3-V TO 5.5-V MULTICHANNEL RS-232 LINE DRIVER/RECEIVER WITH ±15-kV ESD (HBM) PROTECTION

SLLS350E - APRIL 1999 - REVISED OCTOBER 2000

- Single-Chip and Single-Supply Interface for IBM™ PC/AT™ Serial Port
- Meets or Exceeds the Requirements of TIA/EIA-232-F and ITU v.28 Standards
- Operates With 3-V to 5.5-V V_{CC} Supply
- Always-Active Noninverting Receiver Output (ROUT2B)
- Operates up to 250 kbit/s
- Designed to Transmit at a Data Rate of 250 kbit/s
- Low Standby Current . . . 1 μA Typical
- External Capacitors . . . 4 × 0.1 μF
- Accepts 5-V Logic Input With 3.3-V Supply
- Designed to Be Interchangeable With Maxim MAX3243
- Serial-Mouse Driveability
- RS-232 Bus-Pin ESD Protection Exceeds ±15-kV Using Human-Body Model (HBM)
- Auto-Powerdown Feature to Disable Driver Outputs When No Valid RS-232 Signal Is Sensed
- Applications
 - Battery-Powered Systems, PDAs, Notebooks, Laptops, Palmtop PCs, and Hand-Held Equipment
- Package Options Include Plastic Small-Outline (DW), Shrink Small-Outline (DB), and Thin Shrink Small-Outline (PW) Packages

DB, DW, OR PW PACKAGE (TOP VIEW)

		_	
C2+[1	28	C1+
C2-[2	27] V+
V-[3	26] V _{CC}
RIN1	4	25] GND
RIN2	5	24] C1-
RIN3[6	23	FORCEON
RIN4[7	22	FORCEOFF
RIN5[8	21	INVALID
DOUT1[9	20	ROUT2B
DOUT2[10	19	ROUT1
DOUT3[11	18	ROUT2
DIN3[12	17	ROUT3
DIN2	13	16	ROUT4
DIN1	14	15	ROUT5

description

The MAX3243 device consists of three line drivers, five line receivers, and a dual charge-pump circuit with ±15-kV ESD (HBM) protection pin to pin (serial-port connection pins, including GND). The device meets the requirements of TIA/EIA-232-F and provides the electrical interface between an asynchronous communication controller and the serial-port connector. This combination of drivers and receivers matches that needed for the typical serial port used in an IBM PC/AT, or compatible. The charge pump and four small external capacitors allow operation from a single 3-V to 5.5-V supply. In addition, the device includes an always-active noninverting output (ROUT2B), which allows applications using the ring indicator to transmit data while the device is powered down. The device operates at data signaling rates up to 250 kbit/s and a maximum of 30-V/μs driver output slew rate.



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description (continued)

Flexible control options for power management are available when the serial port is inactive. The auto-powerdown feature functions when FORCEON is low and FORCEOFF is high. During this mode of operation, if the device does not sense a valid RS-232 signal, the driver outputs are disabled. If FORCEOFF is set low, both drivers and receivers (except ROUT2B) are shut off, and the supply current is reduced to 1 μA. Disconnecting the serial port or turning off the peripheral drivers causes the auto-powerdown condition to occur.

Auto-powerdown can be disabled when FORCEON and FORCEOFF are high, and should be done when driving a serial mouse. With auto-powerdown enabled, the device is activated automatically when a valid signal is applied to any receiver input. The INVALID output is used to notify the user if an RS-232 signal is present at any receiver input. INVALID is high (valid data) if any receiver input voltage is greater than 2.7 V or less than -2.7 V or has been between –0.3 V and 0.3 V for less than 30 μs. INVALID is low (invalid data) if all receiver input voltages are between –0.3 V and 0.3 V for more than 30 μs. Refer to Figure 5 for receiver input levels.

The MAX3243C is characterized for operation from 0°C to 70°C. The MAX3243I is characterized for operation from -40°C to 85°C.

AVAILABLE OPTIONS

	Р	ACKAGED DEVICES		
TA	SHRINK SMALL OUTLINE (DB)	SMALL OUTLINE (DW)	THIN SHRINK SMALL OUTLINE (PW)	
0°C to 70°C	MAX3243CDBR	MAX3243CDW	MAX3243CPWR	
-40°C to 85°C	MAX3243IDBR	MAX3243IDW	MAX3243IPWR	

The DB and PW packages are only available taped and reeled. The DW package is also available taped and reeled. Add the suffix R to device type (e.g., MAX3243CDWR).

Function Tables

EACH DRIVER

		INPUTS		OUTPUT	
DIN	FORCEON	FORCEOFF	VALID RIN RS-232 LEVEL	DOUT	DRIVER STATUS
Х	Χ	L	Х	Z	Powered off
L	Н	Н	Х	Н	Normal operation with
Н	Н	Н	X	L	auto-powerdown disabled
L	L	Н	Yes	Н	Normal operation with
Н	L	Н	Yes	L	auto-powerdown enabled
L	L	Н	No	Z	Powered off by
Н	L	Н	No	Z	auto-powerdown feature

H = high level, L = low level, X = irrelevant, Z = high impedance





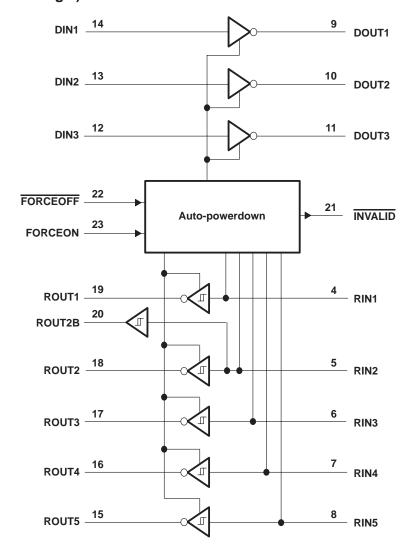
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EACH RECEIVER

		INPUTS		OUTPUTS		
RIN2	RIN1, RIN3–RIN5	FORCEOFF	VALID RIN RS-232 LEVEL	ROUT2B	ROUT	RECEIVER STATUS
L	X	L	Х	L	Z	Powered off while
Н	Χ	L	X	Н	Z	ROUT2B is active
L	L	Н	Yes	L	Н	
L	Н	Н	Yes	L	L	Normal operation with
Н	L	Н	Yes	н	Н	auto-powerdown
Н	Н	Н	Yes	Н	L	disabled/enabled
Open	Open	Н	No	L	Н	

H = high level, L = low level, X = irrelevant, Z = high impedance (off), Open = input disconnected or connected driver off

logic diagram (positive logic)







MAX3243

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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)

Supply voltage range, V _{CC} (see Note 1)	0.3 V to 6 V
Positive output supply voltage range, V+ (see Note 1)	0.3 V to 7 V
Negative output supply voltage range, V– (see Note 1)	0.3 V to –7 V
Supply voltage difference, V+ – V– (see Note 1)	13 V
Input voltage range, V _I : Driver (FORCEOFF, FORCEON)	0.3 V to 6 V
Receiver	
Output voltage range, V _O : Driver	13.2 V to 13.2 V
Receiver (INVALID)	0.3 V to V_{CC} + 0.3 V
Package thermal impedance, θ _{JA} (see Note 2): DB package	62°C/W
DW package	
PW package	62°C/W
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C
Storage temperature range, T _{stq}	

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltages are with respect to network GND.

recommended operating conditions (see Note 3 and Figure 6)

				MIN	NOM	MAX	UNIT
	Supply voltage		V _{CC} = 3.3 V	3	3.3	3.6	V
			V _{CC} = 5 V	4.5	5	5.5	٧
\/	V _{IH} Driver and control high-level input voltage	DIN FORCES FORCES	V _{CC} = 3.3 V	2			V
۷IH		DIN, FORCEOFF, FORCEON	V _{CC} = 5 V	2.4			٧
VIL	Driver and control low-level input voltage	DIN, FORCEOFF, FORCEON				0.8	V
VI	Driver and control input voltage	DIN, FORCEOFF, FORCEON		0		5.5	V
VI	Receiver input voltage			-25		25	V
T. On a water or free a circle and a water			MAX3243C	0		70	°C
TA	Operating nee-an temperature	ng free-air temperature		-40		85	C

NOTE 3: Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 \vee ± 0.3 \vee ; C1 = 0.047 μ F, C2–C4 = 0.33 μ F at V_{CC} = 5 \vee ± 0.5 \vee .

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)

PARAMETER		TEST CONDITIONS	MIN	TYP‡	MAX	UNIT	
П	Input leakage current	FORCEOFF, FORCEON			±0.01	±1	μΑ
		Auto-powerdown disabled	No load, FORCEOFF and FORCEON at V _{CC}		0.3	1	mA
	Supply current	Powered off	No load, FORCEOFF at GND	1 10			
Icc	(T _A = 25°C)	Auto-powerdown enabled	No load, FORCEOFF at V _{CC} , FORCEON at GND, All RIN are open or grounded All DIN are grounded		1	10	μΑ

[‡] All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

NOTE 3. Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 V \pm 0.3 V; C1 = 0.047 μ F, C2–C4 = 0.33 μ F at V_{CC} = 5 V \pm 0.5 V.





^{2.} The package thermal impedance is calculated in accordance with JESD 51-7.

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DRIVER SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)

PARAMETER TEST CONDITIONS		TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
Vон	High-level output voltage	All DOUT at R _L = 3 k Ω to GND	5	5.4		V
VOL	Low-level output voltage	All DOUT at R _L = $3 \text{ k}\Omega$ to GND		-5.4		V
Vo	Output voltage (mouse driveability)	DIN1 = DIN2 = GND, DIN3 = V_{CC} , 3- $k\Omega$ to GND at DOUT3, DOUT1 = DOUT2 = 2.5 mA				V
ΊΗ	High-level input current	$V_I = V_{CC}$		±0.01	±1	μΑ
Ι _Ι L	Low-level input current	V _I at GND		±0.01	±1	μΑ
la a	Object also the terminal	$V_{CC} = 3.6 \text{ V}, \qquad \qquad V_{O} = 0 \text{ V}$		±35	±60	mA
los	Short-circuit output current‡	$V_{CC} = 5.5 \text{ V}, \qquad \qquad V_{O} = 0 \text{ V}$		±33	±00	IIIA
r _O	Output resistance	V_{CC} , V+, and V- = 0 V, V_{O} = ± 2 V	300	10M		Ω
loff	Output leakage current	FORCEOFF = GND, $V_O = \pm 12 \text{ V}$, $V_{CC} = 0 \text{ to } 5.5 \text{ V}$			±25	μΑ

[†] All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

NOTE 3. Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 V ± 0.3 V; C1 = 0.047 μ F, C2–C4 = 0.33 μ F at V_{CC} = 5 V ± 0.5 V.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)

	PARAMETER	TEST CONDITIONS		MIN	TYP†	MAX	UNIT
	Maximum data rate	C _L = 1000 pF, One DOUT switching,	$R_L = 3 \text{ k}\Omega$, See Figure 1	150	250		kbit/s
t _{sk(p)}	Pulse skew§	C _L = 150 pF to 2500 pF	R _L = 3 k Ω to 7 k Ω , See Figure 2		100		ns
SR(tr)	Slew rate, transition region	V_{CC} = 3.3 V, R _L = 3 kΩ to 7 kΩ	C _L = 150 pF to 1000 pF	6		30	V/μs
J SK(II)	(see Figure 1)	$R_L = 3 \text{ k}\Omega \text{ to } 7 \text{ k}\Omega$	C _L = 150 pF to 2500 pF	4		30	v/μs

[†] All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

NOTE 3. Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 V ± 0.3 V; C1 = 0.047 μ F, C2–C4 = 0.33 μ F at V_{CC} = 5 V ± 0.5 V.





^{\$} Short-circuit durations should be controlled to prevent exceeding the device absolute power dissipation ratings, and not more than one output should be shorted at a time.

[§] Pulse skew is defined as |tpLH - tpHL| of each channel of the same device.

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RECEIVER SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)

	PARAMETER	TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
Vон	High-level output voltage	I _{OH} = -1 mA	V _{CC} – 0.6 V	V _{CC} – 0.1 V		V
VOL	Low-level output voltage	I _{OL} = 1.6 mA			0.4	V
\/	Desitive gains input threshold voltage	V _{CC} = 3.3 V		1.6	2.4	V
VIT+	Positive-going input threshold voltage	V _{CC} = 5 V		1.9	2.4	V
\/	Negative-going input threshold voltage	V _{CC} = 3.3 V	0.6	1.1		V
V _{IT} –	Negative-going input threshold voltage	V _{CC} = 5 V	0.8	1.4		V
V _{hys}	Input hysteresis (V _{IT+} - V _{IT-})			0.5		V
l _{off}	Output leakage current (except ROUT2B)	FORCEOFF = 0 V		±0.05	±10	μА
rį	Input resistance	$V_{I} = \pm 3 \text{ V to } \pm 25 \text{ V}$	3	5	7	kΩ

[†] All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

NOTE 3. Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 V ± 0.3 V; C1 = 0.047 μ F, C2–C4 = 0.33 μ F at V_{CC} = 5 V ± 0.5 V.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3)

PARAMETER		TEST CONDITIONS	MIN TYPT MAX	UNIT
tPLH	Propagation delay time, low- to high-level output	Cr. – 150 pE Soo Figure 3	150	ns
tPHL	Propagation delay time, high- to low-level output	C _L = 150 pF, See Figure 3	150	ns
t _{en}	Output enable time	C: 450 pF D: 2 kO See Figure 4	200	ns
tdis	Output disable time	$C_L = 150 \text{ pF}, R_L = 3 \text{ k}\Omega, \text{ See Figure 4}$	200	ns
t _{sk(p)}	Pulse skew [‡]	See Figure 3	50	ns

[†] All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

NOTE 3. Test conditions are C1–C4 = 0.1 μ F at V_{CC} = 3.3 V ± 0.3 V; C1 = 0.047 μ F, C2–C4 = 0.33 μ F at V_{CC} = 5 V ± 0.5 V.



[‡] Pulse skew is defined as |tplh - tphl| of each channel of the same device.

AUTO-POWERDOWN SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5)

	PARAMETER	TEST CONDITIONS	MIN	түр† І	MAX	UNIT
VT+(valid)	Receiver input threshold for INVALID high-level output voltage	FORCEON = GND, FORCEOFF = V _{CC}			2.7	V
VT-(valid)	Receiver input threshold for INVALID high-level output voltage	FORCEON = GND, FORCEOFF = V _{CC}	-2.7			V
VT(invalid)	Receiver input threshold for INVALID low-level output voltage	FORCEON = GND, FORCEOFF = V _{CC}	-0.3		0.3	V
VOH	INVALID high-level output voltage	$I_{OH} = -1 \text{ mA}$, FORCEON = GND, FORCEOFF = V_{CC}	V _{CC} - 0.6			V
VOL	INVALID low-level output voltage	$I_{OL} = 1.6 \text{ mA}$, FORCEON = GND, FORCEOFF = V_{CC}			0.4	V

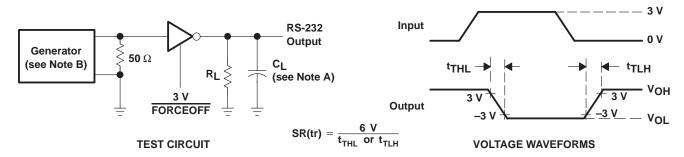
 $[\]dagger$ All typical values are at V_{CC} = 3.3 V or V_{CC} = 5 V, and T_A = 25°C.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5)

	PARAMETER	MIN	TYP [†]	MAX	UNIT
^t valid	Propagation delay time, low- to high-level output		1		μs
^t invalid	Propagation delay time, high- to low-level output		30		μs
t _{en}	Supply enable time		100		μs

[†] All typical values are at $V_{CC} = 3.3 \text{ V}$ or $V_{CC} = 5 \text{ V}$, and $T_A = 25^{\circ}\text{C}$.

PARAMETER MEASUREMENT INFORMATION



NOTES: A. C_L includes probe and jig capacitance.

B. The pulse generator has the following characteristics: PRR = 250 kbit/s, $Z_O = 50 \Omega$, 50% duty cycle, $t_f \le 10$ ns.

Figure 1. Driver Slew Rate

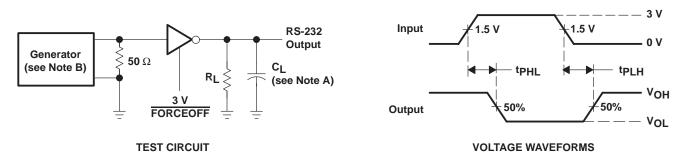




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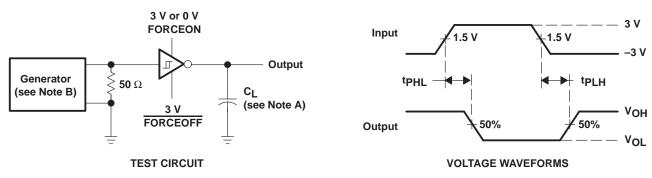
PARAMETER MEASUREMENT INFORMATION



NOTES: A. C_I includes probe and jig capacitance.

B. The pulse generator has the following characteristics: PRR = 250 kbit/s, $Z_O = 50 \Omega$, 50% duty cycle, $t_r \le 10$ ns. $t_f \le 10$ ns.

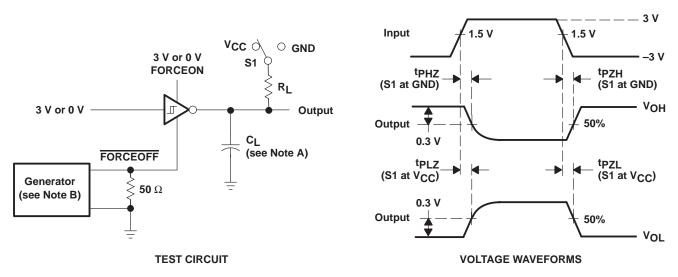
Figure 2. Driver Pulse Skew



NOTES: A. CL includes probe and jig capacitance.

B. The pulse generator has the following characteristics: $Z_O = 50 \ \Omega$, 50% duty cycle, $t_r \le 10 \ ns$, $t_f \le 10 \ ns$.

Figure 3. Receiver Propagation Delay Times



NOTES: A. C_L includes probe and jig capacitance.

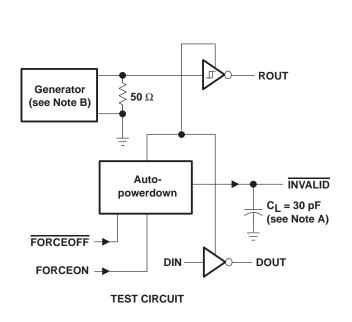
- B. The pulse generator has the following characteristics: $Z_O = 50 \Omega$, 50% duty cycle, $t_f \le 10$ ns. $t_f \le 10$ ns.
- C. tpLz and tpHz are the same as tdis.
- D. tpzL and tpzH are the same as ten.

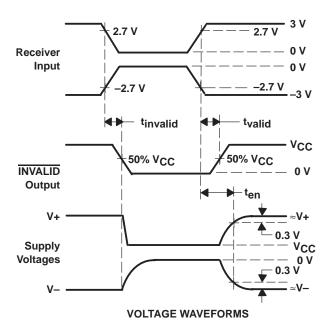
Figure 4. Receiver Enable and Disable Times

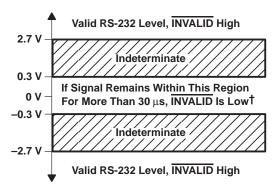




PARAMETER MEASUREMENT INFORMATION







† Auto-powerdown disables drivers and reduces supply current to 1 μ A.

NOTES: A. C_L includes probe and jig capacitance.

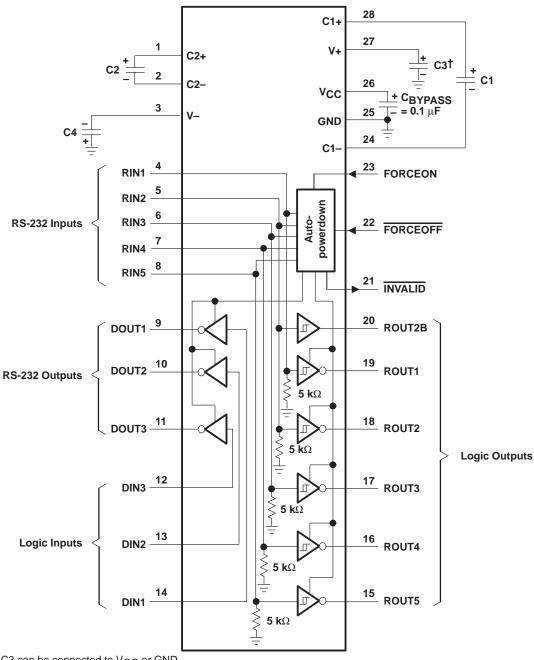
B. The pulse generator has the following characteristics: PRR = 5 kbit/s, $Z_O = 50 \Omega$, 50% duty cycle, $t_f \le 10$ ns.

Figure 5. INVALID Propagation Delay Times and Supply Enabling Time





APPLICATION INFORMATION



 † C3 can be connected to VCC or GND. NOTE A: Resistor values shown are nominal.

V_{CC} vs CAPACITOR VALUES

VCC	C1	C2, C3, and C4
$\begin{array}{c} \textbf{3.3 V} \pm \textbf{0.3 V} \\ \textbf{5 V} \pm \textbf{0.5 V} \\ \textbf{3 V to 5.5 V} \end{array}$	0.1 μF 0.047 μF 0.1 μF	0.1 μF 0.33 μF 0.47 μF

Figure 6. Typical Operating Circuit and Capacitor Values





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