



# MICROCHIP

# 25AA040/25LC040/25C040

## 4K SPI™ Bus Serial EEPROM

### Device Selection Table

Part Number	Vcc Range	Max. Clock Frequency	Temp. Ranges
25AA040	1.8-5.5V	1 MHz	I
25LC040	2.5-5.5V	2 MHz	I
25C040	4.5-5.5V	3 MHz	I,E

### Features

- Low-power CMOS technology
  - Write current: 3 mA typical
  - Read current: 500 µA typical
  - Standby current: 500 nA typical
- 512 x 8-bit organization
- 16 byte page
- Write cycle time: 5 ms max.
- Self-timed ERASE and WRITE cycles
- Block write protection
  - Protect none, 1/4, 1/2 or all of array
- Built-in write protection
  - Power on/off data protection circuitry
  - Write enable latch
  - Write-protect pin
- Sequential read
- High reliability
  - Endurance: 1M cycles
  - Data retention: > 200 years
  - ESD protection: > 4000V
- 8-pin PDIP, SOIC, and TSSOP packages
- Temperature ranges supported:
  - Industrial (I): -40°C to +85°C
  - Automotive (E) (25C040): -40°C to +125°C

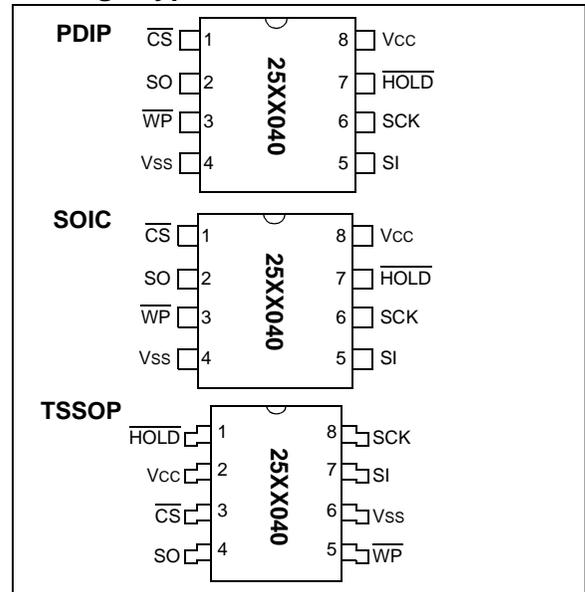
### Description

The Microchip Technology Inc. 25AA040/25LC040/25C040 (25XX040\*) is a 4 Kbit serial Electrically Erasable PROM. The memory is accessed via a simple Serial Peripheral Interface™ (SPI™) compatible serial bus. The bus signals required are a clock input (SCK) plus separate data in (SI) and data out (SO) lines. Access to the device is controlled through a Chip Select ( $\overline{CS}$ ) input.

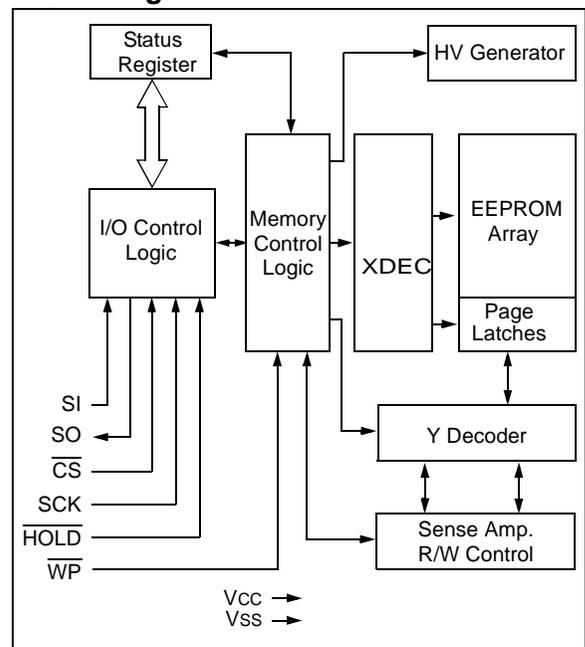
\*25XX040 is used in this document as a generic part number for the 25AA040/25LC040/25C040 devices. SPI is a trademark of Motorola Corporation.

Communication to the device can be paused via the hold pin ( $\overline{HOLD}$ ). While the device is paused, transitions on its inputs will be ignored, with the exception of Chip Select, allowing the host to service higher priority interrupts. Also, write operations to the device can be disabled via the write-protect pin ( $\overline{WP}$ ).

### Package Types



### Block Diagram



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## 1.0 ELECTRICAL CHARACTERISTICS

### Absolute Maximum Ratings<sup>(†)</sup>

V <sub>CC</sub> .....	7.0V
All inputs and outputs w.r.t. V <sub>SS</sub> .....	-0.6V to V <sub>CC</sub> +1.0V
Storage temperature .....	-65°C to 150°C
Ambient temperature under bias .....	-65°C to 125°C
ESD protection on all pins .....	4 KV

† **NOTICE:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for an extended period of time may affect device reliability

**TABLE 1-1: DC CHARACTERISTICS**

DC CHARACTERISTICS			Industrial (I): T <sub>A</sub> = -40°C to +85°C V <sub>CC</sub> = 1.8V to 5.5V Automotive (E): T <sub>A</sub> = -40°C to +125°C V <sub>CC</sub> = 4.5V to 5.5V (25C040 only)			
Param. No.	Sym.	Characteristic	Min.	Max.	Units	Test Conditions
D001	V <sub>IH1</sub>	High-level input voltage	2.0	V <sub>CC</sub> +1	V	V <sub>CC</sub> ≥ 2.7V <b>(Note)</b>
D002	V <sub>IH2</sub>		0.7 V <sub>CC</sub>	V <sub>CC</sub> +1	V	V <sub>CC</sub> < 2.7V <b>(Note)</b>
D003	V <sub>IL1</sub>	Low-level input voltage	-0.3	0.8	V	V <sub>CC</sub> ≥ 2.7V <b>(Note)</b>
D004	V <sub>IL2</sub>		-0.3	0.3 V <sub>CC</sub>	V	V <sub>CC</sub> < 2.7V <b>(Note)</b>
D005	V <sub>OL</sub>	Low-level output voltage	—	0.4	V	I <sub>OL</sub> = 2.1 mA
D006	V <sub>OL</sub>		—	0.2	V	I <sub>OL</sub> = 1.0 mA, V <sub>CC</sub> < 2.5V
D007	V <sub>OH</sub>	High-level output voltage	V <sub>CC</sub> -0.5	—	V	I <sub>OH</sub> = -400 μA
D008	I <sub>LI</sub>	Input leakage current	—	±1	μA	$\overline{CS} = V_{CC}$ , V <sub>IN</sub> = V <sub>SS</sub> TO V <sub>CC</sub>
D009	I <sub>LO</sub>	Output leakage current	—	±1	μA	$\overline{CS} = V_{CC}$ , V <sub>OUT</sub> = V <sub>SS</sub> TO V <sub>CC</sub>
D010	C <sub>INT</sub>	Internal Capacitance (all inputs and outputs)	—	7	pF	T <sub>A</sub> = 25°C, CLK = 1.0 MHz, V <sub>CC</sub> = 5.0V <b>(Note)</b>
D011	I <sub>CC</sub> Read	Operating Current	—	1	mA	V <sub>CC</sub> = 5.5V; F <sub>CLK</sub> = 3.0 MHz; SO = Open
			—	500	μA	V <sub>CC</sub> = 2.5V; F <sub>CLK</sub> = 2.0 MHz; SO = Open
D012	I <sub>CC</sub> Write		—	5	mA	V <sub>CC</sub> = 5.5V
			—	3	mA	V <sub>CC</sub> = 2.5V
D013	I <sub>CCS</sub>	Standby Current	—	5	μA	$\overline{CS} = V_{CC} = 5.5V$ , Inputs tied to V <sub>CC</sub> or V <sub>SS</sub>
			—	1	μA	$\overline{CS} = V_{CC} = 2.5V$ , Inputs tied to V <sub>CC</sub> or V <sub>SS</sub>

**Note:** This parameter is periodically sampled and not 100% tested.

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**TABLE 1-2: AC CHARACTERISTICS**

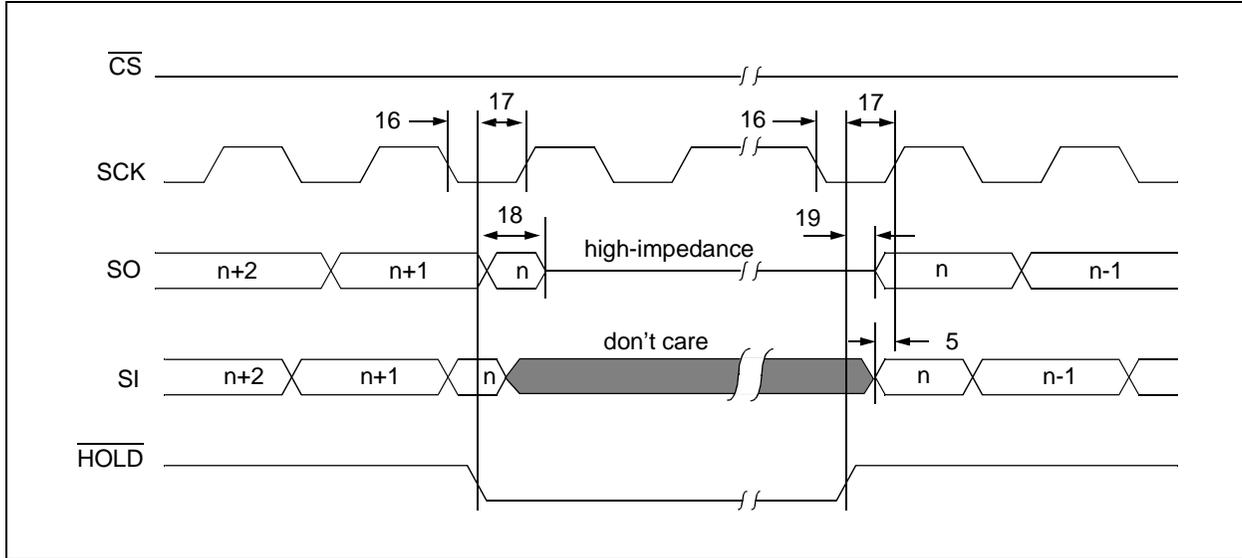
AC CHARACTERISTICS			Industrial (I): TA = -40°C to +85°C		VCC = 1.8V to 5.5V	
			Automotive (E): TA = -40°C to +125°C		VCC = 4.5V to 5.5V (25C040 only)	
Param No.	Sym.	Characteristic	Min.	Max.	Units	Test Conditions
1	FCLK	Clock Frequency	—	3	MHz	VCC = 4.5V to 5.5V
			—	2	MHz	VCC = 2.5V to 4.5V
			—	1	MHz	VCC = 1.8V to 2.5V
2	Tcss	CS Setup Time	100	—	ns	VCC = 4.5V to 5.5V
			250	—	ns	VCC = 2.5V to 4.5V
			500	—	ns	VCC = 1.8V to 2.5V
3	Tcsh	CS Hold Time	150	—	ns	VCC = 4.5V to 5.5V
			250	—	ns	VCC = 2.5V to 4.5V
			475	—	ns	VCC = 1.8V to 2.5V
4	TcSD	CS Disable Time	500	—	ns	—
5	TSU	Data Setup Time	30	—	ns	VCC = 4.5V to 5.5V
			50	—	ns	VCC = 2.5V to 4.5V
			50	—	ns	VCC = 1.8V to 2.5V
6	THD	Data Hold Time	50	—	ns	VCC = 4.5V to 5.5V
			100	—	ns	VCC = 2.5V to 4.5V
			100	—	ns	VCC = 1.8V to 2.5V
7	TR	CLK Rise Time	—	2	μs	(Note 1)
8	TF	CLK Fall Time	—	2	μs	(Note 1)
9	THI	Clock High Time	150	—	ns	VCC = 4.5V to 5.5V
			230	—	ns	VCC = 2.5V to 4.5V
			475	—	ns	VCC = 1.8V to 2.5V
10	TLO	Clock Low Time	150	—	ns	VCC = 4.5V to 5.5V
			230	—	ns	VCC = 2.5V to 4.5V
			475	—	ns	VCC = 1.8V to 2.5V
11	TCLD	Clock Delay Time	50	—	ns	—
12	TCLE	Clock Enable Time	50	—	ns	—
13	TV	Output Valid from Clock Low	—	150	ns	VCC = 4.5V to 5.5V
			—	230	ns	VCC = 2.5V to 4.5V
			—	475	ns	VCC = 1.8V to 2.5V
14	THO	Output Hold Time	0	—	ns	(Note 1)
15	TDis	Output Disable Time	—	200	ns	VCC = 4.5V to 5.5V (Note 1)
			—	250	ns	VCC = 2.5V to 4.5V (Note 1)
			—	500	ns	VCC = 1.8V to 2.5V (Note 1)
16	THS	HOLD Setup Time	100	—	ns	VCC = 4.5V to 5.5V
			100	—	ns	VCC = 2.5V to 4.5V
			200	—	ns	VCC = 1.8V to 2.5V
17	THH	HOLD Hold Time	100	—	ns	VCC = 4.5V to 5.5V
			100	—	ns	VCC = 2.5V to 4.5V
			200	—	ns	VCC = 1.8V to 2.5V
18	THZ	HOLD Low to Output High-Z	100	—	ns	VCC = 4.5V to 5.5V (Note 1)
			150	—	ns	VCC = 2.5V to 4.5V (Note 1)
			200	—	ns	VCC = 1.8V to 2.5V (Note 1)
19	THV	HOLD High to Output Valid	100	—	ns	VCC = 4.5V to 5.5V
			150	—	ns	VCC = 2.5V to 4.5V
			200	—	ns	VCC = 1.8V to 2.5V
20	TWC	Internal Write Cycle Time	—	5	ms	—
21	—	Endurance	1M	—	E/W Cycles	(Note 2)

**Note 1:** This parameter is periodically sampled and not 100% tested.

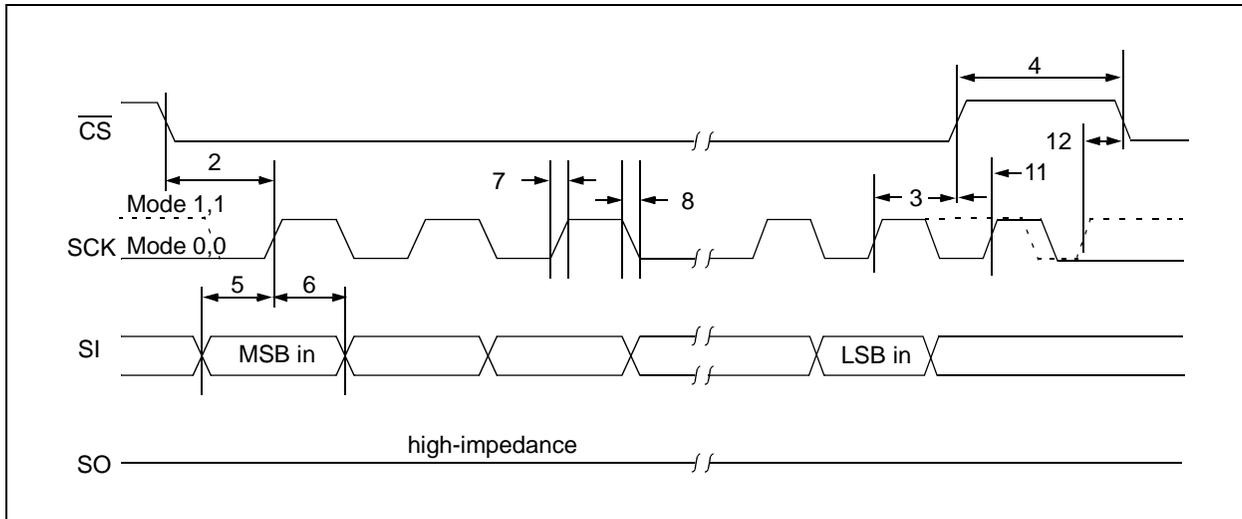
**Note 2:** This parameter is not tested but ensured by characterization. For endurance estimates in a specific application, please consult the Total Endurance™ Model which can be obtained from our web site: [www.microchip.com](http://www.microchip.com).

# 25A040/25LC040/25C040

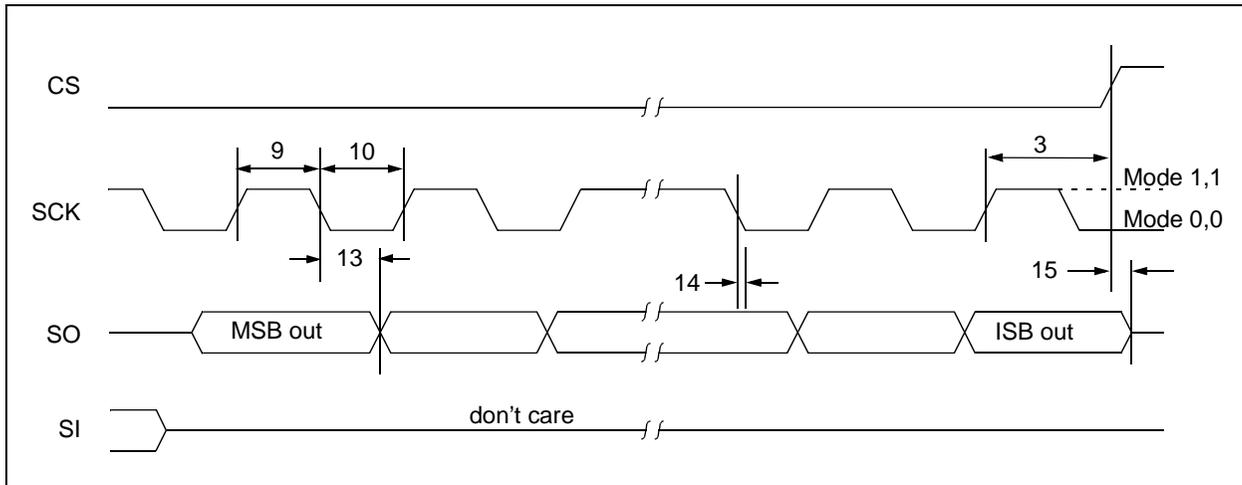
**FIGURE 1-1: HOLD TIMING**



**FIGURE 1-2: SERIAL INPUT TIMING**



**FIGURE 1-3: SERIAL OUTPUT TIMING**



# 25AA040/25LC040/25C040

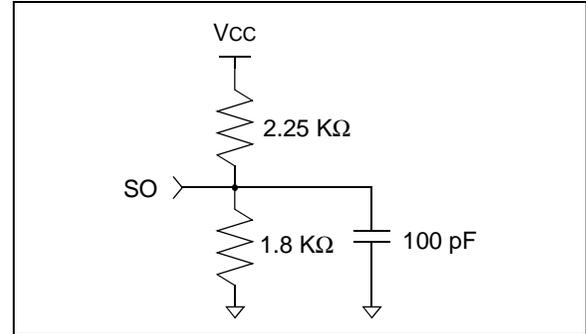
TABLE 1-3: AC TEST CONDITIONS

AC Waveform:	
VLO = 0.2V	—
VHI = Vcc - 0.2V	(Note 1)
VHI = 4.0V	(Note 2)
Timing Measurement Reference Level	
Input	0.5 Vcc
Output	0.5 Vcc

**Note 1:** For  $V_{cc} \leq 4.0V$

**Note 2:** For  $V_{cc} > 4.0V$

FIGURE 1-4: AC TEST CIRCUIT AC



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## 2.0 PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 2-1.

**TABLE 2-1: PIN FUNCTION TABLE**

Name	PDIP	SOIC	TSSOP	Description
$\overline{\text{CS}}$	1	1	3	Chip Select Input
SO	2	2	4	Serial Data Output
$\overline{\text{WP}}$	3	3	5	Write-Protect Pin
Vss	4	4	6	Ground
SI	5	5	7	Serial Data Input
SCK	6	6	8	Serial Clock Input
$\overline{\text{HOLD}}$	7	7	1	Hold Input
Vcc	8	8	2	Supply Voltage

### 2.1 Chip Select ( $\overline{\text{CS}}$ )

A low level on this pin selects the device. A high level deselects the device and forces it into Standby mode. However, a programming cycle which is already initiated or in progress will be completed, regardless of the  $\overline{\text{CS}}$  input signal. If  $\overline{\text{CS}}$  is brought high during a program cycle, the device will go in Standby mode as soon as the programming cycle is complete. When the device is deselected, SO goes into the high-impedance state, allowing multiple parts to share the same SPI bus. A low-to-high transition on  $\overline{\text{CS}}$  after a valid write sequence initiates an internal write cycle. After power-up, a low level on  $\overline{\text{CS}}$  is required prior to any sequence being initiated.

### 2.2 Serial Output (SO)

The SO pin is used to transfer data out of the 25XX040. During a read cycle, data is shifted out on this pin after the falling edge of the serial clock.

### 2.3 Write-Protect ( $\overline{\text{WP}}$ )

This pin is a hardware write-protect input pin. When  $\overline{\text{WP}}$  is low, all writes to the array or Status register are disabled, but any other operation functions normally. When  $\overline{\text{WP}}$  is high, all functions, including nonvolatile writes operate normally.  $\overline{\text{WP}}$  going low at any time will reset the write enable latch and inhibit programming, except when an internal write has already begun. If an internal write cycle has already begun,  $\overline{\text{WP}}$  going low will have no effect on the write. See Table 3-2 for Write-Protect Functionality Matrix.

### 2.4 Serial Input (SI)

The SI pin is used to transfer data into the device. It receives instructions, addresses and data. Data is latched on the rising edge of the serial clock.

### 2.5 Serial Clock (SCK)

The SCK is used to synchronize the communication between a master and the 25XX040. Instructions, addresses or data present on the SI pin are latched on the rising edge of the clock input, while data on the SO pin is updated after the falling edge of the clock input.

### 2.6 Hold ( $\overline{\text{HOLD}}$ )

The  $\overline{\text{HOLD}}$  pin is used to suspend transmission to the 25XX040 while in the middle of a serial sequence without having to retransmit the entire sequence again at a later time. It must be held high any time this function is not being used. Once the device is selected and a serial sequence is underway, the  $\overline{\text{HOLD}}$  pin may be pulled low to pause further serial communication without resetting the serial sequence. The  $\overline{\text{HOLD}}$  pin must be brought low while SCK is low, otherwise the HOLD function will not be invoked until the next SCK high-to-low transition. The 25XX040 must remain selected during this sequence. The SI, SCK and SO pins are in a high-impedance state during the time the part is paused and transitions on these pins will be ignored. To resume serial communication,  $\overline{\text{HOLD}}$  must be brought high while the SCK pin is low, otherwise serial communication will not resume. Lowering the HOLD line at any time will tri-state the SO line.

## 3.0 FUNCTIONAL DESCRIPTION

### 3.1 Principles of Operation

The 25XX040 is a 512 byte Serial EEPROM designed to interface directly with the Serial Peripheral Interface (SPI) port of many of today's popular microcontroller families, including Microchip's PIC16C6X/7X microcontrollers. It may also interface with microcontrollers that do not have a built-in SPI port by using discrete I/O lines programmed properly with the software.

The 25XX040 contains an 8-bit instruction register. The part is accessed via the SI pin, with data being clocked in on the rising edge of SCK. The  $\overline{CS}$  pin must be low and the HOLD pin must be high for the entire operation. The WP pin must be held high to allow writing to the memory array.

Table 3-1 contains a list of the possible instruction bytes and format for device operation. The Most Significant address bit (A8) is located in the instruction byte. All instructions, addresses, and data are transferred MSB first, LSB last.

Data is sampled on the first rising edge of SCK after  $\overline{CS}$  goes low. If the clock line is shared with other peripheral devices on the SPI bus, the user can assert the  $\overline{HOLD}$  input and place the 25XX040 in 'HOLD' mode. After releasing the  $\overline{HOLD}$  pin, operation will resume from the point when the  $\overline{HOLD}$  was asserted.

### 3.2 Read Sequence

The part is selected by pulling  $\overline{CS}$  low. The 8-bit read instruction with the A8 address bit is transmitted to the 25XX040 followed by the lower 8-bit address (A7 through A0). After the correct READ instruction and address are sent, the data stored in the memory at the selected address is shifted out on the SO pin. The data stored in the memory at the next address can be read sequentially by continuing to provide clock pulses. The internal address pointer is automatically incremented to the next higher address after each byte of data is shifted out. When the highest address is reached (01FFh), the address counter rolls over to address 0000h allowing the read cycle to be continued indefinitely. The read operation is terminated by raising the CS pin (Figure 3-1).

**TABLE 3-1: INSTRUCTION SET**

Instruction Name	Instruction Format	Description
READ	0000 A8011	Read data from memory array beginning at selected address
WRITE	0000 A8010	Write data to memory array beginning at selected address
WRDI	0000 0100	Reset the write enable latch (disable write operations)
WREN	0000 0110	Set the write enable latch (enable write operations)
RDSR	0000 0101	Read Status register
WRSR	0000 0001	Write Status register

**Note:** A8 is the 9<sup>th</sup> address bit necessary to fully address 512 bytes.

### 3.3 Write Sequence

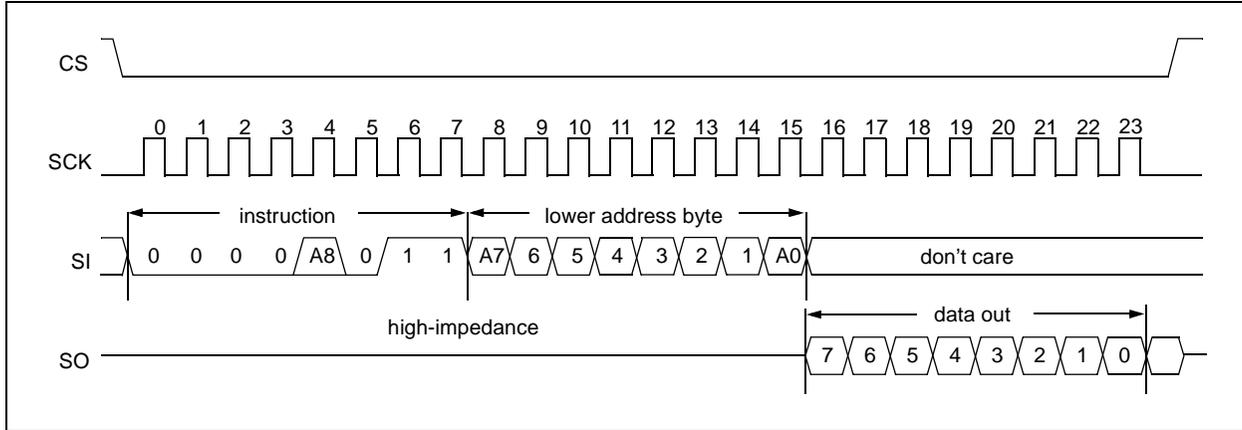
Prior to any attempt to write data to the 25XX040, the write enable latch must be set by issuing the WREN instruction (Figure 3-4). This is done by setting  $\overline{CS}$  low and then clocking out the proper instruction into the 25XX040. After all eight bits of the instruction are transmitted, the  $\overline{CS}$  must be brought high to set the write enable latch. If the write operation is initiated immediately after the WREN instruction without  $\overline{CS}$  being brought high, the data will not be written to the array because the write enable latch will not have been properly set.

Once the write enable latch is set, the user may proceed by setting the  $\overline{CS}$  low, issuing a WRITE instruction, followed by the address, and then the data to be written. Keep in mind that the Most Significant address bit (A8) is included in the instruction byte. Up to 16 bytes of data can be sent to the 25XX040 before a write cycle is necessary. The only restriction is that all of the bytes must reside in the same page. A page address begins with XXXX 0000 and ends with XXXX 1111. If the internal address counter reaches XXXX 1111 and the clock continues, the counter will roll back to the first address of the page and overwrite any data in the page that may have been written.

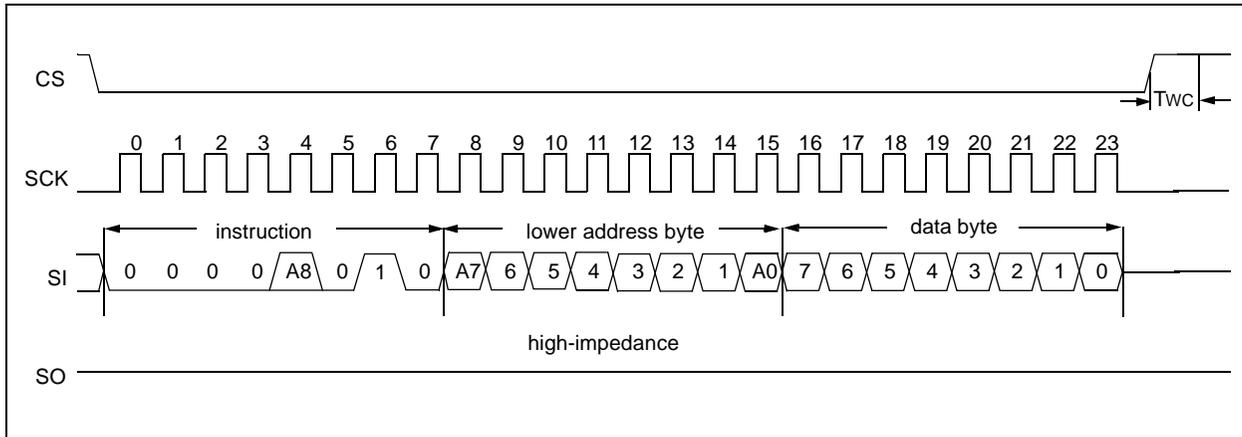
For the data to be actually written to the array, the  $\overline{CS}$  must be brought high after the least significant bit (D0) of the  $n^{\text{th}}$  data byte has been clocked in. If  $\overline{CS}$  is brought high at any other time, the write operation will not be completed. Refer to Figure 3-2 and Figure 3-3 for more detailed illustrations on the byte write sequence and the page write sequence respectively. While the write is in progress, the Status register may be read to check the status of the WIP, WEL, BP1 and BP0 bits (Figure 3-6). A read attempt of a memory array location will not be possible during a write cycle. When the write cycle is completed, the write enable latch is reset.

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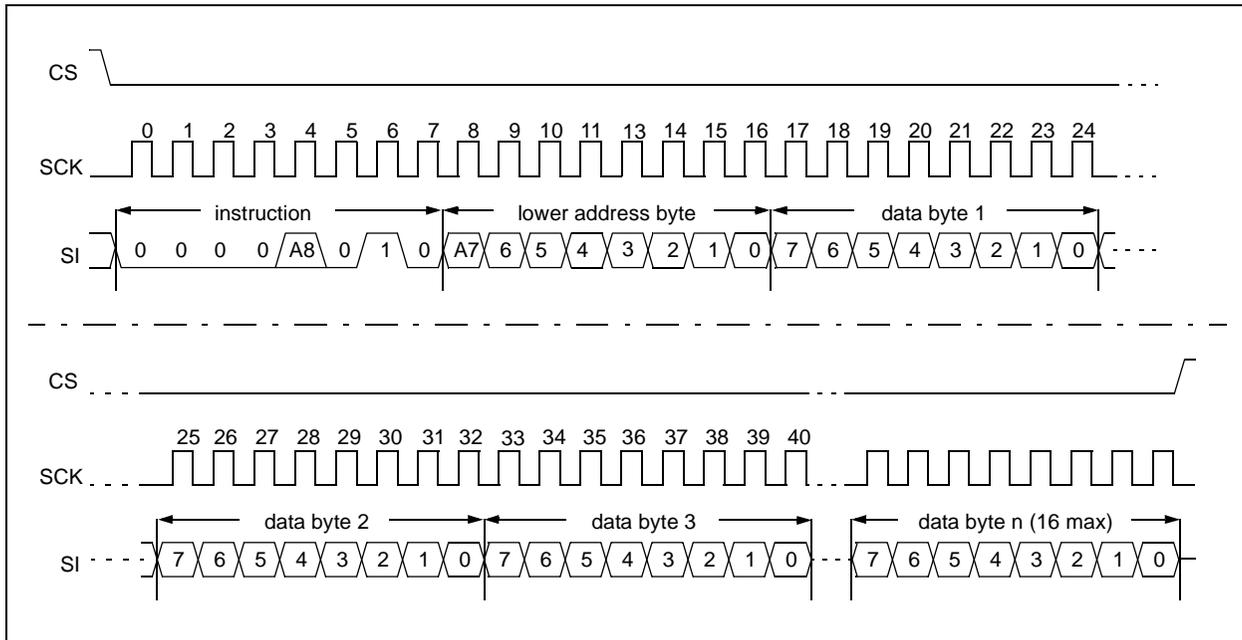
**FIGURE 3-1: READ SEQUENCE**



**FIGURE 3-2: BYTE WRITE SEQUENCE**



**FIGURE 3-3: PAGE WRITE SEQUENCE**



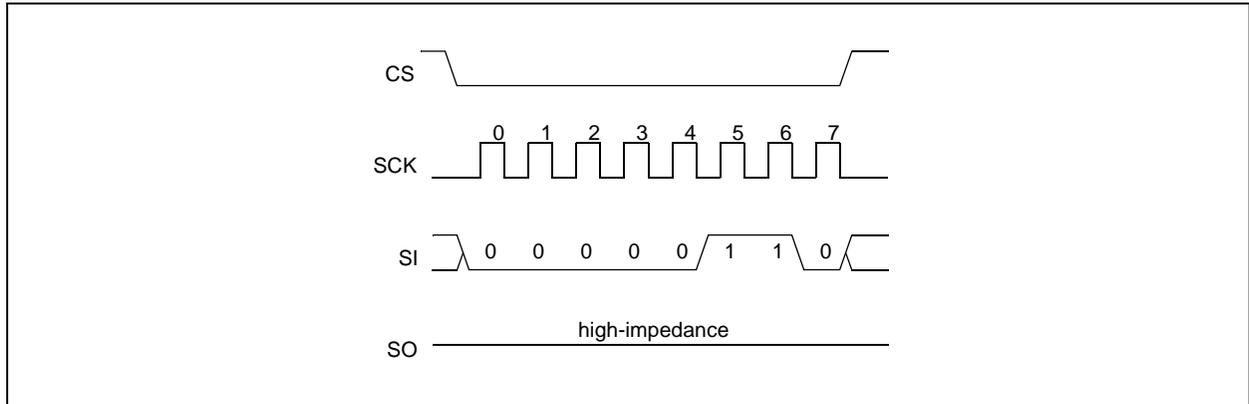
### 3.4 Write Enable (WREN) and Write Disable (WRDI)

The 25XX040 contains a write enable latch. See Table 3-3 for the Write-Protect Functionality Matrix. This latch must be set before any write operation will be completed internally. The `WREN` instruction will set the latch, and the `WRDI` will reset the latch.

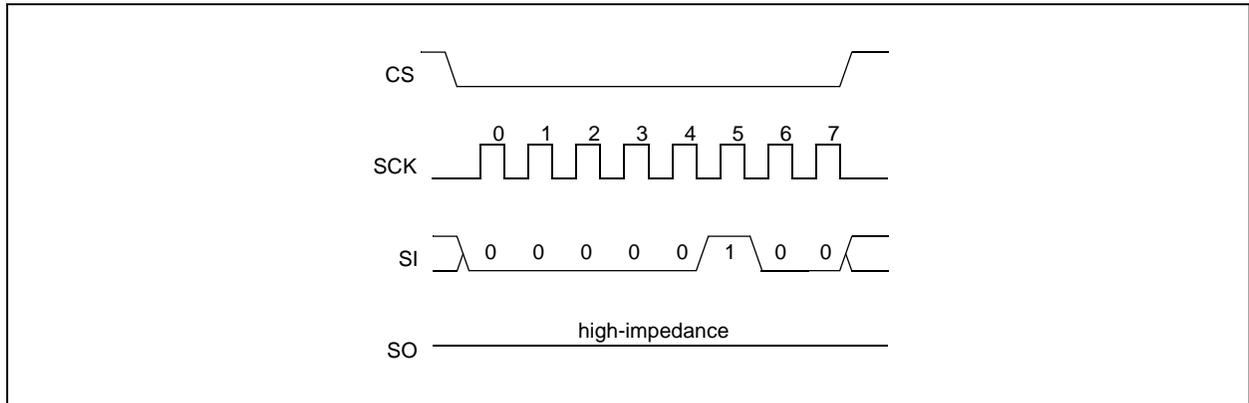
The following is a list of conditions under which the write enable latch will be reset:

- Power-up
- `WRDI` instruction successfully executed
- `WRSR` instruction successfully executed
- `WRITE` instruction successfully executed
- $\overline{WP}$  line is low

**FIGURE 3-4: WRITE ENABLE SEQUENCE**



**FIGURE 3-5: WRITE DISABLE SEQUENCE**



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## 3.5 Read Status Register (RDSR)

The RDSR instruction provides access to the Status register. The Status register may be read at any time, even during a write cycle. The Status register is formatted as follows:

7	6	5	4	3	2	1	0
X	X	X	X	BP1	BP0	WEL	WIP

The **Write-In-Process (WIP)** bit indicates whether the 25XX040 is busy with a write operation. When set to a '1', a write is in progress, when set to a '0', no write is in progress. This bit is read only.

The **Write Enable Latch (WEL)** bit indicates the status of the write enable latch. When set to a '1', the latch allows writes to the array, when set to a '0', the latch prohibits writes to the array. The state of this bit can always be updated via the WREN or WRDI commands regardless of the state of write protection on the Status register. This bit is read only.

The **Block Protection (BP0 and BP1)** bits indicate which blocks are currently write-protected. These bits are set by the user issuing the WRSR instruction. These bits are nonvolatile.

See Figure 3-6 for RDSR timing sequence.

## 3.6 Write Status Register (WRSR)

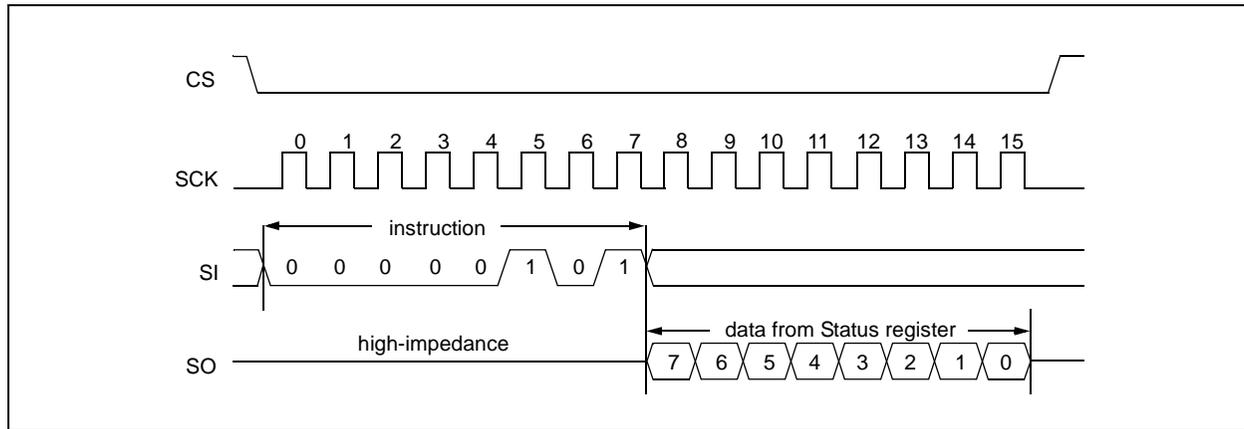
The WRSR instruction allows the user to select one of four levels of protection for the array by writing to the appropriate bits in the Status register. The array is divided up into four segments. The user has the ability to write-protect none, one, two, or all four of the segments of the array. The partitioning is controlled as illustrated in Table 3-2.

See Figure 3-7 for WRSR timing sequence.

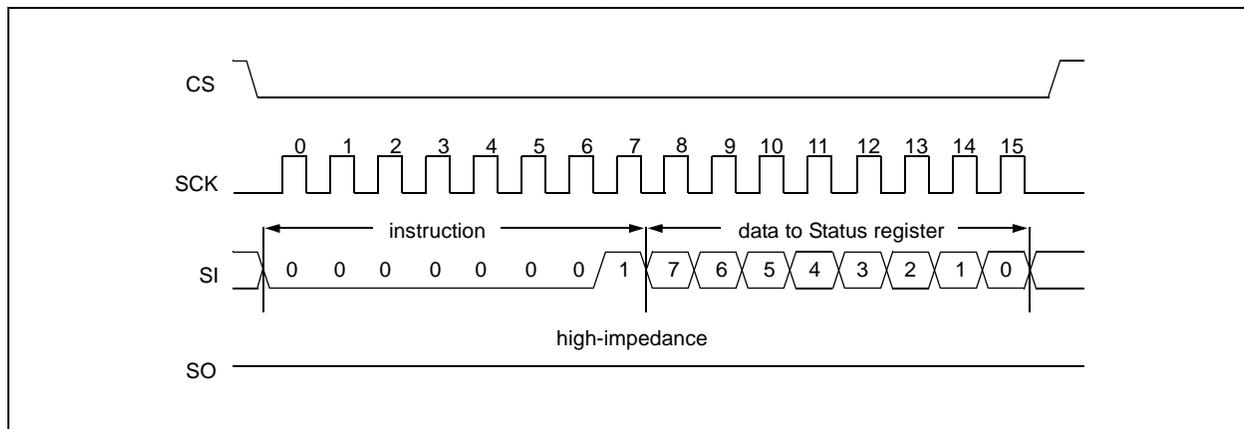
**TABLE 3-2: ARRAY PROTECTION**

BP1	BP0	Array Addresses Write-Protected
0	0	none
0	1	upper 1/4 (0180h - 01FFh)
1	0	upper 1/2 (0100h - 01FFh)
1	1	all (0000h - 01FFh)

**FIGURE 3-6: READ STATUS REGISTER SEQUENCE**



**FIGURE 3-7: WRITE STATUS REGISTER SEQUENCE**



## 3.7 Data Protection

The following protection has been implemented to prevent inadvertent writes to the array:

- The write enable latch is reset on power-up
- A write enable instruction must be issued to set the write enable latch
- After a byte write, page write or Status register write, the write enable latch is reset
- $\overline{CS}$  must be set high after the proper number of clock cycles to start an internal write cycle
- Access to the array during an internal write cycle is ignored and programming is continued
- The write enable latch is reset when the  $\overline{WP}$  pin is low

## 3.8 Power-On State

The 25XX040 powers on in the following state:

- The device is in low-power Standby mode ( $\overline{CS} = 1$ )
- The write enable latch is reset
- SO is in high-impedance state
- A low level on  $\overline{CS}$  is required to enter active state

**TABLE 3-3: WRITE-PROTECT FUNCTIONALITY MATRIX**

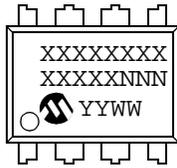
WP	WEL	Protected Blocks	Unprotected Blocks	Status Register
Low	X	Protected	Protected	Protected
High	0	Protected	Protected	Protected
High	1	Protected	Writable	Writable

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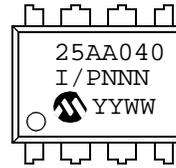
## 4.0 PACKAGING INFORMATION

### 4.1 Package Marking Information

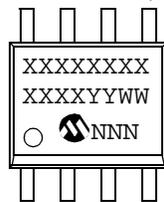
8-Lead PDIP (300 mil)



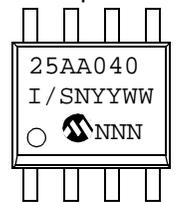
Example:



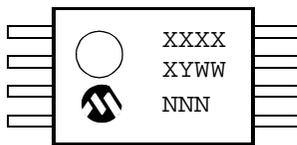
8-Lead SOIC (150 mil)



Example:



8-Lead TSSOP



Example:



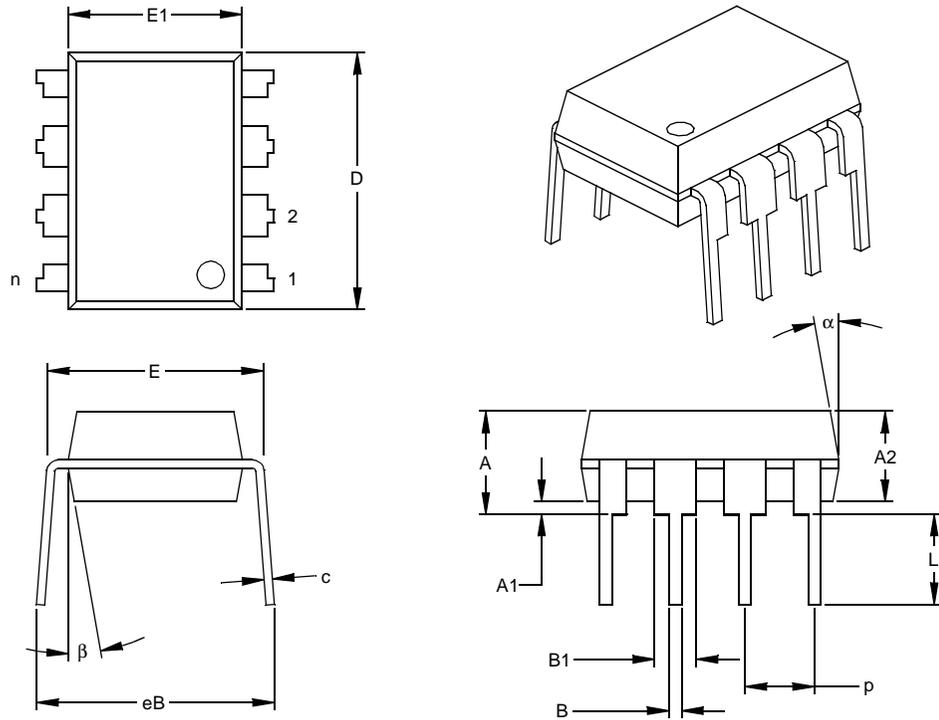
<b>Legend:</b>	XX...X	Customer specific information*
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line thus limiting the number of available characters for customer specific information.

\* Standard PICmicro device marking consists of Microchip part number, year code, week code, and traceability code. For PICmicro device marking beyond this, certain price adders apply. Please check with your Microchip Sales Office. For QTP devices, any special marking adders are included in QTP price.

# 25AA040/25LC040/25C040

## 8-Lead Plastic Dual In-line (P) – 300 mil (PDIP)



Dimension Limits	Units	INCHES*			MILLIMETERS		
		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		8			8	
Pitch	p		.100			2.54	
Top to Seating Plane	A	.140	.155	.170	3.56	3.94	4.32
Molded Package Thickness	A2	.115	.130	.145	2.92	3.30	3.68
Base to Seating Plane	A1	.015			0.38		
Shoulder to Shoulder Width	E	.300	.313	.325	7.62	7.94	8.26
Molded Package Width	E1	.240	.250	.260	6.10	6.35	6.60
Overall Length	D	.360	.373	.385	9.14	9.46	9.78
Tip to Seating Plane	L	.125	.130	.135	3.18	3.30	3.43
Lead Thickness	c	.008	.012	.015	0.20	0.29	0.38
Upper Lead Width	B1	.045	.058	.070	1.14	1.46	1.78
Lower Lead Width	B	.014	.018	.022	0.36	0.46	0.56
Overall Row Spacing	§ eB	.310	.370	.430	7.87	9.40	10.92
Mold Draft Angle Top	α	5	10	15	5	10	15
Mold Draft Angle Bottom	β	5	10	15	5	10	15

\* Controlling Parameter

§ Significant Characteristic

### Notes:

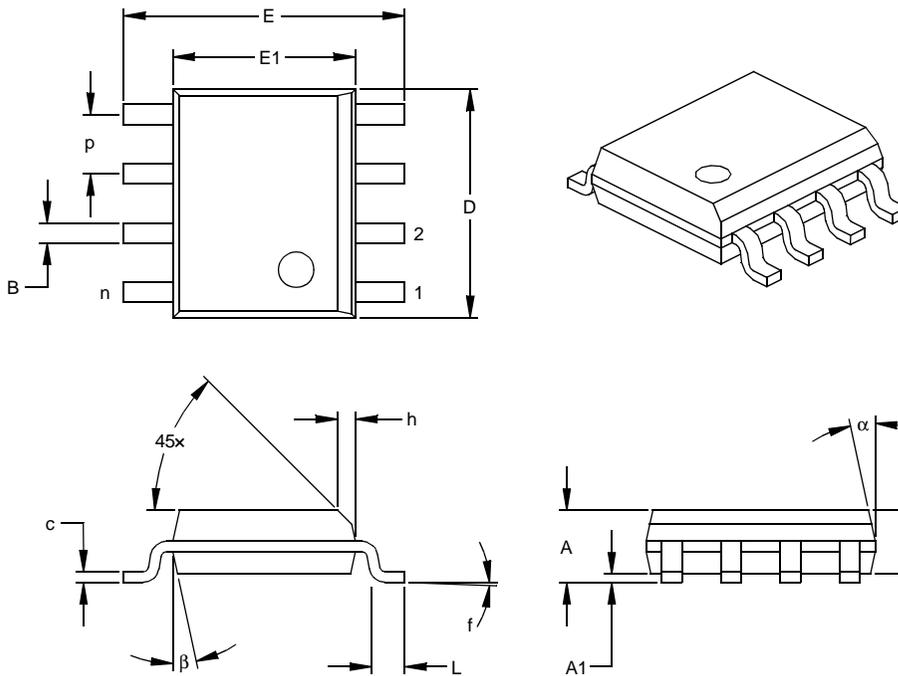
Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side.

JEDEC Equivalent: MS-001

Drawing No. C04-018

# 25AA040/25LC040/25C040

## 8-Lead Plastic Small Outline (SN) – Narrow, 150 mil (SOIC)



Units		INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		8			8	
Pitch	p		.050			1.27	
Overall Height	A	.053	.061	.069	1.35	1.55	1.75
Molded Package Thickness	A2	.052	.056	.061	1.32	1.42	1.55
Standoff §	A1	.004	.007	.010	0.10	0.18	0.25
Overall Width	E	.228	.237	.244	5.79	6.02	6.20
Molded Package Width	E1	.146	.154	.157	3.71	3.91	3.99
Overall Length	D	.189	.193	.197	4.80	4.90	5.00
Chamfer Distance	h	.010	.015	.020	0.25	0.38	0.51
Foot Length	L	.019	.025	.030	0.48	0.62	0.76
Foot Angle	f	0	4	8	0	4	8
Lead Thickness	c	.008	.009	.010	0.20	0.23	0.25
Lead Width	B	.013	.017	.020	0.33	0.42	0.51
Mold Draft Angle Top	$\alpha$	0	12	15	0	12	15
Mold Draft Angle Bottom	$\beta$	0	12	15	0	12	15

\* Controlling Parameter

§ Significant Characteristic

### Notes:

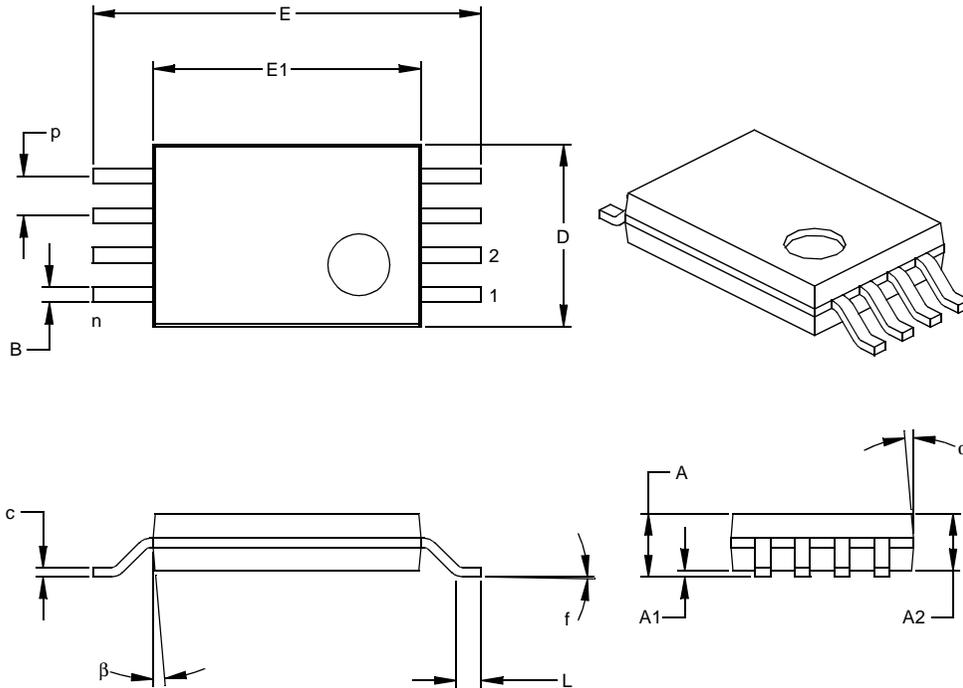
Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side.

JEDEC Equivalent: MS-012

Drawing No. C04-057

# 25AA040/25LC040/25C040

## 8-Lead Plastic Thin Shrink Small Outline (ST) – 4.4 mm (TSSOP)



Units		INCHES			MILLIMETERS*		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		8			8	
Pitch	p		.026			0.65	
Overall Height	A			.043			1.10
Molded Package Thickness	A2	.033	.035	.037	0.85	0.90	0.95
Standoff §	A1	.002	.004	.006	0.05	0.10	0.15
Overall Width	E	.246	.251	.256	6.25	6.38	6.50
Molded Package Width	E1	.169	.173	.177	4.30	4.40	4.50
Molded Package Length	D	.114	.118	.122	2.90	3.00	3.10
Foot Length	L	.020	.024	.028	0.50	0.60	0.70
Foot Angle	f	0	4	8	0	4	8
Lead Thickness	c	.004	.006	.008	0.09	0.15	0.20
Lead Width	B	.007	.010	.012	0.19	0.25	0.30
Mold Draft Angle Top	α	0	5	10	0	5	10
Mold Draft Angle Bottom	β	0	5	10	0	5	10

\* Controlling Parameter

§ Significant Characteristic

### Notes:

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .005" (0.127mm) per side.

JEDEC Equivalent: MO-153

Drawing No. C04-086

# 25AA040/25LC040/25C040

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## APPENDIX A: REVISION HISTORY

### Revision D

Corrections to Section 1.0, Electrical Characteristics.

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NOTES:

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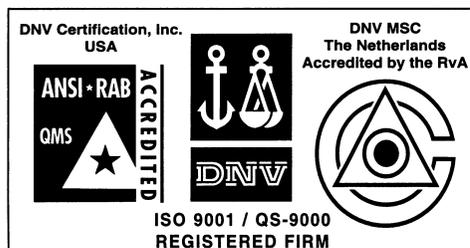
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