = 1.24\text{V}$$

$$\Delta T_a = 125^{\circ}\text{C}$$

$$\alpha V_{ref} \left(\frac{\text{ppm}}{^{\circ}\text{C}} \right) = \frac{\left(\frac{0.010}{1.241} \right) \times 10^6}{125} = 65\text{ppm}/^{\circ}\text{C}$$

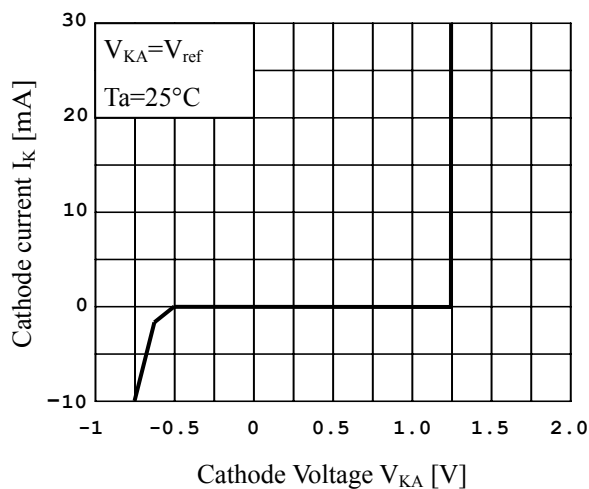
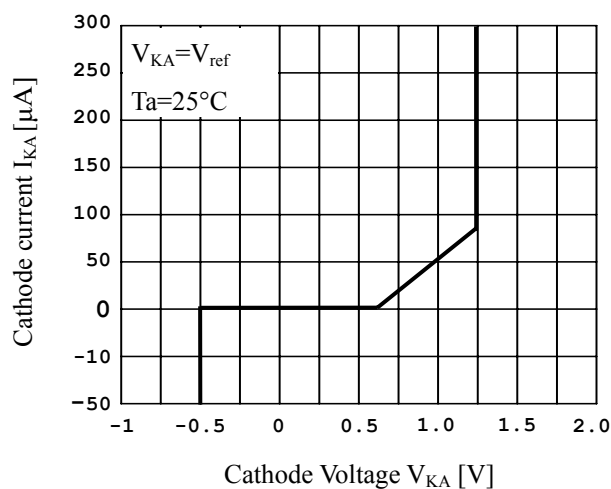
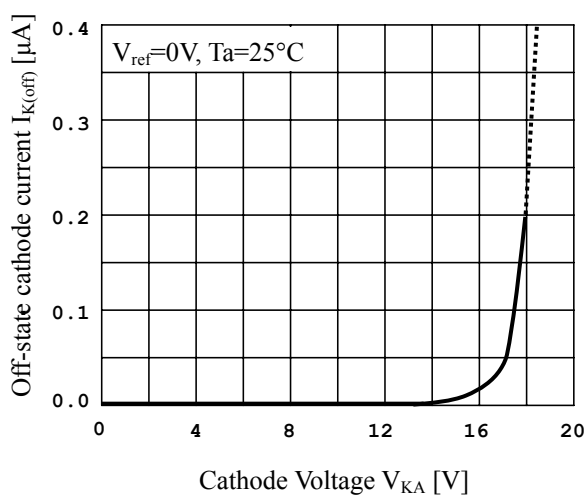
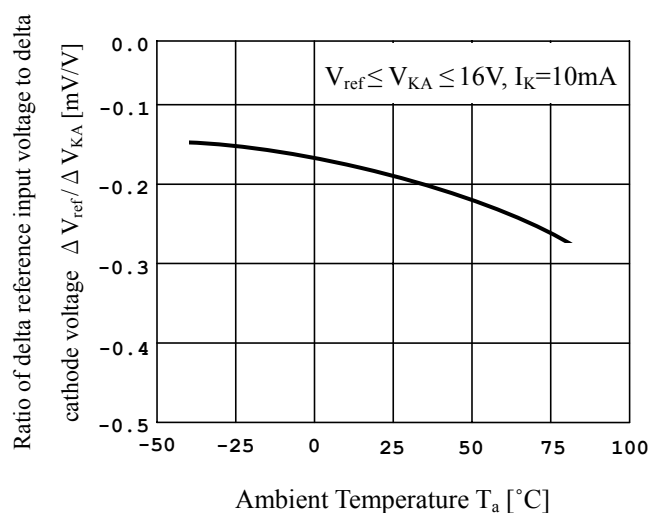
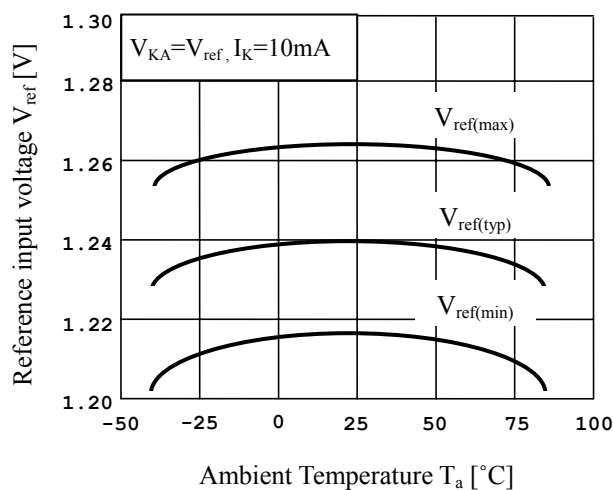
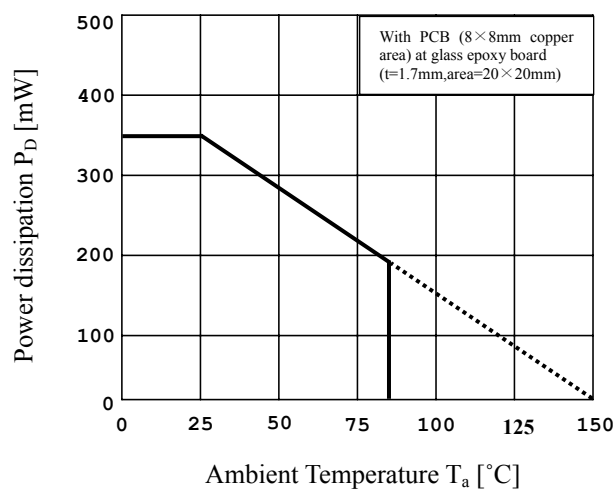
3. The dynamic impedance Z_{KA} is defined as:

$$|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_K}$$

When the device is operating with two external resistors, R_1 and R_2 , (refer to Fig.2) the total dynamic impedance of the circuit is given by:

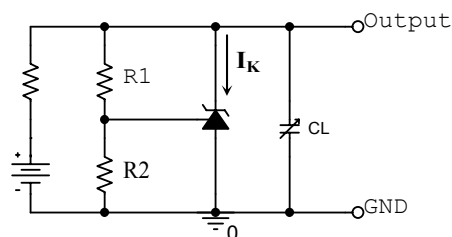
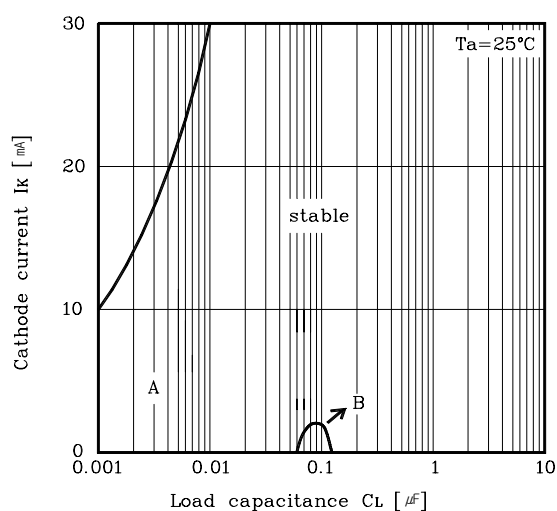
$$|Z_{KA}'| = |Z_{KA}| \times \left(1 + \frac{R_1}{R_2}\right)$$

Electrical Characteristics Curves (Continue)

Fig.4 I_K vs V_{KA} (1)Fig.5 I_K vs V_{KA} (2)Fig.6 $I_{K(off)}$ vs V_{KA} Fig.7 $\Delta V_{ref}/\Delta V_{KA}$ vs T_a Fig.8 V_{ref} vs T_a Fig.9 P_D vs T_a 

Electrical Characteristics Curves

Fig.10 Stability Boundary Conditions



Unstable Regions	V_{KA}	R_1 [K Ω]	R_2 [K Ω]
A, B	V_{ref}	0	∞
A	10V	10	1.415

Fig.11 Test circuit for Fig. 10

The AUK Corp. products are intended for the use as components in general electronic equipment (Office and communication equipment, measuring equipment, home appliance, etc.).

Please make sure that you consult with us before you use these AUK Corp. products in equipments which require high quality and / or reliability, and in equipments which could have major impact to the welfare of human life(atomic energy control, airplane, spaceship, transportation, combustion control, all types of safety device, etc.). AUK Corp. cannot accept liability to any damage which may occur in case these AUK Corp. products were used in the mentioned equipments without prior consultation with AUK Corp..

Specifications mentioned in this publication are subject to change without notice.