



Starter kit User Guide

SK-FM4-U120-9B560

SK-FM4-U120-9B560-MEM

Hardware V1.1 / Documentation V1.6



Information about this PDF document



- For your convenience this user guide includes external links that simplify installing of drivers, software utilities, and quick jumps to documentation.
- Some PDF viewer do not allow access to external content by links because of security reasons.
- A viewer called “PDF XChange” is provided in the software package of this starter kit. Its use is free of charge and no additional installation is required.
- Launching “start.bat” opens this user guide in the PDF XChange viewer.
- Please ensure you have copied the complete software package related to this starter kit in order to use and run the links and examples given on the next pages.
- Please contact the [Spansion Support](#) in case of any question.

Overview

- [MCU Features, Board Features & Contents](#)
- [Test it by a terminal / Test it by a GUI](#)
- [The Hardware / Pin Overview](#)
- [The Jumper Table / Jumper Default](#)
- [Board Power](#)
- [Software Examples & Tools](#)
- [Flash Programming](#)
- [JTAG / CMSIS-DAP](#)
- [IAR-Embedded Workbench](#)
- [KEIL µVision](#)
- [Workshops, Contacts & More](#)



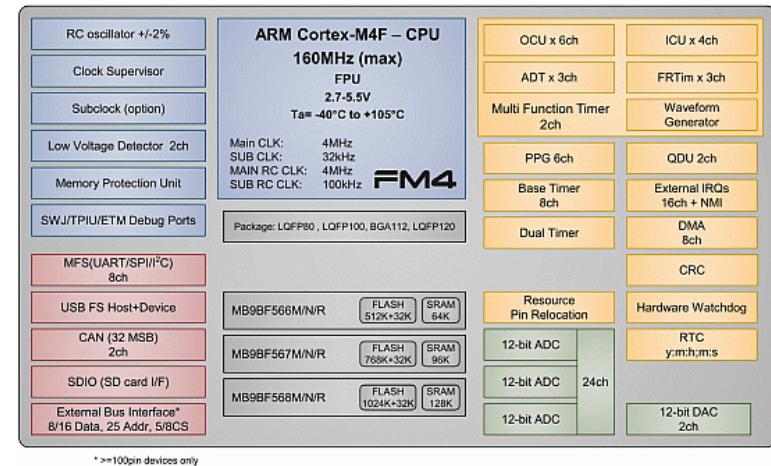
■ Additional documents

- [Schematic](#)
- [Factsheet](#)
- [Data sheet MB9B560R Series](#) and [Errata](#)
- [Peripheral Manual](#) and [Errata](#)
- [Peripheral Manual \(Timer Part\)](#) and [Errata](#)
- [Peripheral Manual \(Analog Part\)](#)
- [Peripheral Manual \(Communication Part\)](#) and [Errata](#)
- [Flash Programming Manual](#) and [Errata](#)

Please visit www.spansion.com to find latest releases of the above mentioned documents.

Features of the microcontroller

- The SK-FM4-U120-9B560 and SK-FM4-U120-9B560-MEM are based on the Spansion ARM® Cortex®-M4 device MB9BF568R
- The MB9B560R Series includes the following features:
 - Up to 1 MByte Flash Memory and 32 KByte Work Flash Memory
 - Up to 128 KByte RAM
 - Up to 160MHz clock
 - Up to 2 CAN controller 2.0A/B
 - Up to 8 UART / LIN / SPI / I²C interfaces
 - USB-Host/-Device interface
 - SD-Card interface
 - Three 12 bit ADCs, up to 24 channels
 - Two 12 bit DACs
 - Up to 16 channel external interrupts
 - Two Multifunction timer with waveform generator, e.g. Motor control
 - Timers (ICUs, OCUs, PPGs, others)



* >=100pin devices only

Features of the board



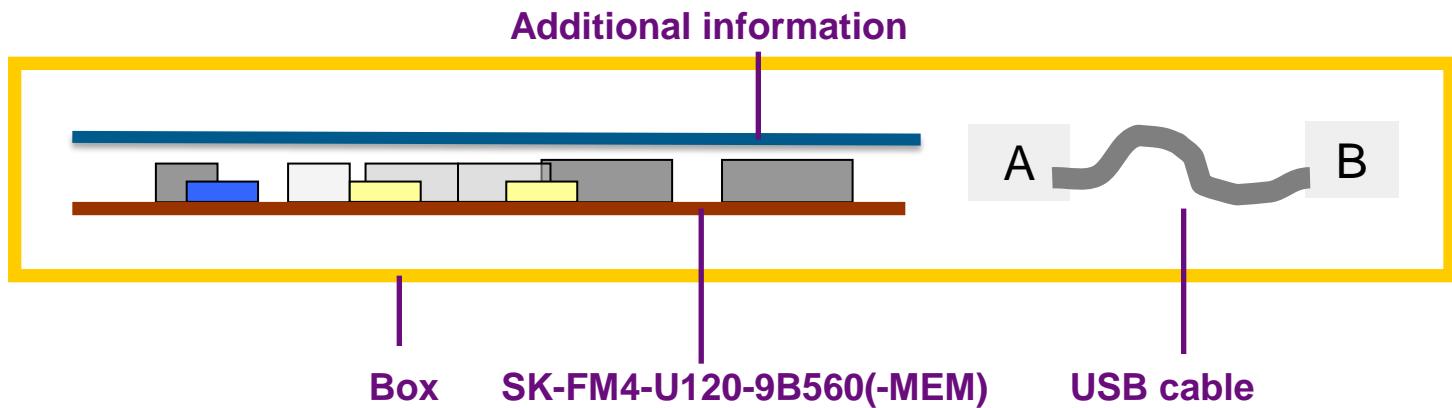
- The SK-FM4-U120-9B560(-MEM) is available in two versions:

Feature	SK-FM4-U120-9B560	SK-FM4-U120-9B560-MEM
External Power Supply	USB, DAP, JTAG or from SK-FM4-U-PERIPHERAL	
On-board Voltage	3.3V or 5V	3.3V
User-LEDs, Reset-LED		3x User-LEDs (R,G,B) + Reset
Buttons		3x buttons: Reset + External Interrupt + NMI
Potentiometer		AN18 (0V .. On-board voltage 3.3V/5V)
Debug interface		On-board CMSIS-DAP incl. Status LEDs (connected, running) (optional 20 pin JTAG-IF to be used with external JTAG adapter)
Virtual COM port (USB-2-UART bridge)		Yes
USB interface		USB Function (Mini-USB Type B)
SD-Card interface	Yes	No
External Memory	No	NAND-Flash: 32MByte SDRAM: 16MByte

Contents SK-FM4-U120-9B560



- The SK-FM4-U120-9B560(-MEM) contents
 - The SK-FM4-U120-9B560 or SK-FM4-U120-9B560-MEM evaluation board
 - One USB mini cable
 - 1-page flyer

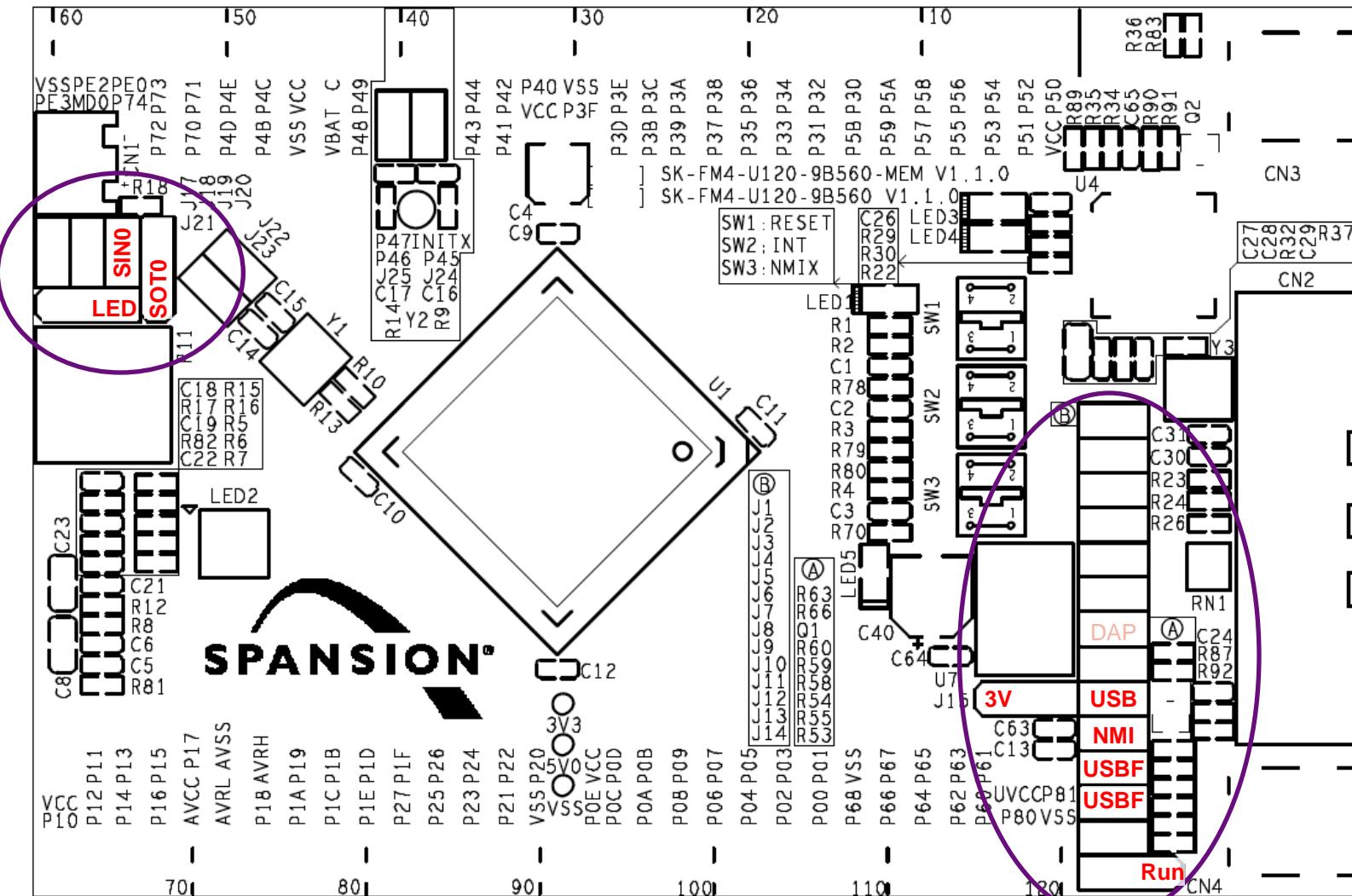


Please check jumper setting

SK-FM4-U120-9B560 supports 5V and 3.3V operation
SK-FM4-U120-9B560-MEM supports only 3.3V operation

Note:

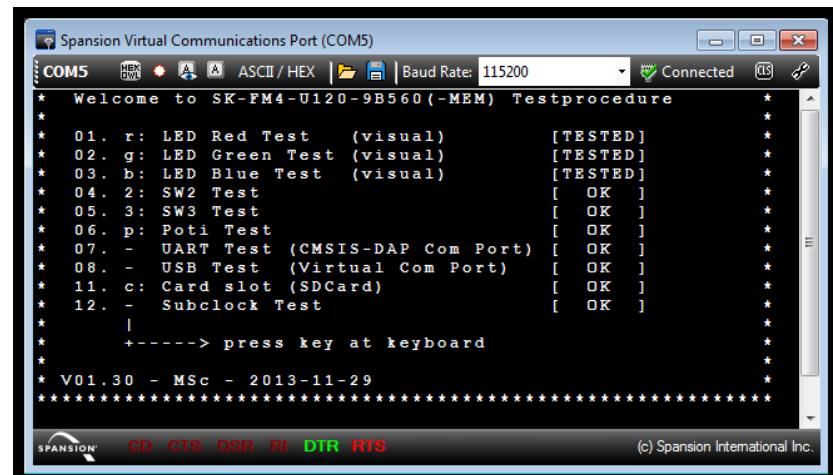
Please set J9 (USB) instead of J7 (CMSIS-DAP)
Please set J19 and J20:1-2 (SIN0/SOT0)



Test it by terminal using USB



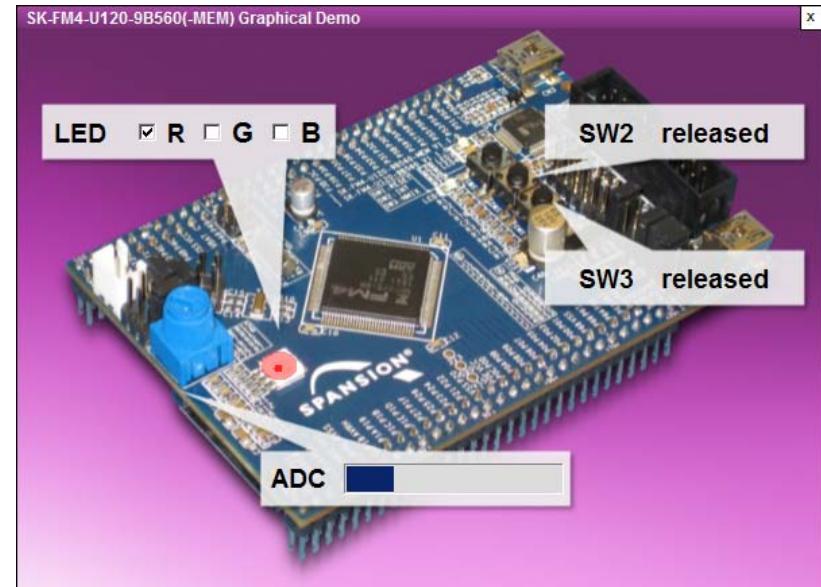
- The microcontroller on the SK-FM4-U120-9B560(-MEM) is already preprogrammed with a test application (<drive:>\sw-examples\testsoftware)
 - Install the USB driver first <drive:>\drivers\driverinstaller.exe
 - Connect the starter kit to CN4 (USB) with your PC
 - ♦ Ensure jumper J9 (USB) is set for correct power supply
 - ♦ Ensure jumper J19 and J20:1-2 are set correctly for use of SIN0/SOT0
 - Press the ,Reset'- Button
 - Check the availability for virtual COM port
 - ♦ e.g. Windows Device Manager
 - Open a serial terminal tool
 - ♦ e.g. Spansion Serial Port Viewer
<drive:>\tools\serialportviewer\setup.exe
 - ♦ Settings 115200 baud, 8N1
 - Press <space> to show welcome menu
 - Please select any function to test the on-board features



Test it by a GUI



- The microcontroller on the SK-FM4-U120-9B560(-MEM) is already preprogrammed with a test application (<drive:>\sw-examples\testsoftware)
 - Install the USB driver first <drive:>\drivers\driverinstaller.exe
 - Connect the starter kit to CN4 (USB) with your PC
 - Open the PC software
[<drive:>\sw-examples\testsoftware\SK-FM4-U120-9B560_demo.exe](#)
 - The picture of the board will be shown with current status of on-board features
 - LED allows control of the RGB-LED
 - ◆ Just click to the checkboxes
 - Status of user-buttons SW2 and SW3 are shown interactively
 - ADC represents the potentiometer R11





- You finished successfully the first test

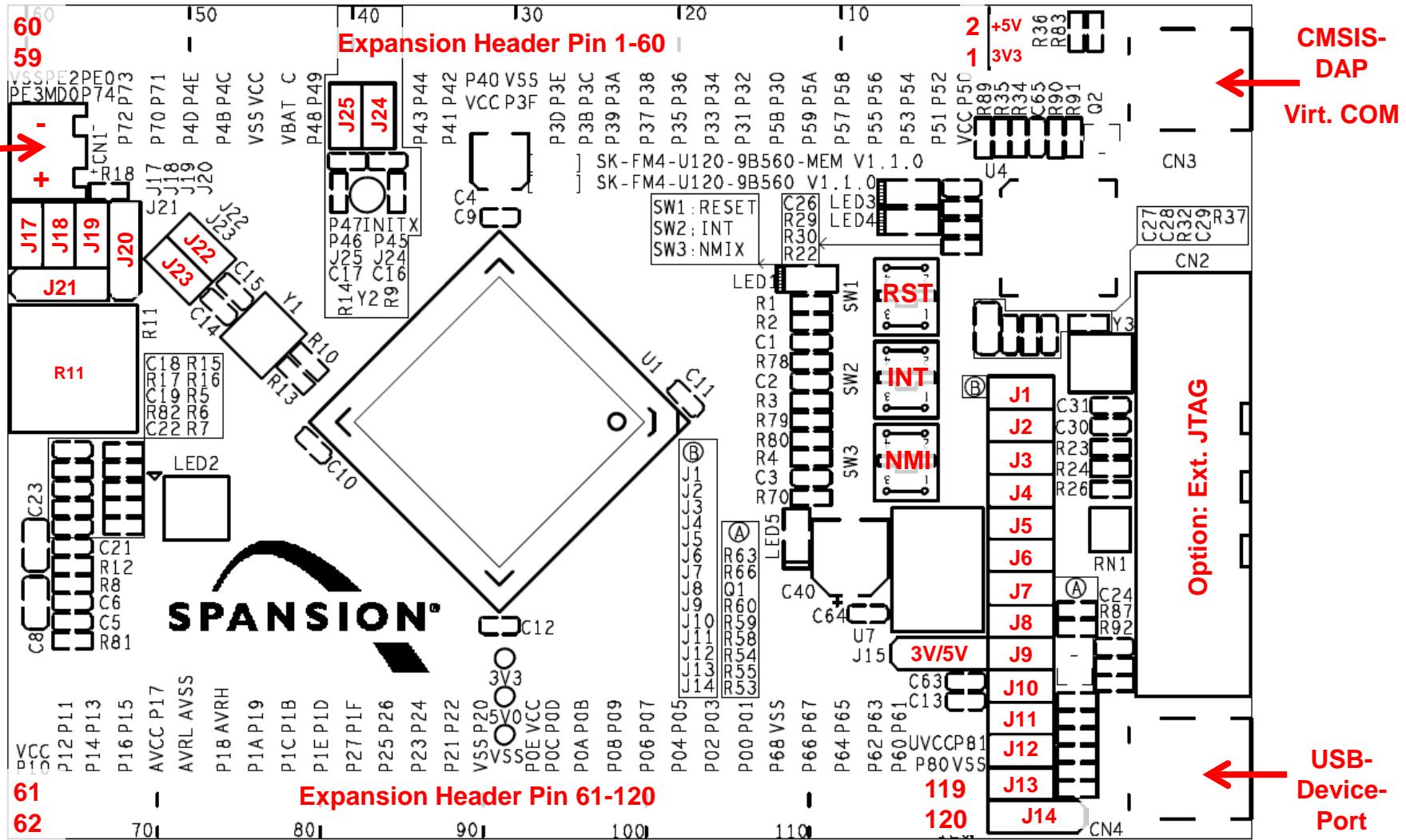
Congratulation!

- Next section covers:
 - The on-board features
 - How to program the Flash
 - ◆ Serial ROM Boot loader
 - USB Direct
 - UART0
 - ◆ On-board CMSIS-DAP
 - ◆ JTAG with optional emulator
 - How to start with IAR-Embedded-Workbench and KEIL µVision

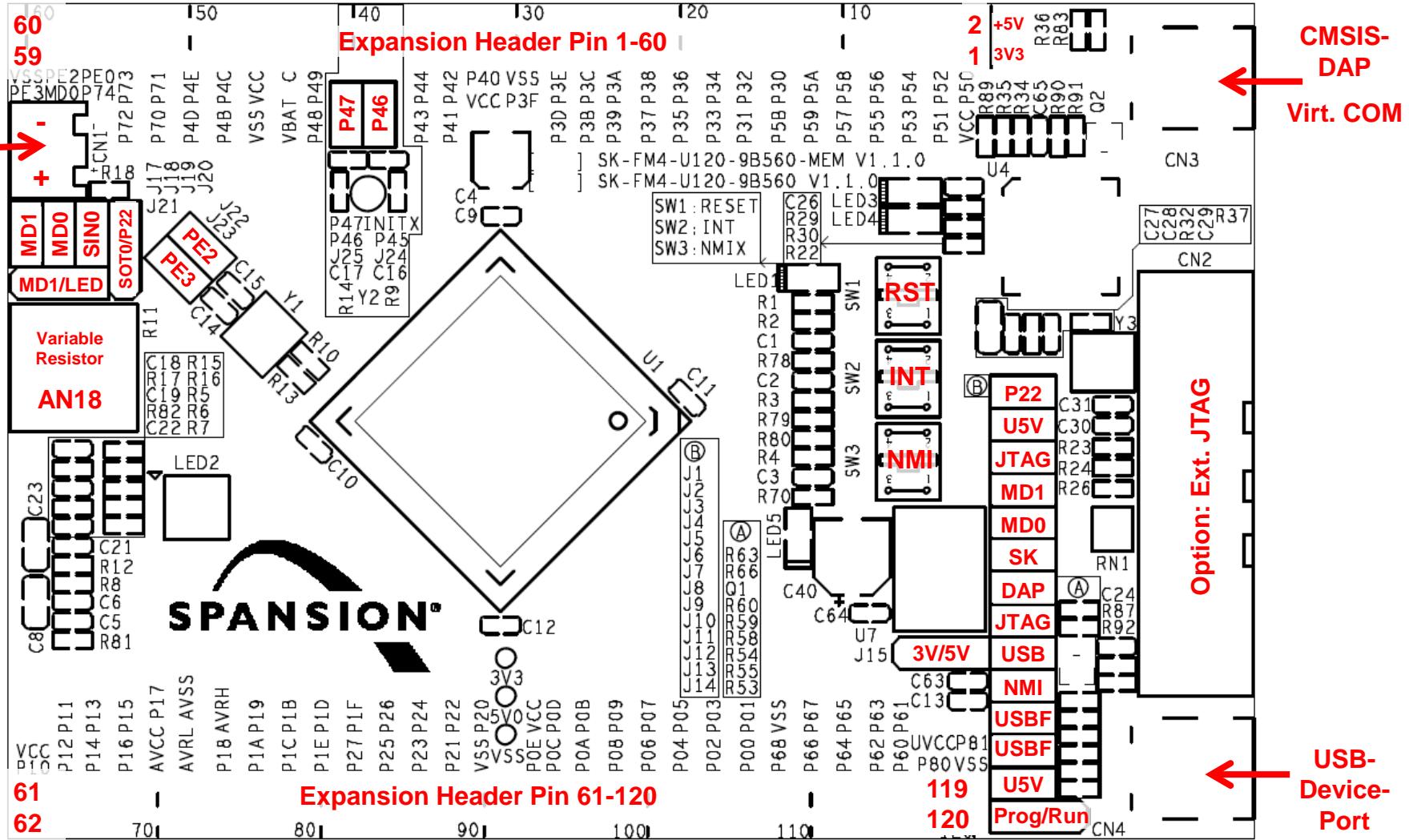


Hardware

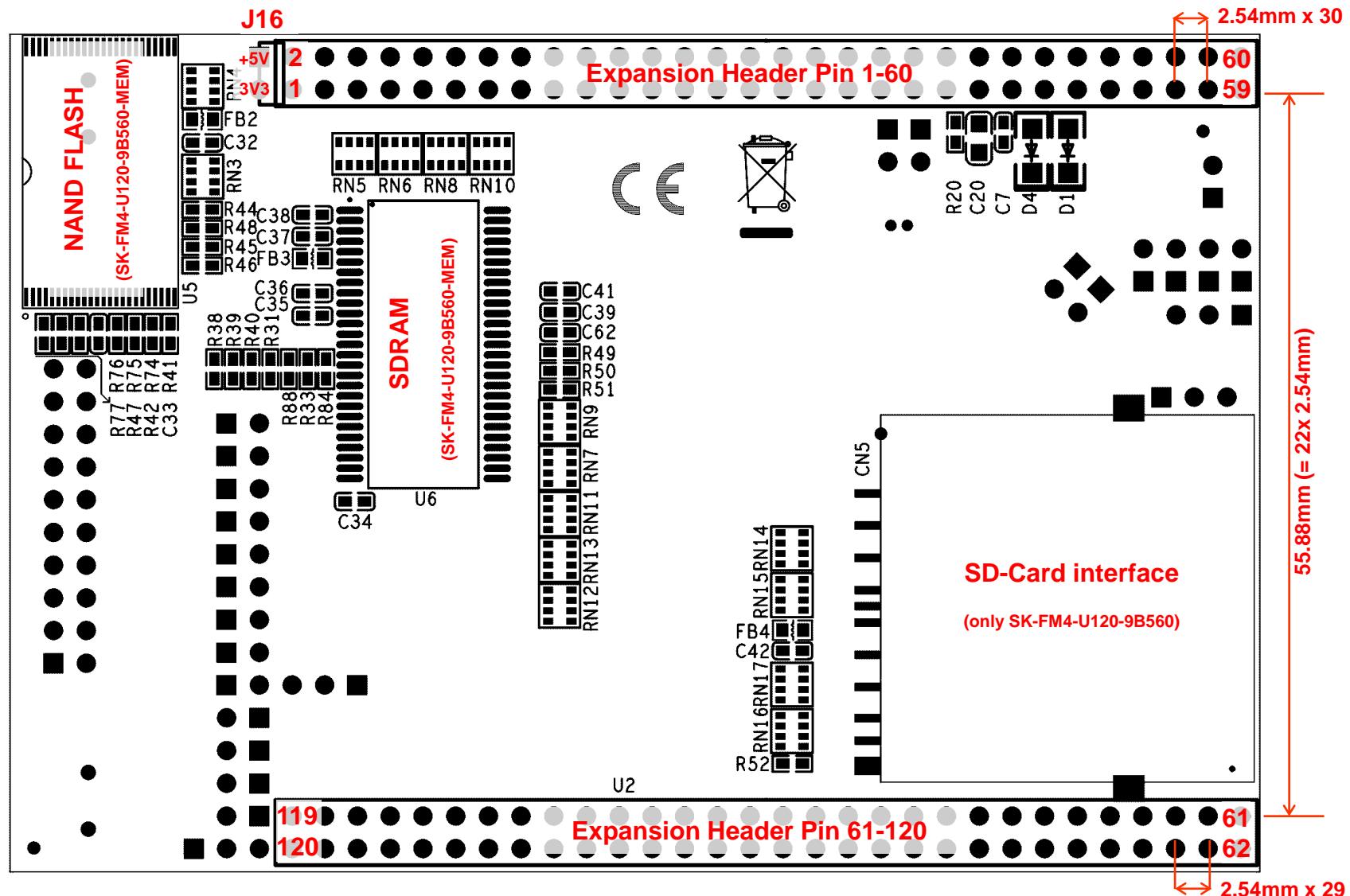
The Hardware (Top Side) – Jumper Overview



The Hardware (Top Side) – Jumper Function Overview



The Hardware (Bottom Side)



Jumper table



Jumper	Function	SK-FM4-U120-9B560(-MEM) (Default setting marked bold)
J1 (2 pin)	CMSIS-DAP Crystal (P22) (Do not change!)	Open: 4MHz Closed: 48MHz
J2 (2 pin)	VBUS detection of CMSIS-DAP	Open: 3V3 Closed: 5V (only for SK-FM4-U120-9B560)
J3 (2 pin)	CMSIS-DAP reset	Open: CMSIS-DAP normal operation Closed: CMSIS-DAP reset assert
J4 (2 pin)	Operation of MD1 (CMSIS-DAP)	Open: Run-Mode Closed: Test-Mode
J5 (2 pin)	Operation of MD0 (CMSIS-DAP)	Open: Run-Mode (CMSIS-DAP) Closed: Firmware update of CMSIS-DAP
J6-J9	Power Supply Source Please select just one power source!	J9: USB Host powered (CN4) J8: JTAG powered (CN2) J7: CMSIS-DAP powered (CN3) J6: Powered by SK-FM4-U-PERIPHERAL (J16)
J10 (2 pin)	SW3 NMI Jumper J10 needs to be open for programming	Open: Button SW3 disconnected / Programming mode Closed: Button SW3 (NMI) is connected
J11 (2 pin)	USB D+	Open: USB is disconnected Closed: USB is connected
J12 (2 pin)	USB D-	Open: USB is disconnected Closed: USB is connected
J13 (2 pin)	VBUS detection	Open: 3V3 Closed: 5V (only for SK-FM4-U120-9B560)

Jumper table (continued)



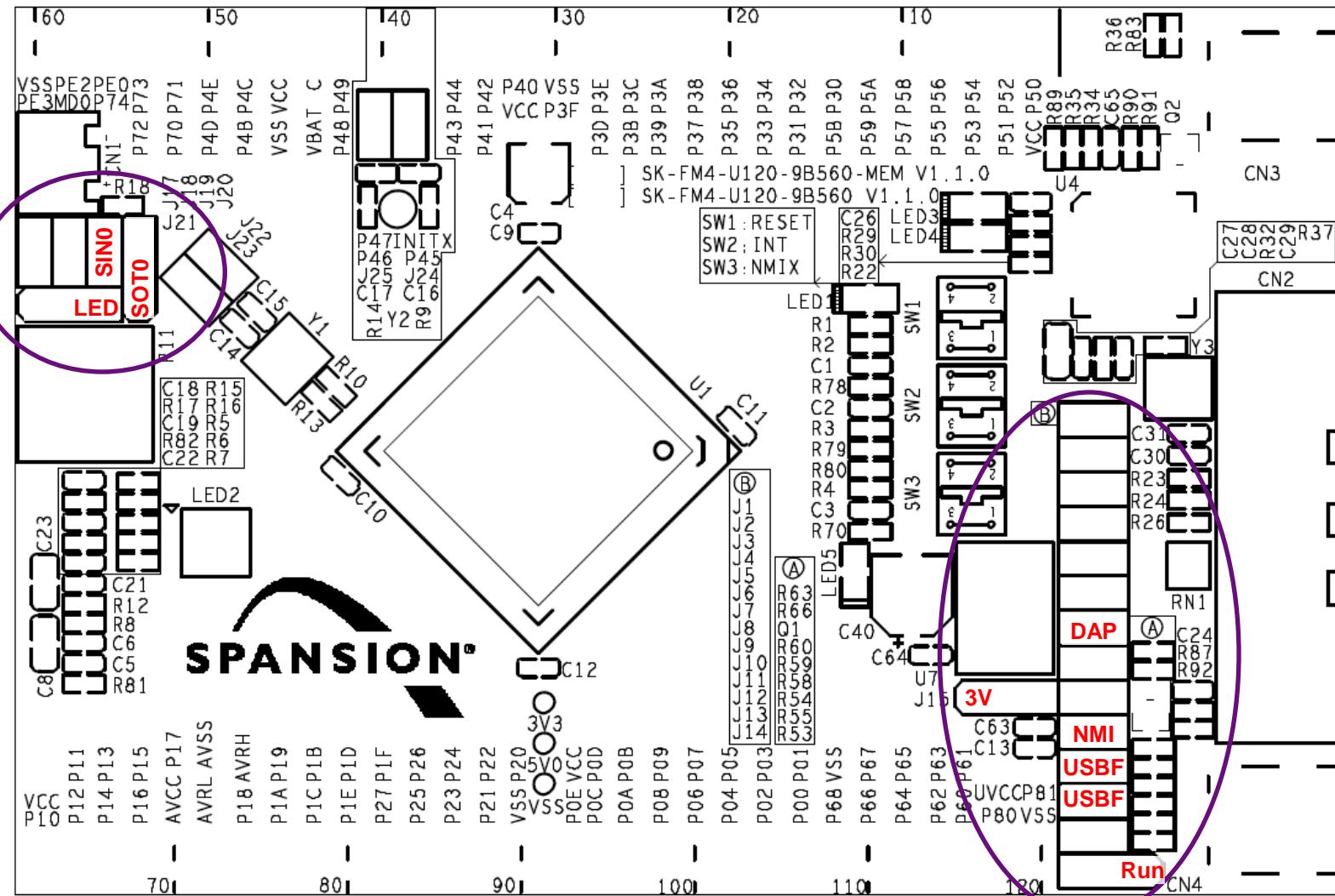
Jumper	Function	SK-FM4-U120-9B560(-MEM) (Default setting marked bold)
J14 (3 pin)	USB VBUS detection See also J10	1-2: VBUS is connected to INT03_2 (Run-Mode) 2-3: VBUS is connected to NMIX (Programming Mode)
J15 (3 pin)	MCU voltage selection SK-FM4-U120-9B560-MEM can be used with 3V3 only	1-2: MCU is powered from 3V3 2-3: MCU is powered from 5V (not SK-FM4-U120-9B560-MEM)
J17 (2 pin)	Operation of MD1 (Do not change!)	Open: Run-Mode and Programming-Mode Closed: Test-Mode
J18 (2 pin)	Operation of MD0	Open: Run-Mode Closed: Programming-Mode
J19 (2 pin)	CMSIS-DAP Virtual COM port (SIN0_0)	Open: SIN0 is disconnected from CMSIS-DAP Closed: CMSIS-DAP's virtual COM port is connected
J20 (3 pin)	CMSIS-DAP Virtual COM port (SOT0_0)	2-3: SOT0/P22 is used for USB programming 1-2: CMSIS-DAP's virtual COM port is connected
J21 (3 pin)	MD1/PE0 See also J17	1-2: MD1 (Programming-Mode) 2-3: PE0 (LED Blue)
J22 (2 pin)	X0/PE2 Do not close J22 if crystal Y1 is assembled.	Open: PE2 is disconnected Closed: PE2 is connected to pin header U2
J23 (2 pin)	X1/PE3 Do not close J23 if crystal Y1 is assembled.	Open: PE3 is disconnected Closed: PE3 is connected to pin header U2
J24 (2 pin)	X0A/P46 Do not close J24 if crystal Y2 is assembled.	Open: P46 is disconnected Closed: PE2 is connected to pin header U2
J25 (2 pin)	X1A/P47 Do not close J25 if crystal Y2 is assembled.	Open: P47 is disconnected Closed: PE2 is connected to pin header U2

Jumper – Default (Run mode, CMSIS-DAP)

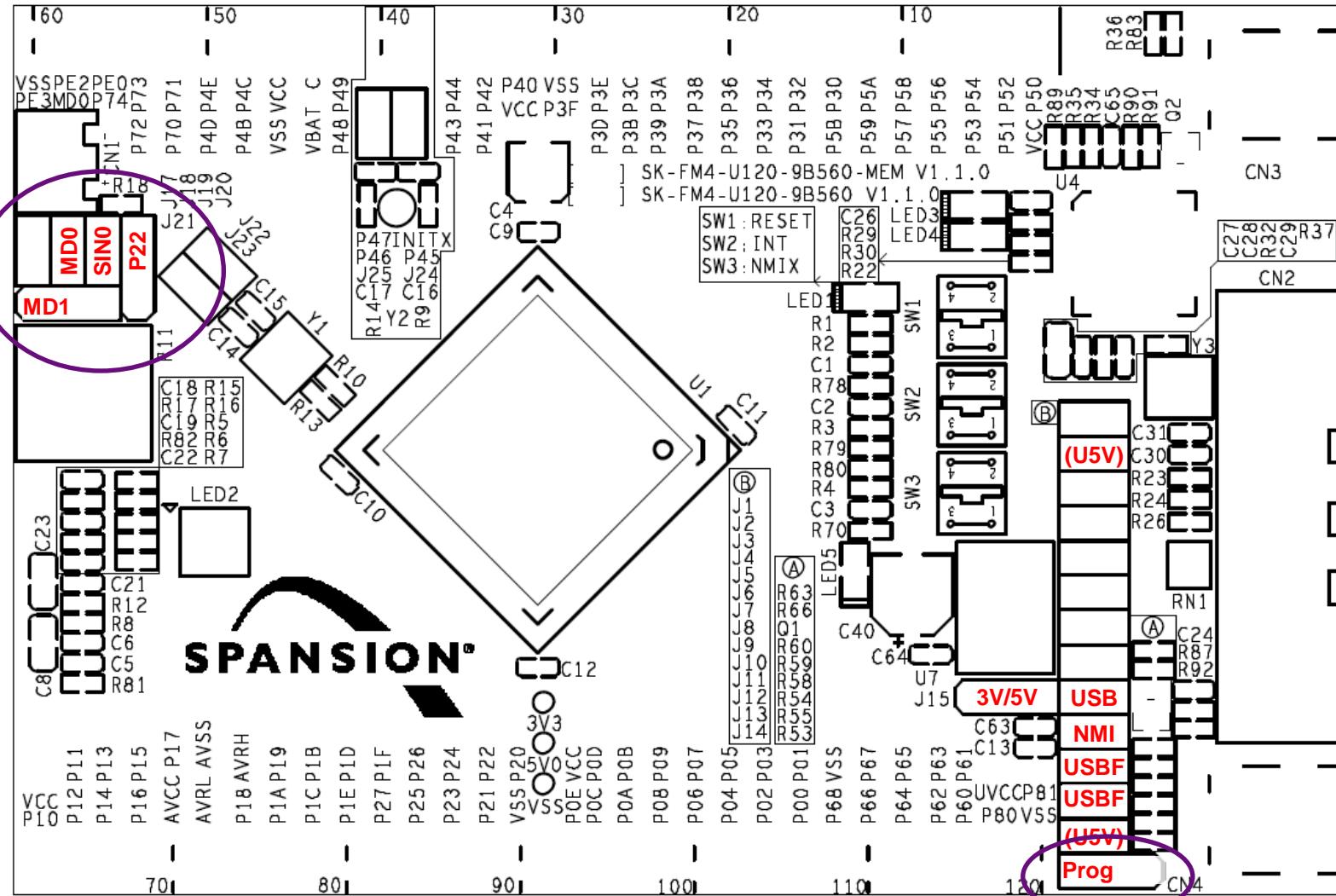


SK-FM4-U120-9B560 supports 5V and 3.3V operation

SK-FM4-U120-9B560-MEM supports only 3.3V operation

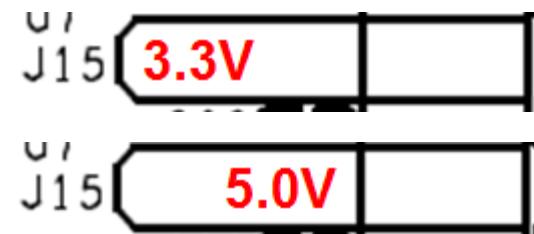
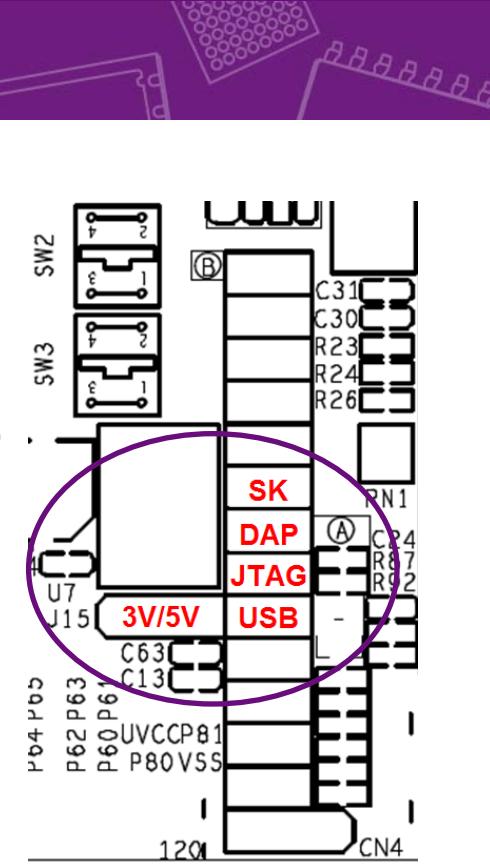


Jumper – Programming Mode (USB Direct mode)



Jumper – Power the Starter kit

- The starter kit can be powered
 - by peripheral base-board (J16): Close jumper J6
 - by CMSIS-DAP (CN3): Close jumper J7 (default)
 - by external JTAG (CN2): Close jumper J8
 - by USB-host (CN4): Close jumper J9
- 3.3V or 5V
 - Jumper J15 selects the target voltage
 - ◆ SK-FM4-U120-9B560 can operate 3.3V or 5V
 - ◆ SK-FM4-U120-9B560-MEM can operate 3.3V only
 - Default: J15: 1-2 (3.3V)





Software



- Simple example that demonstrates the usage of some peripherals
 - Available for IAR EWARM or KEIL µVision:
See <drive:>\sw-examples\ or www.spansion.com
 - [mb9bf56xr_template](#)
 - ◆ ,Empty' project as base for user applications
 - [mb9bf56xr_adc_dvm](#)
 - ◆ Digital Voltage Meter based on the A/D-Converter and UART
 - [mb9bf56xr_gpio](#)
 - ◆ I/O example to control LEDs and readout the user buttons
 - [mb9bf56xr_mfs](#)
 - ◆ An UART example allows serial communication

Software Examples (2/2) – Peripheral Driver Library (PDL)

- Example projects that are built with PDL (Peripheral Driver Library)
 - Available for IAR EWARM or KEIL µVision:
See <drive:>\sw-examples\ or www.spansion.com
 - [mb9bf56xr_pdl](#)
 - ◆ The Peripheral Drivel Library (PDL) includes an API for all peripherals
 - mb9bf56xr_pdl_adc_dvm : Example for ADC
 - mb9bf56xr_pdl_gpio : Example for simple IO access
 - mb9bf56xr_pdl_mfs : Example for serial communication (UART)
 - mb9bf56xr_pdl_template : Project frame for user applications based on PDL
- Functional test
 - [tp_sk-fm4-u120-9b560](#)
 - ◆ Program for testing the board features (LEDs, buttons, ADC, USB, ...)



- The following software utility tools are available
 - USB Virtual-COM port
 - ◆ allows UART communication via the PC's USB connection
 - ◆ On-board UART-2-USB converter (via CN3, CMSIS-DAP)
 - ◆ For driver installation <drive:>[\drivers\driverinstaller.exe](#)
 - FLASH USB DIRECT Programmer
 - ◆ Microcontroller Flash programming (via CN4, USB-Device-Port)
 - ◆ Install from <drive:>[\tools\USBDIRECT\setup.exe](#)
 - Terminal program ,Serial Port Viewer
 - ◆ Install from <drive:>[\tools\serialportviewer\setup.exe](#)



Flash Programming



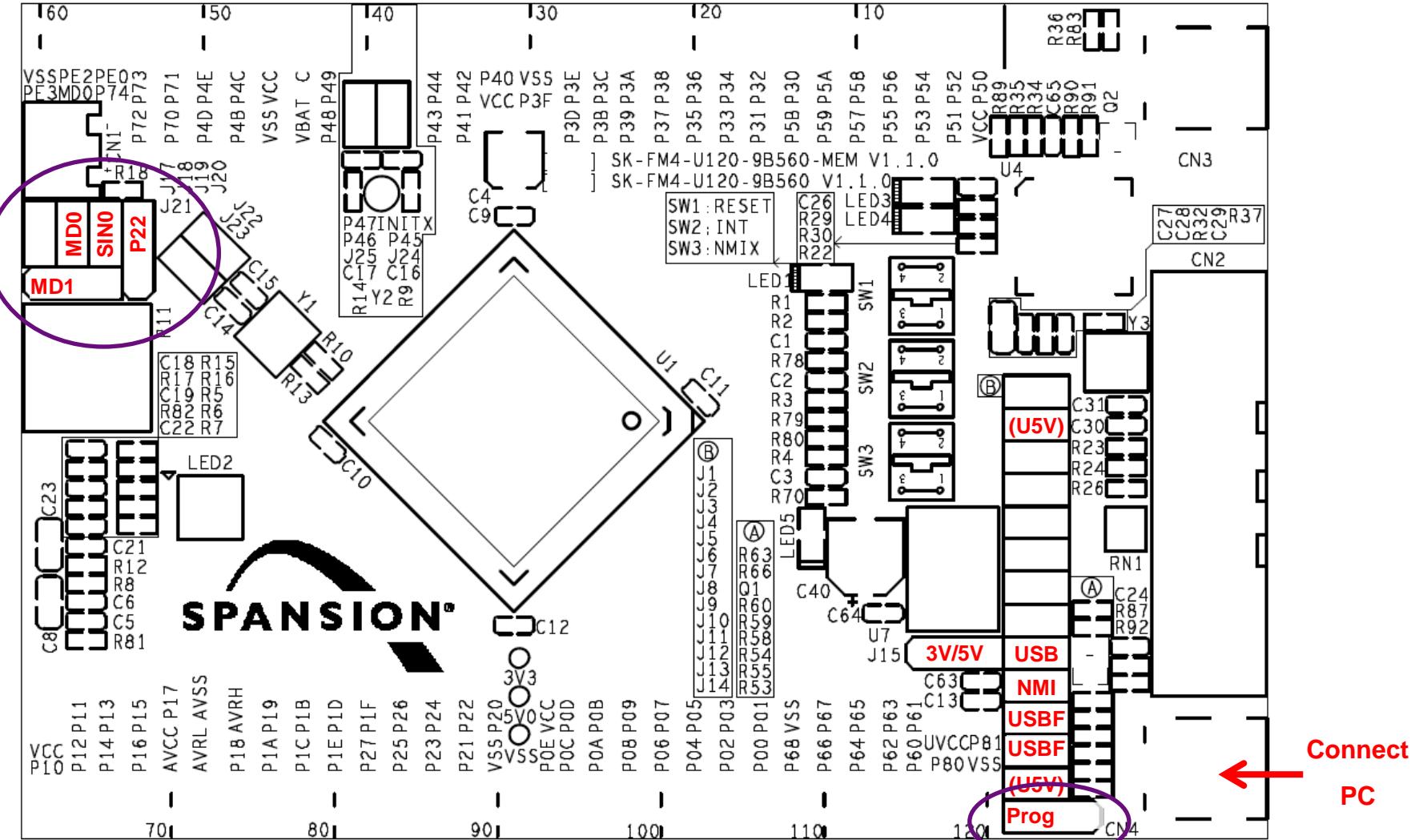
- There are several options to program the microcontroller's flash:
 - [FLASH USB DIRECT Programmer via CN4 \(USB\)](#)
 - ◆ For installation <drive:>\tools\USBDIRECT\setup.exe
 - ◆ USB driver is located in subdirectory of FLASH USB DIRECT Programmer
 - [FLASH MCU Programmer via CN3 \(Serial by use of virtual COM-port\)](#)
 - ◆ For installation <drive:>\tools\PCWFM\setup.exe
 - ◆ For driver installation of USB/Virtual-COM port
<drive:>\drivers\driverinstaller.exe
 - JTAG Programming via CN3 (CMSIS-DAP)
 - ◆ Example is given for [IAR](#) and [KEIL](#)
 - ◆ See documentation of your development suite, how to setup CMSIS-DAP
 - JTAG Programming via CN2 (optional JTAG adapter)
 - ◆ The correct JTAG-adapter must be selected in the IDE toolchain
 - ◆ No dedicated jumper setting is required



- FLASH USB DIRECT Programming via CN4 (USB)
 - Jumper Setting
 - ◆ Close J9 (Power:USB), J11 (USB D+), J12 (USB D-) and J18 (MD0)
 - ◆ Set J14 to position 2-3 (P60, USB_VCC_DETECT)
 - ◆ Set J20 to position 2-3 (P22)
 - ◆ Set J21 to position 1-2 (MD1)
 - ◆ For 5V operation set J15 to 2-3, close J2 and J13
 - ◆ For 3.3V operation set J15 to 1-2, open J2 and J13
 - Connect the board via USB-Device (CN4) to the USB-Port of the PC
 - ◆ If connected for first time Windows OS may ask for a driver
 - See subfolder „driver“ of USBdirect installation path or <drive:>\tools\USBDIRECT\driver
 - Start the FLASH USB DIRECT Programmer
 - ◆ For first installation: <drive:>\tools\USBDIRECT\setup.exe

Flash Programming via CN4 (USB direct)

Jumper setting PRG-mode using USB direct

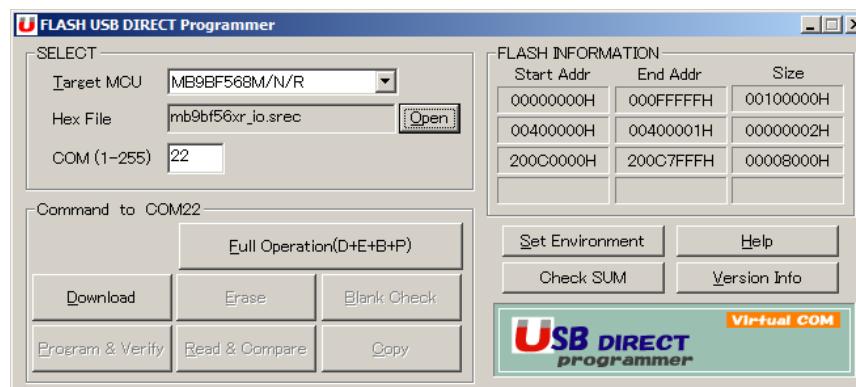


Flash Programming via CN4 (USB direct)



- Choose the right target MCU MB9BF568M/N/R
- Browse for the programming file (*.srec or *.hex)
 - IAR: see subfolder <project>\example\IAR\output\release\exe
 - ARM/KEIL: see subfolder <project>\example\ARM\output\release
- Adjust the corresponding virtual COM-port

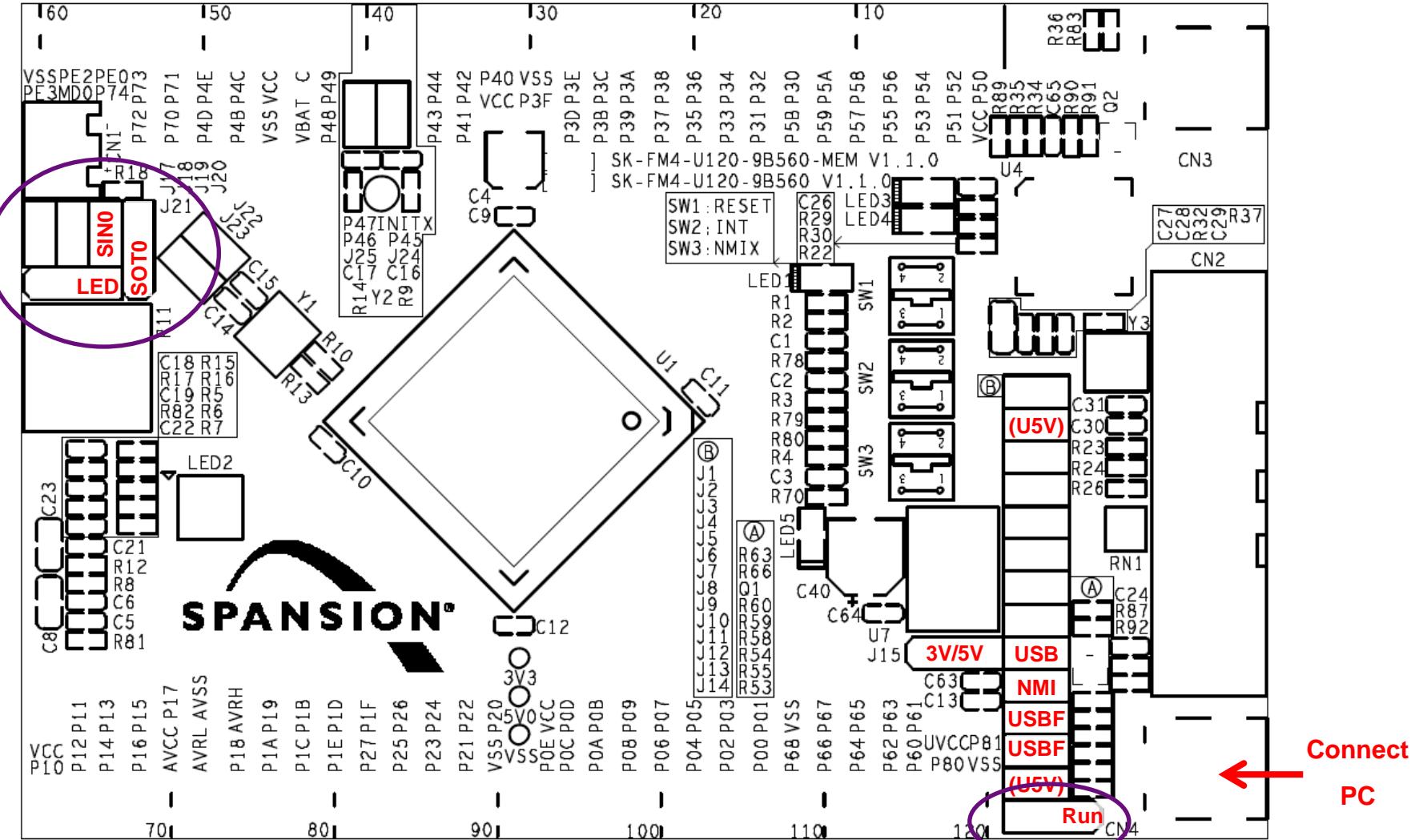
Select MCU: MB9BF568M/N/R
Select file (*.srec; *.hex)
Select Virtual COM-port



- Use Full Operation
 - Download
 - Erase / Blank check
 - Program & Verify
- Reset jumpers and return to Run-mode jumper setting

Flash Programming via CN4 (USB direct)

Jumper setting RUN-mode using USB direct



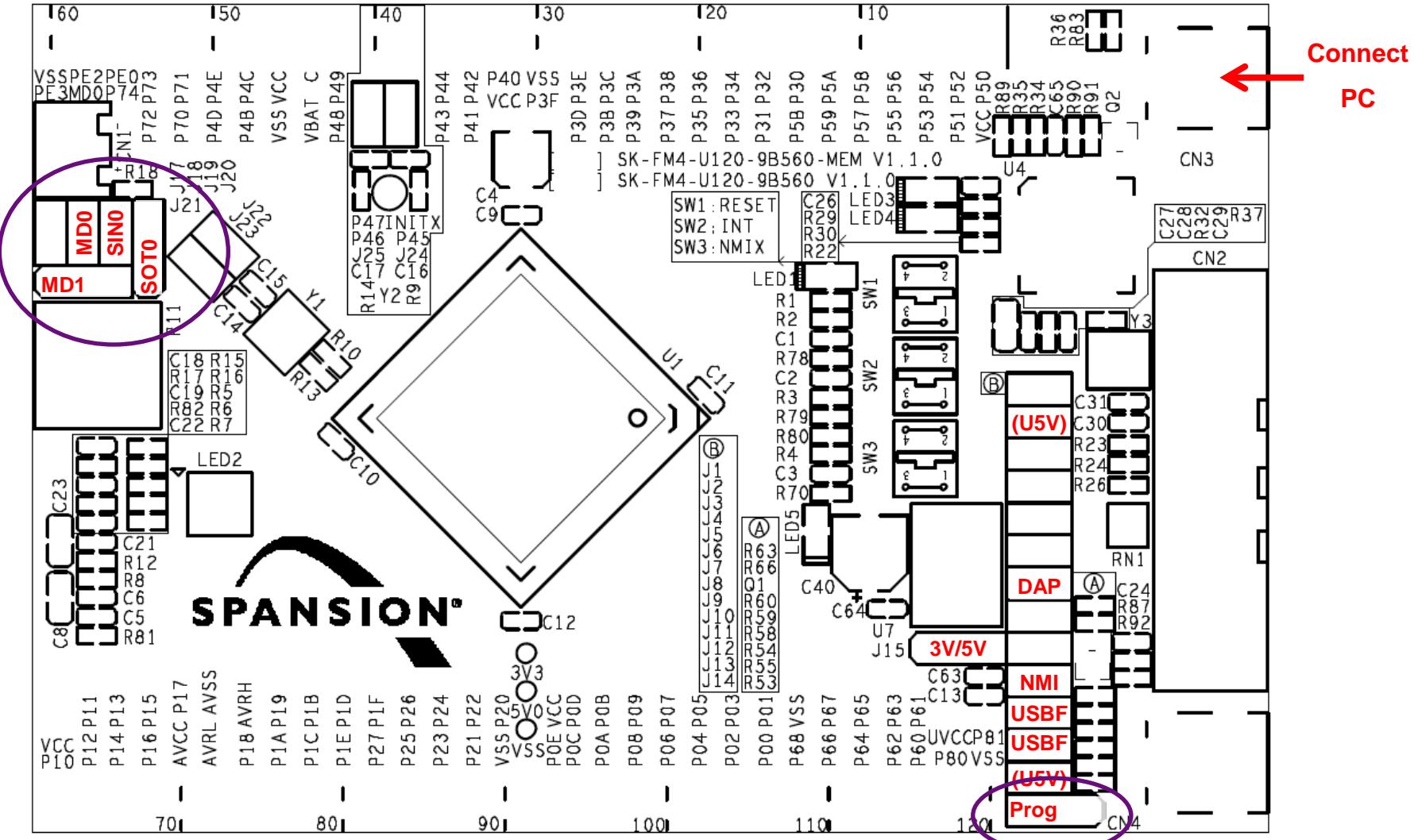


- FLASH MCU Programming via CN3 (Serial)*
 - Jumper setting
 - ◆ Open jumpers J3 (JTAG) and J10 (NMIX)
 - ◆ Close jumpers J7 (Power: DAP), J18 (MD0) and J19 (SIN0)
 - Do not set J9 (USB Host powered)!
 - ◆ Set J20 to position 1-2 (SOT0)
 - ◆ Set J21 to position 1-2 (MD1)
 - ◆ Check jumper setting: J14:2-3 (P60)
 - Connect the board via USB CMSIS-DAP (CN3) to the USB-Port of the PC
 - ◆ When connected for first time Windows OS may ask for „spansionusbvcomm.inf“
 - <drive:>\drivers\cmsis-dap
 - Use the FLASH MCU Programmer for FM3/FM4
 - ◆ For installation <drive:>\tools\PCWFM\setup.exe

***Note: Do not connect CN4 to PC/USB while using serial programming**

Flash Programming via CN3 (Serial)

Jumper setting PRG-mode using CMSIS-DAP (serial communication)



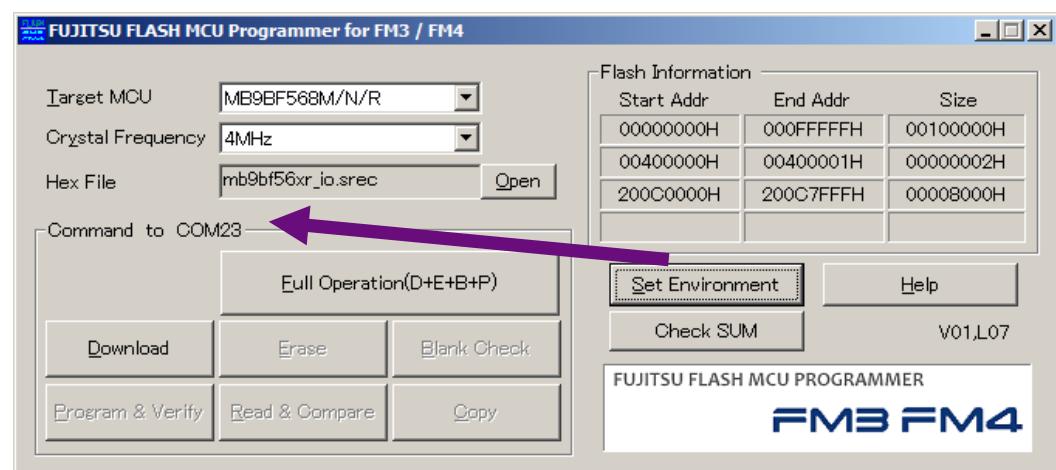
Flash Programming via CN3 (Serial)



- Choose the right target MCU MB9BF568M/N/R
- Select 4MHz Crystal Frequency
- Browse for the programming file (*.srec or *.hex)
 - IAR: see subfolder <project>\example\IAR\output\release\exe
 - ARM/KEIL: see subfolder <project>\example\ARM\output\release
- Adjust the corresponding virtual COM-port

Select MCU: MB9BF568M/N/R
Select 4MHz Crystal Frequency
Select file (*.srec / *.hex)
Select Virtual COM-port
Execute 'Full Operation'
incl. stand-alone operations

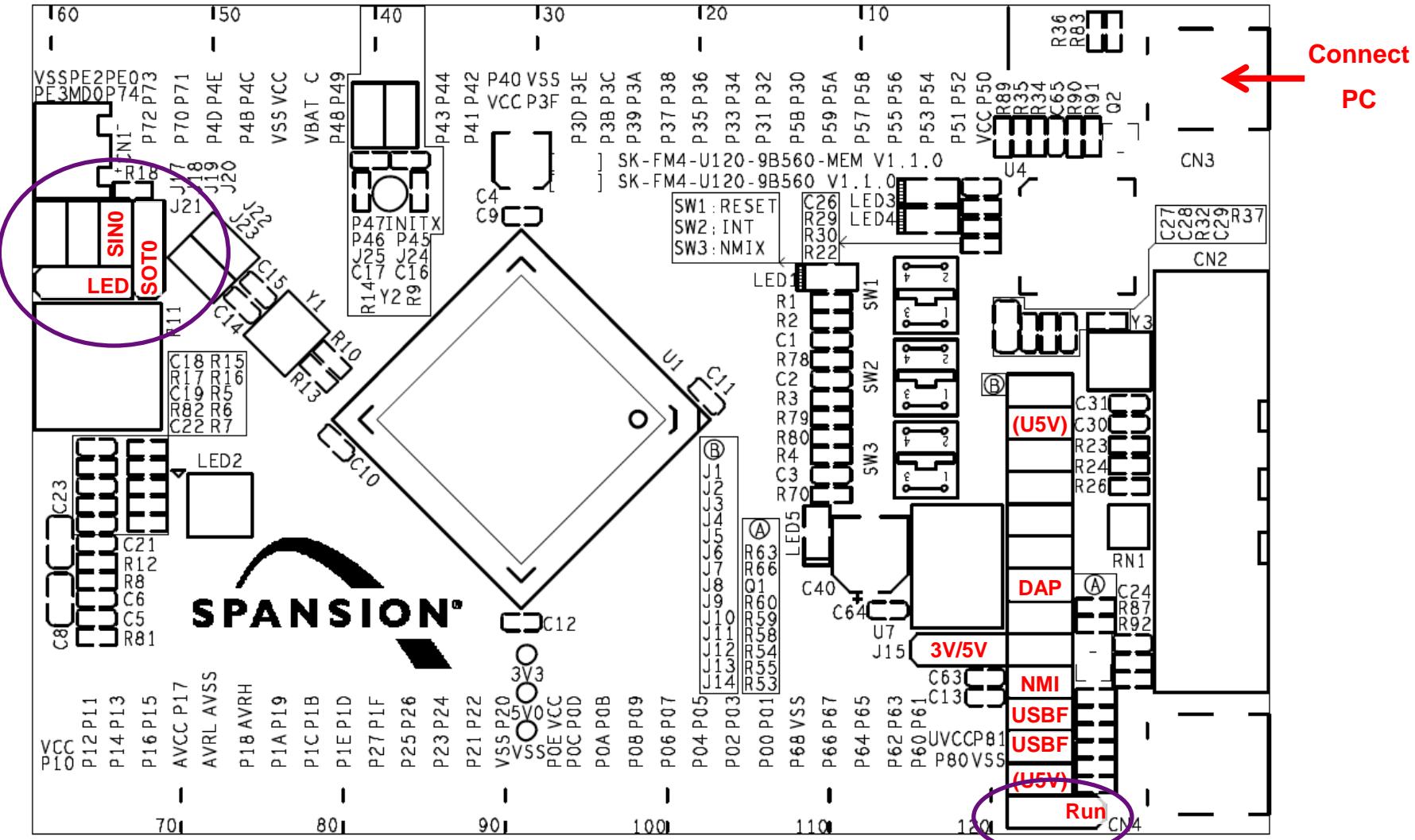
- Download
- Erase
- Blank Check
- Program&Verify



- Reset jumpers and return to Run-mode jumper setting

Flash Programming via CN3 (Serial)

Jumper setting RUN-mode using CMSIS-DAP (serial communication)

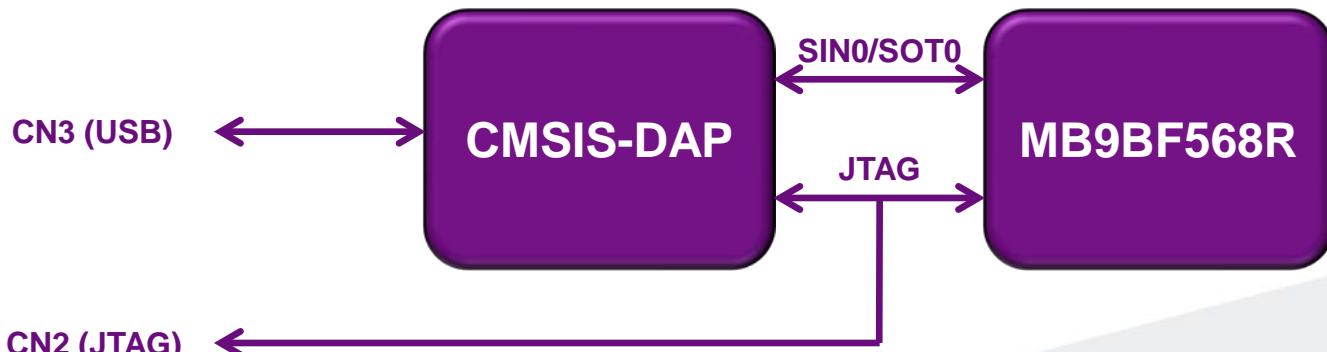




JTAG Debugger



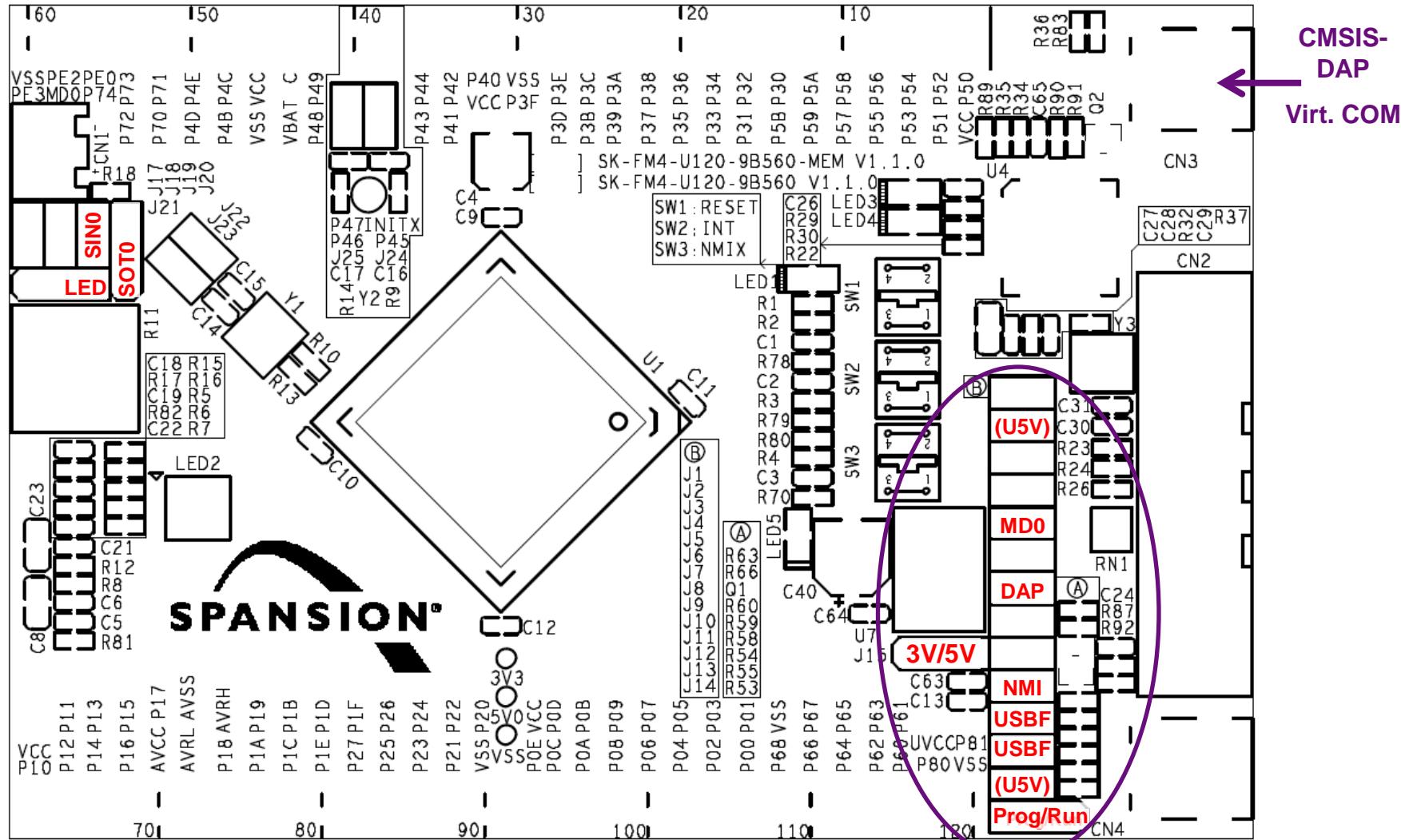
- This starter kit includes an on-board JTAG adapter
 - Compatible to CMSIS-DAP
http://www.keil.com/support/man/docs/dapdebug/dapdebug_introduction.htm
 - Please update the on-board CMSIS-DAP with [latest firmware](#)
 - Select debugger CMSIS-DAP in your tool chain
- Any other JTAG-adapter can be connected to CN2, too.
 - Select used JTAG-adapter within IDE tool chain (No jumper setting is required)
- Additional virtual COM port is provided by CN3
 - ◆ For driver installation <drive:>\[drivers\driverinstaller.exe](#)
 - ◆ Please set jumper J19 and J20 accordingly



CMSIS-DAP Firmware update

Please see instructions coming with Firmware update package!

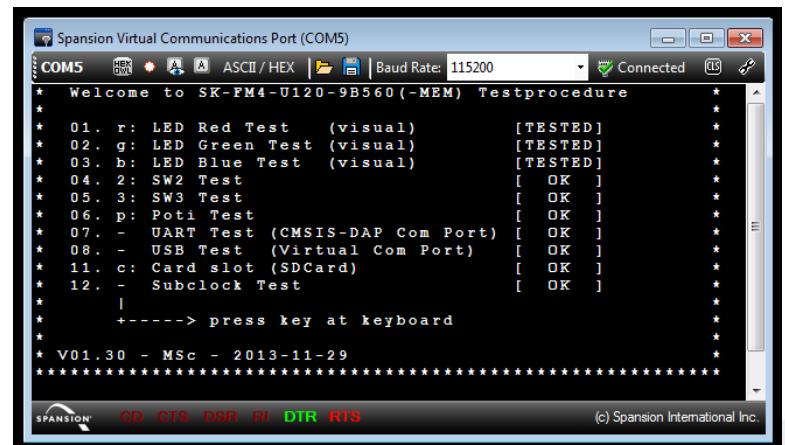
- ◆ See <drive:>[tools\cmsisdap_fw_update](#)



Test it by terminal using CMSIS-DAP

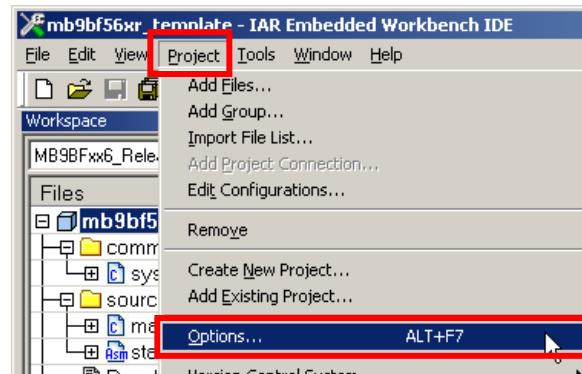


- The microcontroller on the SK-FM4-U120-9B560(-MEM) is already preprogrammed with a test application (<drive:>\sw-examples\testsoftware)
 - Install the USB Driver first <drive:>\[drivers\driverinstaller.exe](#)
 - Connect the starter kit to CN3 (CMSIS-DAP) with your PC
 - ◆ Ensure jumper J7 (CMSIS-DAP) is set for correct power supply
 - Press the ,Reset‘- Button
 - Check the availability for virtual COM port
 - ◆ e.g. Windows Device Manager
 - Open a serial terminal tool
 - ◆ e.g. Spansion Serial Port Viewer
<drive:>\[tools\serialportviewer\setup.exe](#)
 - ◆ Settings 115200 baud, 8N1
 - Press <space> to show welcome menu
 - Please select any function to test the on-board features



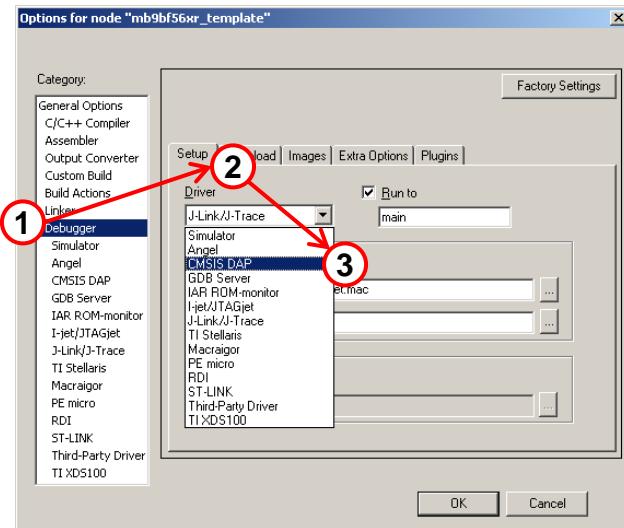
Setup in IAR EWARM (1)

- Navigate to project options:
 - Via Files-List
 - ◆ Right-click at the project
 - ◆ Select [Options...]
 - Or via menu tab [Project]
 - ◆ Select [Options...]

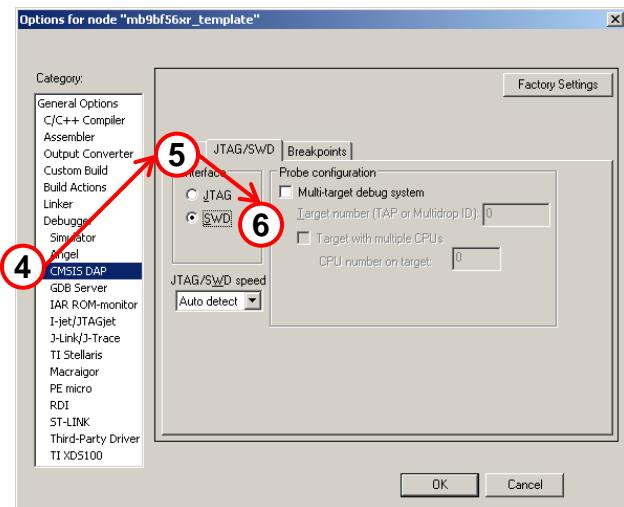


Setup in IAR EWARM (2)

- Setup Project Debugger Options
 - (1) Navigate to [Debugger]
 - (2) Select tab [Setup]
 - (3) Select driver [CMSIS-DAP]



- (4) Select in [CMSIS-DAP]
- (5) Select tab [JTAG/SWD]
- (6) Select [SWD]



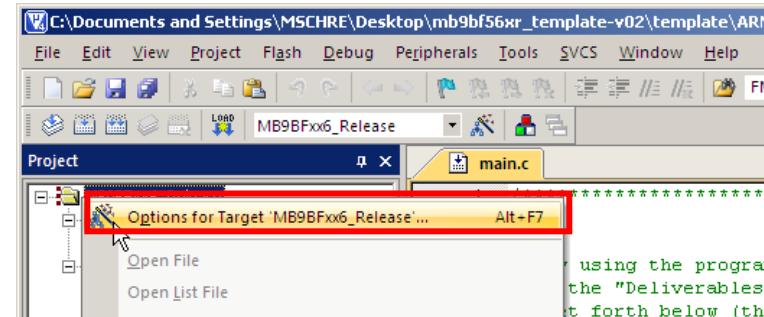


Setup in Keil µVision (1)

- Navigate to project options:

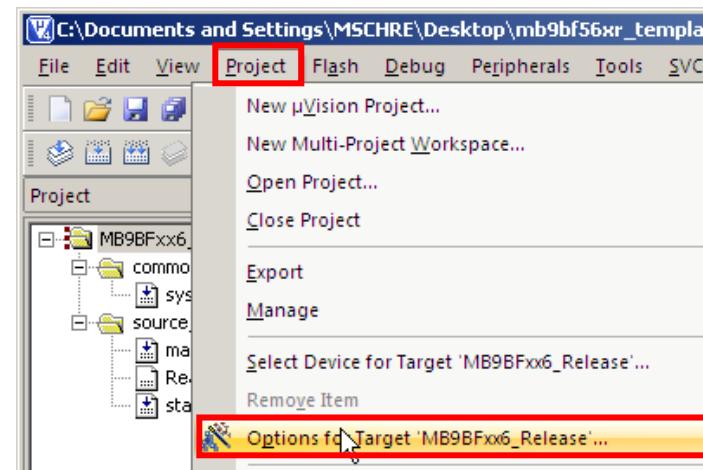
- Via Project

- ◆ Right-click at the project
 - ◆ Select [Options...]



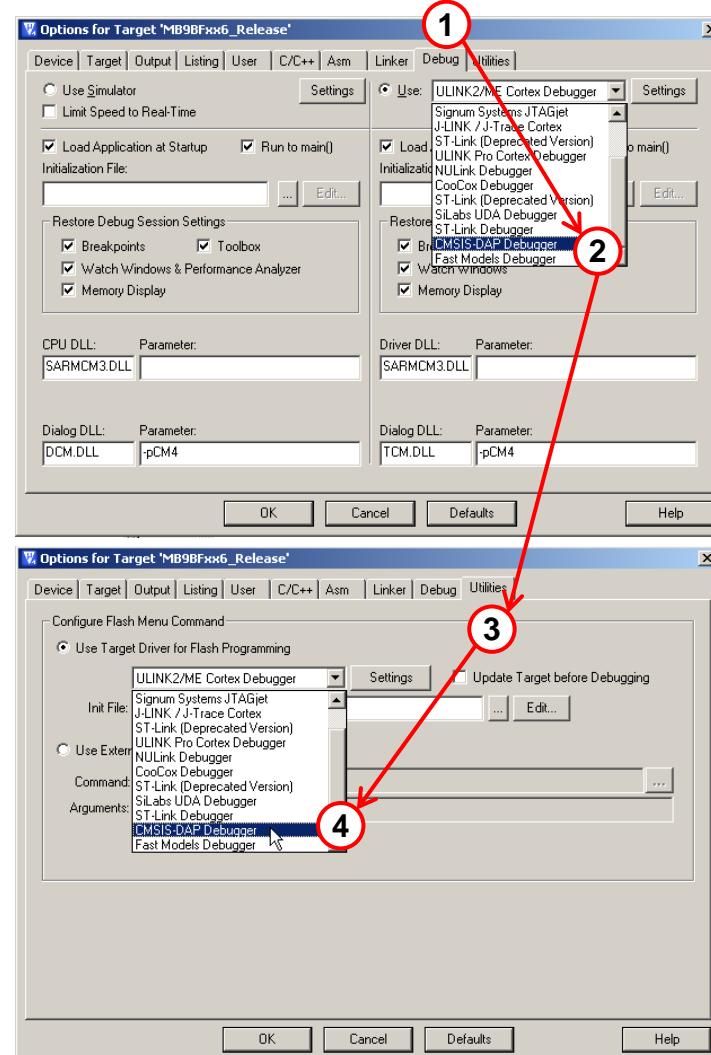
- Or via menu tab [Project]

- ◆ Select [Options...]



Setup in Keil µVision (2)

- Setup Debug & Utilities
 - (1) Select tab [Debug]
 - (2) Select [CMSIS-DAP Debugger]



- (3) Select tab [Utilities]
- (4) Select [CMSIS-DAP Debugger]

IAR Embedded Workbench

- Installation
- Getting Started
- Open Project
- Build Project
- Debug Project





- Install EWARM from IAR-CD or download latest version from IAR Website
 - EWARM size-limited (32k) or time-limited (full) Evaluation Version
 - ◆ <http://supp.iar.com/Download/SW/?item=EWARM-EVAL>
- Start EWARM Workbench
- Choose File → Open → Workspace
 - e.g.: <drive:>\sw-examples\mb9bf56xr_gpio-v11\example\IAR\mb9bf56xr_io.eww

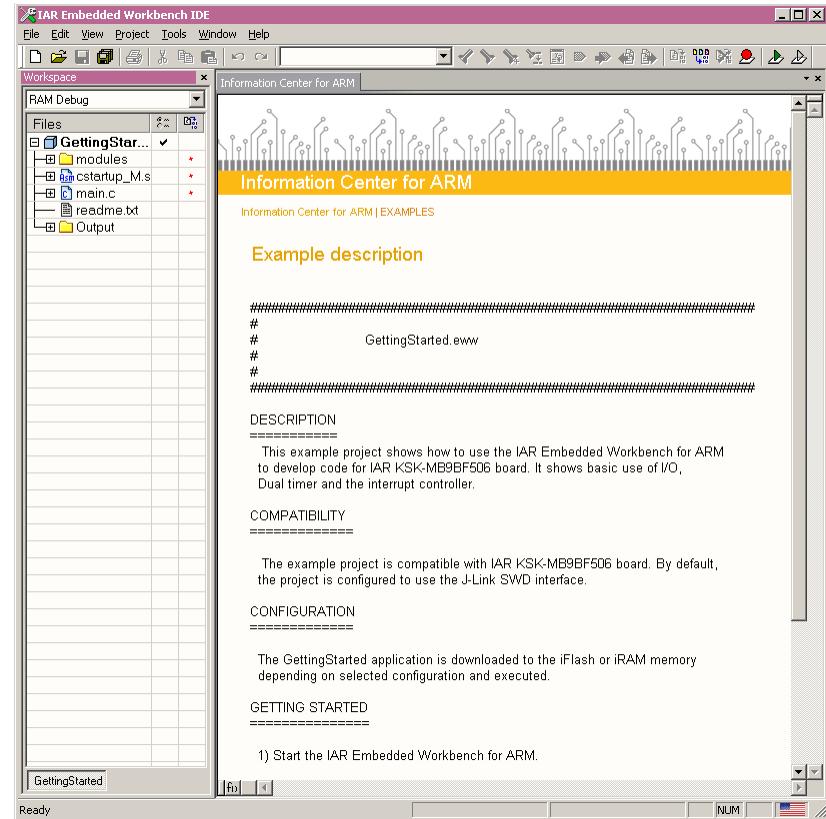


IAR Workbench – Main Window



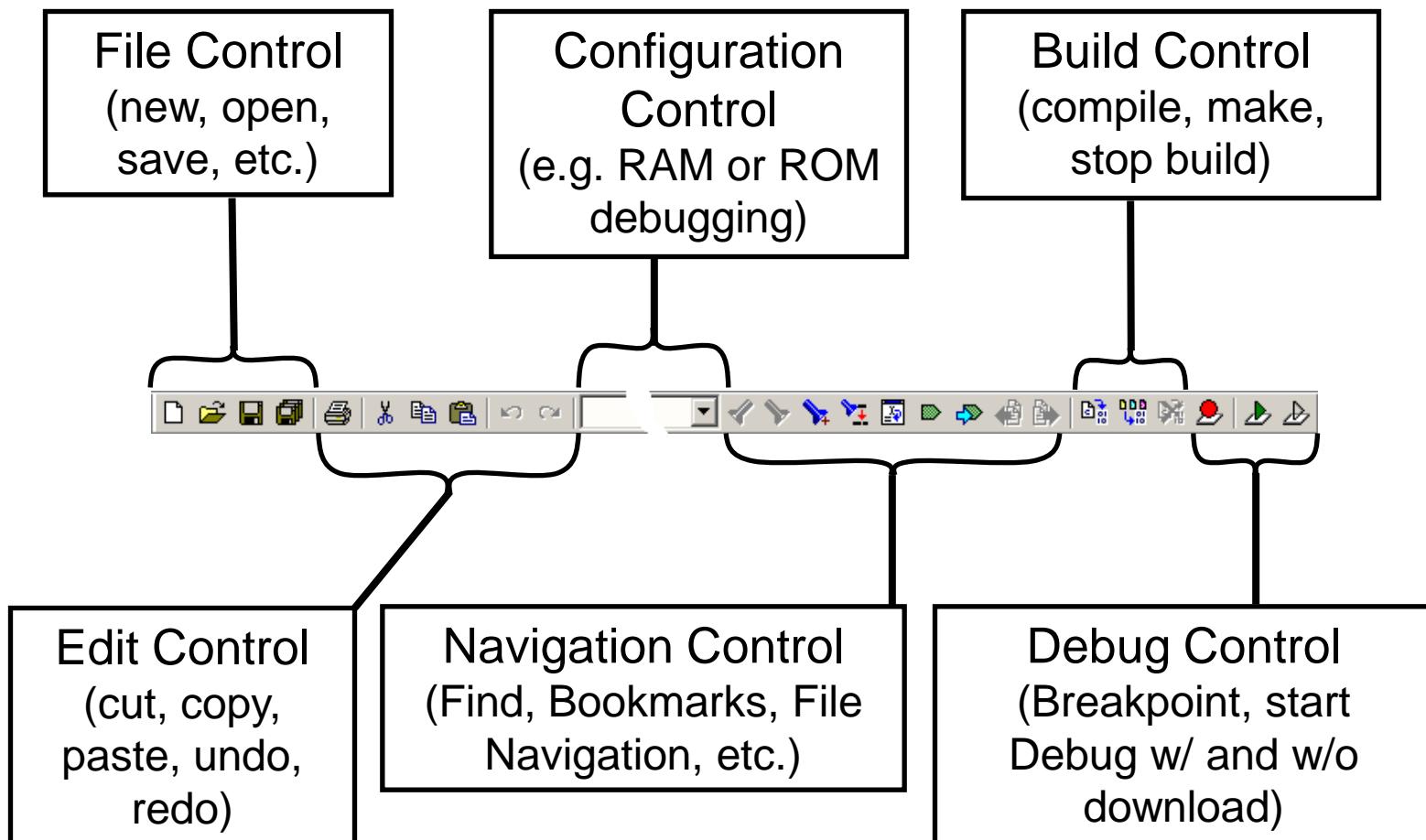
■ IAR Workbench

- Workspace on left side of Workbench window
 - ◆ If hidden then View→Workspace
- Source files on right side of Workbench window as tabbed windows
- Project open
File → Open → Workspace → *.eww
- For new projects
start with ,mb9bf56xr_template'



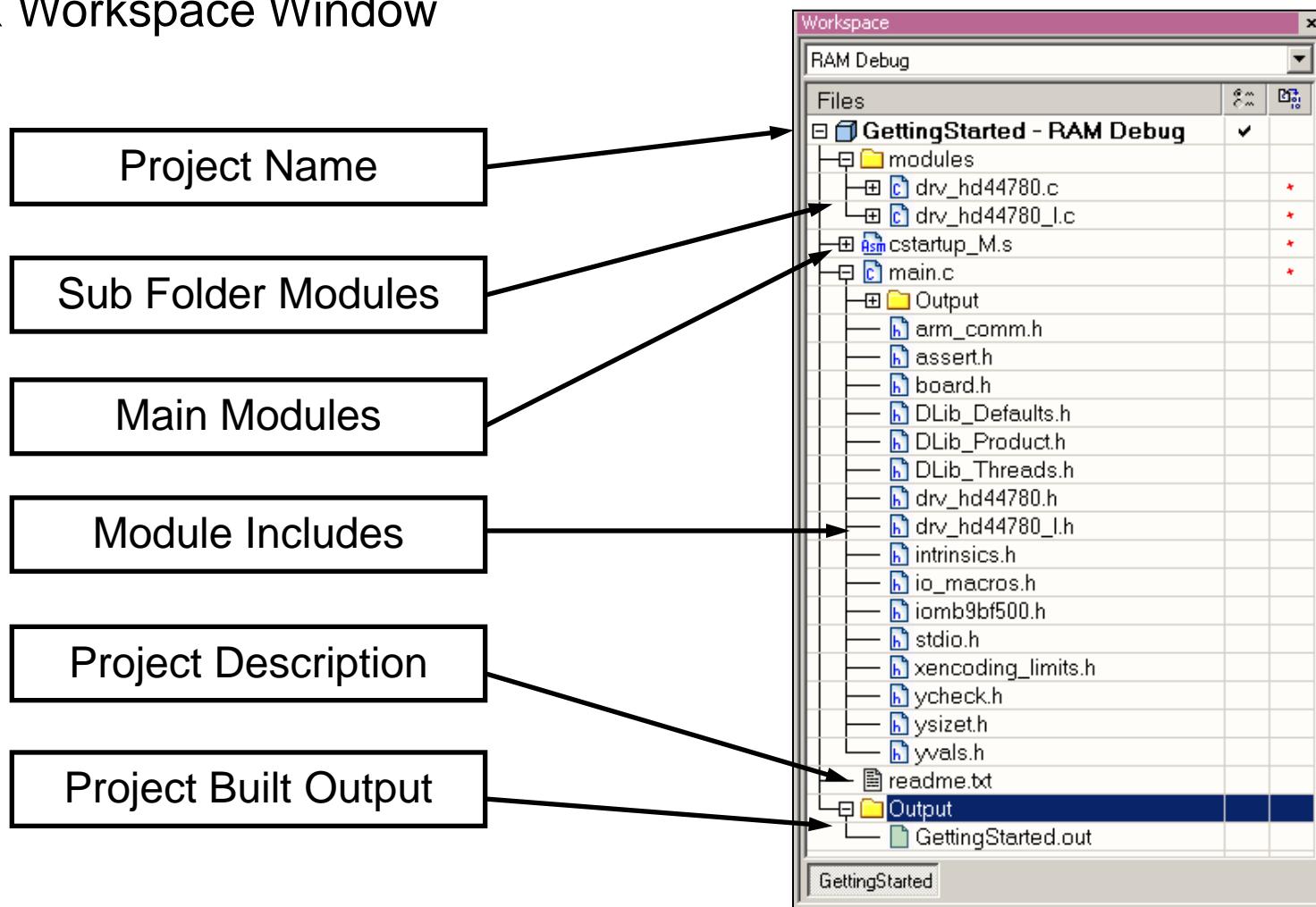


- IAR Menu Bar



IAR Workbench – Workspace

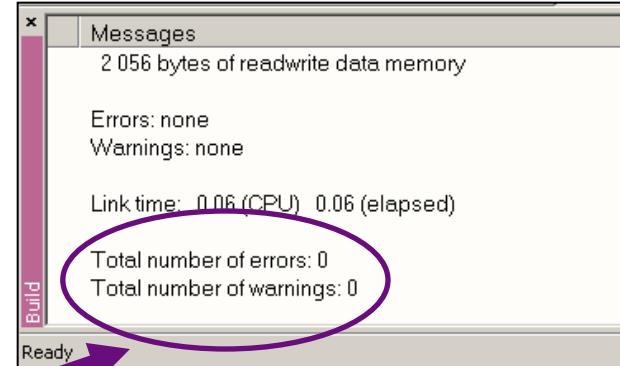
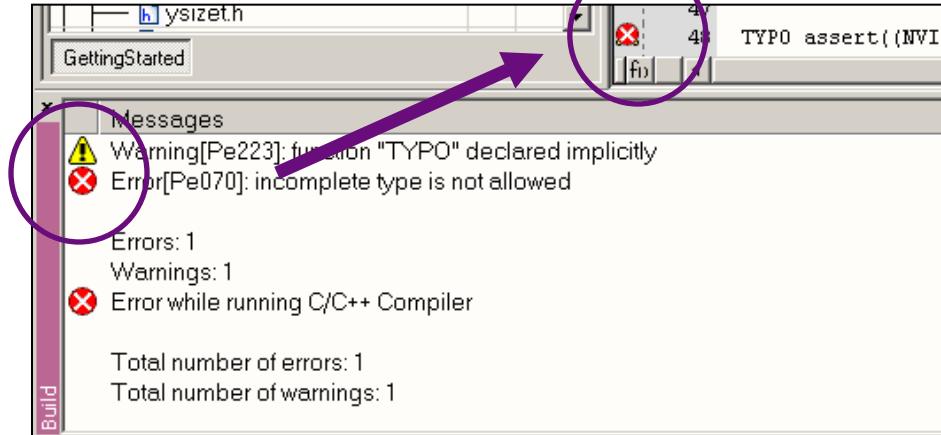
■ IAR Workspace Window





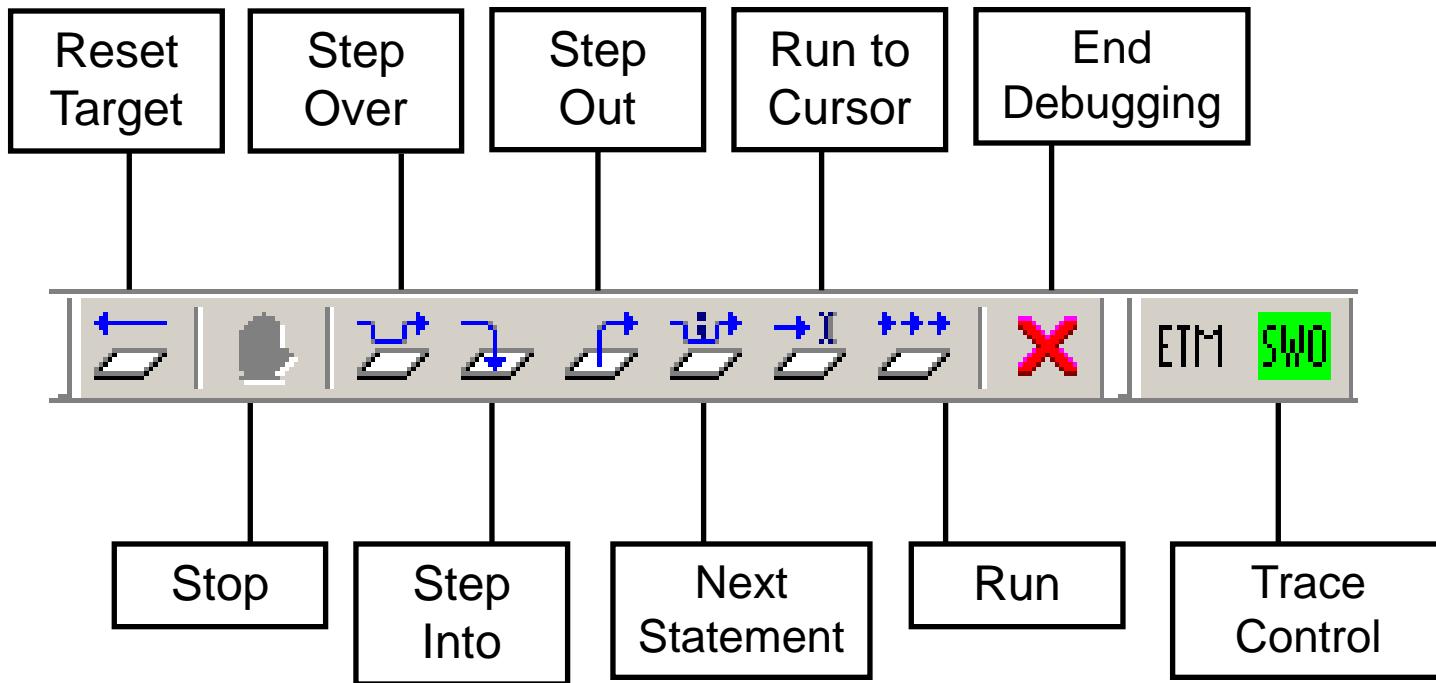
- Making the Project

- Use Make-Icon (), <F7> or
Menu: Project→Make
- Check for no errors in Output window
below
- Build errors are indicated by or
In Output window and Source view





- Download to Target and Start Debugging
 - Use  Icon, <Ctrl>-D, or Project→Download and Debug
 - A new menu bar will occur on sucessful connection to target





▪ Source Window

- The Source windows do not change contents but get additional information
 - ◆ Current line (PC):
 - ◆ Halted on Breakpoint:
 - ◆ Halted on Data break (example):

▪ Disassembly Window

- Shows ‘pure’ disassembly view
- Shows mixed mode view

The screenshot shows the IAR Workbench Disassembly window with the title bar "Disassembly". The window contains assembly code for the "main" function. The assembly code includes instructions like STR, LDR.N, ISLS, BMI.N, and LDR. The memory locations and register values are also displayed. A green highlight covers the instruction at address 0x1ffffc3c2, which is 0x0780 and labeled "ISLS". The assembly code is as follows:

```
Disassembly
Go to | Memory | 
0x1ffffc3bc: 0x6001      STR    r1, [r0]
if(!BUT_PDIR&PSW2)
??main_4:
0x1ffffc3be: 0x4824      LDR.N  r0, ??DataTable10_33 [0x1ffffc450] ; PDIR5
0x1ffffc3c0: 0x6800      LDR    r0, [r0]
0x1ffffc3c2: 0x0780      ISLS   r0, r0, #30
Timer1Control_bit.TimerEn = 1;
0x1ffffc3c4: 0xd4dc      BMI.N r0, ??main_2           ; 0x1ffffc380
0x1ffffc3c6: 0x4821      LDR.N  r0, ??DataTable10_32 [0x1ffffc44c] ; Timer1Control
0x1ffffc3c8: 0x6800      LDR    r0, [r0]
0x1ffffc3ca: 0xf050      ORRPS  r0, r0, #128        ; 0x80
```



- Watch Window

- Watch

- ◆ Expressions/Variables have to be added by user and are updated by Halt/Breakpoint

Expression	Value	Location	Type
Tmr1Tick	0	0x20000804	int
[...]			

Watch Locals Statics Auto Live Watch Quick Watch

- Quick Watch

- ◆ The Quick watch allows the user to calculate and recalculate expressions even with variables

Quick Watch			
Expression	Value	Location	Type
<input type="text" value="Q"/> Tmr1Tick + 0xAA - 123			
Tmr1Tick + 0xAA - 123	0x00000030		int

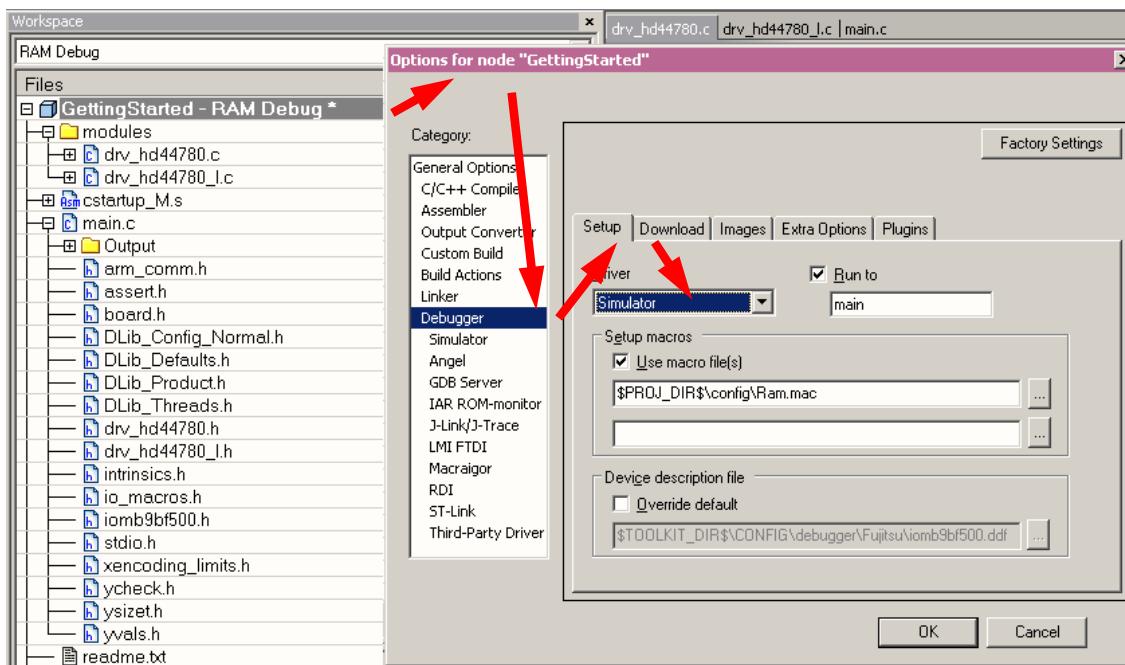
Watch Locals Statics Auto Live Watch Quick Watch

- ◆ The drop down menu memorizes the last typed contents



▪ Simulator

- Mark Project File in Workspace
- Choose Project→Options
- Choose Simulator in Debugger Setup
- Start Simulator with usual  Icon



KEIL µVision

- Installation
- Getting Started
- Open Project
- Build Project
- Debug Project

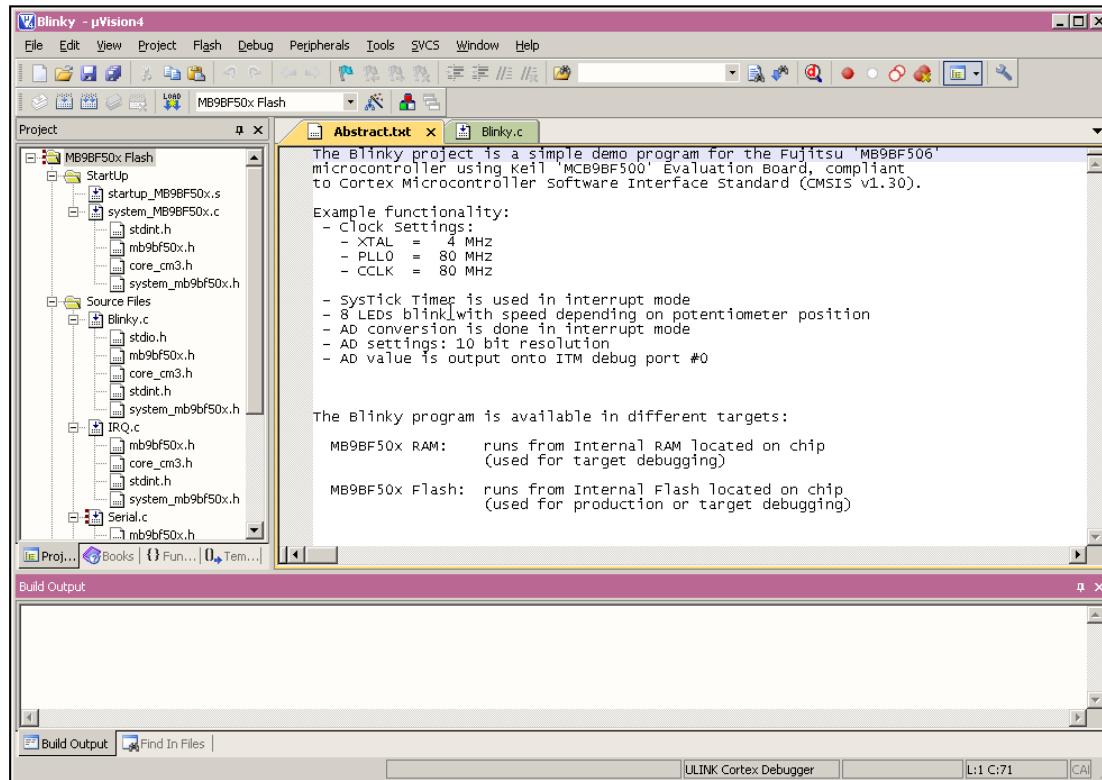




- Install µVision from KEIL-CD or download latest version from KEIL Website
 - Evaluation Version
 - ◆ <https://www.keil.com/demo/eval/arm.htm>
 - ◆ Registration required
- Install ULINK-ME
 - Special installation is not needed, because ULINK-ME acts as a USB Human Interface Device (HID) and thus needs no extra USB driver
- Install ULINK Pro (optional)
 - ULINK Pro needs an own dedicated USB driver located in:
<Installation Path>\KEIL\ARM\ULINK
- Start µVision



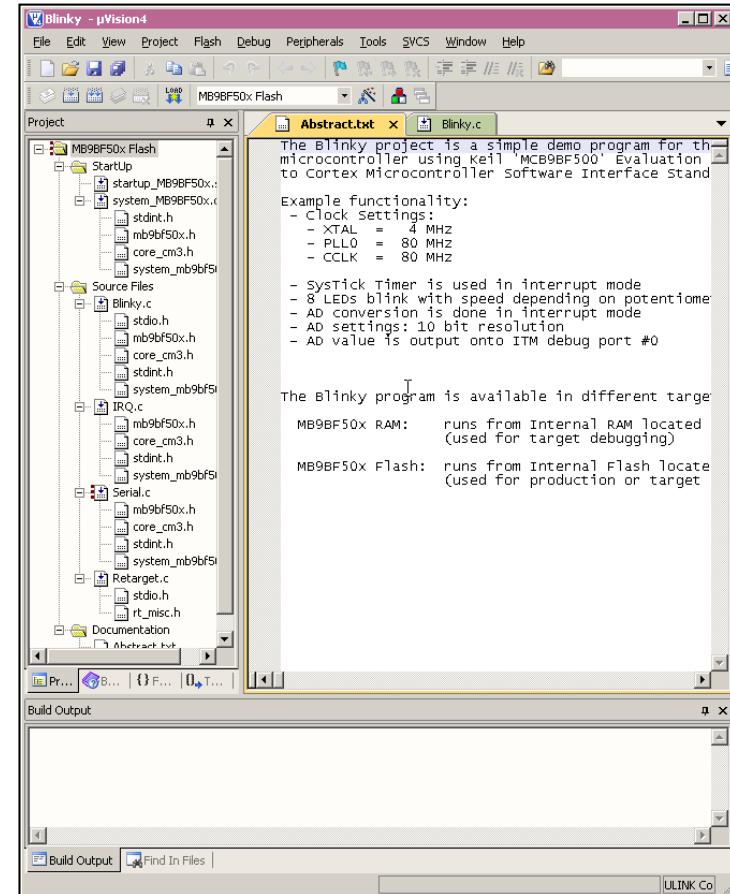
- Choose Menu: Project→Open Project...
 - Browse to: <drive:>\sw-examples\mb9bf56xr_gpio-v11\example\ARM\
 - Choose mb9bf56xr_gpio.uvproj



KEIL µVision – Main Window

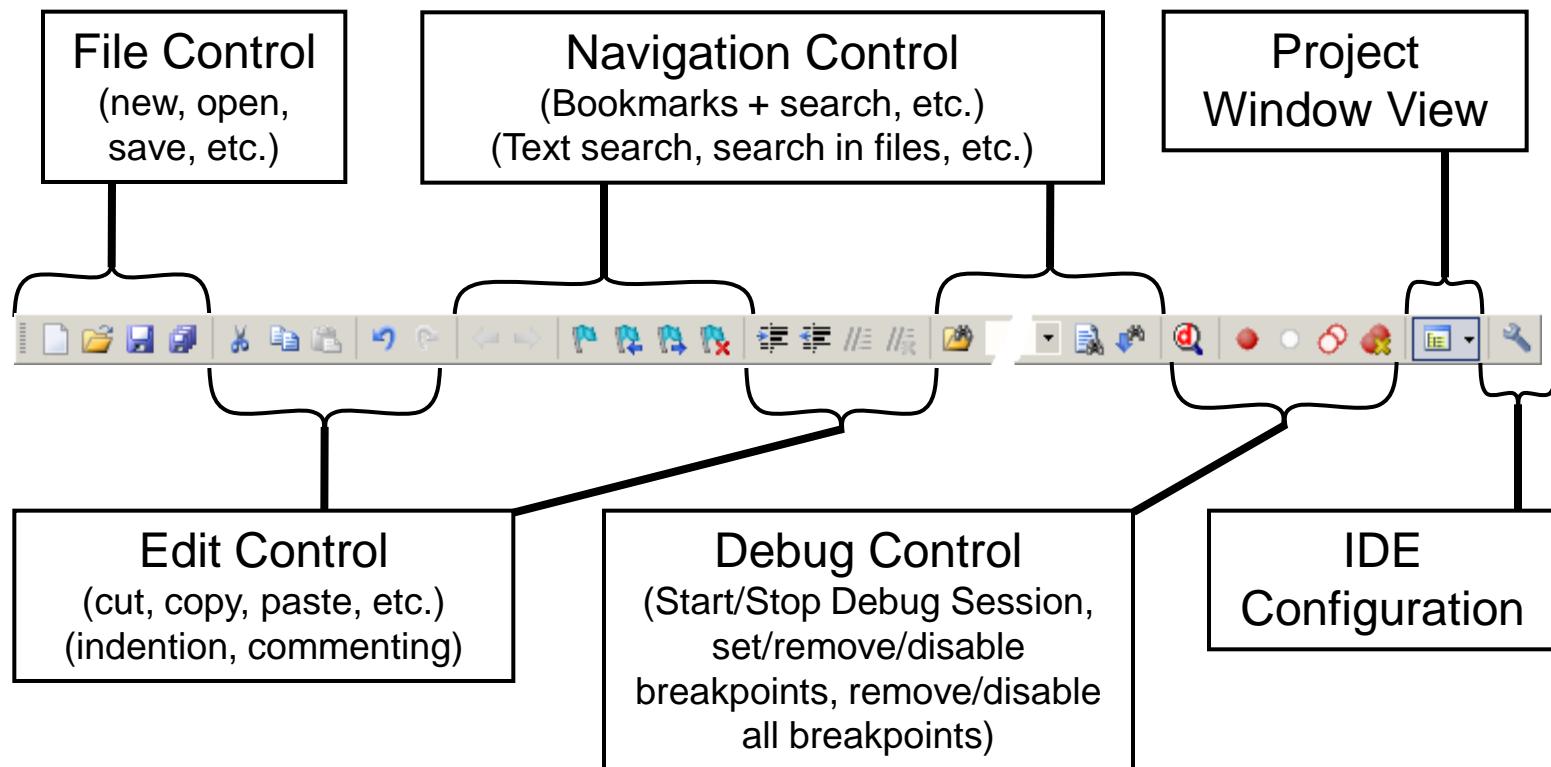
■ KEIL µVision

- Project window on left side of IDE window
 - ◆ Choose:
View→Project Window
if hidden
- Source files on right side of IDE window as tabbed windows
- Output window on bottom side of IDE window



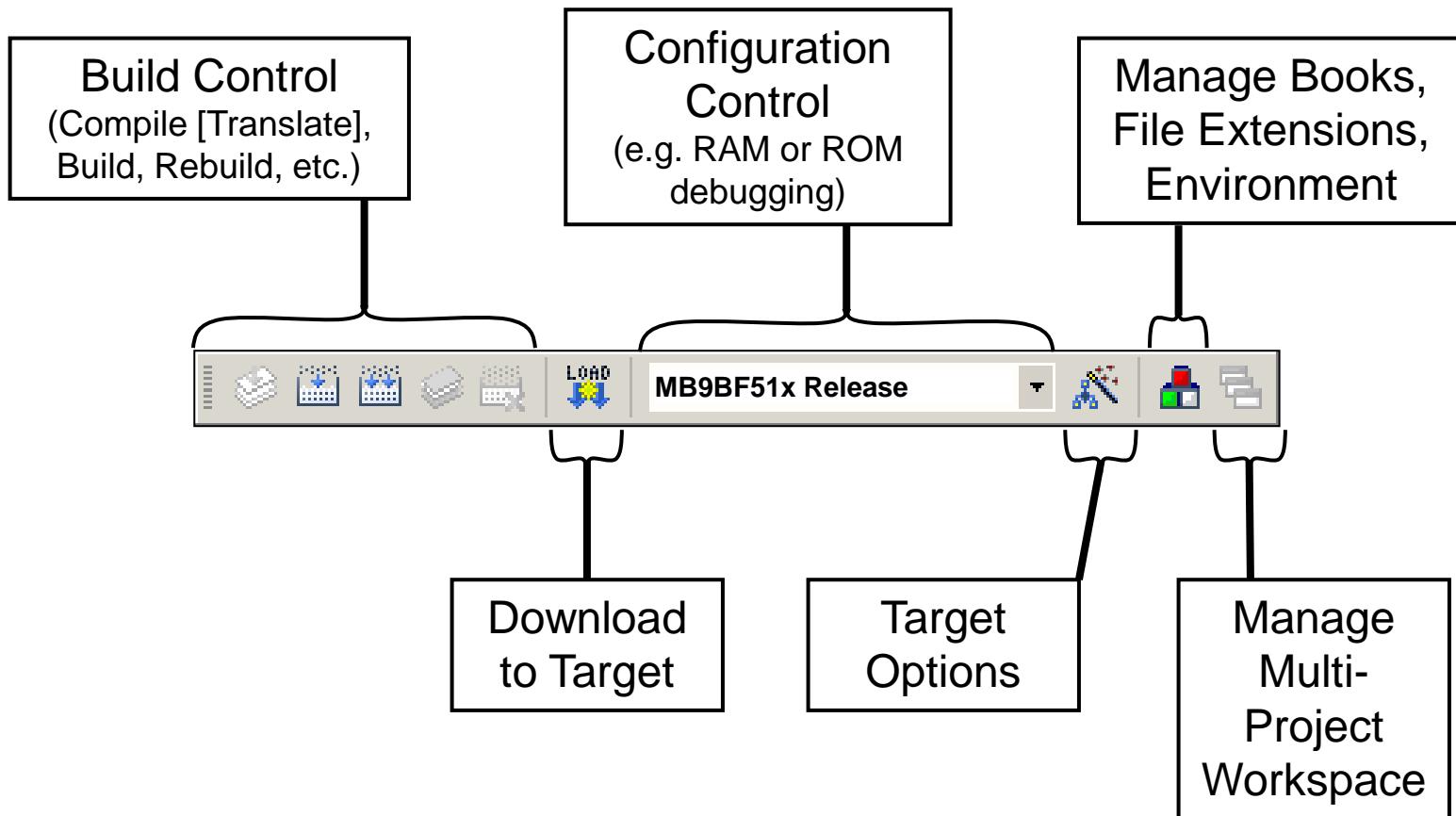


- Menu Bar 1
 - Can be moved in bar window area or set floating



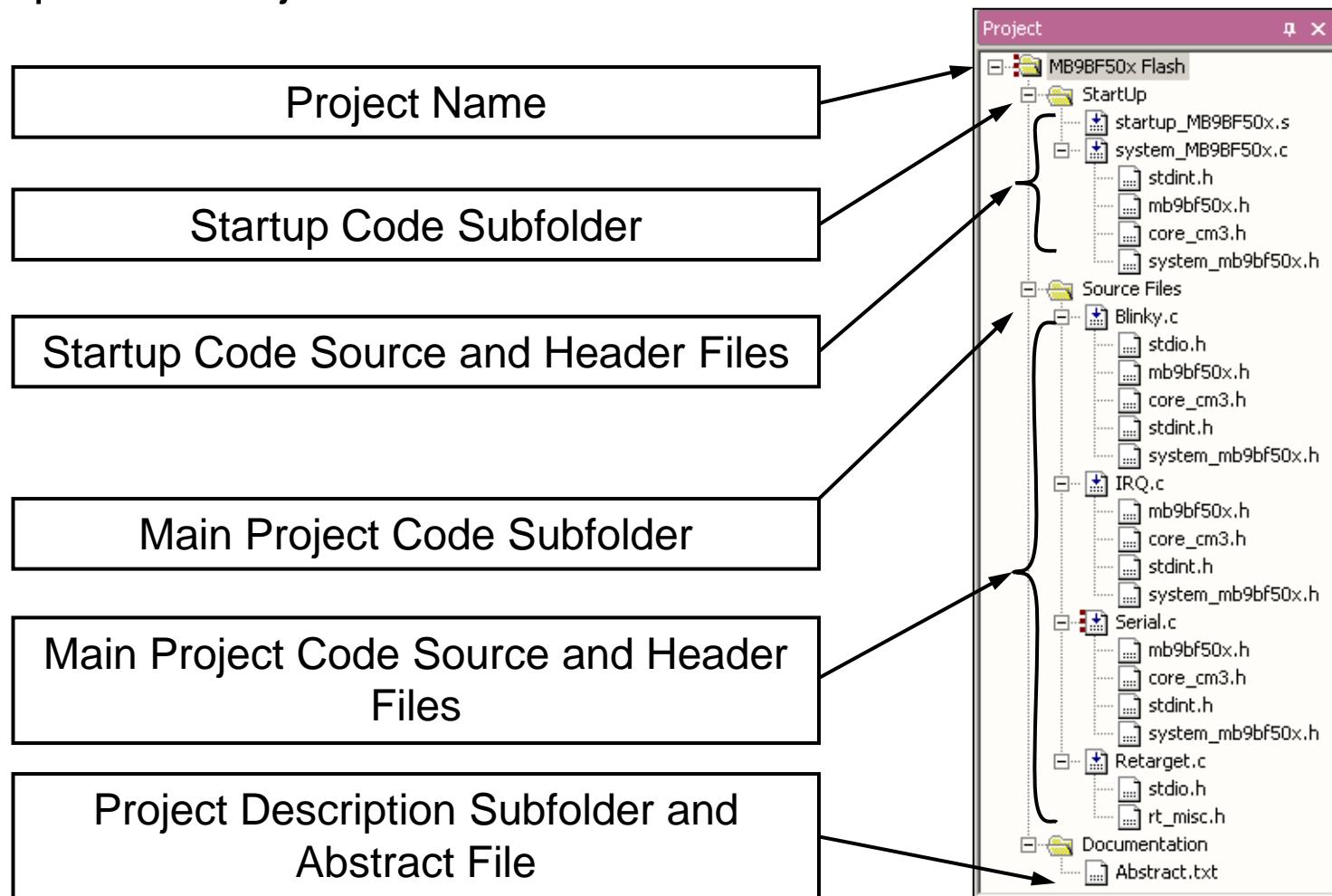


- Menu Bar 2
 - Can be moved in bar window area or set floating



KEIL µVision – Project Window

- µVision Project Window

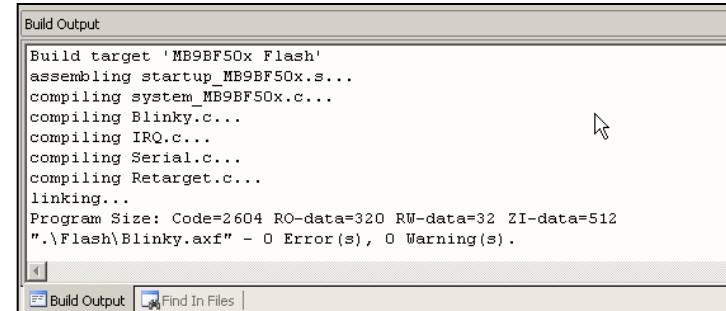




▪ Making the Project

- Use Rebuild Icon
() or
Project→Rebuild all target files

- Check for no errors in Output window below

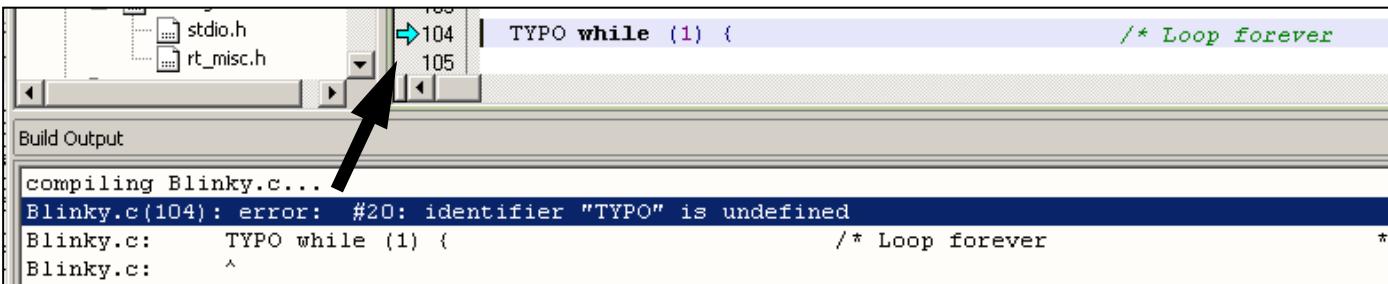


Build Output

```
Build target 'MB9BF50x Flash'
assembling startup_MB9BF50x.s...
compiling system_MB9BF50x.c...
compiling Blinky.c...
compiling IRQ.c...
compiling Serial.c...
compiling Retarget.c...
linking...
Program Size: Code=2604 RO-data=320 RW-data=32 ZI-data=512
".\Flash\Blinky.axf" - 0 Error(s), 0 Warning(s).
```

Build Output Find In Files

- Build errors are shown in Output window.
 - ◆ Can be double-clicked by showing the source line with a blue arrow



stdio.h rt_misc.h 104 TYPO while (1) { /* Loop forever

Build Output

```
compiling Blinky.c...
Blinky.c(104): error: #20: identifier "TYPO" is undefined
Blinky.c:    TYPO while (1) { /* Loop forever
Blinky.c:        ^
Blinky.c:
```



- Start Debugging

- Download to target first, when MCU Flash does not contain the current application openend and built in the IDE

- ◆ Use Download Icon () or Menu: Flash→Download

- Start Debug Session

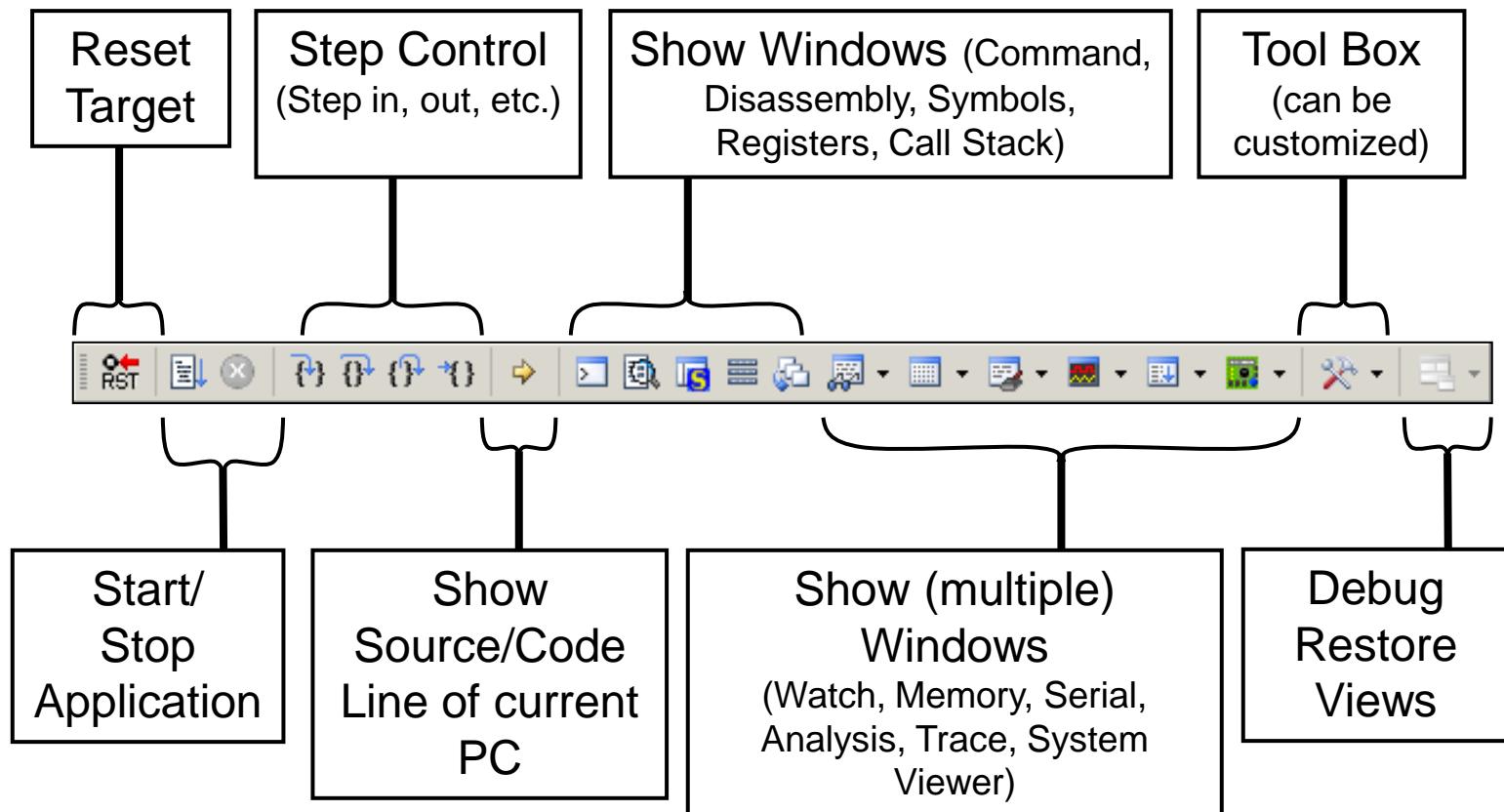
- ◆ Use Start/Stop Debug Icon () or Menu: Debug→Start/Stop Debug Session

- Ending Debug Session

- ◆ Use same way as for starting debug session



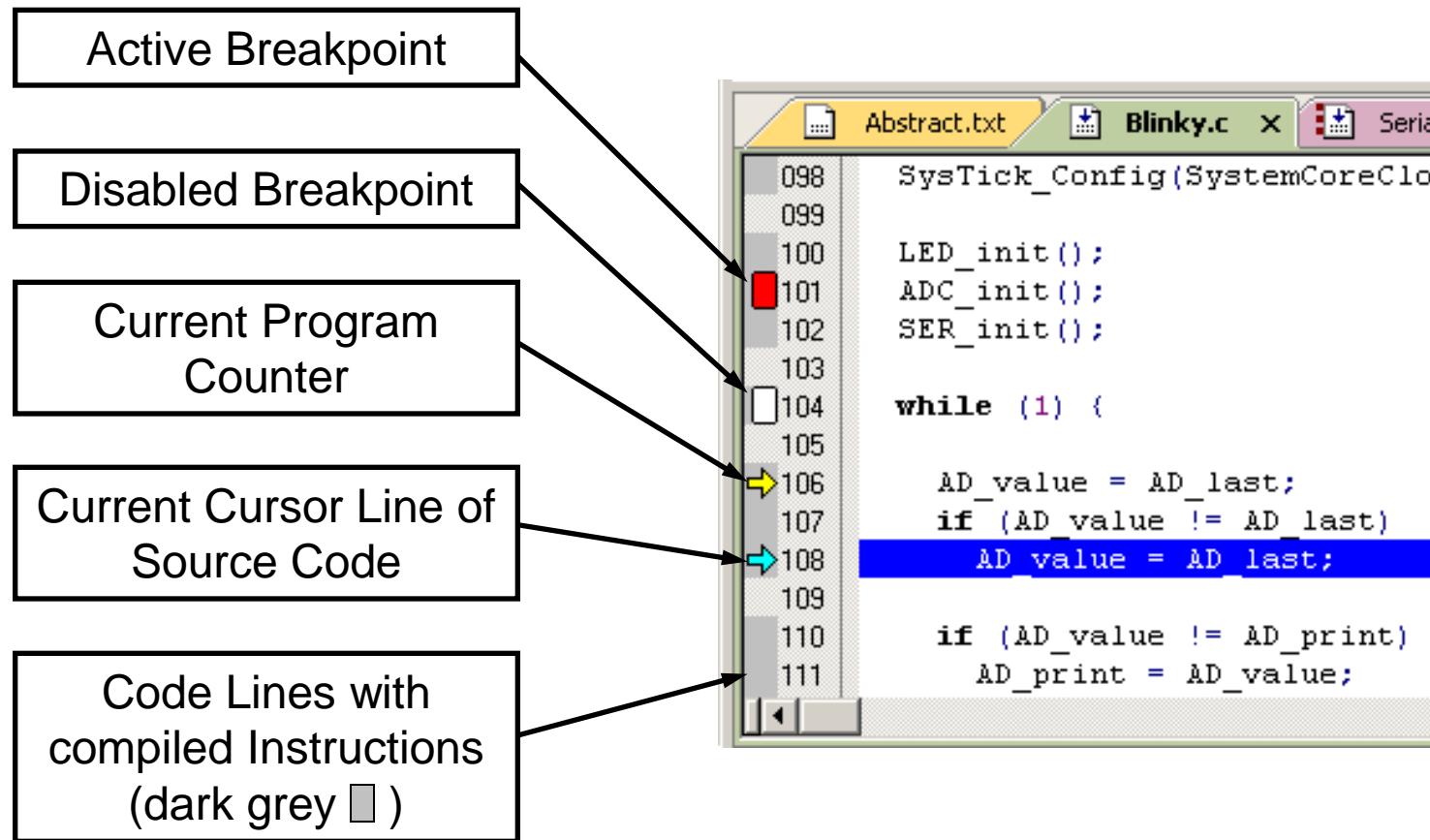
- Debugging Icon Bar
 - During a Debug Session there will be visible a new icon bar





- Source View

- The Source windows do not change contents but get additional information





- Disassembly View
 - Mixed mode is selectable and deselectable

The diagram illustrates the Keil µVision Disassembly View window with four callout boxes:

- Active Breakpoint:** Points to a red square marker at address 0x0000042E.
- Disabled Breakpoint:** Points to a grey square marker at address 0x00000432.
- Current Program Counter:** Points to a white square marker at address 0x00000436.
- Current Cursor Line of Code highlighted in yellow background (Yellow Box):** Points to a yellow square marker at address 0x00000438.

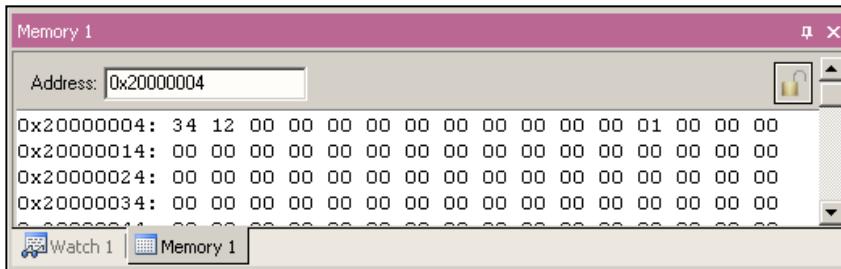
Disassembly Window Content:

Address	OpCode	Instruction	Comment
0x0000042A	F7FFFFA3	BL.W	LED_i:
101:	ADC_init();		
0x0000042E	F7FFFF67	BL.W	ADC_i:
102:	SER_init();		
103:			
0x00000432	F000F8AE	BL.W	SER_i:
104:	while (1) {		
105:			
0x00000436	E015	B	0x00000436
106:	AD_value = AD_last;		
→0x00000438	4816	LDR r0,[p]	
0x0000043A	8804	LDRH r4,[r]	
107:	if (AD_value != AD_last		



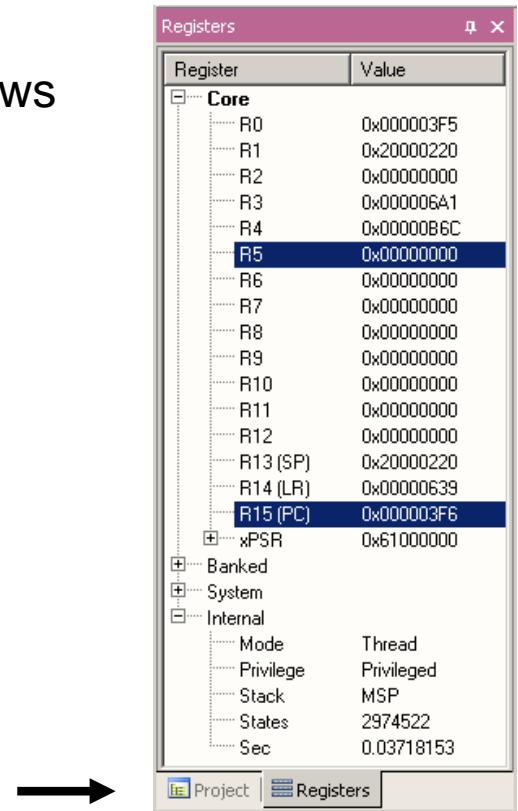
▪ Memory Window

- Up to 4 Memory windows can be displayed in tabs
- Memory is updated during runtime
- Memory window tabs are shared with Watch windows



▪ Register View

- Register view is a tab of the Project window
- Changes are highlighted in dark blue text background
- Register tree knots can be expanded





- Variable Windows

- Watch Windows

- ◆ Up to 2 Watch windows are sharing their tabs with e.g. Memory and Local views
 - ◆ Updated during runtime
 - ◆ Any changes are highlighted in dark blue text background color
 - ◆ Displayed values can be changed by user during break

Watch 1	
Name	Value
\Blinky\AD_dbg	0x01EA
<double-click or F2 to add>	
Locals	Watch 1
Memory 1	

- Local View

- ◆ The local view shares the tab with e.g. Memory and Watch windows
 - ◆ Any changes are highlighted in dark blue text background color
 - ◆ Displayed values can be changed by user during break

Locals	
Name	Value
AD_value	0x01EA
AD_print	0x01EA
ticks	<out of scope>
Locals	Watch 1
Memory 1	

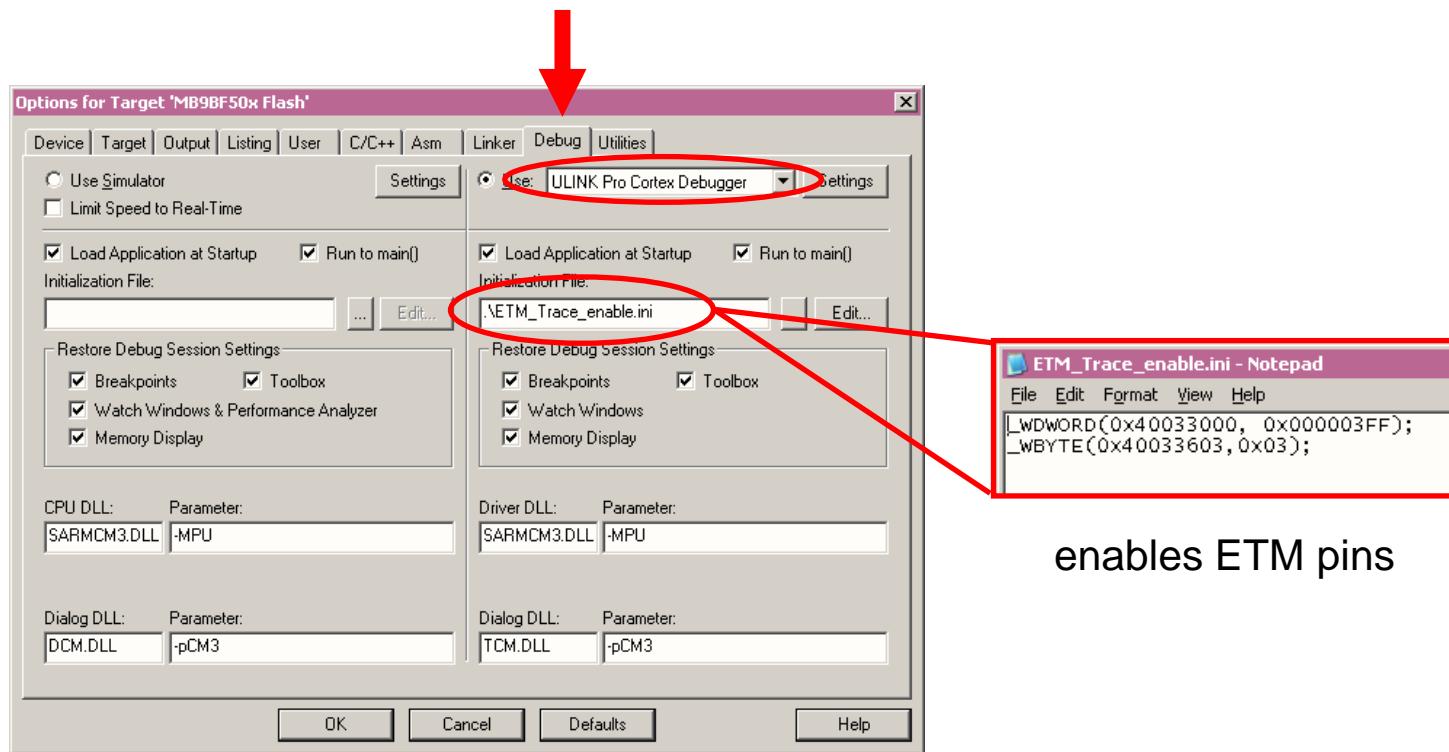


- Trace via ITM
 - Simple Trace views via Instrumentation Trace Macro is supported by µLINK ME
 - ◆ Records
 - ◆ Exceptions
 - ◆ Counters

Type	Ovf	Num	Address	Data	PC	Dly	Cycles	Time[s]
ITM		0		41H			82975148	1.03718935
ITM		0		44H			82975293	1.03719116
ITM		0		20H		X	82988592	1.03735740
ITM		0		76H		X	82988592	1.03735740
ITM		0		61H		X	82988592	1.03735740
ITM				6CH		X	82988592	1.03735740
ITM				75H		X	82988592	1.03735740
ITM				65H		X	82988592	1.03735740
ITM				20H		X	82988592	1.03735740
ITM				3DH		X	82988592	1.03735740
ITM				20H		X	82988592	1.03735740
ITM				30H		X	82988592	1.03735740
ITM				78H		X	82988592	1.03735740
ITM		0		30H			82993831	1.03742289
ITM		0		31H		X	83001392	1.03751740
ITM		0		45H		X	83001392	1.03751740
ITM		0		42H		X	83001392	1.03751740
ITM		0		0DH		X	83001392	1.03751740
ITM		0		0AH		X	83001392	1.03751740
ITM		0		0DH		X	83001392	1.03751740



- Trace via ETM
 - Check settings in menu:
Flash→Configure Flash Tools... Tab:Debug



enables ETM pins



■ Instruction Trace

- Real Time Trace recording
- Output can be filtered by several ETM and ITM events
- Trace buffer is held in PC memory and transferred to µVision on break

Instruction Trace

#	Type	Flag	Num	PC	Opcode	Instruction	Source Code
1048564	ETM			0x0000043E	4284	CMP r4,r0	
1048565	ETM			0x00000440	D001	BEQ 0x00000446	
1048566	ETM			0x00000446	42AC	CMP r4,r5	111: if (AD_value != AD_print) { /* Make sure that AD inter
1048567	ETM			0x00000448	D002	BEQ 0x00000450	
1048568	ETM			0x00000450	4814	LDR r0,[pc,#80] ; @0x000004A4	116: if (clock_1s) {
1048569	ETM			0x00000452	7800	LDRB r0,[r0,#0x00]	

Blinky.c Abstract.txt stdio.h

```

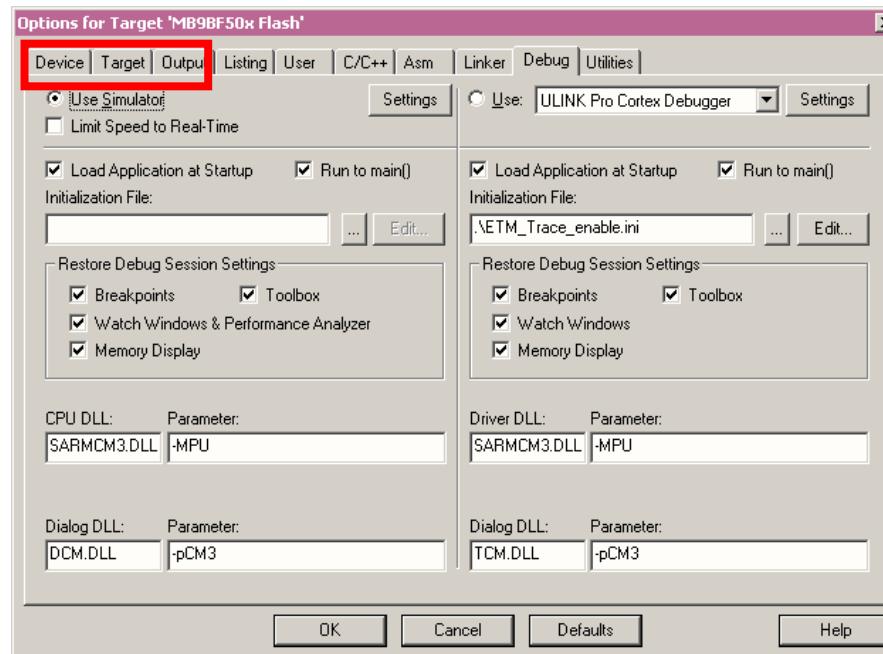
108     if (AD_value != AD_last)          /* Make sure that AD interrupt did    */
109         AD_value = AD_last;           /* not interfere with value reading */
110
111     if (AD_value != AD_print) {      /* Make sure that AD interrupt did    */
112         AD_print = AD_value;        /* Get unscaled value for printout   */
113         AD_dbg   = AD_value;

```



▪ Simulator

- The Core Simulator can be selected by the menu:
[Flash] → [Configure Flash Tools...] → [Debug]
and then choosing [Use Simulator]
- Look & feel is like using ULINK debugger
- Controllable also with *.ini files





Finally

Workshops & Seminars



FM Seminar	Motor Control	USB Workshop	Ethernet Workshop
<p>Please register here: http://news.spansion.com/seminars</p>			
<ul style="list-style-type: none">• Overview FM family<ul style="list-style-type: none">• Memory• Peripheral resources• Packages• Processor architecture<ul style="list-style-type: none">• Bus structure• Flash memory• Flash programming• Peripheral resources<ul style="list-style-type: none">• Clock distribution• Timer• Interfaces• FM features• Development tool chains<ul style="list-style-type: none">• IAR workbench / J-Link• KEIL µVision / uLink• Starter Kits• Practical exercises<ul style="list-style-type: none">• Flash programming• Project setup/modification• Debugging• External interrupts	<ul style="list-style-type: none">• Introduction of Spansion MCU<ul style="list-style-type: none">• Line-Up of microcontrollers with motion control features• Performance• Introduction of motors types<ul style="list-style-type: none">• ACIM• BLDC• PMSM• Introduction of control types<ul style="list-style-type: none">• Sinusoidal commutation• Field Orientated Control• Space Vector Modulation• Peripherals of FM3/FM4 MCUs<ul style="list-style-type: none">• Base Timer• Multifunction Timer• 12-bit A/D Converter• Quadrature Position and Revolution Counter• Interrupt Controller• Hands-on exercise / SW-Example<ul style="list-style-type: none">• BLDC motor with hall sensor• PMSM motor with field orientated control	<ul style="list-style-type: none">• Introduction of Spansion MCU<ul style="list-style-type: none">• Line-up of USB MCUs• USB vs. RS232<ul style="list-style-type: none">• Historical Background• Electrical Layer• USB Protocol<ul style="list-style-type: none">• Enumeration Process (Descriptors & USB Settings)• Transfer Types• Data Transfers• USB Class Concept• Software Driver Concepts<ul style="list-style-type: none">• USB Host• USB Examples<ul style="list-style-type: none">• Virtual COM Port• USB Descriptor Manager<ul style="list-style-type: none">• Create Template Classes• Create Descriptors• PC software based on LibUSB• Special Use Cases<ul style="list-style-type: none">• e.g. boot loader	<ul style="list-style-type: none">• Introduction of Spansion MCU<ul style="list-style-type: none">• Line-up of Ethernet MCUs• Fundamentals of Ethernet• Ethernet Microcontrollers• Hardware Design considerations• Software Design considerations• Communication layer models• The Internet Protocol suite• Web technologies in embedded systems• Developing Ethernet applications<ul style="list-style-type: none">• Tools and methods• Practical hints and advice on FM3 Ethernet solutions• Hands-on training



- Please check the following website, for any available updates

www.spansion.com

www.spansion.com/starterkit

- Please contact your local support team for any technical question

America: Spansion.Solutions@Spansion.com

China: mcu-ticket-cn@spansion.com

Europe: mcu-ticket-de@spansion.com

Japan: mcu-ticket-jp@spansion.com

Other: <http://www.spansion.com/Support/SES/Pages/Ask-Spansion.aspx>



- Gültig für EU-Länder:
 - Gemäß der Europäischen WEEE-Richtlinie und deren Umsetzung in landesspezifische Gesetze nehmen wir dieses Gerät wieder zurück.
 - Zur Entsorgung schicken Sie das Gerät bitte an die folgende Adresse:
- Valid for European Union Countries:
 - According to the European WEEE-Directive and its implementation into national laws we take this device back.
 - For disposal please send the device to the following address:



CCS Express GMBH
c/o Spansion International Inc.
Frankfurter Str. 83-107
D-65479 Raunheim
Germany



- This board is compliant with China RoHS



www.spansion.com

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