



Flex Network High Speed Counter Unit User Manual



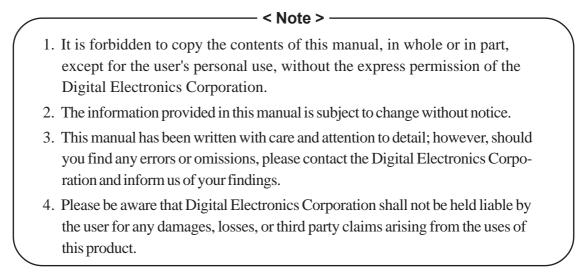
Preface

Thank you for purchasing the Pro-face's Flex Network High-Speed Counter unit, hereafter referred to as "FN-HC unit" or "unit".

The unit is designed to be used with Pro-face's Graphical Logic Controller (GLC) Series, LT Series, and GP3000 Series FLEX NETWORK board type (hereafter referred to as "GLC") as a remote I/O system.

This manual explains the overall features and specifications of the unit, as well as its installation procedures.

Please be sure to read this manual thoroughly to understand the correct and safe usage of this product and its features.



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Essential Safety Precautions

This guide contains a variety of safety markings for safe and correct operation of the FN-HC unit. Please read this installation guide and any related manuals carefully to fully understand how to correctly use the FN-HC unit's functions.

Safety Symbols

Please pay attention to these symbols and follow all instructions given. The safety symbols and their meanings are as follows:



Indicates situations where severe bodily injury, death or major machine damage will definitely occur.

Indicates situations where severe bodily injury, death or major machine damage can possibly occur.

Indicates situations where slight bodily injury or machine damage can occur.

- An emergency stop circuit and an interlock circuit should be constructed outside of this unit. Constructing these circuits inside a system that uses this unit may cause a runaway situation, system failure, or an accident due to unit failure.
- Systems using this unit should be designed so that output signals which could cause a serious accident are monitored from outside the unit.
- This product is not appropriate for use with aircraft control devices, medical life-support equipment, central trunk data transmission (communication) devices, or nuclear power control devices, due to their inherent requirements of extremely high levels of safety and reliability.
- When using this product with transportation vehicles (trains, cars, and ships), disaster and crime-prevention devices, various types of safety equipment, and medical devices that are not life-support related, use redundant and/or failsafe system designs to ensure proper reliability and safety.

- Prior to installing, removing, wiring, and conducting maintenance or inspections, be sure to disconnect power to this unit to prevent an electric shock or fire.
- Do not disassemble or remodel this unit, since it may lead to an electric shock or fire.
- Do not use this unit in an environment that contains flammable gases since an explosion may occur.
- Do not use this unit in an environment that is not specified in either the Installation Guide or User Manual. Otherwise, an electric shock, fire, malfunction or other failure may occur.
- Due to the possibility of an electric shock or malfunction, do not touch the unit's power terminals while it is operating.

- Communication cables or I/O signal lines must be wired separately from the main circuit (high-voltage, large-current) line, high-frequency lines such as inverter and power lines. Otherwise, a malfunction may occur due to noise.
- This unit must be installed according to directions given in its Installation Guide and User manual. Improper installation may cause the unit to malfunction or fail.
- This unit must be wired according to directions in the Installation Guide and User Manual. Improper wiring may cause a malfunction, failure or electric shock.
- Do not allow foreign substances, including chips, wire pieces, water, or liquids to enter inside this unit's case. Otherwise, a malfunction, failure, electric shock, or fire may occur.
- When disposing of this unit, it should be processed according to your country's industrial waste disposal laws.

General Precautions

■ To Prevent Unit Damage

- Avoid storing or operating this unit in either direct sunlight or excessively dusty or dirty environments.
- Because this unit is a precision instrument, do not store or use it in locations where excessive shocks or vibration may occur.
- Avoid covering this unit's ventilation holes, or operating it in an environment that may cause it to overheat.
- Avoid operating this unit in locations where sudden temperature changes can cause condensation to form inside the unit.
- Do not use paint thinner or organic solvents to clean this unit.

Flex Network Unit Models

Flex Network units allow the GLC to communicate via a Flex Network system. The Flex Network unit model numbers are listed as follows:

Product Family	Unit Name	Model No.	Nodes Required	Manual
		FN-X16TS41	1	
		FN-X32TS41	2	
		FN-Y16SK41	1	
		FN-Y16SC41	1	
	I/O Unit	FN-XY08TS41	1	DIO Unit User Manual
		FN-XY16SK41	1	
		FN-XY16SC41	1	
Flex Network		FN-XY32SKS41	4	
FIEX NELWOIK		FN-Y08RL41	1	
	Analog Unit	FN-AD02AH41	1	2-Channel Analog Unit
		FN-DA02AH41	1	User Manual
		FN-AD04AH11	4	Analog Unit User Manual
		FN-DA04AH11	4	Analog Onit Osci Manaa
	Single-Axis Positioning Unit	FN-PC10SK41	4	Single-Axis Positioning Unit
		FN-PC10LD41	-	User Manual
	High-Speed Counter Unit	FN-HC10SK41	8	This Manual

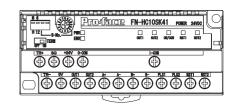
Compatible GLC Units

The following GLC units can be used with the Flex Network units. (GLC, LT, and GP are referred to collectively as the "GLC" in this manual.)

Product Family	Series Name		Unit Name	Model No.
		GLC2300 Series	GLC2300T	GLC2300-TC41-24V
		GLC2300 Selles	GLC2300L	GLC2300-LG41-24V
		GLC2400 Series	GLC2400T	GLC2400-TC41-24V
GLC	GLC2000 Series	GLC2500 Series	GLC2500T	GLC2500-TC41-24V
		OLC2300 JUNUS	02023001	GLC2500-TC41-200V
		GLC2600 Series	GLC2600T	GLC2600-TC41-24V
		GLC2000 Series	GLC20001	GLC2600-TC41-200V
	LT Series		LT TypeB	GLC150-BG41-FLEX-24V
LT			LT Type B+	GLC150-BG41-XY32KF-24V
LI			LTC Type B+	GLC150-SC41-XY32KF-24V
			LT Type C	GLC150-BG41-RSFL-24V
		GP-3300 Series	AGP-3300L	AGP3300-L1-D24-FN1M
	GP3000 Series	01-3300 30103	AGP-3300T	AGP3300-T1-D24-FN1M
		GP-3400 Series	AGP-3400T	AGP3400-T1-D24-FN1M
GP		GP-3500 Series	AGP-3500T	AGP3500-T1-D24-FN1M
				AGP3500-T1-AF-FN1M
		GP-3600 Series	AGP-3600T	AGP3600-T1-D24-FN1M
				AGP3600-T1-AF-FN1M

Package Contents

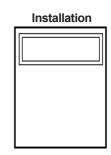
Flex Network High-Speed Counter Unit (1) (FN-HC10SK41)



Flex Network High-Speed Counter Unit Installation Guide – English/Japanese (1)

Note:

The Flex Network High-Speed Counter Unit User Manual is sold separately.



Special care and attention have been given to the packaging of this unit. However, if any of the items are damaged or missing, please contact your local distributor immediately for prompt service.

Driver

The driver for the Flex Network Unit is required in order to use the unit.

For GLC2000 series and LT series,

You can select the Flex Network Driver via GP-PRO/PBIII C-Package (Pro-Control Editor) or LT Editor.

If the selection of the appropriate unit's name does not appear in the [I/O Configuration] - [I/O Unit Settings] area, you will need to update the driver file.

You can download the latest driver from Pro-face's web site.

URL :http://www.pro-face.com/

For GP3000 Series,

You can select the Flex Network Driver via GP-Pro EX as an I/O driver.

UL/c-UL (CSA) Application Notes

The FN-HC10SK41 is a UL/c-UL (CSA) listed product. (UL file No. E220851)

This unit conforms to the following standards:

UL 508 Industrial Control Equipment

■ CAN/CSA C22.2 No.1010-1 MEASUREMENT AND CONTROL EQUIPMENT (Safety requirements for electrical equipment for measurement and laboratory use)

FN-HC10SK41 (UL Registration Model: 2980051-01)

<Cautions>

- The FN-HC must be a built-in component of an end-use product.
- If the FN-HC is mounted so as to cool itself naturally, be sure to install the unit in a vertical (upright) panel, using either a DIN rail, or the installation screw holes.
- The power unit attached to the FN-HC should be a UL/c-UL (CSA) approved Class 2 power unit, or a Class 2 transformer. *1

If a single power supply is used to power the GLC, or multiple Flex Network units, design the wiring so the sum of the Flex Network unit's consumption current and the total load current does not exceed the Class 2 power unit or the Class 2 transformer's rating.

CE Marking Notes

The FN-HC10SK41 is a CE marked product that conform to EMC directives EN55011 class A and EN61000-6-2. For detailed CE Marking information, please contact your Flex Network distributor.

*1 A Class 2 power supply unit or Class 2 power supply transformer is defined by NEC as being 30V and, at 8A or less output, at less than 100VA.

Documentation Conventions

The list below describes the documentation conventions used in this manual.

Symbol	Meaning		
Important	Indicates important information or procedures that must be followed for correct and risk-free software/device operation.		
Note:	Provides useful or important supplemental information.		
*1	Provides useful or important supplemental information.		
Reference	Cross-references useful or important supplemental information.		
	Generic name for the "GLC Series" of Graphic Logic Controllers made by		
GLC	Pro-face. In this manual, it also indicates "LT Series" and "GP3000 Series		
	FLEX NET WORK board type".		

Memo

2. Accessories

Chapter 1 Introduction

This high-speed counter unit can be connected to a Flex Network. There are three types of counting operations. Select the type of counting that fits your application needs. **Reference** See 4.2 Functions

- DC input/16-bit up counter (at 10kpps/1 multiplication)
- DC input/32-bit up counter (at 10kpps/1 multiplication)
- Differential input/32-bit up/down counter (at 200kpps/1 multiplication) and DC input (at 3kpps/1 multiplication)

1.1 System Design

When connecting to the Flex Network, two channels are available – CH1 and CH2. Each channel outputs the same data and either can be used for data transmission.

No software setup is required.

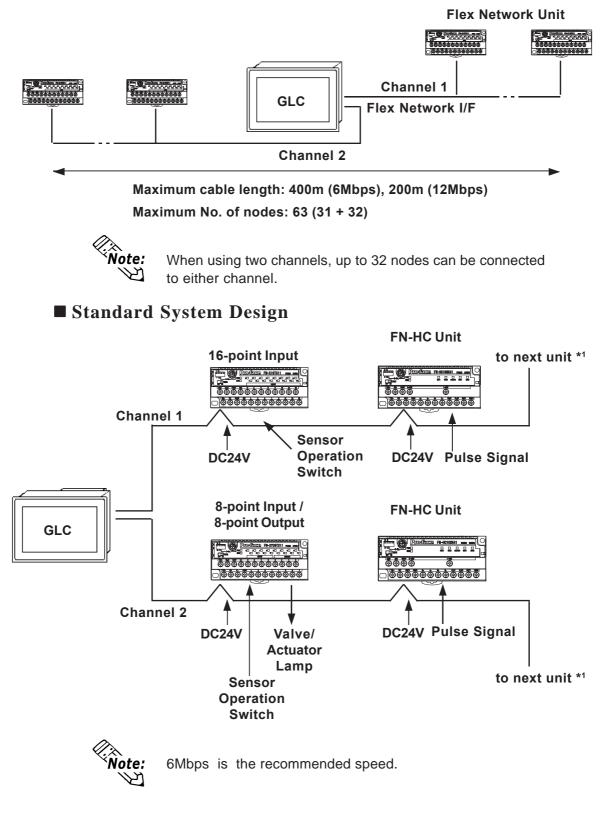
The maximum number of connectable nodes when using a single channel is 31, and when using a second channel, the number increases by 32 to a total of 63.



- When conecting the FN-HC to the Flex Network, each unit connected will use 128 bits of GLC memory, equivalent to 8 I/O nodes. The maximum number of connectable nodes (see above) therefore differs from the maximum number of connectable units.
- The Flex Network uses high-speed data-transfer technology, and if a cable used for data transfer is not the same as that specified in this document, network data-transfer performance cannot be guaranteed. Thus, be sure to use only the cable(s) recommended.

With One (1) Channel Flex Network Units GLC Maximum cable length: 200m (6Mbps) 100m (12Mbps) Maximum No. of nodes: 31

■ With Two (2) Channels



*1.Be sure the Terminal Switch (TERM) at each end of the network's last unit is ON.

1.2 Accessories

All optional equipment listed here is sold separately.

♦ Optional Items

ltem	Model No.	Description
Flex Network Communication Cable	FN-CABLE 2010-31-MS (10m)	
	FN-CABLE 2050-31-MS (50m)	Connect GLC units with Flex Network units.
	FN-CABLE 2200-31-MS (200m)	

Memo



- 1. General Specifications
- 2. Functional Specifications
- 3. I/O Circuit Connection Drawings
- 4. Part Names and Features
- 5. Dimensions

2.1 General Specifications

2.1.1 Electrical

Rated Voltage	DC24V
Rated Voltage Range	DC20.4V to DC28.8V
Allowable Voltage Drop	10 ms or less (Power Voltage DC24V)
Power Consumption	2.5W or less
In-rush Current	15A or less
Voltage Endurance	AC500V 20mA for 1 min. (between I/O and earth terminals)
Insulation Resistance	DC500V at 10M Ω or higher (between I/O and earth terminals)

2.1.2 Environmental

T	
Ambient	
Operating	0°C to 55°C
Temperature	
Storage Temp.	-25°C to +70°C
Ambient Humidity	30% RH to 95% RH (no condensation) Level RH-1
Storage Humidity	30% RH to 95% RH (no condensation) Level RH-1
Air Purity (Dust)	0.1mg/m ³ or less (non-conductive levels)
Corrosive Gasses	Free of corrosive gasses
Atmospheric Pressure	800 hPa to 1114 hPa (2,000 meters or lower)
Vibration Resistance	IEC61131-2 (JIS B 3501) compliant When vibration IS NOT continuous: 10Hz to 57Hz 0.075mm, 57Hz to 150 Hz 9.8m/s ² When vibration IS continuous: 10Hz to 57Hz 0.035mm, 57Hz to 150 Hz 4.9m/s ²
Shock Endurance	X,Y, Z directions for 10 times (80 min.) IEC61131-2 (JIS B 3501) compliant 147m/s ² (for 11ms in X,Y, Z directions - 2 times each)
Noise Immunity	Noise Voltage: 1000Vp-p
(via noise	Pulse Duration: 1µs
simulator)	Arise Time: 1ns
Electrostatic Discharge Immunity	Contact discharge of 6kV (IEC61000-4-2, Level 3)

	Protection: Equivalent to IP20
Protection	Installation method: 35mm [1.38 in.] DIN railing or screw installation
Cooling Method Natural air circulation	
Weight 150g or less	
External W 108mm [4.25 in.] x H 45mm [1.77 in.] x D 49mm [1.93 in.]	
Dimensions	

2.1.3 Structural

2.2 Performance Specifications

Counter Type	Input Type	Pulse Count Method (up/down counter)	Calculated Speed	No. of Counters	Calculation Range	Compare Output Mode
16-bit up counter	DC Input (DC24V		10kpps/ 1kpps	2	0 to FFFF 0 to 65535 (16 bits)	Comparator Output x2 (=)
32-bit up counter	Open Collector)		10kpps/ 1kpps	1	0 to FFFFFFF 0 to 4,294,967,295 (32 bits)	Comparator Output x 2 (=)
32-bit up/ down	Differ- ential Input (Line Driver)	1-phase 1-multiplication / 2-phase 1-multiplication ^{*1} 2-phase 2-multiplication ^{*1} 4-multiplication ^{*1}	200kpps / 50kpps 100kpps / 25kpps 50kpps / 12.5kpps	1 (Encoder A, B differential input)	80000000h to 7FFFFFFh (32-bit signed binary) -2,147,483,648 to +2,147,483,647	Cam Switch Simultaneous Output x 2
counter	DC Input (DC24V Open Collector)	1-phase 1-multiplication / 2-phase 1-multiplication ^{*1} 2-phase 4-multiplication ^{*1}	3kpps / 1kpps 1.5kpps / 0.5kpps 0.75kpps/ 0.25kpps	1 (DC input)	80000000h to 7FFFFFFh (32-bit signed binary) -2,147,483,648 to +2,147,483,647	Cam Switch Simultaneous Output x 2

2.2.1 Performance Specifications

1. Refer to page 4–4 for the measurement speed of each counter.

	GLC2000/LT Series	GP3000 Series		
Communication Configuration	1:N			
Connection Method	Multi-Drop Connection			
Maximum	200m/channel at 6 Mbps			
Distance	100m/channel at 12 Mbps			
Communication Method	Cyclic Time Division, half-duplex			
Communication Speed	6Mbps, 12Mbps			
Communication Interface	Differential, pulse-transformer isolation			
Error Check	Format detection, bit detection, CRC	C-12 detection		
		63 stations max.,		
		Bit variable input: 256 points,		
Number of	63 (max.), 1008 I/O points	Bit variable output: 256 points,		
Connectable Nodes	(depending on type of units used.)	Integer variable input: 64 points,		
Nodes		Integer variable output: 64 points		
		(depending on type of units used.)		
Number of Occupied Nodes	8			

2.2.2 Data Transfer Settings (Flex Network Specifications)

				DC Input (DC24V Ope	n collector)
	1 51		Differential Input (line driver)	Pulse Input (PLS 1/2)	External Reset Input (RST 1/2)
	Rated In Voltage	put	DC5V	DC24V	
	Max. Inp	out Voltage	DC4.5V to DC5.5V	DC26.4 V	
I N	-		t t t t = 0.5μs or less (200kpps)	t t t t t t t t t t	
P U T	Min. Pulse Width		5μs − − − − − − − − − − − − − − − − − − −	 100µs 100µs 100µs	2.5ms
	Input Signal Phase		Square wave 0/24V signal		•
			90° phase differential 2-phase signal, 1 phase + directional signal, 1 phase addition signal		
	Input Imp	bedence	470Ω	4.9kΩ	
	Input ON	Voltage	EIA Standard RS-422-A	DC19V or higher	
	Input OF	F Voltage	Differential Driver	DC5V or lower	
	Input	OFF-ON	(Equivalent to Texas		Maximum: 1.5ms
	Delay	ON-OFF	Instruments SN75157)		Maximum: 1.5ms
	Rated Or Voltage	utput	DC24V		
0	Rated Output Voltage Range		DC24V (+/-10%)		
U T	J Output Voltage		DC1.5V or lower		
Ρ			50mA or lower		
U	Output OFF-ON		Maximum: 1ms		
т	Delay	ON-OFF	Maximum: 1ms		
	Short-cir Protectio		None		
	Leakage	Current	0.1mA or lower		

2.2.3 Input / Output Specifications

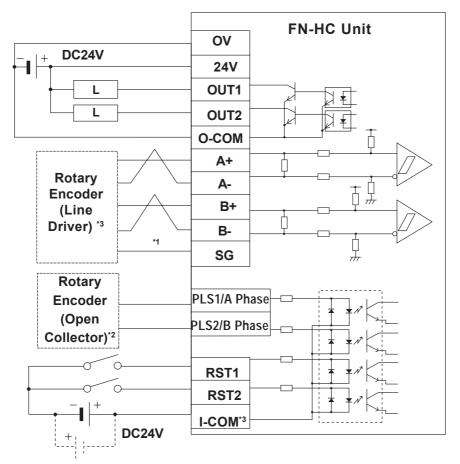
2.3 Input / Output Circuit

This section explains the I/O connection (see circuit diagram, below) for the FN-HC unit.

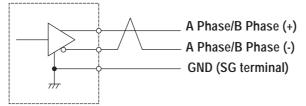


If the FN-HC unit's power lines and output lines, and the sensor power lines seem to be receiving excessive levels of field noise, be sure to separate the power and signal lines.

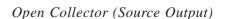
FN-HC Unit Connection Diagram (from Rotary Encoder)

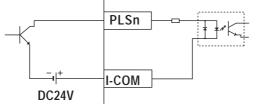


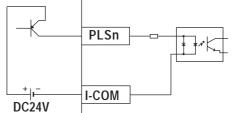
- 1. The FN-HC unit's input line is not isolated. When connecting this unit to a line driver that is not isolated, be sure to connect the signal ground (SG) terminal.
- 2. Line Driver



3. Open Collector (Sink Output)







4. The Input Common (I-COM) shown here is connected to a Sink Output type. (The dotted line shows the connection with a Source Output type.)

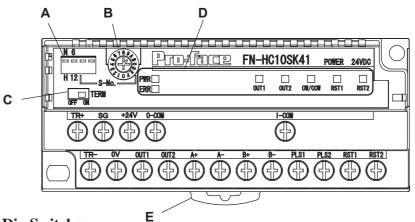
♦ Input/Output Signal

Terminal Name	Feature	
TR+	Flex Network Communication	Communication
TR-	Flex Network Communication	Channel
+24V	Unit Power (DC24V)	Power
OV	Unit Power (DC0V)	
OUT1	Comparator Output (Counter 1) /	
0011	Cam Switch 1 Output	Control Output
OUT2	Comparator Output (Counter 2) /	(DC24V Open
0012	Cam Switch 2 Output Collector	
O-COM	Output Common	
+A	A Phase Line Driver DC5V Differential Input +	
-A	A Phase Line Driver DC5V Differential Input -	Differential Line
+B	B Phase Line Driver DC5V Differential Input +	Driver Input
-В	B Phase Line Driver DC5V Differential Input -	
SG	Signal Ground	
PLS1	Counter 1 DC Input	
PLS2	Counter 2 DC Input ^{*1}	
RST1	External Reset Signal (Counter 1)	DC24V Input
RST2 External Reset Signal (Counter 2) ^{*1}		
I-COM	Input Common DC24V	
	(with Source Output type connection: 0V)	

1. PLS2 and RST2 Input are available only with Input Mode 1 (Mode 1).

2.4 Part Names and Features

2.4.1 Flex Network High-Speed Counter Unit



A: Dip Switches

Designates, from left to right, the Output Hold setting, Communication Speed setting, and first (hex) digit of the FN-HC unit's S-No.

Factory Settings

Communication Speed:	6 Mbps
Station Number (S-No):	0
Output Hold:	Non-Hold

B: Station No. Switch

Designates the second (hex) digit of the FN-HC unit's S-No.





ON

TERM

C: Terminator

Turns the termination resistance feature ON or OFF.

or OFF. ____ OFF

D:Status LED

Indicates the following conditions.

PWR	Green	Power	ON when power is turned ON.	
ERR	Red	Error	ON when communication error occurs;	
ERR	Reu		OFF when communication is normal.	
OUT1	Green	Cam Switch 1 / Counter 1 Comparator Output	ON when Cam Switch 1 Output is ON; ON when Counter 1 Comparator outputs.	
OUT2	Green	Cam Switch 2 / Counter 2 Comparator Output	ON when Cam Switch 2 Output is ON; ON when Counter 2 Comparator outputs.	
cw/ccw	Green	Rotating Direction	ON during CW (forward rotation); OFF during CCW (reverse rotation).	
RST1	Orange	External Reset 1 (Counter 1)	ON when Reset 1 input is ON.	
RST2	Orange	External Reset 2 (Counter 2)	OFF when Reset 2 input is ON.	

E: DIN Rail Attachment Hook

Use to attach the FN-HC Unit to the DIN rail.

Chapter 2 – Specifications

■ Output Hold Settings (Dip Switch 1)

• Output Hold ON (Hold)

When a communication error occurs, the unit will HOLD the previously-received cam and comparator outputs, and the current value of the counter. When the next cycle is performed and the next command is successfully received, the output will then be changed.

• Output Hold OFF (Non Hold)

When a communication error occurs, the current value in the counter, the comparator output, and the cam switch output are reset to 0 (OFF). When normal communication is restored, the output is also restored. This is the default setting.



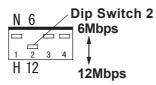
- The output hold setting status is read when the FN-HC unit is turned ON. To change this setting, turn the FN-HC unit OFF, change the setting and then turn the unit ON again.
- When the Output Hold setting is used, the external output received before an error occurs is retained when a communication error occurs. Therefore, be sure to design a failsafe system to ensure safety when operating the system.
- When the Logic Program changes from the RUN condition to either the OFFLINE or RESET mode, the GLC or external outputs will be performed as follows, regardless of the Output Hold Setting. Be sure to consider this when changing to either the OFFLINE or RESET mode.

	>			
GLC Condition	RUN	OFFLINE	RUN	
External Output	Output from Logic Program	OFF	Output from Logic Program	

When using the RESET command, the timing of the external output OFF timing is not fixed and can vary.

■ Communication Speed Settings (Dip Swtich 2)

Dip Switch No. 2 controls the communication speed (6Mbps or 12Mbps). The recommended factory setting is 6Mbps.

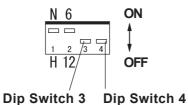




The Communication Speed setting status is read when the FN-HC unit is turned ON. To change this setting, turn the FN-HC unit OFF, change the setting and then turn the unit ON again.

S-No. (Station Number) Setting (Dip Switches 3, 4)

Station numbers from 1 to 63 are set in hexadecimal (01h to 3Fh). The factory setting is 0. The hex upper digit is controlled by the ON/OFF settings of Dip switch 3 and 4, and the lower digit is set via the S-No. 0 to F setting.





The arrow's tip indicates the position

S-No. Setting Example

S-No. (Station No.)	Dip Switch		S-No. (Station No.)
	SW3	SW4	Switch
	OFF	OFF	1
S-No. 1 (01h)	N 6		(1) (1) (1) (1) (1) (1) (1) (1) (1) (1)
	OFF	ON	0
S-No. 16 (10h)	N 6 1 2 3 4 H 12		(1) (1) (1) (1) (1) (1) (1) (1) (1) (1)
	ON	ON	F
S-No. 63 (3Fh)	N 6 1 2 H 12	3 4	0 1 0 4 5 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

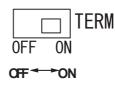


The S-No. setting status is read when the FN-HC unit is turned ON. To change this setting, turn the FN-HC unit OFF, change the setting and then turn the unit ON again.

Termination Settings

This setting helps prevent reflections (echoes) from the terminating unit (adjusts the termination impedance).

Be sure that this termination setting for each channel in your system's final unit is set to ON.

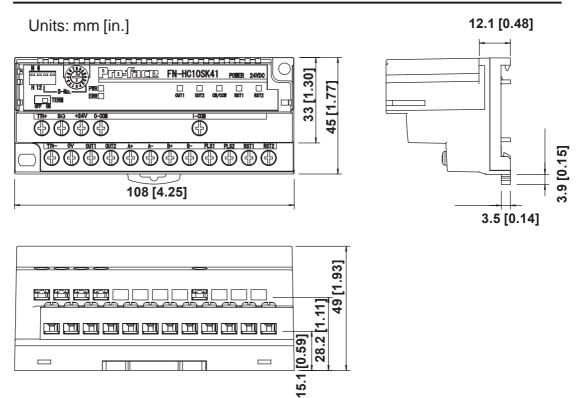




The Termination Resistance setting status is read when the FN-HC unit is turned ON. To change this setting, turn the FN-HC unit OFF, change the setting and then turn the unit ON again.

2.5 Dimensions

2.5.1 Flex Network High-Speed Counter Unit



1. Installation

2. Wiring

Chapter 3 Installation and Wiring

3.1 Installation

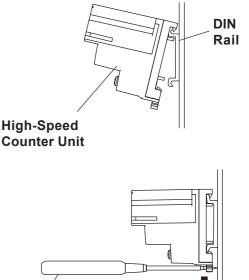
Prior to installing the FN-HC Unit, be sure that the main power supply is turned completely OFF.

3.1.1 Flex Network High-Speed Counter Unit Installation / Removal

Attaching the Unit to a 35 mm DIN Rail

Attachment

Place the unit's curved, top lip over the top of the DIN rail, and then tilt the unit down until the bottom face attachment clip clicks into place.



♦ Removal

Use a standard screwdriver to force the unit's attachment clip down until the bottom of the unit is freed from the rail. Next, tilt the unit up and remove.





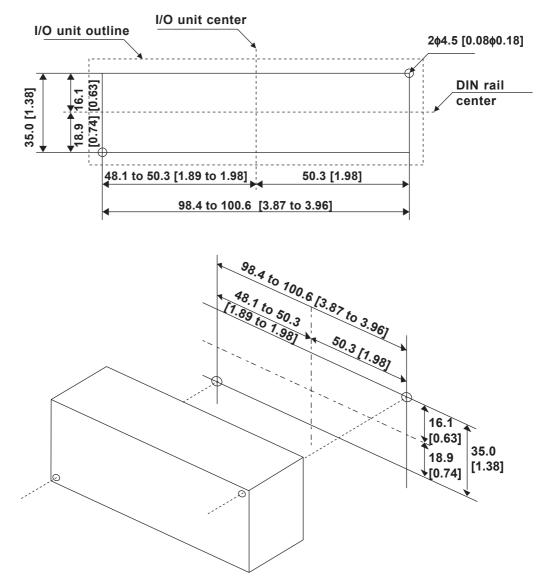
Check that the FN-HC unit is installed horizontally. If it is not correctly installed, it may overheat and cause a malfunction.

Down

■ When Installing the Unit in a Panel

Drill installation holes in the panel according to the dimensions given below and use M4 screws to attach the unit. A torque of only 1.0 to 1.3N•m is sufficient.

Unit: mm [in.]





Check that the FN-HC unit is installed horizontally. If it is not correctly installed, it may overheat and cause a malfunction.

3.2 Wiring

To prevent an electric shock, prior to wiring the FN-HC unit, be sure that the main power supply is turned OFF.

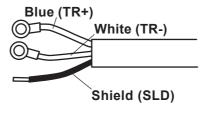
3.2.1 Connecting the Flex Network Communication Cable

Use jumper wiring between the distributed Flex Network units (T-type connections are not possible).

Pro-face recommends that the following cables be used:

Manufacturer	Model No.	Length
Digital Electronics Corporation	FN-CABLE2010-31-MS	10m
	FN-CABLE2050-31-MS	50m
	FN-CABLE2200-31-MS	200m

The cable should be made as shown below:

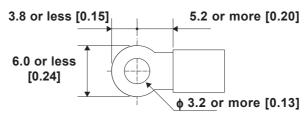




The shield line should either be taped or covered with a plastic tube. Also, since the FN-HC unit has no shield (SLD) line, be sure to connect this line to an insulated or closed terminal connector.

Use the following type of crimp terminals.

Unit: mm [in.]





Crimp terminals should be either taped or covered with a plastic tube.

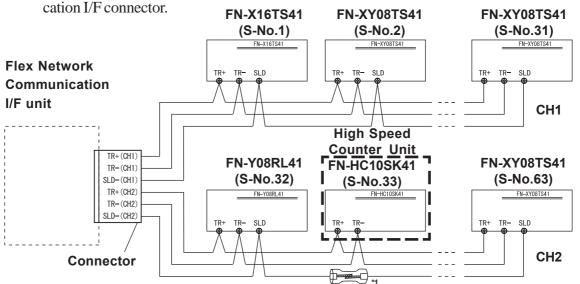


 The required torque for securing ring terminals is 0.6 to 1.0 N•m.

• Up to 2 terminals can be connected.

■ Flex Network System Wiring Layout

The following diagram illustrates the wiring layout used for the Flex Network Communi-



*1 The FN-HC unit has no shield terminal (SLD). Be sure to connect an external insulated intermediate terminal.



The number of nodes used by the FN-HC unit is 8. Thus, a regular FN unit connected after the FN-HC unit must use a number that is 8 higher than the FN-HC unit's.

For example, if the node number of the High-Speed Counter is 20H, the number of the next FN unit connected will be 28H. To ensure correct Flex Network operation, be sure to check that all node numbers are set correctly.

3.2.2 Connecting the Power Cord



- Be sure that the main power supply is turned completely OFF before wiring the unit's power cord.
- The FN-HC unit uses only DC24V power. Using either the incorrect voltage or AC power could result in damage to both the power supply and the unit.
- Since this unit has no ON/OFF switch, be sure to install a breaker device to switch the power ON or OFF.



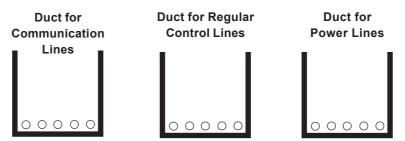
Wherever possible, use thick wires (max. 1.25mm²[0.05in²]), and be sure to twist the wires' ends to reduce noise.

• Use the same type of crimp terminals used for the Flex Network Communication Cable.

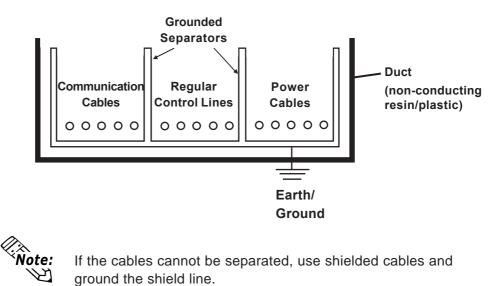
Reference 3.2.1 – "Connecting the Flex Network Communication Cable"

3.2.3 General Cautions

To help prevent noise and interference problems, separate all communication lines from power lines by placing them in a separate duct.



If the wires must be placed in the same duct, separate them via an earthed/grounded divider.





- Use noice-reducing external wiring methods to increase overall system reliability.
- To prevent power surges or noise interference, use ducts to separate all DC I/O or current circuit wires from communication cables.
- To prevent malfunctions due to noise, communication cables must be wired separately from high-frequency lines and power lines such as high-voltage lines, high-current lines, and inverters.

Memo

1. Operation Mode

2. Functions

Chapter

4 Functional Specifications

4.1 Operation Mode

There are two operation modes — RUN Mode and Setting Mode — which can be switched using bit 14 and bit 15 of the Control (CTL) register. If two 16-bit up counters are used, the modes in each counter can be changed.

RUN Mode

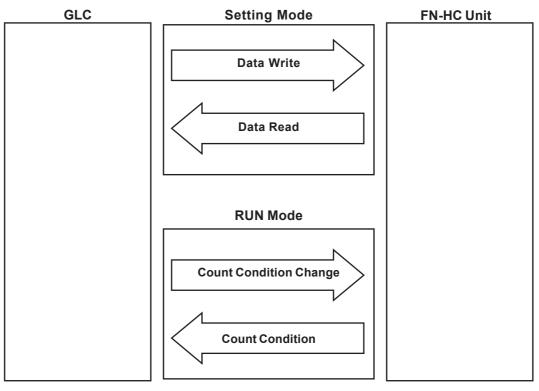
The current value of the counter can be read. Commands cannot be used, however, to send read/write data to the FN-HC unit.

Setting Mode

In this mode, commands can be used to read/write data to the FN-HC unit. While in Setting Mode, FN-HC unit count input is not changed, however, output control is performed based on this count data.



When performing data Write in RUN mode, both the GLC unit and the FN-HC unit must be set to the same mode. If they are not, a malfunction can occur.





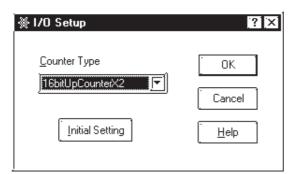
- Even in Setting Mode, the output produced will depend on the current setting value. for example, if the Current Value is equal to the Comparator Output Value, the Comparator Output turns ON. Also, When the Current Value is inside the Dog Setting Range, the Cam Switch Output will turn ON.
- After turning the FN-HC unit's power OFF, all write data is reset to its initial values. In this case, be sure to reset all write data.

4.2 Functions

The following settings are performed via the following dialog box.



For Flex Network Driver settings information, refer to the Pro-Control Editor or LT Editor On-line Help.



		Mode 1	Mode 2	Modes 3&4
No.	Counter Types	16-bit	32-bit	32-bit
		up counter	up counter	up/down
		x 2	x 1	counter x 1
1	Counter Functions	0	0	0
2	Pulse Count Method	Х	Х	0
3	Measurement Speed	0	0	0
4	Input Type	Х	Х	0
5	Simultaneous Comparator Output	0	0	Х
6	Cam Switch Output	Х	Х	0
7	Preset	0	0	0
8	Reset	0	0	0
9	Overflow Alarm	0	0	0
10	Count Disable	0	0	0
11	Current Value Read	0	0	0

Counter Types

You can choose one of the following three types of counters:

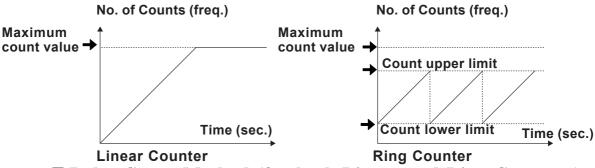
- 16-bit Up Counter counts in ascending order within a 16-bit range. These two counters operate independently.
- 32-bit up counter counts in ascending order within a 32-bit range.
- 32-bit up/down counter counts in both ascending and descending order within a 32-bit range.

Counter Functions

You can choose one of the following three types of functions. When using the 16-bit up counter X 2, you can select a counter function for each of the two independent counters.

- Linear counter counts up to and maintains the maximum counting value.
- Ring counter counts between the Ring Counter's upper and lower limit values. After counting from the lower limit value to the upper limit value, the counter returns to the lower limit value and begins to count again.
- Frequency counter continuously displays the frequency.

Chapter 4 – Functional Specifications



Pulse Count Method (for both Linear and Ring Counters)

You can select one of four pulse count methods: 1-Phase 1-Multiplication; 2-Phase 1-Multiplication; 2-Phase 2-Multiplication; and 2-Phase 4-Multiplication. The Pulse Count Method function is available only when using a 32-bit up/down counter.

Pulse Count Method		Cou	nt Timing	Description
1-Phase	Count Up	A Phase B Phase	OFF	When B phase is OFF, counts up.
1-multiplication	Count Down	A Phase B Phase		When B phase is ON, counts down.
2-Phase	Count Up	A Phase B Phase		Counts up only when B phase occurs before A. Counts only while A phase bit is rising.
1-Multiplication	Count Down	A Phase B Phase		Counts down only when B phase occurs after A. Counts only while A phase bit is falling.
2-Phase	Count Up	A Phase B Phase		Counts up only when B phase occurs before A. Counts only while A phase bit is rising or falling. Performs 2-phase multiplication at 2 times resolution.
2-Multiplication	Count Down	A Phase B Phase		Counts down only when B phase occurs after A. Counts only while A phase bit is rising or falling. Performs 2-phase multiplication at 2 times resolution.
2-Phase	Count Up	A Phase B Phase		Counts up only when B phase occurs before A. Counts only while A phase bit is rising or falling. Performs 2-phase multiplication at 4 times resolution.
4-Multiplication	Count Down	A Phase B Phase		Counts down only when B phase occurs after A. Counts only while A phase bit is rising or falling. Performs 2-phase multiplication at 4 times resolution.



When the 16-bit up counter X 2 or the 32-bit up counter X 1 is selected, the count increases only when the input pulse is rising.

Measurement Speed

When the 16-bit up counter X 2 or the 32-bit up counter X 1 is selected, 1kpps or 10kpps can be selected. When the 32-bit up/down counter is selected, the speed selected depends on the pulse count method. The speed selections are as follows:

Chapter 4 – Functional Specifications

Pulse Count Method	Input Type	
	Differential Input (Line Drivers)	DC Input (Open Collector)
1-Phase 1-Multiplication	50kpps or 200kpps	1kpps or 3kpps
2-Phase 1-Multiplilcation	50kpps or 200kpps	1kpps or 3kpps
2-Phase 2-Multiplication	25kpps or 100kpps	0.5kpps or 1.5kpps
2-Phase 4-Multiplication	12.5kpps or 50kpps	0.25kpps or 0.75kpps



When using the 16-bit up counter X 2, the measurement speed must be the same for both counters.

Input Type

You can select an input type from either the line driver or the open collector. This feature is available only when a 32-bit up/down counter is selected.

Ring Counter Function

The Ring Counter function counts repeatedly between the lower limit value and the upper limit value. These limits are set in the Command setting.

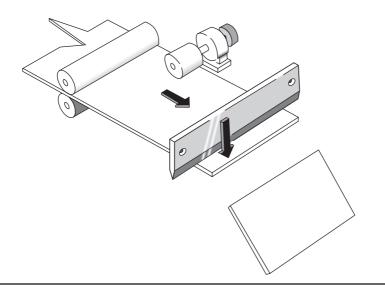
The ring counter can be used to control conditions, such as constant feed.

Ring Counter Function – Example

A ring counter can be used in a system designed to cut a continuously-fed sheet, from the roller, at a value set by the ring counter.

The Ring Counter functions as follows:

- 1. The upper limit value and the lower limit value are set.
- 2. The motor turns ON and the roller rotates.
- 3. When the roller rolls out a specified length of sheet, the simultaneous ring counter output causes the motor to turn OFF.
- 4. The blade cuts the sheet.
- 5. Steps 2 to 4 are repeated.



Chapter 4 – Functional Specifications

Because the Comparator Output and the Cam Switch Output functions are set in and processed by the FN-HC unit, regardless of the GLC unit's sequence program scan time, these functions can process at high speeds (max. 1ms).

Comparator Output Function (for both Linear and Ring Counters)

When the current count value of the FN-HC unit equals the previously set Comparator Output setting, the FN-HC unit can perform simultaneous external output. Once the external output is produced, the unit will latch (will retain the output) until the Reset or Preset command is used.



The Comparator Output setting must be entered in the Write Data register.

Explanation

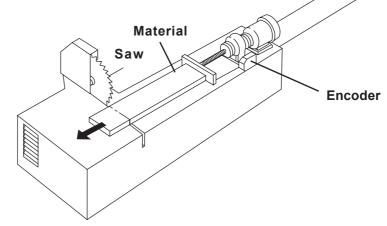
When the FN-HC unit's current value matches the FN-HC unit's user-specified previously set count value, Comparator Output is produced. Since there is no effect from the GLC's scan time, high-precision high-speed times as small as 1msec. can be used.

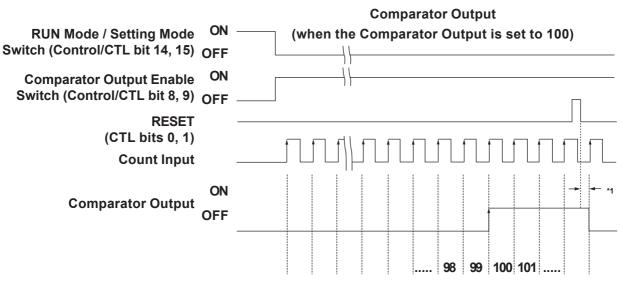
Using the Comparator Output function requires that bit 8 and bit 9 of the Control (CTL) register be turned ON.

Comparator Output Function – Example

In a factory-processing system, the manufacture of a product corresponds to the comparator output in each processing operation.

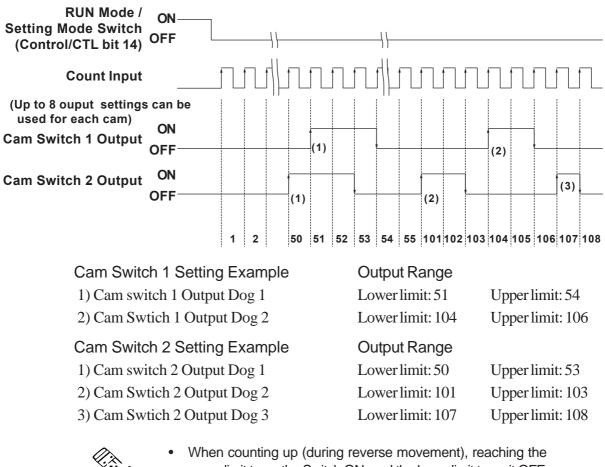
- 1. Material is moved via the motor.
- 2. The encoder gives the current value of the pulse, which corresponds to the current position of the material.
- 3. When the material moves into its specified position, the High-Speed Counter unit produces the comparator output.





Operation of Comparator Output Function

- *1 At a communication speed of 6Mbps with 63 nodes (Stations), allow at least 6ms for RESET to turn all comparator outputs OFF. 8 nodes would be approx. 2ms. (Comm. + Output delay)
- **Cam Switch Output Function (both Linear and Ring Counters)** The High-Speed Counter unit performs external output only when its count value is set within the range of a cam switch's dog. Two (2) imaginary cam switches operating via software can be used. Each switch can set up to eight (8) dogs.



- lote:
- upper limit turns the Switch ON, and the lower limit turns it OFF.
- Set start and end points to zero for unused dogs.

Chapter 4 – Functional Specifications

Because the Comparator Output and the Cam Switch Output functions are set in and processed by the High-Speed Counter unit, regardless of the GLC unit's sequence program scan time, these functions can process at high speeds (max. 1msec).



- Set the Cam Switch Output Range so that the dog's lower limit and upper limit values have at least three (3) seconds gap between them.
- Set the Cam switch Output Range from -2147483392 (0x80000100) to 2147483391 (0x7FFFEFF).
- Set the Cam Switch Ouput Range so that the Dog upper and lower limit value range is less than 2147483647 (0x7FFFFFF).

Preset Function (both Linear and Ring Counters)

By turning the Preset command ON, you can change the High-Speed Counter unit's current count values to preset values.



Preset values must be entered in the Write Data register before using the Preset Function.

When using Setting Mode, the Preset feature cannot be used.

Explanation

The Preset Function enters a user-specified numeric value (preset value) from the current counter value.

The Preset Function is used when the pulse count starts from a user-specified value.

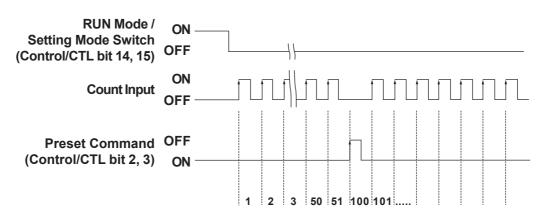
Another feature of the Preset Function is that it can also be set with a Logic Program.

Preset Function Usage – Example

Using the Preset Function allows a product-counting system to continue from the previous day's production count.

- 1. Products are carried by a loader.
- 2. An encoder gives the current value of the pulse, which corresponds to the number of products and the distance each product is carried.
- 3. At the end of the day's production, the buffer memory for that day's last successful current count value is stored in the retentive variable.

```
Operation of Preset Function
(Preset to 100)
```



Chapter 4 – Functional Specifications

Reset Function (both Linear and Ring Counters)

You can reset the unit's current count value to its initial value. The comparator output and the cam switch output are reset to 0 (OFF). The initial value for a Linear Counter is zero, and the initial value for a Ring Counter is minimum value.



During Setting Mode, the Reset Feature cannot be used.

• Overflow Alarm Function (Ring Counter only)

When a counter reaches the maximum value, the overflow flag turns ON. To turn OFF the overflow flag, use either the Preset command or Reset function. The Overflow Alarm Function feature is available only when the counter function is set as a Linear Counter.

• Count Disable Function (both Linear and Ring Counters)

When the Setting Mode is selected, the High-Speed Counter unit's count function can be temporarily stopped. After reselecting RUN Mode, the count value resumes from the time the count stopped — when the Setting Mode was selected. Only while the Setting Mode is selected can each setting be entered with the Write Data register.

Current Value Read Function (both Linear and Ring Counters)

The current value output by a High-Speed Counter unit can be read at every scan.

Type of Counter	Initial Value	Minimum Value	Maximum Value
16-bit up counter x 2	0 (decimal)	0 (decimal)	65535 (decimal)
TO-DIL UP COUNTER X Z	0h (hexadecimal)	0h (hexadecimal)	FFFFh (hexadecimal)
32-bit up counter	0 (decimal)	0 (decimal)	-1 (decimal) ^{*1}
52-bit up counter	0h (hexadecimal)	0h (hexadecimal)	FFFFh (hexadecimal)
32-bit up/down	0 (decimal)	-2147483648 (decimal)	2147483647 (decimal)
counter	0h (hexadecimal)	80000000h (hexadecimal)	7FFFFFFFh (hexadecimal)

1. When a GLC unit's 32-bit up counter uses a decimal format setting, and because the MSB of the 32-bit variable is a sign bit, the number that follows +2147483647 is -2147483648.



When the Setting Mode is selected, the current value is not updated, but is retained until the RUN Mode resumes.

1. Flex Network Driver Settings

2. Data Settings

Chapter 5 Data Settings

<GLC2000/LT Series>

5.1 Flex Network Driver Settings

The use of integer variables depends on the integer variable allocated to each tree structure terminal in the Flex Network Driver.

When using GLC2000 series/LT series, integer variables can be allocated in GP-PRO/ PBIII C-Package (Pro-Control Editor) or LT Editor. For details of each setup method, refer to each Editor's online Help.

When using GP3000 series, refer to GP-Pro EX Reference Manual.

CLC2000/LI Sel	10.5/		
🛠 Configure I/O			
<u>Eile E</u> dit <u>V</u> iew <u>H</u> elp			
Flex Network Driver (ID:#1) (Spee	:d:6Mbps)		Close
📕 🖵 🗐 S-No.1 (FN-HC10SK: 3	32bitUpCounter)		
-Ø STA.STA	16400	(%IW1.1.0)	Drivers
-Ø CTL.CTL	16384	(%QW1.1.1)	Setyp
-Ø CMD.CMD	3	(%QW1.1.2)	
-Ø RD.RD	4096	(%lW1.1.3)	<u>A</u> ddj
—Ø WD.WD	1000	(%QW1.1.4)	Remove
└─Ø CV1.CV1	0	(%lW1.1.5)	
			<u>M</u> lap,
			<u>U</u> ppag,
			<u> </u>

<GP3000 Series>

📓 FLEX N	ETWORK		
1 % 1	• × 🗍		
FLEXINETW	ORK Driver(ID:#1)		
Name	Variable	IEC Address	
🖽 🚦 S-No.1 (FN-HC10SK)			
💋 STA	STA	(%lW.1.1.0)	
💋 CTL	CTL	(%QW.1.1.1)	
— ⊘ смр	CMD	(%QW.1.1.2)	
💋 RD	RD	(%IW.1.1.3)	
🔕 WD	WD	(%QW.1.1.4)	
🦾 🙆 CV1	CV1	(%IW.1.1.5)	



When setting up the I/O configuration, prior to starting the Logic Program, or while the program is being executed, when the I/O configuration is used to change the type of counter or function, depending on the command used, the written data may be reset to its initial value. When the FN-HC unit's power is turned ON, this data is written to the FN-HC unit.

The use of integer variables allocated to each terminal are as follows:

- STA : Status register
- CTL : Control register
- CMD: Command register
- RD : Read Data register
- WD : Write Data register
- CV1 : Current Value (Counter 1)
- CV2 : Current Value (Counter 2)



- CV2 is displayed only when the setting is the 16-bit up counter X 2.
- If variables are not allocated to all terminals, an error message will occur at the time of error check or download.
 - The above-listed variable/registers are examples of program variables.

Chapter 5 – Data Settings

Status Register (STA)

Stores bit information, such as the High-Speed Counter unit's status.

Each bit is used as follows:

Bit Position	Description	16-bit up counter X 2	32-bit up counter	32-bit up/down counter	Note
0	Comparator Output (Counter 1) 0: No Output; 1: Output	0	0	х	Reads out Comparator Output 1's status to the Logic Program.
0	Cam Switch Output 1 0: No Output; 1: Output	Х	Х	0	Reads out Cam Switch 1's status to the Logic Program.
1	Comparator Output (Counter 2) 0: No Output; 1: Output	0	0	Х	Reads out Comparator Output 2's status to the Logic Program.
	Cam Switch Output 2 0: No Output; 1: Output	Х	Х	0	Reads out Cam Switch 2's status to the Logic Program.
2	Overflow Flag (Counter 1) 0: OFF; 1: ON	0	0	0	Reads out Counter 1's overflow status to the Logic Program.
3	Overflow Flag (Counter 2) 0: OFF; 1: ON	0	Х	Х	Reads out Counter 2's overflow status to the Logic Program.
4	CW/CCW Rotate Notification 0: CCW; 1: CW	О	0	0	Reads out Count Up direction (CW, Count Down direction (CCW) to the Logic Program.
5	Reserved	-	-	-	_
6	Reserved	-	-	-	_
7	Reserved	-	-	-	_
8	Comparator Output Check (Counter 1) 0: Disable; 1: Enable	0	0	х	Reads out Counter 1's Comparator Output Use/Not Use status to the Logic Program.
0	CW Rotate Check (Cam Switch 1) 0: Disable; 1: Enable	х	Х	0	When Cam SW1 is used, reads out CW Output Use/Not Use status to the Logic Program.
9	Comparator Output Check (Counter 2) 0: Disable; 1: Enable	0	х	х	Reads out Counter 2's Comparator Output Use/Not Use status to the Logic Program.
7	CCW Rotate Check (Cam Switch 1) 0: Disable; 1: Enable	Х	Х	0	When Cam SW1 is used, reads out CCW Output Use/Not Use status to the Logic Program.
10	CW Rotate Check (Cam Switch 2) 0: Disable; 1: Enable	Х	Х	0	When Cam SW2 is used, reads out CW Output Use/Not Use status to the Logic Program.
11	CCW Rotate Check (Cam Switch 2) 0: Disable; 1: Enable	х	х	0	When Cam SW2 is used, reads out CCW Output Use/Not Use status to the Logic Program.
12	Reserved	-	-	-	_
13	Command Completion Flag	0	0	0	Confirms sending of CMD is completed.
14	RUN Mode / Setting Mode Switch (Counter 1) 0: RUN Mode; 1: Setting Mode	0	0	0	Reads out Counter 1's mode selection to the Logic Program.
15	RUN Mode / Setting Mode Switch (Counter 2) 0: RUN Mode; 1: Setting Mode	0	х	х	Reads out Counter 2's mode selection to the Logic Program.



Reserved locations cannot be used.

Control Register (CTL)

Used to control the High-Speed Counter unit's operation.

Each bit is used as follows:

Modes Available	Bit Location	Description	16-bit up counter X 2	32-bit up counter	32-bit up/down counter	Note
Enabled in	0	Reset (Counter 1)	0	0	0	Requests Counter 1 Reset
RUN or	1	Reset (Counter 2)	0	Х	Х	Requests Counter 2 Reset
Setting	2	Preset Command (Counter 1)	0	0	0	Requests Counter 1 Preset
Mode	3	Preset Command (Counter 2)	0	Х	Х	Requests Counter 2 Preset
	4	Reserved	-	-	-	
	5	Reserved	-	-	-	
-	6	Reserved	-	-	-	_
	7	Reserved	-	-	-	
	0	Comparator Output (Counter 1) 0: Disable; 1: Enable	0	0	х	Requests Comparator Output Enable/Disable for Counter 1
	8	CW Direction (Cam Switch 1) 0: Disable; 1: Enable	Х	Х	0	Requests CW Enable setting for Cam SW 1. CCW can also be set simultaneously.
Enabled only during	9	Comparator Output (Counter 2) 0: Disable; 1: Enable	0	Х	х	Requests Comparator Output Enable/Disable for Counter 2
Setting Mode	9	CCW Rotate (Cam Switch 1) 0: Disable; 1: Enable	Х	x	0	Requests CCW Enable setting for Cam SW 1. CW can also be set simultaneously.
	10	CW Rotate (Cam Switch 2) 0: Disable; 1: Enable	х	х	0	Requests CW Enable setting for Cam SW 2. CCW can also be set simultaneously.
	11	CCW Rotate (Cam Switch 2) 0: Disable; 1: Enable	Х	x	0	Requests CCW Enable setting for Cam SW 2. CW can also be set simultaneously.
	12	Reserved	-	-	-	
	13	Reserved	_	-	_	
Enabled in RUN or Setting Mode	14	RUN Mode / Setting Mode Switch (Counter 1) 0: RUN Mode; 1: Setting Mode	0	0	0	Requests RUN Mode or Setting Mode for Counter 1.
	15	RUN Mode / Setting Mode Switch (Counter 2) 0: RUN Mode; 1: Setting Mode	0	х	х	Requests RUN Mode or Setting Mode for Counter 2.



• When the process has completed, the Reset and Preset commands will turn OFF.

- Bits 8 to 11 are available only while the unit is operating in Setting Mode.
- Reserved locations cannot be used.



Even when bits 8 to 11 are disabled in setting mode, output is not turned OFF. The Reset and Preset commands will turn output OFF.

Chapter 5 – Data Settings

Command Register (CMD)

Used when data is written to the High-Speed Counter unit or when the unit's data is read. This register is used together with either a WD or RD register.

Prior to using a command, be sure to confirm that the FN-HC is in Setting Mode. Each command is requested once. If a command needs to be repeated, repeat the command's request for the desired number of times.

• Example

When writing a Preset value, enter "1" as the "CMD".

When reading a Preset value, enter "129" as the "CMD".

The following commands are use in the same way.

Write Command	Read Command	Description	Initial Value
1 (01h)	129 (81h)	Preset Value (Counter 1)	0
2 (02h)	130 (82h)	Preset Value (Counter 2) ^{*1}	0
3 (03h)	131 (83h)	Ring Counter Lower Limit (Counter 1) ^{*2}	Cntr. Min. value.
4 (04h)	132 (84h)	Ring Counter Upper Limit (Counter 1)*2	Cntr. Max. value.
5 (05h)	133 (85h)	Ring Counter Lower Limit (Counter 2)*1,*2	Cntr. Min. value.
6 (06h)	134 (86h)	Ring Counter Upper Limit (Counter 2)*1,*2	Cntr. Max. value.
7 (07h)	135 (87h)	Comparator Output Value (Counter 1)*3	0
8 (08h)	136 (88h)	Comparator Output Value (Counter 2)*1	0
9 (09h)	137 (89h)	Dog 1 Lower Limit of Cam Switch 1 ^{*4}	0
10 (0Ah)	138 (8Ah)	Dog 1 Upper Limit of Cam Switch 1 ^{*4}	0
11 (0Bh)	139 (8Bh)	Dog 2 Lower Limit of Cam Switch 1 ^{*4}	0
12 (0Ch)	140 (8Ch)	Dog 2 Upper Limit of Cam Switch 1 ^{*4}	0
13 (0Dh)	141 (8Dh)	Dog 3 Lower Limit of Cam Switch 1 ^{*4}	0
14 (0Eh)	142 (8Eh)	Dog 3 Upper Limit of Cam Switch 1*4	0
15 (0Fh)	143 (8Fh)	Dog 4 Lower Limit of Cam Switch 1 ^{*4}	0
16 (10h)	144 (90h)	Dog 4 Upper Limit of Cam Switch 1 ^{*4}	0
17 (11h)	145 (91h)	Dog 5 Lower Limit of Cam Switch 1 ^{*4}	0
18 (12h)	146 (92h)	Dog 5 Upper Limit of Cam Switch 1*4	0
19 (13h)	147 (93h)	Dog 6 Lower Limit of Cam Switch 1 ^{*4}	0
20 (14h)	148 (94h)	Dog 6 Upper Limit of Cam Switch 1 ^{*4}	0
21 (15h)	149 (95h)	Dog 7 Lower Limit of Cam Switch 1 ^{*4}	0
22 (16h)	150 (96h)	Dog 7 Upper Limit of Cam Switch 1 ^{*4}	0
23 (17h)	151 (97h)	Dog 8 Lower Limit of Cam Switch 1 ^{*4}	0
24 (18h)	152 (98h)	Dog 8 Upper Limit of Cam Switch 1 ^{*4}	0

1. Available only with the 16-bit up counter X 2.

- 2. Available only with the ring counter function.
- 3. Available only with the 16-bit up counter X 2 or the 32-bit up counter.
- 4. Available only with the 32-bit up/down counter.



Be sure to set the Cam Switch Output Range so that the dog's lower limit and upper limit values have at least three (3) seconds gap between them.

Write	Read	Description	Initial Value
Command	Command	-	-
25 (19h)	153 (99h)	Dog 1 Lower Limit of Cam Switch 2 ^{*1}	0
26 (1Ah)	154 (9 A h)	Dog 1 Upper Limit of Cam Switch 2 ^{*1}	0
27 (1Bh)	155 (9Bh)	Dog 2 Lower Limit of Cam Switch 2 ^{*1}	0
28 (1Ch)	156 (9Ch)	Dog 2 Upper Limit of Cam Switch 2 ^{*1}	0
29 (1Dh)	157 (9Dh)	Dog 3 Lower Limit of Cam Switch 2 ^{*1}	0
30 (1Eh)	158 (9Eh)	Dog 3 Upper Limit of Cam Switch 2 ^{*1}	0
31 (1Fh)	159 (9Fh)	Dog 4 Lower Limit of Cam Switch 2 ^{*1}	0
32 (20h)	160 (A0h)	Dog 4 Upper Limit of Cam Switch 2 ^{*1}	0
33 (21h)	161 (A1h)	Dog 5 Lower Limit of Cam Switch 2 ^{*1}	0
34 (22h)	162 (A2h)	Dog 5 Upper Limit of Cam Switch 2 ^{*1}	0
35 (23h)	163 (A3h)	Dog 6 Lower Limit of Cam Switch 2 ^{*1}	0
36 (24h)	164 (A4h)	Dog 6 Upper Limit of Cam Switch 2*1	0
37 (25h)	165 (A5h)	Dog 7 Lower Limit of Cam Switch 2 ^{*1}	0
38 (26h)	166 (A6h)	Dog 7 Upper Limit of Cam Switch 2 ^{*1}	0
39 (27h)	167 (A7h)	Dog 8 Lower Limit of Cam Switch 2*1	0
40 (28h)	168 (A8h)	Dog 8 Upper Limit of Cam Switch 2*1	0
	254 (FEh)	Error Code Read	
	255 (FFh)	Version Read	

Command List (cont.)

1. Available only with the 32-bit up/down counter.



- After turning the FN-HC unit's power OFF, all write data is reset to its initial values. In this case, be sure to reset all write data.
- Be sure to set the Cam Switch Output Range so that the dog's lower limit and upper limit values have at least three (3) seconds gap between them.

Read Data Register/RD (Enabled in Setting Mode)

Stores data when the command to read data from the High-Speed Counter unit is entered. Also, stores data written after the command to write data to the High-Speed Counter unit is entered.

■ Write Data Register/WD (Enabled in Setting Mode)

Stores data before the command to write data to the High-Speed Counter unit is entered.

■ Current Value/CV1

Normally used to store the current count value of Counter 1.

Current Value/CV2

Normally used to store the current count value of Counter 2.

5.2 Data Settings

Data settings are performed in the Setting Mode. Mode changes are controlled via the

Control (CTL) bits 14 and 15. **Reference** 4.1 – "Operation Mode"



When performing data Write in RUN mode, both the GLC unit and the FN-HC unit must be set to the same mode. If they are not, a malfunction can occur.

Data Write

Values written to the FN-HC unit are set in the Write Data (WD) register.



If the WD register contains a value that is outside the allowable Write command range, and the CMD register has been set to a Write command, the maximum or minimum value will be written to the High-Speed Counter unit.

When you enter a Write command value in the Command (CMD) register, the WD value is written as data to the High-Speed Counter unit.



When data containing more than 16 bits is written to data designated as 16-bit, the 16-bit data will be overwritten.

After turning the FN-HC unit's power OFF, all write data is reset to its initial values. In this case, be sure to reset all write data.



- When an incorrect value is entered to the command (SMD) setting, that value will remain unchanged, in the register.
- When commands can be accepted, Bit 13 (Command Completed Flag) and the command value input will both be cleared (set to "0").

Values written to the FN-HC unit will be reflected in the RD command.

Also, when command write is completed, it can be confirmed via the status area's bit 13 (Command Completed Flag), which will turn ON.

Data Read

If a Read command is set in the Command (CMD) register, values that are read from the High-Speed Counter unit are stored in the Read Data (RD) register.



- When an incorrect value is entered to the command (SMD) setting, that value will remain unchanged, in the register.
- When commands can be accepted, Bit 13 (Command Completed Flag) and the command value input will both be cleared (set to "0").

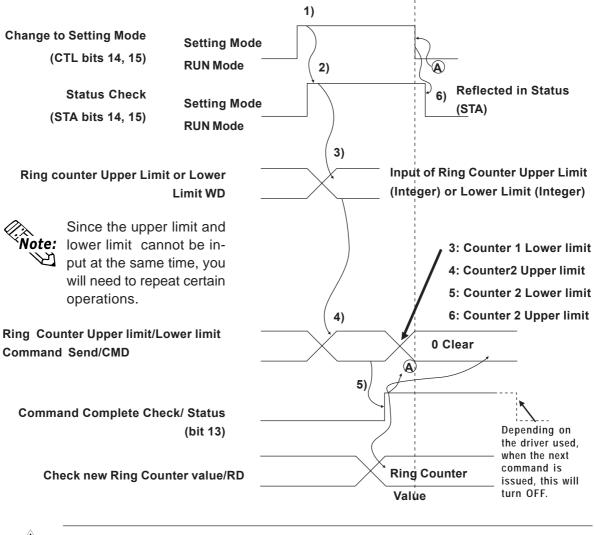
Also, when command read is completed, it can be confirmed via the status area's bit 13 (Command Completed Flag), which will turn ON.

Data Setting Procedures

	Write	Read
1.	Set WD register to a value.	1. Enter a Read command in the
2.	Enter a Write command in the	CMD register.
	CMD register.	\bigvee
	Data is written to the High-speed Counter unit.	Data is read from the High-speed Counter unit to the RD register.

■ High Speed Counter Command Flow

◆ Data Write to Ring Counter Upper/Lower Limit Values

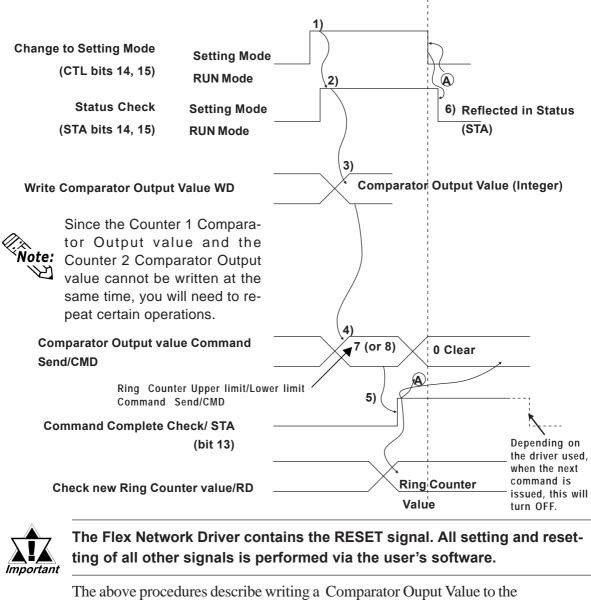




The Flex Network Driver contains the RESET signal. All setting and resetting of all other signals is performed via the user's software.

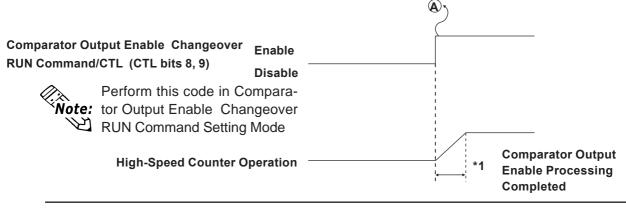
Chapter 5 – Data Settings

♦ Comparator Output Value/Enable & Disable Changeover Settings

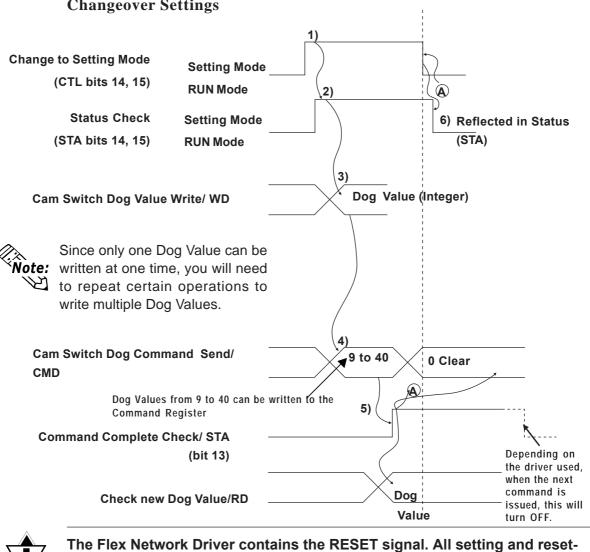


The above procedures describe writing a Comparator Ouput Value to the FN-HC unit. However, while entering the above data is possible, it does not provide functionality for this feature.

To use the above data for the Comparator Value Count Up Output, use the following Comparator Output Enable Changeover to enable output.



*1 At a communication speed of 6Mbps with 63 nodes (Stations), allow at least 5ms for RESET to turn all Comparator Outputs OFF. 8 nodes would be approx. 1ms.



Cam Switch Dog Value Write & Direction Change and Enable/Disable Changeover Settings



The Flex Network Driver contains the RESET signal. All setting and resetting of all other signals is performed via the user's software.

A

The above procedures describe writing a Dog Value to the FN-HC unit. However, while entering the above data is possible, it does not provide functionality for the Cam Switch Output feature.

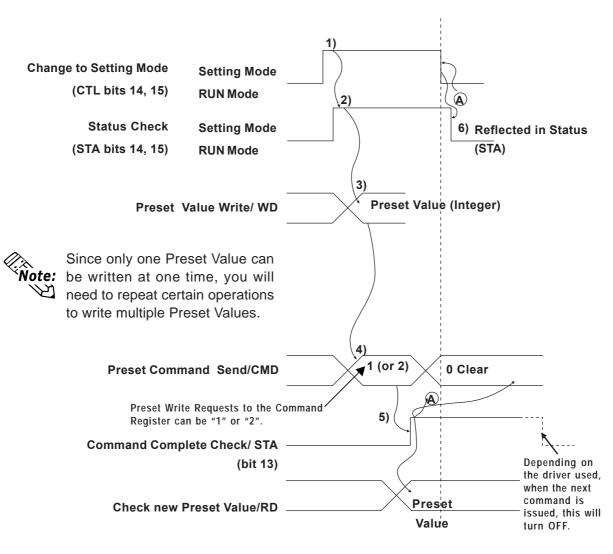
To use the above Dog Value Setting data for simultaneous output, use the following Cam Switch RUN Command to enable the Cam Switch.

		2
Cam switch RUN Command/CTL (CTL bits 8, 9, 10, 11)	Enable Disable	 1
Note: Command in Setting M	ch RUN ode	1 1 1 1 1 1
High-Speed Counter O	peration	 *1

*1 At a communication speed of 6Mbps with 63 nodes (Stations), allow at least 5ms for RESET. 8 nodes would be approx. 1ms.

Chapter 5 – Data Settings

◆ Preset Value Write and Preset RUN

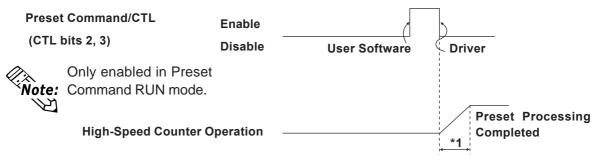




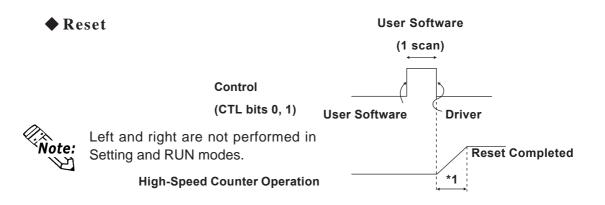
The Flex Network Driver contains the RESET signal. All setting and resetting of all other signals is performed via the user's software.

The above procedures describe writing a Preset Value to the FN-HC unit. However, while entering the above data is possible, it does not provide functionality for the Preset command.

To use the above Preset data for simultaneous output, use the following Preset Command to enable the Preset feature.



*1 At a communication speed of 6Mbps with 63 nodes (Stations), allow at least 5ms for RESET. 8 nodes would be approx. 1ms.



*1 At a communication speed of 6Mbps with 63 nodes (Stations), allow at least 5ms for RESET. 8 nodes would be approx. 1ms.

Memo

- 1. Prior to Troubleshooting
- 4. Troubleshooting for GP3000 Series
- 2. Error Code Display
- 3. Troubleshooting for GLC2000/ LT Series

6 Problems and Solutions

This section describes the Flex Network system's error messages and countermeasures.

6.1 Prior to Troubleshooting

Before reading this chapter's "*Troubleshooting Checklist*" section for the cause(s) of a unit's problem, first identify the type of problem itself, and then check other basic items.

Flex Network errors are classified, as follows, into three types of errors:

1. Logic Program Error

Chapter

The logic program does not run (GLC status LED: Green is not lit).

2. Flex Network I/F Error

Communication cannot be performed with any Flex Network unit.

3. Flex Network Unit Error

Flex Network unit cannot input or output signals.

Check Items

After completing your preliminary check, and before troubleshooting for the cause(s) of a unit's problem, be sure to check the following items:

- Is the correct power voltage supplied to the GLC and Flex Network units?
- Is the power supplied to the GLC and Flex Network units within the allowable voltage range?
- Are all connected cable wiring and connections (communication cable, I/O cable) secure and correct?
- Are any Flex Network unit terminals loose or disconnected?
- Are all Flex Network unit switches (S-No. switch, dip switch, terminal switch) set correctly?
- Is the required communication cable being used?

6.2 Error Code Display

By displaying an error code on the GLC screen with using the system variables that indicate the I/O driver error codes, troubleshooting can be performed quickly.

Model	System Variable
GLC2000/LT Series	#IOStatus
GP3000 Series	#L_IOStatus

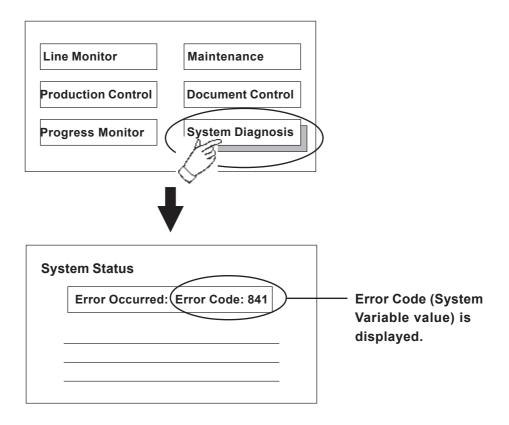


Note: For GP3000 series, an error code is displayed in the system window on the GP screen without using the system variables.

The following is an example of an error code display application.

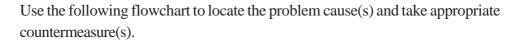
Example Application

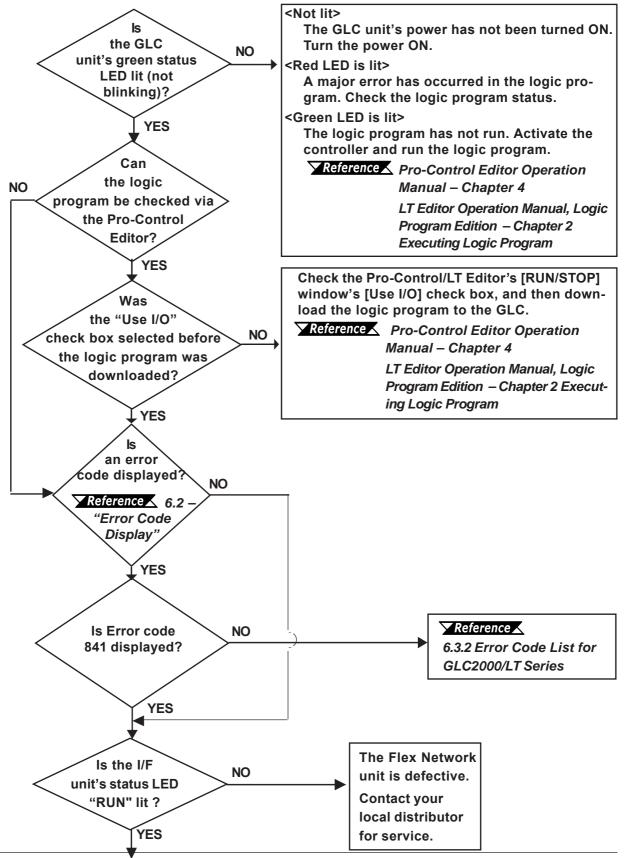
- 1. Create an I/O System Diagnosis button.
- 2. Create a ladder logic program that displays the system status as an error code when the [System Diagnosis] button is pressed.

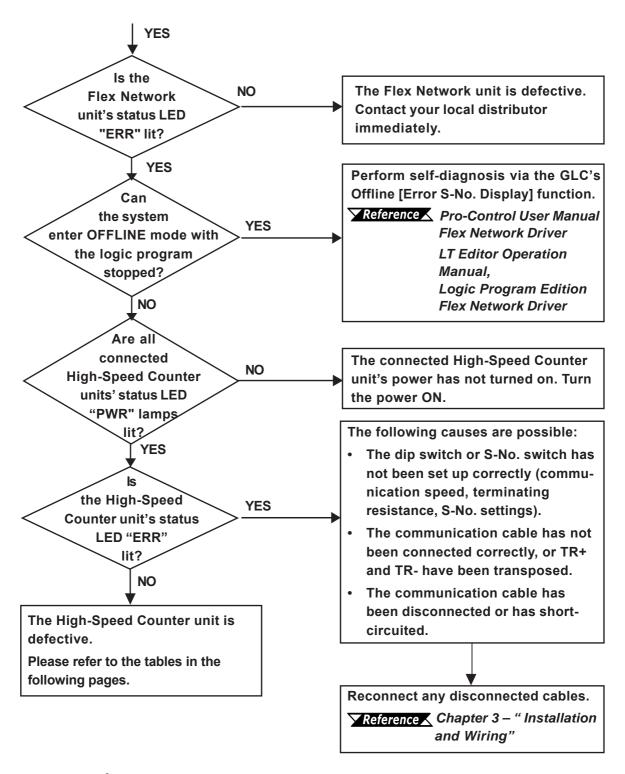


6.3 Troubleshooting for GLC2000/LT Series

6.3.1 Troubleshooting Checklist for GLC2000/LT Series









To minimize the amount of system downtime, Pro-face recommends that you prepare Flex Network unit substitutes in case of unexpected errors or problems.

If you cannot find the source of the problem in this section's "*Troubleshooting*" flowcharts, the High-Speed Counter unit itself may be the problem. Use the following table to take the appropriate problem-solving measures.

Condition	Check Item	Solution
	Is the operation mode	Set the RUN Mode / Setting Mode
	set to RUN Mode?	switch (Control bits 14, 15) to ON.
		Failed to write initial set value.
		Either STOP and RUN the
		controller, or turn the High-Speed
		Counter unit OFF and then ON.
	844 in #IOSTATUS?	If the condition is the same, the
		communication cable may be
		disconnected or improperly
Cannot write set		connected, or the High-Speed
		Counter unit may have failed.
value correctly		Failed to write set value.
		Write set value again.
		If the condition is the same, the
	845 in #IOSTATUS?	communication cable may be
		disconnected or improperly
		connected, or the High-Speed
		Counter unit may have failed.
	Does the previous Command value	Check the values entered in
	remain in CMD (has the value not	the Command (CMD) setting,
	cleared to 0)?	and enter valid values.
		If the GLC unit displays an error, use
		the troubleshooting section of the
	Does the GLC display an error?	corresponding GLC manual to set
		the GLC unit to normal operation.
	Are A Phase, B Phase, and	Check and fix external wiring.
	PLS1/2 wired correctly?	
	Is voltage directly applied	If the unit does not perform count
Does not	to pulse input terminals?	operation, check and fix the pulse
perform count		generator and/or the external wiring.
operation	Is the operation mode	Set the RUN Mode and the Setting
operation	set to Setting Mode?	Mode (CTL bits 14, 15) to OFF.
	Has an overflow error occurred?	Clear the overflow error by
		running Reset or Preset.
		An error was detected in the
		High-Speed Counter unit.
	843 in #IOSTATUS?	Reference
		6.3.2 – "Error Code List for
		GLC2000/LT Series"

FN-HC Unit Troubleshooting Checklist

Condition	Check Item	Solution
	Is 844 written to #IOST AT US?	The read in of the initial value has failed. Turn the controller to STOP, then RUN, or turn the FN-HC unit's power ON/OFF. IF the problem repeats, check if the data transfer cable is either cut, the connector is loose or if the FN-HC unit is damaged.
	Does the input type of pulse	Match the input type of pulse
	match the pulse input type in	with the pulse input type
	the I/O configuration settings?	in the I/O configuration.
	Is the maximum speed of	Correct the calculated speed
	input pulses within the range	settings in the I/O configuration so
	of calculated speed set in the	as to correspond with the maximum
	I/O configuration?	speed.
		Check pulse shape with a
	Does the pulse shape entered	synchroscope. If it does not match
	match performance specifications?	specifications, enter the correct
		pulse shape.
Count value is	Do the differential input wires	Use a twist pair shield cable for
not normal.	use a twist pair shield cable?	differential input wires. If the shield
	Is the shield line grounded?	line is not grounded, ground it.
	Are the insides of the panel and surrounding units	Protect from noise.
	protected from noise?	
	Is there enough distance	Use an independent line for pulse
	between high voltage units	input wires. The pulse input line
	а с	and the power line should be
	and the pulse input line?	separated by more than 15cm.
	Are the count input values that	When the count values are different,
	are entered in PLS1 and PLS2	a hardware error exists. Please
	the same?	contact your local distributor.

FN-HC Unit Troubleshooting Checklist (cont.)

6.3.2 Error Code List for GLC2000/LT Series

System Design Errors

Error Code	Definition
501	Internal variable mapped to I/O terminal.
502	Input variable mapped to output terminal.
503	Output variable allocated to input terminal.
504	Discrete variable mapped to integer terminal.
505	Integer variable mapped to discrete terminal.
506	Variable type not supported by driver.
507	Variable is not mapped to terminal.
801	Duplicate terminal number encountered.
802	Duplicate S-No.
803	S-No. exceeded the range.
804	S-No. is duplicated in an analog unit.
805	S-No. is duplicated in a counter unit.
806	S-No. is duplicated in a single-axis positioning unit.

Initialization Errors

Error Code	Definition
821	There is no hardware unit. Or the type is incorrect.
822	Initial error.
823	Analog unit setting error.

Runtime Errors

Error Code	Definition		
841	Error (disconnect, malfunction) among connected I/O units.		
842	Error (disconnect, malfunction) in analog input unit.		
042	(Input range: set at 4 – 20mA)		
	Error in the High-Speed Counter unit. Use a command to refer to the unit's error		
843	code details.		
	Reference 🖌 📁 High-Speed Counter Unit Errors		
844	Initial error in the High-Speed Counter unit.		
845	Communication error with the High-Speed Counter unit.		
	Error in the single-axis positioning unit. Use a command to refer to the unit's		
846	error code details.		
	Reference Flex Network Single-Axis Positioning Unit User Manual		
847	Communication error with the single-axis positioning unit.		

Internal Error

Error Code	Definition
850 –	Driver error #850. Please contact your local distributor.

Error Code	Definition
1	Set value error on the cam switch.
2	Set data error on the Ring Counter value (Counter 1).
3	Set data error on the Ring Counter value (Counter 2).

■ High-Speed Counter Unit Errors

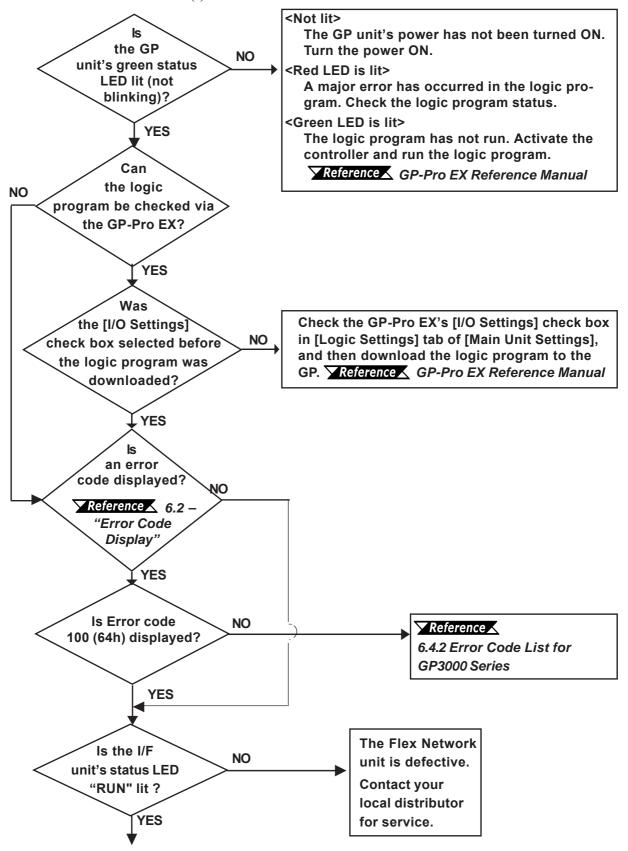


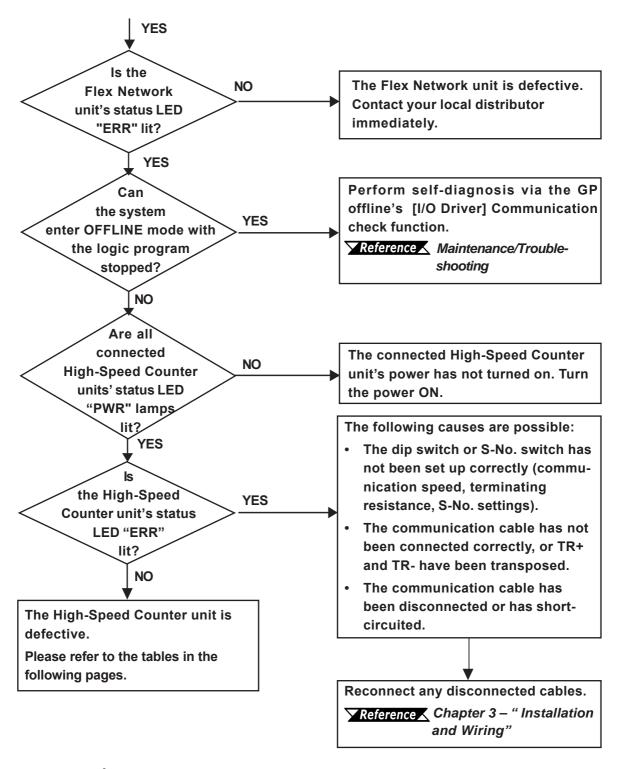
Use a Read Command to check the High-Speed Counter unit's error code details.

6.4 Troubleshooting for GP3000 Series

6.4.1 Troubleshooting Checklist for GP3000 Series

Use the following flowchart to locate the problem cause(s) and take appropriate countermeasure(s).







To minimize the amount of system downtime, Pro-face recommends that you prepare Flex Network unit substitutes in case of unexpected errors or problems.

If you cannot find the source of the problem in this section's "*Troubleshooting*" flowcharts, the High-Speed Counter unit itself may be the problem. Use the following table to take the appropriate problem-solving measures.

Condition Check Item		Solution		
	Is the operation mode	Set the RUN Mode / Setting Mode		
	set to RUN Mode?	switch (Control bits 14, 15) to ON.		
		Failed to write initial set value.		
		Either STOP and RUN the		
		controller, or turn the High-Speed		
		Counter unit OFF and then ON.		
	105 in #L_IOStatus?	If the condition is the same, the		
		communication cable may be		
		disconnected or improperly		
Connotwrite eat		connected, or the High-Speed		
Cannot write set		Counter unit may have failed.		
value correctly		Failed to write set value.		
		Write set value again.		
		If the condition is the same, the		
	106 in #L_IOStatus?	communication cable maybe		
		disconnected or improperly		
		connected, or the High-Speed		
		Counter unit may have failed.		
	Does the previous Command value	Check the values entered in		
	remain in CMD (has the value not	the Command (CMD) setting,		
	cleared to 0)?	and enter valid values.		
		If the GP unit displays an error, use		
		the troubleshooting section of the		
	Does the GP display an error?	corresponding GP manual to set		
		the GP unit to normal operation.		
	Are A Phase, B Phase, and	Check and fix external wiring.		
	PLS1/2 wired correctly?			
	Is voltage directly applied	If the unit does not perform count		
Does not	to pulse input terminals?	operation, check and fix the pulse		
perform count		generator and/or the external wiring.		
operation	Is the operation mode	Set the RUN Mode and the Setting		
operation	set to Setting Mode?	Mode (CTL bits 14, 15) to OFF.		
	Has an overflow error occurred?	Clear the overflow error by		
		running Reset or Preset.		
		An error was detected in the		
		High-Speed Counter unit.		
	104 in #L_IOStatus?	▼ Reference ▲		
		6.4.2 – "Error Code List for GP3000		
		Series"		

FN-HC Unit Troubleshooting Checklist

Condition	Check Item	Solution	
	Is 105 written to #L_IOStatus?	The read in of the initial value has failed. Turn the controller to STOP, then RUN, or turn the FN-HC unit's power ON/OFF. IF the problem repeats, check if the data transfer cable is either cut, the connector is loose or if the FN-HC unit is damaged.	
	Does the input type of pulse	Match the input type of pulse	
	match the pulse input type in	with the pulse input type	
	the I/O configuration settings?	in the I/O configuration.	
	Is the maximum speed of	Correct the calculated speed	
	input pulses within the range	settings in the I/O configuration so	
	of calculated speed set in the	as to correspond with the maximum	
	I/O configuration?	speed.	
		Check pulse shape with a	
	Does the pulse shape entered	synchroscope. If it does not match	
	match performance specifications?	specifications, enter the correct	
		pulse shape.	
Count value is	Do the differential input wires	Use a twist pair shield cable for	
not normal.	use a twist pair shield cable?	differential input wires. If the shield	
	Is the shield line grounded?	line is not grounded, ground it.	
	Are the insides of the panel and surrounding units protected from noise?	Protect from noise.	
	Is there enough distance	Use an independent line for pulse	
	between high voltage units	input wires. The pulse input line	
	and the pulse input line?	and the power line should be	
		separated by more than 15cm.	
	Are the count input values that	When the count values are different,	
	are entered in PLS1 and PLS2	a hardware error exists. Please	
	the same?	contact your local distributor.	

FN-HC Unit Troubleshooting Checklist (cont.)

6.4.2 Error Code List for GP3000 Series



In the system window on the GP screen, an error code is displayed with RGE* put to the top of the error code. Ex.) RGE*001 Not supported unit

System Design Errors

Error Code	Error Message	Definition		
001	Not supported unit.	T he type of the unit is different.		
		The data type of the symbol variable assigned to the		
002	Illegal Parameter.	Flex Network unit is illegal.		
		The Flex Network unit setting value is illegal.		
003	Device offset beyond limit.	The address of the symbol variable assigned to the		
003	Device offset beyond finnt.	Flex Network unit is out of range.		
004		The number of Flex Network unit terminals exceeds		
004	Terminal config overlapped.	the limit.		
005	Illegal terminal coguence	The I/O terminal numbers are not specified in		
005	Illegal terminal sequence.	ascending order.		
00/	Incufficient terminale	The number of I/O terminals is not appropriate		
006	Insufficient terminals.	(insufficient).		
007	Units config overlapped.	Flex Network unit S-No. is duplicated and set.		
	Units count over limit.	The maximum number of connected Flex Network		
		units (63 units) is exceeded.		
000		The maximum value of S-No. (S-No. 63) is		
008		exceeded.		
		S-No. of the Flex Network unit that occupies more		
		than one node has exceeded the max. (S-No. 63).		
009	Drivers config overlapped.	The driver has been registered twice.		
010	Unmatched In/Out terminal.	The input/output settings of the Flex Network unit are		
010		not correct.		
011	Unmatched bit/word term.	The variable type specified in the Flex Network unit		
011		is incorrect.		
012	Illegal level nunber.	Something is wrong with the I/O driver.		
010	Illegal data addr. Gotten.	The I/O driver information is incorrect.		
013		The controller information is incorrect.		
014	No drivers/units registed.	The I/O driver or Flex Network unit is not registered.		

Error Code	ror Code Error Message Definition			
100		A communication error has occurred between the		
		main unit and the Flex Network unit.		
	Unit communication error.	The communication cable is cut off. The Flex		
		Network unit is not connected. The editor settings		
		have problems.		
101	4ch. analog setting error.	Communication with the 4ch. analog unit has failed.		
102	2ch. analog setting error.	Communication with the 2ch. analog unit has failed.		
102	Analog unit's wire broken	The 4 to 20mA-ranging input signal of the 4ch. or		
103	Analog unit's wire broken.	2ch. analog unit is cut off.		
		An error has occurred in the high-speed counter unit.		
104	Countor unitio orror	For details, use a command to call up the unit's error		
104	Counter unit's error.	code. Reference <i>High-Speed Counter Unit</i>		
		Errors		
105	Counter initial error.	Initializing the high-speed counter unit has failed.		
	Counter communication err.	A communication error with the high-speed counter		
		unit has occurred.		
106		The communication cable is cut off. The high-		
		speed counter unit is not connected. The editor		
		settings have problems.		
		An error has occurred in the positioning unit. For		
107	Positioning Unit's error.	details, use a command to call up the unit's error		
107		code. Reference <i>Flex Network Single-Axis</i>		
		Positioning Unit User Manual		
	2ch. analog comm. error.	A communication error with the positioning unit has		
		occurred.		
108		The communication cable is cut off. The positioning		
		unit is not connected. The editor settings have		
		problems.		
	2ch. analog comm. error.	A communication error with the 2ch. analog unit has		
		occurred.		
109		The communication cable is cut off. The 2ch.		
		analog unit is not connected. The editor settings		
		have problems.		

Runtime Errors

Internal Error

Error Code	Error Message	Definition	
200	SetValue func.(INT) NG.	Integer-type Terminal data of the Flex Network unit	
		could not be read.	
201	SetValue func.(bit) NG.	Bit-type Terminal data could not be read.	
202	GetValue func.(INT) NG.	Integer-type Terminal data could not be written.	
203	GetValue func.(bit) NG.	Bit-type Terminal data could not be written.	

■ High-Speed Counter Unit Errors

Error Code	Definition
1	Set value error on the cam switch.
2	Set data error on the Ring Counter value (Counter 1).
3	Set data error on the Ring Counter value (Counter 2).



Use a Read Command to check the High-Speed Counter unit's error code details.

Memo

- 1. Ring Counter Function Program Example
- 2. Comparator Output Function Program Example
- 3. Cam Switch Output Function Program Example

Appendix

This section gives examples of the logic program's ring counter function, comparator output function, and cam switch output function.

In the following programs, the first action performed is Version data read out. In order to set the Setting Value Write Flag to ON, the Preset value, Ring lower and upper limit values are read into the FN-HC unit.

Next, turn the Counter Start Flag ON when you wish to begin counting. When you want to make the current value the Preset Value, turn the Preset Command Flag ON. To use the Reset feature, turn the Reset Flag ON.

A.1 Ring Counter Function - Program Example

■ I/O Configuration

<GLC2000/LT Series>

≹ Configure I/O Eile Edit <u>V</u> iew <u>H</u> elp		
Flex Network Driver (ID:#1) (Speed	 (%IW1.1.0) (%QW1.1.2) (%IW1.1.3) (%QW1.1.4) (%IW1.1.5)	Close Drivers Setup Add Add Add Map Map Uhmap

<GP3000 Series>

📓 FLEX N	ETWORK	
4 % 4	l � X −	
FLEX NETW	ORK Driver(ID:#1)
Name	Variable	IEC Address
📮 🖡 S-No.1	(FN-HC10SK)	
Ø STA	STA	(%IW.1.1.0)
🛛 🖳 🖉 CTL	CTL	(%QW.1.1.1)
🛛 🦳 🥥 СМС	CMD	(%QW.1.1.2)
Ø RD	RD	(%IW.1.1.3)
🛛 🖳 🥥 WD	WD	(%QW.1.1.4)
🖳 🖉 CV1	CV1	(%IW.1.1.5)

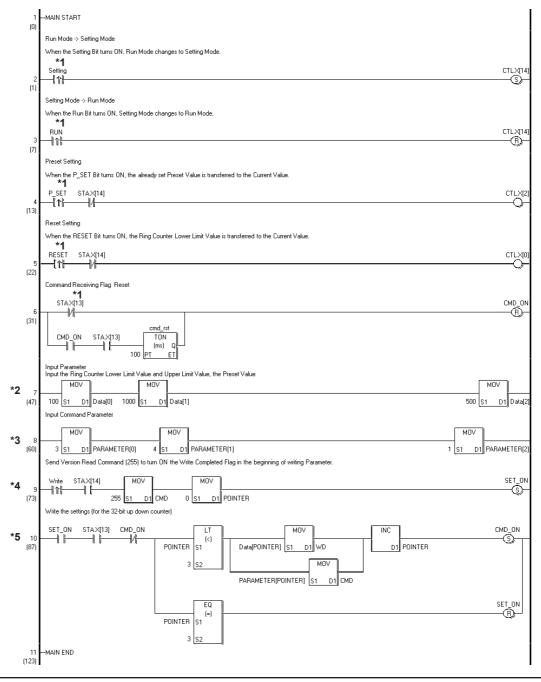
■ Logic Program Example for GLC2000/LT Series

1	-START
	Run Mode -> Setting Mode When the Setting Bit turns ON, Run Mode changes to Setting Mode.
	Setting Mode
2	*1 Setting CTL.X[14] -PI
2	Off On
	Setting Mode -> Run Mode When the Run Bit turns ON, Setting Mode changes to Run Mode.
	Run Mode
	*1 RUN CTL.X[14]
3	
	Preset Setting
	When the P_SET Bit turns ON, the already set Preset Value is transferred to the Current Value.
	P_SET_STA.X[14] CTL.X[2]
4	P!/1
	Reset Setting When the RESET Bit turns ON, the Ring Counter Lower Limit Value is transferred to the Current Value.
5	RESET STAX[14] CTLX[0]
Ŭ	Off On Off Command Receiving Flag. Reset
	<pre>cummanu necerving riag necer *1</pre>
6	STAX[13] CMD.ON
0	off Off
	cmdjst
	Off Off 100 PT ET 0 Input Parameter
	Input the Ring Counter Lower Limit Value and Upper Limit Value, the Preset Value
	Data[D]Ring Counter Lower Limit Value -> 100 (variable) Data[]]Ring Counter Upper Limit Value -> 1000 (variable) Data[2]:Preset Value -> 500 (variable)
7	EN DN EN DN EN DN EN DN EN DN EN DN DT Data[1] 500 [N OUT Data[2]
	100050005000
	Parameter Setting for writing the Ring Counter Lower Limit Value and Upper Limit Value, and the Preset Value to the high speed counter unit.
	PARAMETER[0] Parameter of the command to be written for writing the Ring Counter Lower Limit Value to the high speed counter unit -> 3 (invariable) PARAMETER[1] Parameter of the command to be written for writing the Ring Counter Upper Limit Value to the high speed counter unit -> 4 (invariable) PARAMETER[2] Parameter of the command to be written for writing the Preset Value to the high speed counter unit -> 1 (invariable)
8	EN_DN
	Send Version Read Command (255) to turn ON the Write Completed Flag in the beginning of writing Parameter. When the Write Bit turns ON, the program for writing Parameter to the high-speed counter unit operates.
	WRITE Trigger
	*1 Write STAX[14] MOV MOV SET_ON
9	
	Write the settings (for the 32-bit up down counter)
	Program for writing the already set parameter to the high-speed counter unit (Continuous WRITE using array variables)
10	SET_ON STAX[13] CMD_ON LT CMD_ON CMD_ON CMD_ON
	Off Off POINTER Data[POINTER]IN OUT WD A POINTER Off 1 10000 10000 1
	3 B
	MOV
	EN O
	POINTER A Off
	3 B

*1 Turn each ON with the switches or the programs on the screen.

Appendix

■Logic Program Example of GP3000 Series



*1 Turn each ON with the switches or the programs on the screen.

- *2 Data[0]:Ring Counter Lower Limit Value -> 100 (variable) Data[1]:Ring Counter Upper Limit Value -> 1000 (variable) Data[2]:Preset Value -> 500 (variable)
- *3 Parameter Setting for writing the Ring Counter Lower Limit Value and Upper Limit Value, and the Preset Value to the high speed counter unit. PARAMETER[0]:Parameter of the command to be written for writing the Ring Counter Lower Limit Value to the high speed counter unit -> 3 (invariable) PARAMETER[1]:Parameter of the command to be written for writing the Ring Counter Upper Limit Value to the high speed counter unit -> 4 (invariable) PARAMETER[2]:Parameter of the command to be written for writing the Preset Value to the high speed counter unit -> 1 (invariable)
- *4 When the Write Bit turns ON, the program for writing Parameter to the highspeed counter unit operates.
- *5 Program for writing the already set parameter to the high-speed counter unit (Continuous WRITE using array variables)

A.2 Comparator Output Function - Program Example

■ I/O Configuration

<GLC2000/LT Series>

X Configure I/O <u>File E</u> dit <u>V</u> iew <u>H</u> elp		
Flex Network Driver (ID:#1) (Speed:6	 (%IW1.1.0) (%QW1.1.1) (%QW1.1.2) (%IW1.1.3) (%QW1.1.4) (%IW1.1.5)	Close

<GP3000 Series>

🕎 FLEX N	ETWORK	
4 × R	★ ★	
FLEX NETW	ORK Driver(ID:#1)	
Name	Variable	IEC Address
📮 🖡 S-No.1	(FN-HC10SK)	
💋 STA	STA	(%IW.1.1.0)
💋 CTL	CTL	(%QW.1.1.1)
🦳 🖉 СМД	CMD	(%QW.1.1.2)
💋 RD	RD	(%IW.1.1.3)
🔕 WD	WD	(%QW.1.1.4)
🖳 🙆 CV1	CV1	(%IW.1.1.5)

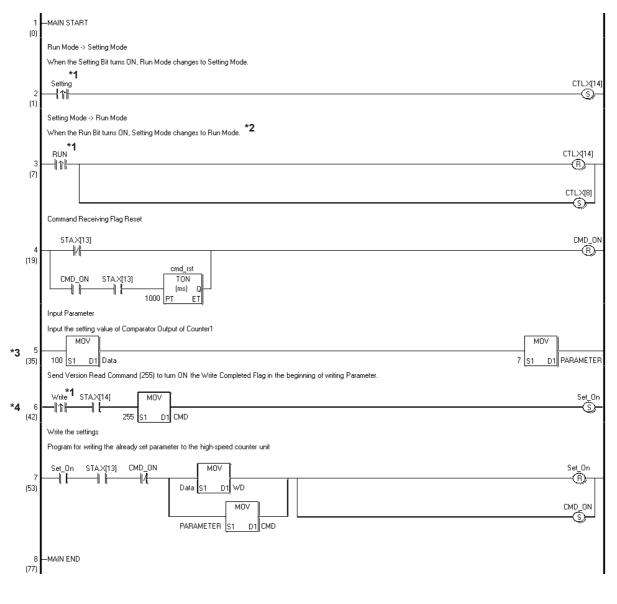
Appendix

■ Logic Program Example for GLC2000/LT Series

1			
	Run Mode -> Setting Mode		
	When the Setting Bit turns ON, Run Mode changes to Setting Mode.		
	*1 Setting	CTL.X[14]	
2	Off	SM Off	
	Setting Mode -> Run Mode		
	When the Run Bit turns ON, Setting Mode changes to Run Mode. (Simultaneously, Comparator Output of Counter1 is enabled.)		
	*1		
3	RUN	CTL.X[14]	
1	Öff	Off	
		CTL.X[8]	
		On	
	Command Receiving Flag Reset		
	STA.X[13]	CMD_ON	
4		B	
		0	
	CMD_ON_STAX[13] TON		
	Input Parameter		
	Input the setting value of Comparator Output of Counter1		
	Data: Setting Value of Comparator Output of Counter1 (variable) PARAMETER: Parameter of the command to be written for writing the setting value of Comparator Output of Counter1 to the high-speed cou Gravities	nter unit -> 7	
	(invariable)		
5		EN DN	
	100 IN OUT Data 7 100 100	IN OUT PARAMETER	
	Send Version Read Command (255) to turn ON the Write Completed Flag in the beginning of writing Parameter.		
	When the Write Bit turns ON, the program for writing Parameter to the high-speed counter unit operates. WRITE		
	Triseer		
6	Write STAX[14] MOV 	Set_On	
	Off Off 255 IN OUT CMD	ŎŤſ	
	Write the settings		
	Program for writing the already set parameter to the high-speed counter unit		
		S-1 0-	
7	Set_On_STAX[13]_CMD_ON	Set_On 	
	Off Off Off Data IN OUT WD 100 100	Off	
		CMD_ON	
	PARAMETERIN OUT CMD 7 0		
8	I – END		
9	-PEND		
	·		

*1 Turn each ON with the switches or the programs on the screen.

■Logic Program Example of GP3000 Series



- *2 Simultaneously, Comparator Output of Counter1 is enabled.
- *3 Data: Setting Value of Comparator Output of Counter1 (variable)
 - PARAMETER: Parameter of the command to be written for writing the setting value of Comparator Output of Counter1 to the high-speed counter unit -> 7 (invariable)
- *4 When the Write Bit turns ON, the program for writing Parameter to the highspeed counter unit operates.

^{*1} Turn each ON with the switches or the programs on the screen.

A.3 Cam Switch Output Function - Program Example

■ I/O Configuration

<GLC2000/LT Series>

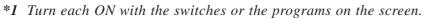
X Configure I/O <u>File E</u> dit <u>View H</u> elp		
Flex Network Driver (ID:#1) (Speed:6Mbps)	nCounter) 768 (%IW1.1.0 768 (%IW1.1.1 0 (%IW1.1.2 4096 (%IW1.1.3 2000 (%IW1.1.4 0 (%IW1.1.5	<u>S</u> etup <u>A</u> dd

<GP3000 Series>

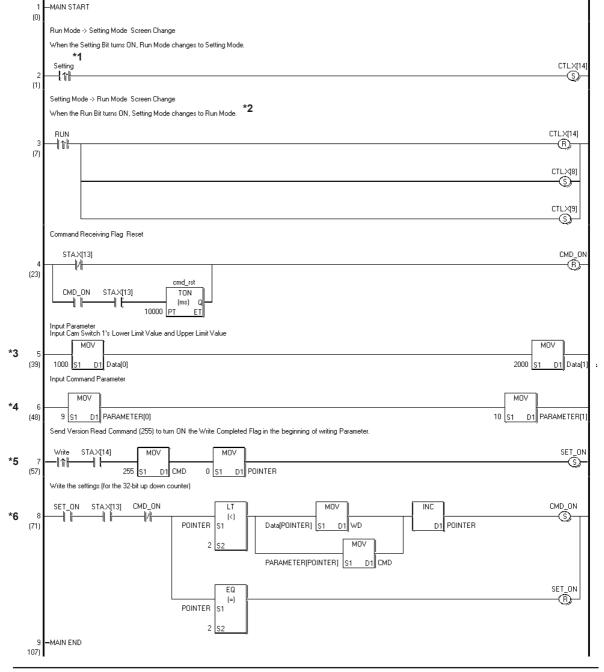
مستر ا			
4 1 3 1	5 🕂 🕈 🗶		
FLEX NETWORK Driver(ID:#1)			
Name	Variable	IEC Address	
📮 🖥 S-No	.1 (FN-HC10SK)		
🗶 ST	A STA	(%IW.1.1.0)	
🛛 🖳 🖉 CT	L CTL	(%QW.1.1.1)	
🛛 🖳 🖉 CN	4D CMD	(%QW.1.1.2)	
🛛 🖳 🖉 RI) RD	(%IW.1.1.3)	
🛛 🖳 🖉 W	D WD	(%QW.1.1.4)	
🖳 🗶 CV	/1 CV1	(%IW.1.1.5)	

■ Logic Program Example for GLC2000/LT Series

1	-START Run Mode ->Setting Mode Screen Change
	Hun Mode -/ Setting Mode -Screen Change When the Setting Bit turns ON, Run Mode changes to Setting Mode.
	Setting Mode
	*1 Settine CTLX[14]
2	
	Setting Mode -> Run Mode Screen Change
	When the Run Bit turns ON, Setting Mode changes to Run Mode. (Simultaneously, CW, CCW Direction of Cam Switch 1 is enabled.) Run Mode
	RUN CTLX[14]
3	P
	CTL.X[8]
	Silo on
	CTL X[9]
	Command Receiving Flag. Reset
4	STAX[13] CMD_ON
	Off Off
	cmd_rst
	Off Off 10000 PT ET0 Input Parameter
	Input Cam Switch 1's Lower Limit Value and Upper Limit Value
	Data[0]: Parameter of Cam Switch 1's Lower Limit Value -> 1000 (variable) Data[1]: Parameter of Cam Switch 1's Upper Limit Value -> 2000 (variable)
	MOV
5	
	100020002000
	Parameter Setting for writing the Cam Switch 1's Lower Limit Value and Upper Limit Value to the high speed counter unit.
	PARAMETER(0) Parameter of the command to be written for writing the Cam Switch 1's Lower Limit Value to the high speed counter unit -> 9 (invariable) PARAMETER[1] Parameter of the command to be written for writing the Cam Switch 1's Upper Limit Value to the high speed counter unit -> 10 (invariable)
6	
0	9 [N OUT PARAMETER[0] 10 [N OUT PARAMETER[1] 9
	Send Version Read Command (255) to turn ON the Write Completed Flag in the beginning of writing Parameter.
	When the Write Bit turns ON, the program for writing Parameter to the high-speed counter unit operates.
	WRTE Trigger
7	Write STAX[14] MOV SET_ON
	Write the settings (for the 32-bit up down counter)
	Program for writing the already set parameter to the high-speed counter unit (Continuous WRITE using array variables)
8	SET_ON STAX(13) CMD_ON
0	Off Off Off POINTERA Data[POINTER]]N OUT WD APOINTER Off Off 2 0 2000 2
	MOV
	POINTER A Off
	2 B
9	- END
10	-PEND



Appendix



■Logic Program Example of GP3000 Series

- *1 Turn each ON with the switches or the programs on the screen.
- *2 Simultaneously, CW, CCW Direction of Cam Switch 1 is enabled.
- *3 Data[0]: Parameter of Cam Switch 1's Lower Limit Value -> 1000 (variable) Data[1]: Parameter of Cam Switch 1's Upper Limit Value -> 2000 (variable)
- *4 Parameter Setting for writing the Cam Switch 1's Lower Limit Value and Upper Limit Value to the high speed counter unit.
 - PARAMETER[0]:Parameter of the command to be written for writing the Cam Switch 1's Lower Limit Value to the high speed counter unit -> 9 (invariable) PARAMETER[1]:Parameter of the command to be written for writing the Cam Switch 1's Upper Limit Value to the high speed counter unit -> 10 (invariable)
- *5 When the Write Bit turns ON, the program for writing Parameter to the highspeed counter unit operates.
- *6 Program for writing the already set parameter to the high-speed counter unit (Continuous WRITE using array variables)

Memo