

# 3.3V Radiation Tolerant CAN Transceiver with Listen Mode and Loopback

## ISL72026SEH

The Intersil [ISL72026SEH](#) is a radiation tolerant 3.3V CAN transceiver that is compatible with the ISO11898-2 standard for applications calling for Controller Area Network (CAN) serial communication in satellites and aerospace communications and telemetry data processing in harsh industrial environments.

The transceiver can transmit and receive at bus speeds up to 5Mbps. It can drive a 40m cable at 1Mbps per the ISO11898-2 specification. The device is designed to operate over a common-mode range of -7V to +12V with a maximum of 120 nodes. The device has three discrete selectable driver rise/fall time options, a listen mode feature and loopback test capability.

Receiver (Rx) inputs feature a “full fail-safe” design, which ensures a logic high Rx output if the Rx inputs are floating, shorted, or terminated but undriven.

The ISL72026SEH is available in an 8 Ld hermetic ceramic flatpack and die form that operate across the temperature range of -55°C to +125°C. The logic inputs are tolerant with 5V systems.

Other CAN transceivers available are the [ISL72027SEH](#) and [ISL72028SEH](#). For a list of differences see [Table 1 on page 2](#).

## Related Literature

- [UG051](#), “ISL7202xSEHEVAL1Z Evaluation Board User Guide”
- [TR018](#), “SEE Testing of the ISL72027SEH CAN Transceiver”
- [TR022](#), “Total Dose Testing of the ISL72026SEH, ISL72027SEH and ISL72028SEH CAN Transceivers”

## Features

- Electrically screened to SMD [5962-15228](#)
- ESD protection on all pins. . . . . 4kV HBM
- Compatible with ISO11898-2
- Operating supply range . . . . . 3.0V to 3.6V
- Bus pin fault protection to ±20V
- Undervoltage lockout
- Cold spare: powered down devices/nodes will not affect active devices operating in parallel
- Three selectable driver rise and fall times
- Glitch free bus I/O during power-up and power-down
- Full fail-safe (open, short, terminated/undriven) receiver
- Hi Z input allows for 120 nodes on the bus
- High data rates. . . . . up to 5Mbps
- Quiescent supply current . . . . . 7mA (max)
- Listen mode supply current . . . . . 2mA (max)
- -7V to +12V common mode input voltage range
- 5V tolerant logic inputs
- Thermal shutdown
- Acceptance tested to 75krad(Si) (LDR) wafer-by-wafer
- Radiation tolerance
  - SEL/B immune to LET 60MeV·cm<sup>2</sup>/mg
  - Low dose rate (0.01rad(Si)/s) . . . . . 75krad(Si)

## Applications

- Satellites and aerospace communications
- Telemetry data processing
- High-end industrial environments
- Harsh environments

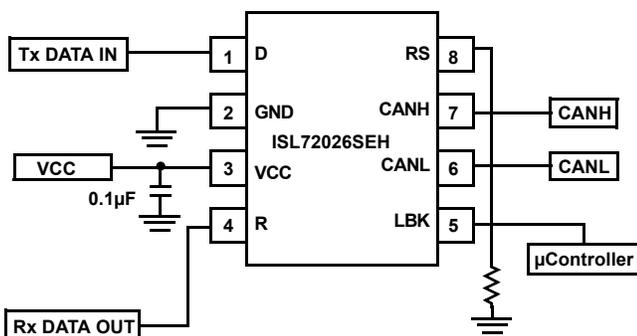


FIGURE 1. TYPICAL APPLICATION

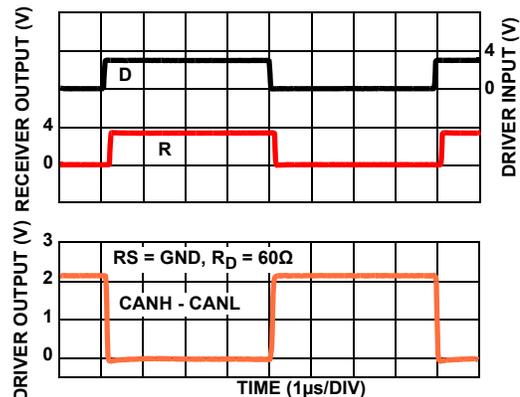


FIGURE 2. FAST DRIVER AND RECEIVER WAVEFORMS

# ISL72026SEH

## Ordering Information

ORDERING / SMD NUMBER (Note 1)	PART NUMBER (Note 2)	TEMPERATURE RANGE (°C)	PACKAGE (RoHS Compliant)	PACKAGE DRAWING #
5962L1522801VXC	ISL72026SEHVF	-55 to +125	8 Ld Ceramic Flat Pack	K8.A
N/A	ISL72026SEHF/PROTO	-55 to +125	8 Ld Ceramic Flat Pack	K8.A
5962L1522801V9A	ISL72026SEHVX	-55 to +125	Die	
N/A	ISL72026SEHX/SAMPLE	-55 to +125	Die	
N/A	ISL72026SEHEVAL1Z	Evaluation Board		

### NOTES:

- Specifications for Radiation Tolerant QML devices are controlled by the Defense Logistics Agency Land and Maritime (DLA). The SMD numbers listed in the "Ordering Information" table must be used when ordering.
- These Intersil Pb-free Hermetic packaged products employ 100% Au plate - e4 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations.

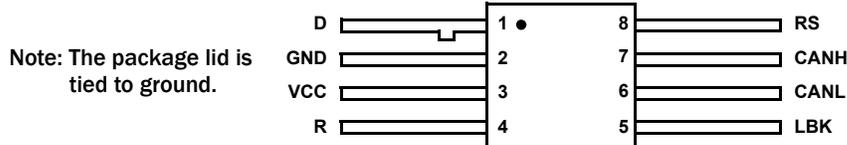
TABLE 1. ISL7202xSEH PRODUCT FAMILY FEATURE TABLE

SPEC	ISL72026SEH	ISL72027SEH	ISL72028SEH
Loopback Feature	Yes	No	No
VREF Output	No	Yes	Yes
Listen Mode	Yes	Yes	No
Shutdown Mode	No	No	Yes
VTHRLM	1150mV (Max)	1150mV (Max)	N/A
VTHFLM	525mV (Min)	525mV (Min)	N/A
VHYSLM	50mV (Min)	50mV (Min)	N/A
Supply Current, Listen Mode	2mA (Max)	2mA (Max)	N/A
Supply Current, Shutdown Mode	N/A	N/A	50µA (Max)
VREF Leakage Current	N/A	±25µA (Max)	±25µA (Max)

N/A: Not Applicable

## Pin Configuration

ISL72026SEH  
(8 LD CERAMIC FLATPACK)  
TOP VIEW



## Pin Descriptions

PIN NUMBER	PIN NAME	FUNCTION
1	D	CAN driver digital input. The bus states are LOW = Dominant and HIGH = Recessive. Internally tied HIGH.
2	GND	Ground connection.
3	VCC	System power supply input (3.0V to 3.6V). The typical voltage for the device is 3.3V.
4	R	CAN Data Receiver Output. The bus states are LOW = Dominant and HIGH = Recessive.
8	RS	A resistor to GND from this pin controls the rise and fall time of the CAN output waveform. Drive RS HIGH to put into Listen Mode.
6	CANL	CAN bus line for low level output
7	CANH	CAN bus line for high level output
5	LBK	A HIGH on this pin places CANH and CANL pins in a high impedance state. The rest of the circuit remains active so that the TX and RX can loopback diagnostic information. Internally tied LOW.

Equivalent Input and Output Schematic Diagrams

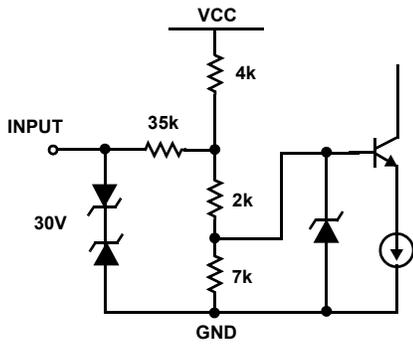


FIGURE 3. CANH AND CANL INPUTS

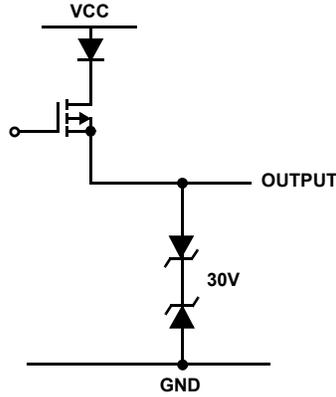


FIGURE 4. CANH OUTPUT

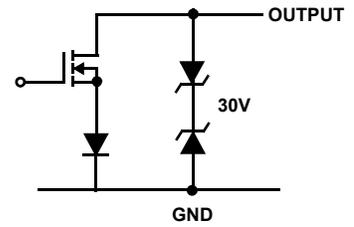


FIGURE 5. CANL OUTPUT

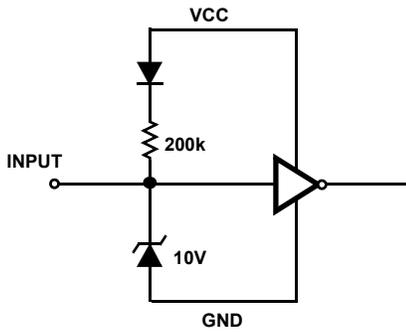


FIGURE 6. D INPUT

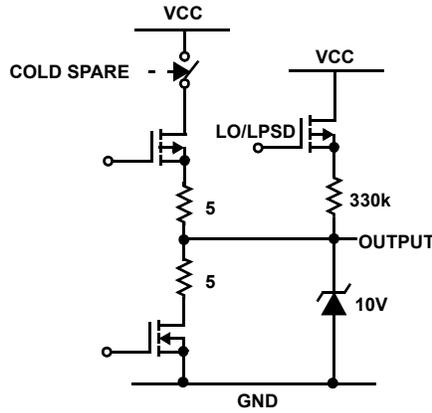


FIGURE 7. R OUTPUT

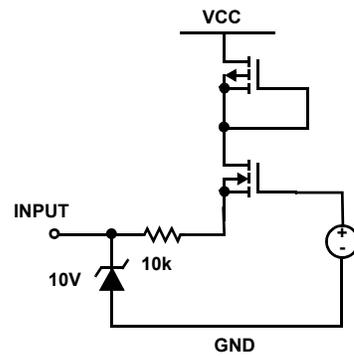


FIGURE 8. RS INPUT

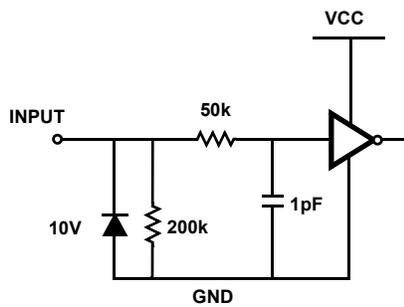


FIGURE 9. LBK INPUT

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## Absolute Maximum Ratings

VCC to GND with/without Ion Beam	-0.3V to 5.5V
CANH, CANL, VREF Under Ion Beam	±18V
CANH, CANL, VREF	±20V
I/O Voltages	
D, R, RS	-0.5V to 7V
Receiver Output Current	-10mA to 10mA
Output Short-Circuit Duration	Continuous
ESD Rating:	
Human Body Model (Tested per MIL-PRF-883 3015.7)	
CANH, CANL Bus Pins	4kV
All Other Pins	4kV
Charged Device Model (Tested per JESD22-C101D)	750V
Machine Model (Tested per JESD22-A115-A)	200V

## Thermal Information

Thermal Resistance (Typical)	$\theta_{JA}$ (°C/W)	$\theta_{JC}$ (°C/W)
8 Ld FP Package (Notes 3, 4) Direct Attach	39	7
Maximum Junction Temperature	+175°C	
Storage Temperature Range	-65°C to +150°C	

## Operating Conditions

Temperature Range	-55°C to +125°C
VCC Supply Voltage	3.0V to 3.6V
Voltage on CAN I/O	-7V to 12V
V <sub>IH</sub> D Logic Pins (D, LBK)	2V to 5.5V
V <sub>IL</sub> D Logic Pins (D, LBK)	0V to 0.8V
I <sub>OH</sub> Driver (CANH - CANL = 1.5V, V <sub>CC</sub> = 3.3V)	-40mA
I <sub>OH</sub> Receiver (V <sub>OH</sub> = 2.4V)	-4mA
I <sub>OL</sub> Driver (CANH - CANL = 1.5V, V <sub>CC</sub> = 3.3V)	+40mA
I <sub>OL</sub> Receiver (V <sub>OL</sub> = 0.4V)	+4mA

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

- $\theta_{JA}$  is measured with the component mounted on a high effective thermal conductivity test board (two buried 1oz copper planes) with "direct attach" features (package base mounted to PCB thermal land with a 10 mil gap fill material having a k of 1W/m-K. See Tech Brief [TB379](#)).
- For  $\theta_{JC}$ , the "case temp" location is the center of the package underside.

**Electrical Specifications** Test Conditions: VCC = 3.0V to 3.6V; Typicals are at T<sub>A</sub> = +25°C (Note 7); unless otherwise specified (Note 5). **Boldface limits apply across the operating temperature range, -55°C to +125°C or over a total ionizing dose of 75krad(Si) at +25°C with exposure at a low dose rate of <10mrad(Si)/s.**

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN (Note 6)	TYP (Note 7)	MAX (Note 6)	UNIT	
<b>DRIVER ELECTRICAL CHARACTERISTICS</b>								
Dominant Bus Output Voltage	V <sub>O(DOM)</sub>	D = 0V, CANH, RS = 0V, Figures 10 and 11	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>2.25</b>	2.85	<b>V<sub>CC</sub></b>	V
		D = 0V, CANL, RS = 0V, Figures 10 and 11		Full	<b>0.1</b>	0.65	<b>1.25</b>	V
Recessive Bus Output Voltage	V <sub>O(REC)</sub>	D = 3V, CANH, RS = 0V, 60Ω and no load, Figures 10 and 11	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>1.80</b>	2.3	<b>2.70</b>	V
		D = 3V, CANL, RS = 0V, 60Ω and no load, Figures 10 and 11		Full	<b>1.80</b>	2.3	<b>2.80</b>	V
Dominant Output Differential Voltage	V <sub>OD(DOM)</sub>	D = 0V, RS = 0V, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, Figures 10 and 11	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>1.5</b>	2.2	<b>3</b>	V
		D = 0V, RS = 0V, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, Figures 11 and 12		Full	<b>1.2</b>	2.1	<b>3</b>	V
Recessive Output Differential Voltage	V <sub>OD(REC)</sub>	D = 3V, RS = 0V, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, Figures 10 and 11	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>-120</b>	0.2	<b>12</b>	mV
		D = 3V, RS = 0V, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, no load		Full	<b>-500</b>	-34	<b>50</b>	mV
Logic Input High Voltage (D, LBK)	V <sub>IH</sub>	3.0V ≤ V <sub>CC</sub> ≤ 3.6V, Note 8	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>2.0</b>	-	<b>5.5</b>	V
Logic Input Low Voltage (D, LBK)	V <sub>IL</sub>	3.0V ≤ V <sub>CC</sub> ≤ 3.6V, Note 8	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>0</b>	-	<b>0.8</b>	V
Logic High Level Input Current (D, LBK)	I <sub>IH</sub>	D = 2.0V, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, Note 9	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>-30</b>	-3	<b>30</b>	μA
Logic Low Level Input Current (D, LBK)	I <sub>IL</sub>	D = 0.8V, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, Note 9	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>-30</b>	-7	<b>30</b>	μA
RS Input Voltage for Listen Mode	V <sub>IN(RS)</sub>	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	<b>0.75 VCC</b>	1.9	<b>5.5</b>	V

# ISL72026SEH

**Electrical Specifications** Test Conditions: VCC = 3.0V to 3.6V; Typicals are at T<sub>A</sub> = +25 °C (Note 7); unless otherwise specified (Note 5). Boldface limits apply across the operating temperature range, -55 °C to +125 °C or over a total ionizing dose of 75krad(SI) at +25 °C with exposure at a low dose rate of <10mrad(SI)/s. (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN (Note 6)	TYP (Note 7)	MAX (Note 6)	UNIT
Output Short-Circuit Current	I <sub>OSC</sub>	V <sub>CANH</sub> = -7V, CANL = OPEN, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, <a href="#">Figure 19</a>	Full	<b>-250</b>	-100	-	mA
		V <sub>CANH</sub> = +12V, CANL = OPEN, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, <a href="#">Figure 19</a>	Full	-	0.4	<b>1</b>	mA
		V <sub>CANL</sub> = -7V, CANH = OPEN, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, <a href="#">Figure 19</a>	Full	<b>-1</b>	-0.4	-	mA
		V <sub>CANL</sub> = +12V, CANH = OPEN, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V, <a href="#">Figure 19</a>	Full	-	100	<b>250</b>	mA
Thermal Shutdown Temperature	T <sub>SHDN</sub>	3.0V < V <sub>IN</sub> < 3.6V	-	-	163	-	°C
Thermal Shutdown Hysteresis	T <sub>HYS</sub>	3.0V < V <sub>IN</sub> < 3.6V	-	-	12	-	°C
<b>RECEIVER ELECTRICAL CHARACTERISTICS</b>							
Input Threshold Voltage (Rising)	V <sub>THR</sub>	LBK = 0V, RS = 0V, 10k, 50k, (recessive to dominant), <a href="#">Figures 14</a> and <a href="#">15</a>	Full	-	750	<b>900</b>	mV
Input Threshold Voltage (Falling)	V <sub>THF</sub>	LBK = 0V, RS = 0V, 10k, 50k, (dominant to recessive), <a href="#">Figures 14</a> and <a href="#">15</a>	Full	<b>500</b>	650	-	mV
Input Hysteresis	V <sub>HYS</sub>	(V <sub>THR</sub> - V <sub>THF</sub> ), RS = 0V, 10k, 50k, <a href="#">Figures 14</a> and <a href="#">15</a>	Full	<b>40</b>	90	-	mV
Listen Mode Input Threshold Voltage (Rising)	V <sub>THRLM</sub>	RS = V <sub>CC</sub> , (recessive to dominant), <a href="#">Figure 14</a>	Full	-	920	<b>1150</b>	mV
Listen Mode Input Threshold Voltage (Falling)	V <sub>THFLM</sub>	RS = V <sub>CC</sub> , (dominant to recessive), <a href="#">Figure 14</a>	Full	<b>525</b>	820	-	mV
Listen Mode Input Hysteresis	V <sub>HYSLM</sub>	(V <sub>THR</sub> - V <sub>THF</sub> ), RS = V <sub>CC</sub> , <a href="#">Figure 14</a>	Full	<b>50</b>	100	-	mV
Receiver Output High Voltage	V <sub>OH</sub>	I <sub>O</sub> = -4mA	Full	<b>2.4</b>	V <sub>CC</sub> - 0.2	-	V
Receiver Output Low Voltage	V <sub>OL</sub>	I <sub>O</sub> = +4mA	Full	-	0.2	<b>0.4</b>	V
Input Current for CAN Bus	I <sub>CAN</sub>	CANH or CANL at 12V, D = 3V, other bus pin at 0V, LBK = RS = 0V	Full	-	420	<b>500</b>	μA
		CANH or CANL at 12V, D = 3V, V <sub>CC</sub> = 0V, other bus pin at 0V, LBK = RS = 0V	Full	-	150	<b>250</b>	μA
		CANH or CANL at -7V, D = 3V, other bus pin at 0V, LBK = RS = 0V	Full	<b>-400</b>	-300	-	μA
		CANH or CANL at -7V, D = 3V, V <sub>CC</sub> = 0V, other bus pin at 0V, LBK = RS = 0V	Full	<b>-150</b>	-85	-	μA
Input Capacitance (CANH or CANL)	C <sub>IN</sub>	Input to GND, D = 3V, LBK = RS = 0V	25	-	35	-	pF
Differential Input Capacitance	C <sub>IND</sub>	Input to Input, D = 3V, LBK = RS = 0V	25	-	15	-	pF
Input Resistance (CANH or CANL)	R <sub>IN</sub>	Input to GND, D = 3V, LBK = RS = 0V	Full	<b>20</b>	40	<b>50</b>	kΩ
Differential Input Resistance	R <sub>IND</sub>	Input to Input, D = 3V, LBK = RS = 0V	Full	<b>40</b>	80	<b>100</b>	kΩ
<b>SUPPLY CURRENT</b>							
Supply Current, Listen Mode	I <sub>CC(L)</sub>	RS = D = V <sub>CC</sub> , LBK = 0V, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	-	1	<b>2</b>	mA
Supply Current, Dominant	I <sub>CC(DOM)</sub>	D = LBK = RS = 0V, no load, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	-	5	<b>7</b>	mA
Supply Current, Recessive	I <sub>CC(REC)</sub>	D = V <sub>CC</sub> , LBK = RS = 0V, no load, 3.0V ≤ V <sub>CC</sub> ≤ 3.6V	Full	-	2.6	<b>5</b>	mA
<b>COLD SPARING BUS CURRENT</b>							
CANH Leakage Current	I <sub>L(CANH)</sub>	V <sub>CC</sub> = 0.2V, CANH = -7V or 12V, CANL = float, D = V <sub>CC</sub> , RS = 0V	Full	<b>-25</b>	-4	<b>25</b>	μA
CANL Leakage Current	I <sub>L(CANL)</sub>	V <sub>CC</sub> = 0.2V, CANL = -7V or 12V, CANH = float, D = V <sub>CC</sub> , RS = 0V	Full	<b>-25</b>	-4	<b>25</b>	μA

# ISL72026SEH

**Electrical Specifications** Test Conditions: VCC = 3.0V to 3.6V; Typicals are at T<sub>A</sub> = +25 °C (Note 7); unless otherwise specified (Note 5). Boldface limits apply across the operating temperature range, -55 °C to +125 °C or over a total ionizing dose of 75krad(Si) at +25 °C with exposure at a low dose rate of <10mrad(Si)/s. (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN (Note 6)	TYP (Note 7)	MAX (Note 6)	UNIT
<b>DRIVER SWITCHING CHARACTERISTICS</b>							
Propagation Delay LOW to HIGH	t <sub>PDLH1</sub>	RS = 0V, <a href="#">Figure 13</a>	Full	-	75	<b>150</b>	ns
Propagation Delay LOW to HIGH	t <sub>PDLH2</sub>	RS = 10kΩ, <a href="#">Figure 13</a>	Full	-	520	<b>850</b>	ns
Propagation Delay LOW to HIGH	t <sub>PDLH3</sub>	RS = 50kΩ, <a href="#">Figure 13</a>	Full	-	850	<b>1400</b>	ns
Propagation Delay HIGH to LOW	t <sub>PDHL1</sub>	RS = 0V, <a href="#">Figure 13</a>	Full	-	80	<b>155</b>	ns
Propagation Delay HIGH to LOW	t <sub>PDHL2</sub>	RS = 10kΩ, <a href="#">Figure 13</a>	Full	-	460	<b>800</b>	ns
Propagation Delay HIGH to LOW	t <sub>PDHL3</sub>	RS = 50kΩ, <a href="#">Figure 13</a>	Full	-	725	<b>1300</b>	ns
Output Skew	t <sub>SKEW1</sub>	RS = 0V, ( t <sub>PHL</sub> - t <sub>PLH</sub>  ), <a href="#">Figure 13</a>	Full	-	5	<b>50</b>	ns
Output Skew	t <sub>SKEW2</sub>	RS = 10kΩ, ( t <sub>PHL</sub> - t <sub>PLH</sub>  ), <a href="#">Figure 13</a>	Full	-	60	<b>510</b>	ns
Output Skew	t <sub>SKEW3</sub>	RS = 50kΩ, ( t <sub>PHL</sub> - t <sub>PLH</sub>  ), <a href="#">Figure 13</a>	Full	-	110	<b>800</b>	ns
Output Rise Time	t <sub>r1</sub>	RS = 0V, (fast speed) <a href="#">Figure 13</a>	Full	<b>20</b>	55	<b>100</b>	ns
Output Fall Time	t <sub>f1</sub>		Full	<b>10</b>	25	<b>75</b>	ns
Output Rise Time	t <sub>r2</sub>	RS = 10kΩ, (medium speed - 250kbps) <a href="#">Figure 13</a>	Full	<b>200</b>	400	<b>780</b>	ns
Output Fall Time	t <sub>f2</sub>		Full	<b>175</b>	300	<b>500</b>	ns
Output Rise Time	t <sub>r3</sub>	RS = 50kΩ, (slow speed - 125kbps) <a href="#">Figure 13</a>	Full	<b>400</b>	700	<b>1400</b>	ns
Output Fall Time	t <sub>f3</sub>		Full	<b>300</b>	650	<b>1000</b>	ns
Total Loop Delay, Driver Input to Receiver Output, Recessive to Dominant	t <sub>(LOOP1)</sub>	RS = 0V, <a href="#">Figure 17</a>	Full	-	115	<b>210</b>	ns
		RS = 10kΩ, <a href="#">Figure 17</a>	Full	-	550	<b>875</b>	ns
		RS = 50kΩ, <a href="#">Figure 17</a>	Full	-	850	<b>1400</b>	ns
Total Loop Delay, Driver Input to Receiver Output, Dominant to Recessive	t <sub>(LOOP2)</sub>	RS = 0V, <a href="#">Figure 17</a>	Full	-	130	<b>270</b>	ns
		RS = 10kΩ, <a href="#">Figure 17</a>	Full	-	500	<b>825</b>	ns
		RS = 50kΩ, <a href="#">Figure 17</a>	Full	-	750	<b>1300</b>	ns
Listen to Valid Dominant Time	t <sub>L-DOM</sub>	<a href="#">Figure 16</a>	Full	-	5	<b>15</b>	μs
<b>RECEIVER SWITCHING CHARACTERISTICS</b>							
Propagation Delay LOW to HIGH	t <sub>PLH</sub>	<a href="#">Figure 14</a>	Full	-	50	<b>110</b>	ns
Propagation Delay HIGH to LOW	t <sub>PHL</sub>	<a href="#">Figure 14</a>	Full	-	50	<b>110</b>	ns
Rx Skew	t <sub>SKEW1</sub>	t <sub>PHL</sub> - t <sub>PLH</sub>  , <a href="#">Figure 14</a>	Full	-	2	<b>35</b>	ns
Rx Rise Time	t <sub>r</sub>	<a href="#">Figure 14</a>	Full	-	2	-	ns
Rx Fall Time	t <sub>f</sub>	<a href="#">Figure 14</a>	Full	-	2	-	ns
LBK Delay I/O to Rx Output	t <sub>LBK</sub>	<a href="#">Figure 18, Note 9</a>	Full	-	35	<b>75</b>	ns
<b>RS PIN CHARACTERISTICS</b>							
RS Input Current	I <sub>RS(H)</sub>	RS = 0.75 x V <sub>CC</sub>	Full	<b>-10</b>	-0.2	-	μA
	I <sub>RS(L)</sub>	V <sub>RS</sub> = 0V	Full	<b>-450</b>	-125	<b>0</b>	μA

**NOTES:**

- All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
- Parameters with MIN and/or MAX limits are 100% tested at -55 °C, +25 °C and +125 °C, unless otherwise specified.
- Typical values are at 3.3V. Parameters with a single entry in the "TYP" column apply to 3.3V. Typical values shown are not guaranteed.
- Parameter included in functional testing.
- Performed during the 100% screening operations over the full operating temperature range. Not performed as part of TCI Group E and Group C. Radiation characterization testing performed as part of the initial release and any major changes in design.

## Test Circuits and Waveforms

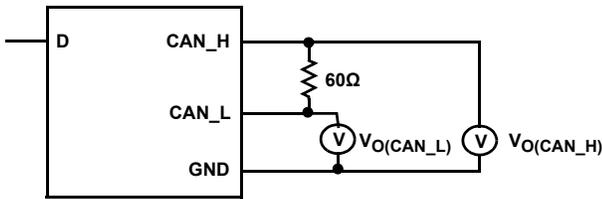


FIGURE 10. DRIVER TEST CIRCUIT

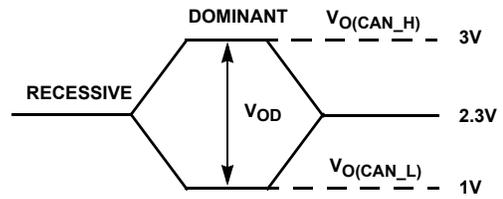


FIGURE 11. DRIVER BUS VOLTAGE DEFINITIONS

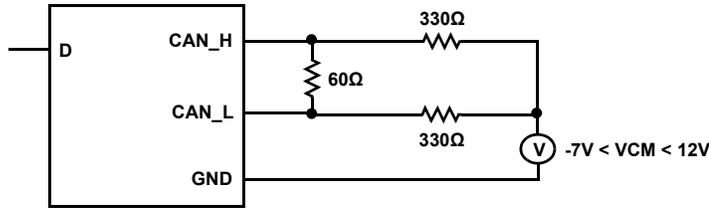
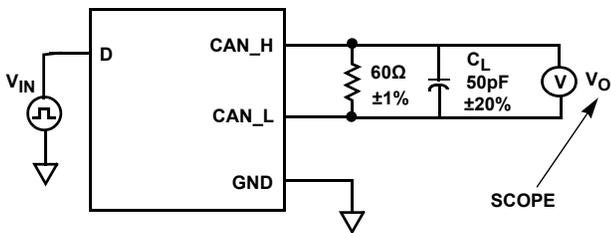


FIGURE 12. DRIVER COMMON MODE CIRCUIT



$V_{IN} = 125\text{kHz}$ ,  $0\text{V}$  to  $V_{CC}$ , Duty Cycle 50%,  $t_r = t_f \leq 6\text{ns}$ ,  $Z_O = 50\Omega$   
 $C_L$  includes fixture and instrumentation capacitance.

FIGURE 13A. DRIVER TIMING TEST CIRCUIT

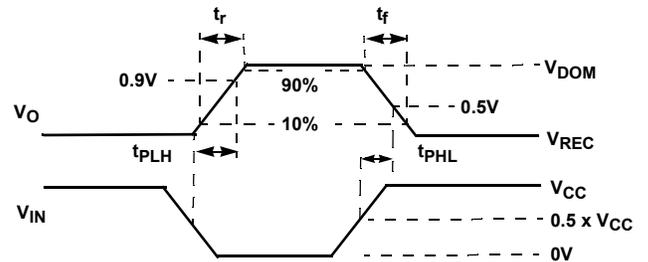


FIGURE 13B. DRIVER TIMING MEASUREMENT POINTS

FIGURE 13. DRIVER TIMING

## Test Circuits and Waveforms (Continued)

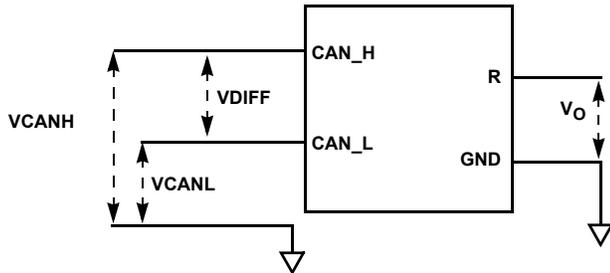
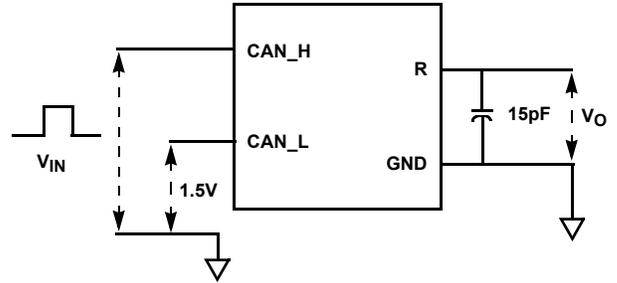


FIGURE 14A. RECEIVER VOLTAGE DEFINITIONS



$V_{IN} = 125\text{kHz}$ , Duty Cycle 50%,  $t_r = t_f = 6\text{ns}$ ,  $Z_O = 50\Omega$   
 $C_L$  includes test setup capacitance

FIGURE 14B. RECEIVER TEST CIRCUIT

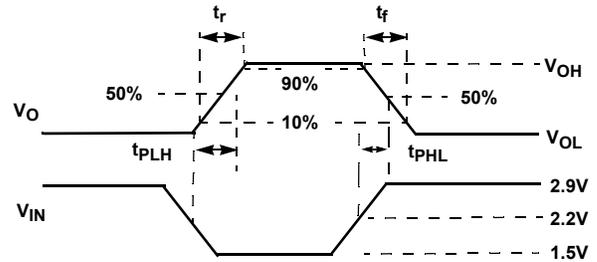


FIGURE 14C. RECEIVER TEST MEASUREMENT POINTS

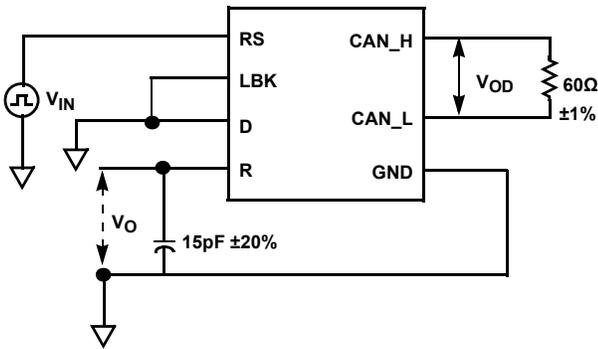
FIGURE 14. RECEIVER TEST

TABLE 2.

INPUT		OUTPUT	MEASURED
VCANH	VCANL	R	VDIFF
-6.1V	-7V	L	900mV
12V	11.1V	L	900mV
-1V	-7V	L	6V
12V	6V	L	6V
-6.5V	-7V	H	500mV
12V	11.5V	H	500mV
-7V	-1V	H	6V
6V	12V	H	6V

FIGURE 15. DIFFERENTIAL INPUT VOLTAGE THRESHOLD TEST

## Test Circuits and Waveforms (Continued)



$V_{IN} = 125\text{kHz}$ ,  $0\text{V}$  to  $V_{CC}$ , Duty Cycle 50%,  $t_r = t_f \leq 6\text{ns}$

FIGURE 16A. LISTEN TO VALID DOMINANT TIME TEST CIRCUIT

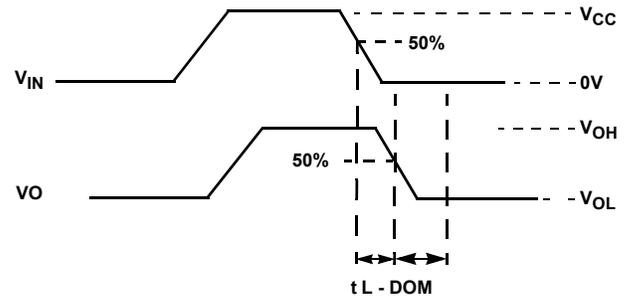
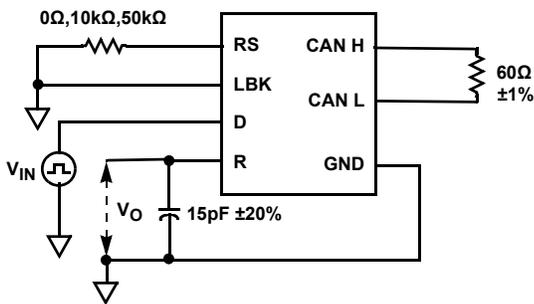


FIGURE 16B. LISTEN TO VALID DOMINANT TIME MEASUREMENT POINTS

FIGURE 16. LISTEN TO VALID DOMINANT TIME



$V_{IN} = 125\text{kHz}$ , Duty Cycle 50%,  $t_r = t_f \leq 6\text{ns}$ .

FIGURE 17A. TOTAL LOOP DELAY TEST CIRCUIT

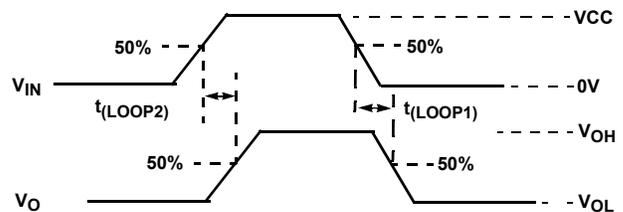
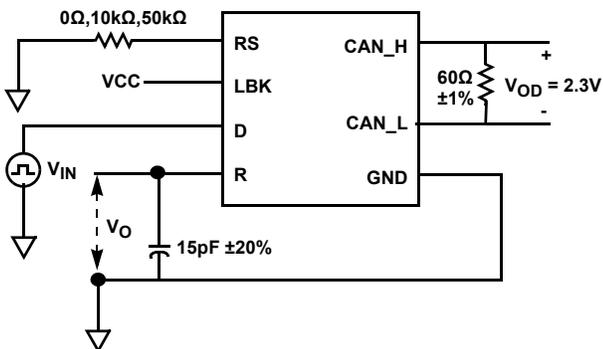


FIGURE 17B. TOTAL LOOP DELAY MEASUREMENT POINTS

FIGURE 17. TOTAL LOOP DELAY



$V_{IN} = 125\text{kHz}$ ,  $0\text{V}$  to  $V_{CC}$ , Duty Cycle 50%,  $t_r = t_f \leq 6\text{ns}$

FIGURE 18A. LOOP BACK DELAY TO DOMINANT TIME TEST CIRCUIT

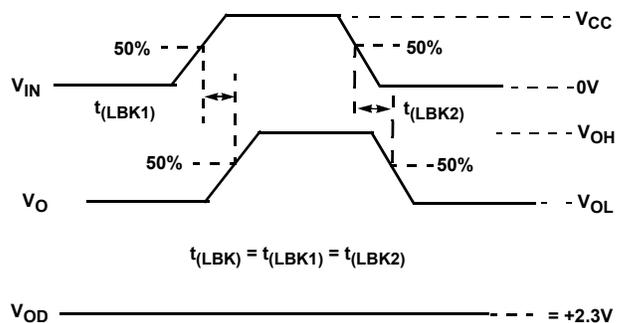


FIGURE 18B. LOOP BACK DELAY TO DOMINANT MEASUREMENT POINTS

FIGURE 18. LOOP BACK DELAY

## Test Circuits and Waveforms (Continued)

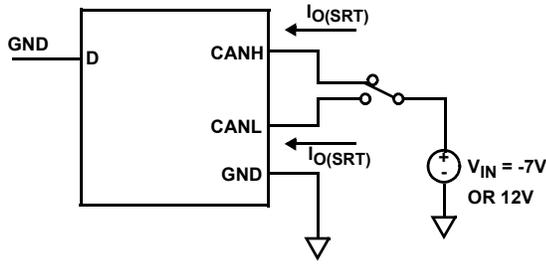


FIGURE 19A. OUTPUT SHORT CIRCUIT CURRENT TEST CIRCUIT

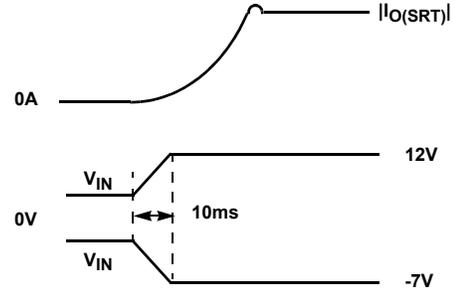


FIGURE 19B. OUTPUT SHORT CIRCUIT CURRENT WAVEFORMS

FIGURE 19. OUTPUT SHORT CIRCUIT CURRENT

## Functional Description

### Overview

The Intersil ISL72026SEH is a 3.3V radiation tolerant CAN transceiver that is compatible with the ISO11898-2 standard for use in CAN (Controller Area Network) serial communication systems.

The device performs transmit and receive functions between the CAN controller and the CAN differential bus. It can transmit and receive at bus speeds of up to 5Mbps. It is designed to operate over a common mode range of -7V to +12V with a maximum of 120 nodes. The device is capable of withstanding  $\pm 20V$  on the CANH and CANL bus pins outside of ion beam and  $\pm 16V$  under ion beam.

### Slope Adjustment

The output driver rise and fall time has three distinct selections that may be chosen by using a resistor from the RS pin to GND. Connecting the RS pin directly to GND results in output switching times that are the fastest, limited only by the drive capability of the output stage.  $RS = 10k\Omega$  provides for a typical slew rate of  $8V/\mu s$  and  $RS = 50k\Omega$  provides for a typical slew rate of  $4V/\mu s$ .

Putting a high logic level to the RS pin places the device in a low current listen mode. The protocol controller uses this mode to switch between low power listen mode and normal transmit mode.

### Cable Length

The device can work per ISO11898 specification with a 40m cable and stub length of 0.3m and 60 nodes at 1Mbps. This is greater than the ISO requirement of 30 nodes. The cable type specified is twisted pair (shielded or unshielded) with a characteristic impedance of  $120\Omega$ . Resistors equal to this are to be terminated at both ends of the cable. Stubs should be kept as short as possible to prevent reflections.

### Cold Spare

High reliability system designers implementing data communications have to be sensitive to the potential for single point failures. To mitigate the risk of a failure they will use redundant bus transceivers in parallel. In this arrangement both active and quiescent devices can be present simultaneously on the bus. The quiescent devices are powered down for cold spare and do not affect the communication of the other active nodes.

To achieve this, a powered down transceiver ( $V_{CC} < 200mV$ ) has a resistance between the CANH or CANL bus pin and the  $V_{CC}$  supply rail of  $> 480k\Omega$  (max) with a typical resistance  $> 2M\Omega$ . The resistance between CANH and CANL of a powered-down transceiver has a typical resistance of  $80k\Omega$ .

### Listen Mode

When a high level is applied to the RS pin, the device enters a low power listen mode. The driver of the transceiver is switched off to conserve power while the receiver remains active. In listen mode the transceiver draws 2mA (max) of current.

A low level on the RS pin brings the device back to normal operation.

### Loopback Mode

When a high level is applied to the LBK pin, the device enters the loopback state. The transceiver CANH and CANL pins are disconnected from the bus. The driver and receiver circuitry of the transceiver remains active to allow for diagnostic testing of the node.

### Using 3.3V Devices in 5V Systems

Looking at the differential voltage of both the 3.3V and 5V devices, the differential voltage is the same, the recessive common mode output is the same. The dominant common mode output voltage is slightly lower than the 5V counterparts. The receiver specs are also the same. Though the electrical parameters appear compatible it is advised that necessary system testing be performed to verify interchangeable operation.

## Typical Performance Curves $C_L = 15\text{pF}$ , $T_A = +25^\circ\text{C}$ ; Unless Otherwise Specified.

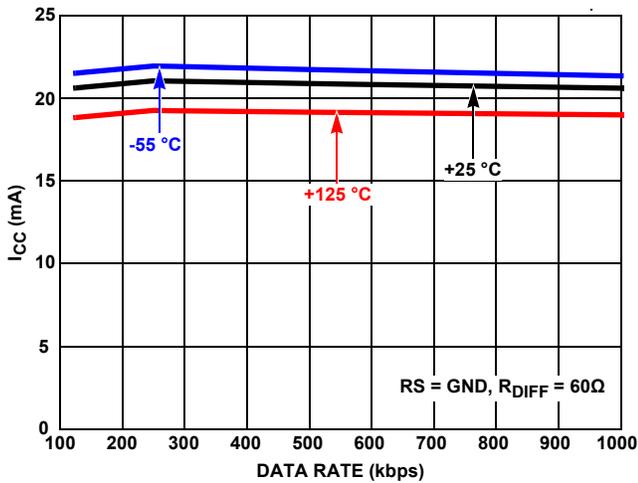


FIGURE 20. SUPPLY CURRENT vs FAST DATA RATE vs TEMPERATURE

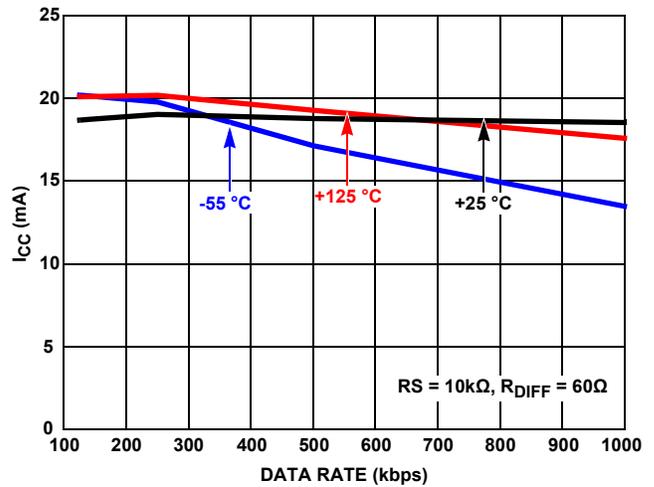


FIGURE 21. SUPPLY CURRENT vs MEDIUM DATA RATE vs TEMPERATURE

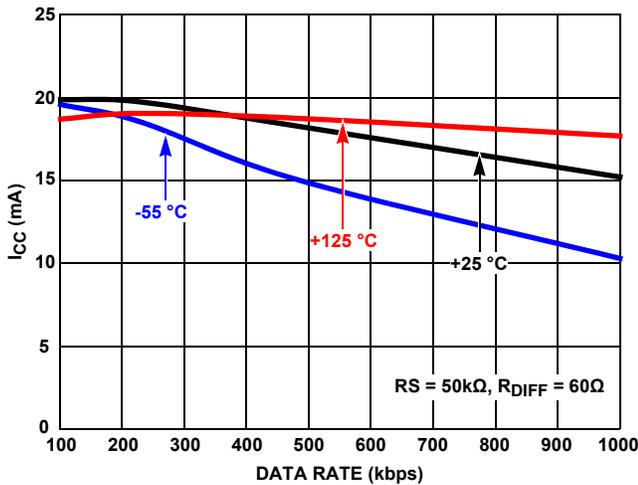


FIGURE 22. SUPPLY CURRENT vs SLOW DATA RATE vs TEMPERATURE

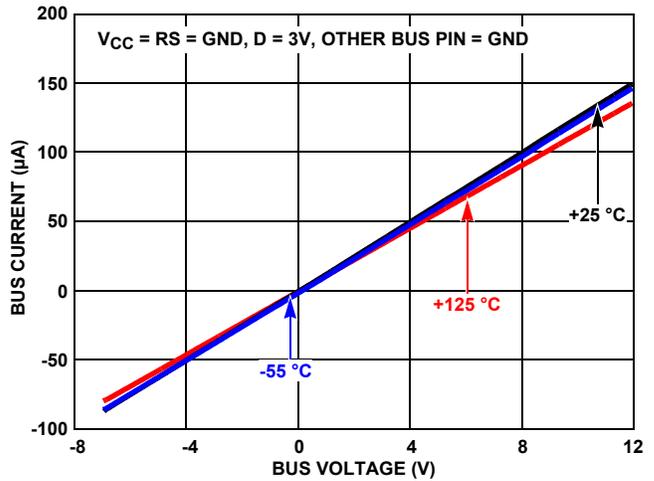


FIGURE 23. BUS PIN LEAKAGE vs VCM AT  $V_{CC} = 0\text{V}$

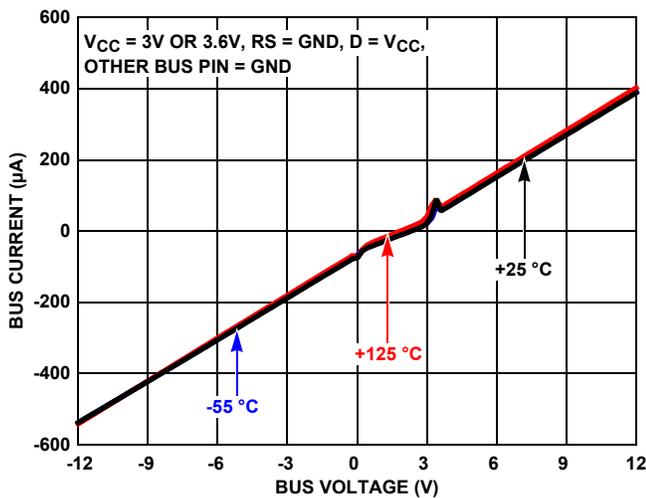


FIGURE 24. BUS PIN LEAKAGE vs  $\pm 12\text{V}$  VCM

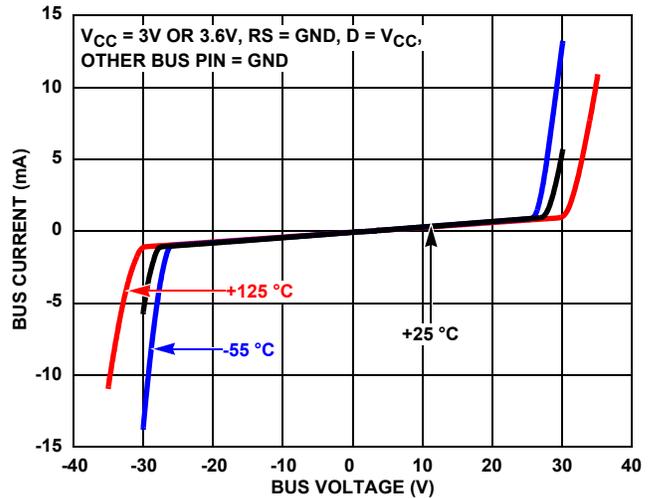


FIGURE 25. BUS PIN LEAKAGE vs  $\pm 35\text{V}$  VCM

## Typical Performance Curves

$C_L = 15\text{pF}$ ,  $T_A = +25^\circ\text{C}$ ; Unless Otherwise Specified. (Continued)

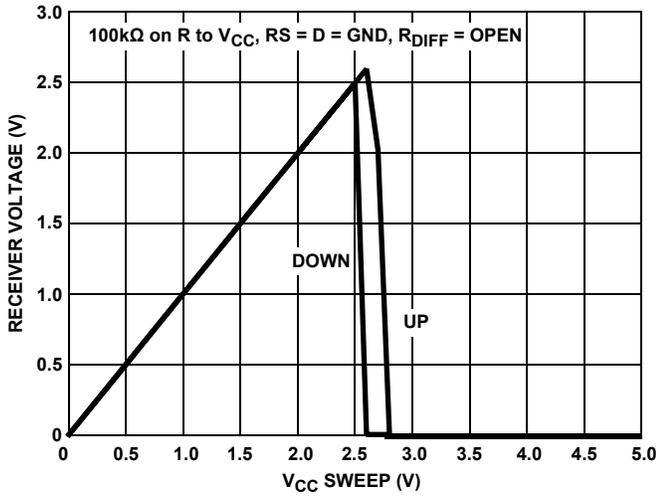


FIGURE 26.  $V_{CC}$  UNDERVOLTAGE LOCKOUT

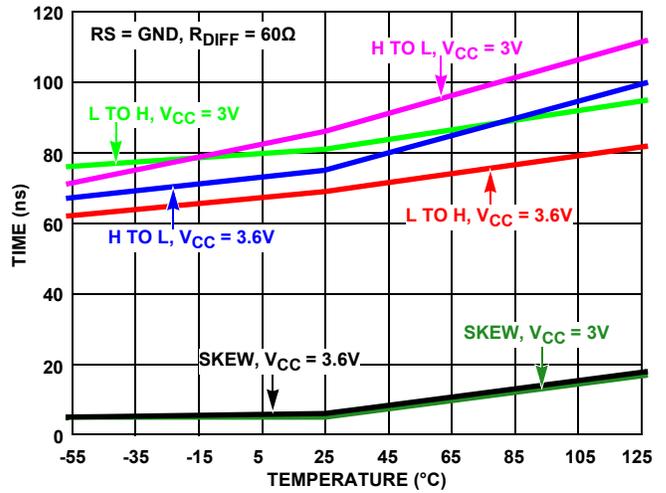


FIGURE 27. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT FAST SPEED

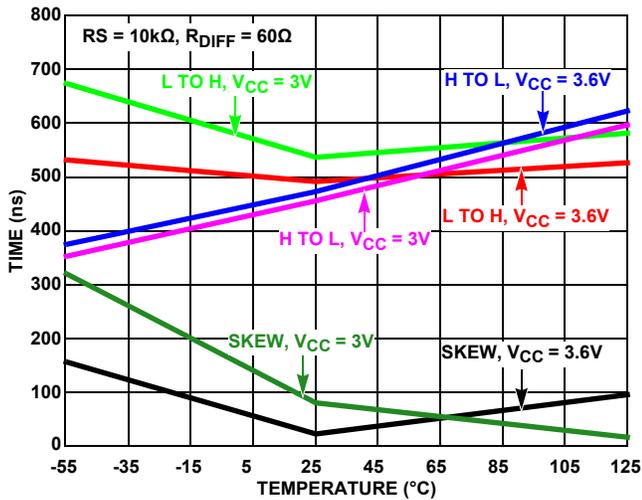


FIGURE 28. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT MEDIUM SPEED

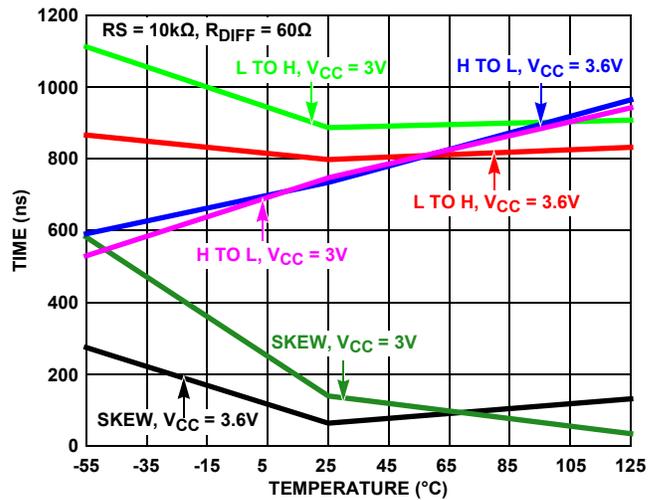


FIGURE 29. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT SLOW SPEED

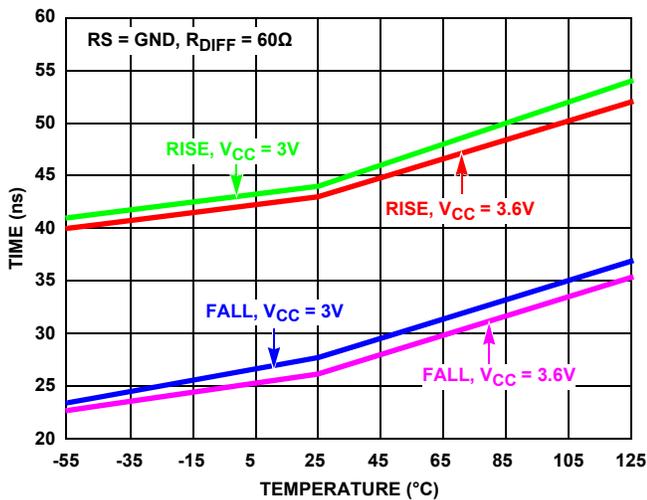


FIGURE 30. TRANSMITTER RISE AND FALL TIMES vs TEMPERATURE AT FAST SPEED

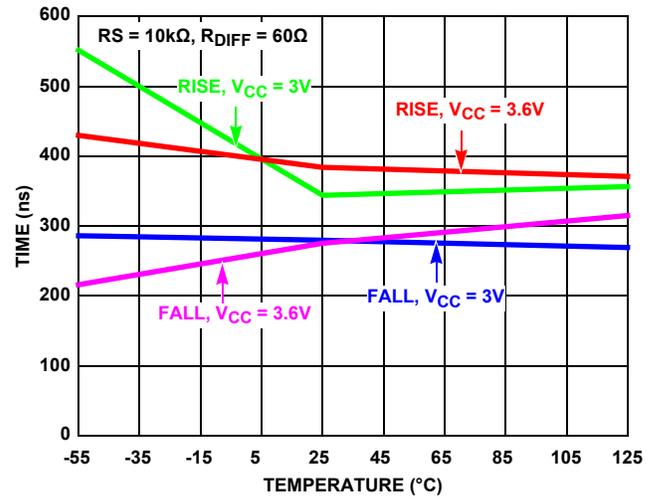


FIGURE 31. TRANSMITTER RISE AND FALL TIMES vs TEMPERATURE AT MEDIUM SPEED

## Typical Performance Curves

$C_L = 15\text{pF}$ ,  $T_A = +25^\circ\text{C}$ ; Unless Otherwise Specified. (Continued)

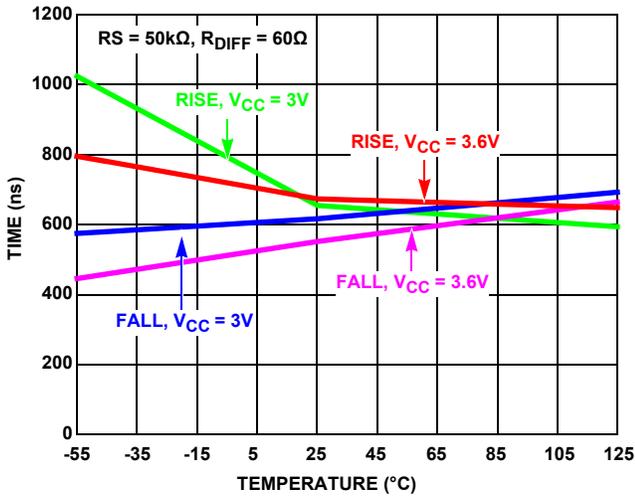


FIGURE 32. TRANSMITTER RISE AND FALL TIMES vs TEMPERATURE AT SLOW SPEED

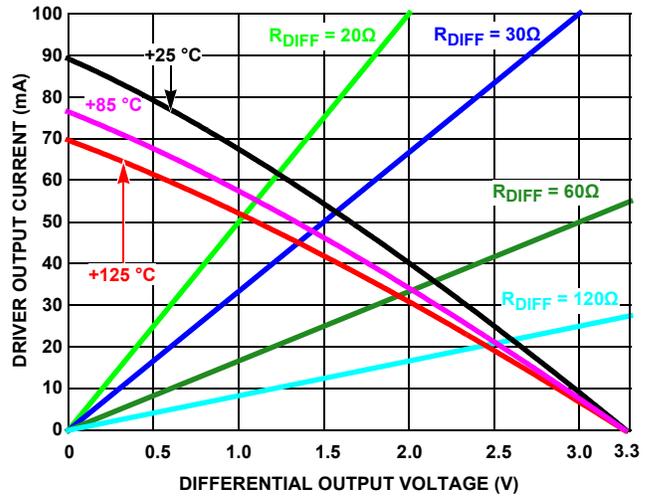


FIGURE 33. DRIVER OUTPUT CURRENT vs DIFFERENTIAL OUTPUT VOLTAGE

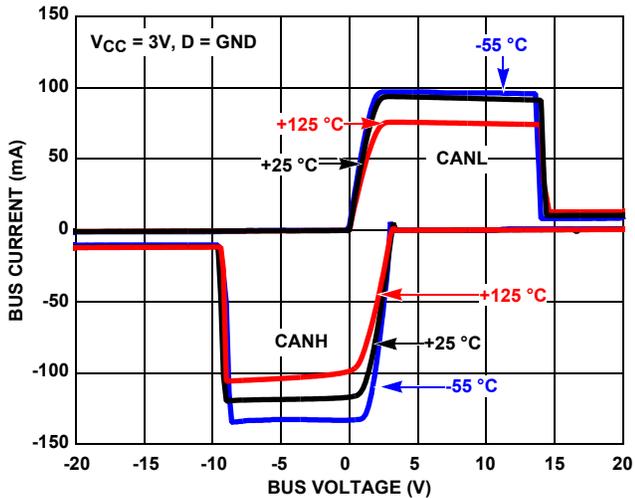


FIGURE 34. DRIVER OUTPUT CURRENT vs SHORT CIRCUIT VOLTAGE vs TEMPERATURE

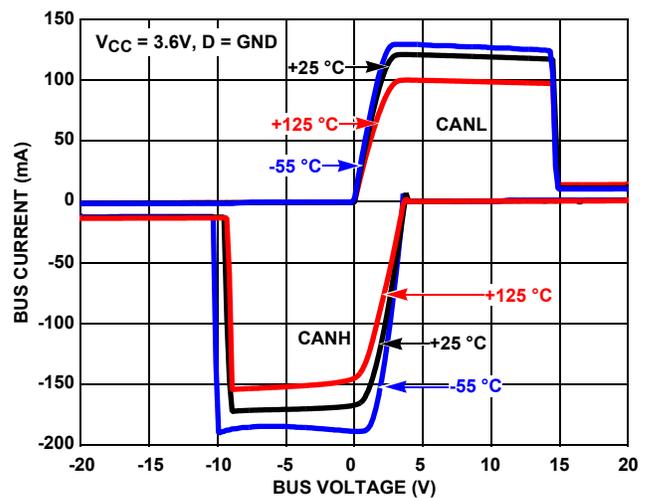


FIGURE 35. DRIVER OUTPUT CURRENT vs SHORT CIRCUIT VOLTAGE vs TEMPERATURE

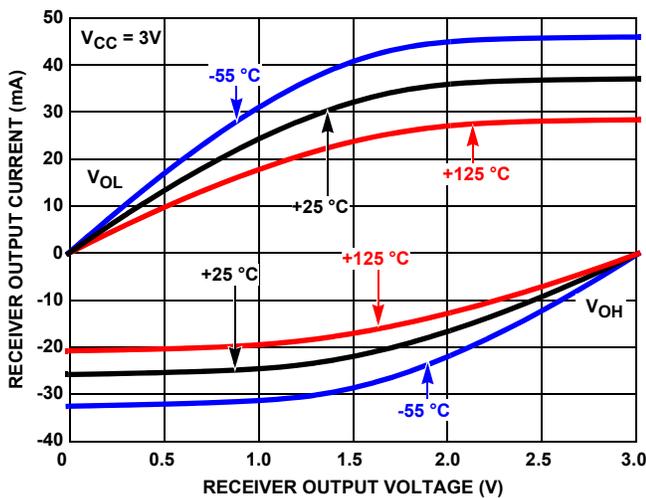


FIGURE 36. RECEIVER OUTPUT CURRENT vs RECEIVER OUTPUT VOLTAGE AT  $V_{CC} = 3\text{V}$

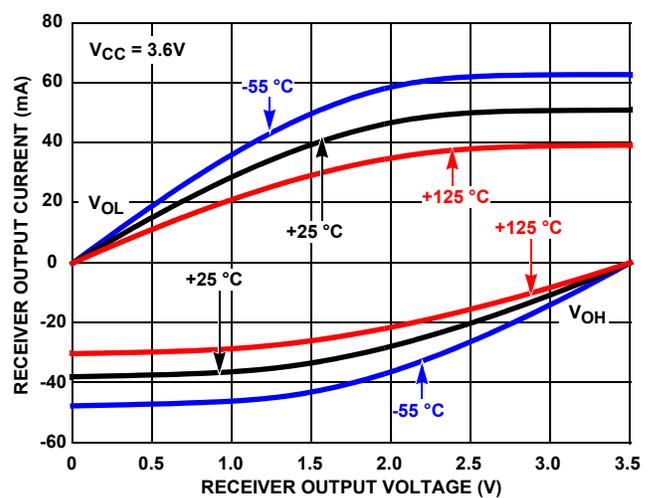


FIGURE 37. RECEIVER OUTPUT CURRENT vs RECEIVER OUTPUT VOLTAGE AT  $V_{CC} = 3.6\text{V}$

## Typical Performance Curves

$C_L = 15\text{pF}$ ,  $T_A = +25^\circ\text{C}$ ; Unless Otherwise Specified. (Continued)

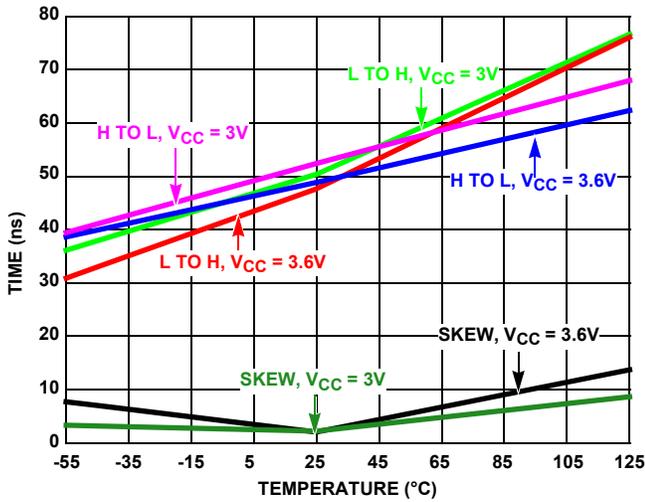


FIGURE 38. RECEIVER PROPAGATION DELAY AND SKEW vs TEMPERATURE

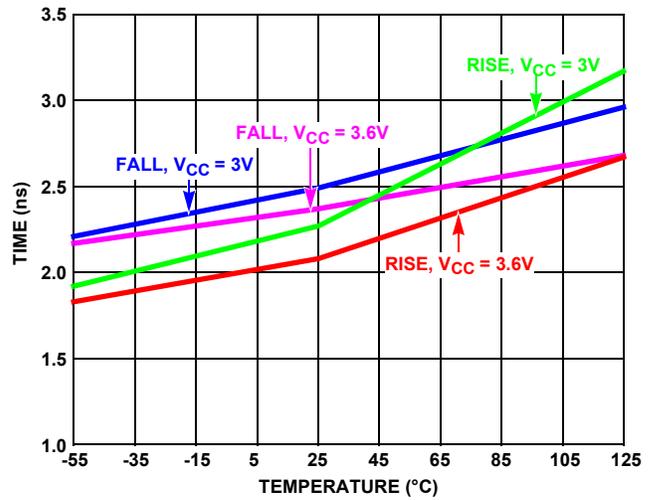


FIGURE 39. RECEIVER RISE AND FALL TIMES vs TEMPERATURE

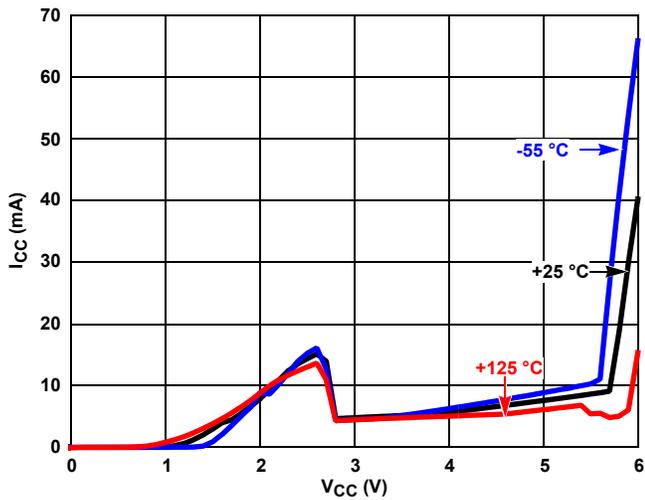


FIGURE 40. SUPPLY CURRENT vs SUPPLY VOLTAGE vs TEMPERATURE

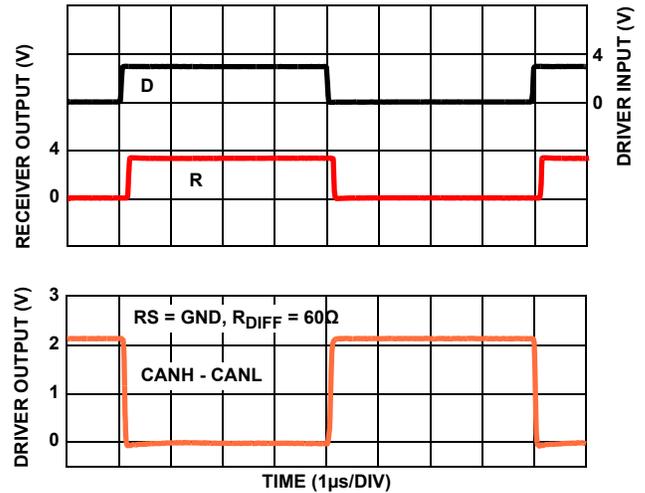


FIGURE 41. FAST DRIVER AND RECEIVER WAVEFORMS

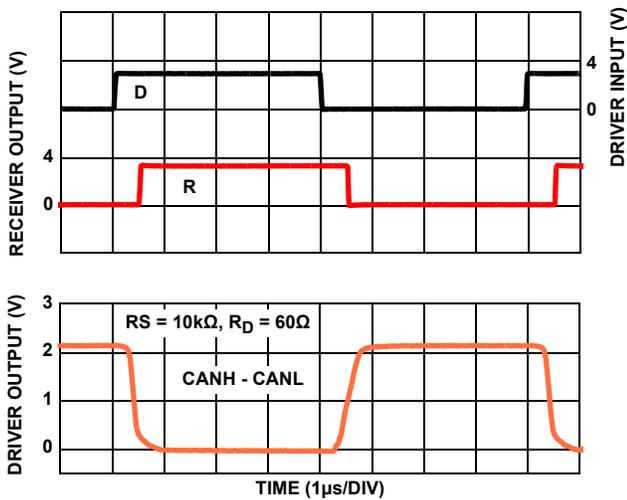


FIGURE 42. MEDIUM DRIVER AND RECEIVER WAVEFORMS

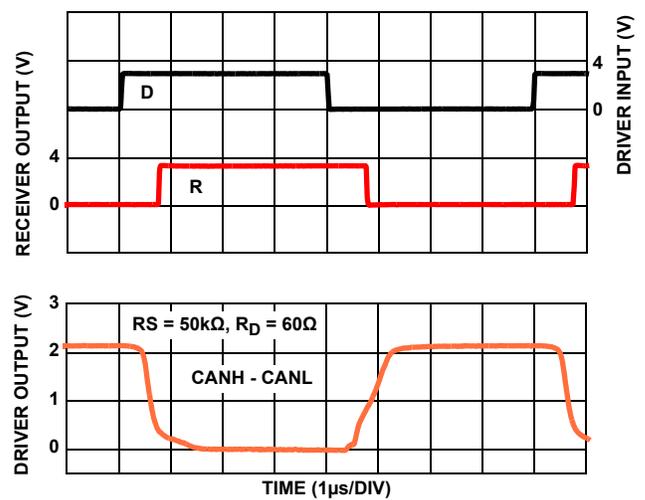


FIGURE 43. SLOW DRIVER AND RECEIVER WAVEFORMS

# ISL72026SEH

## Die Dimensions

2413 $\mu$ m x 3322 $\mu$ m (95 mils x 130.79 mils)  
Thickness: 305 $\mu$ m  $\pm$ 25 $\mu$ m (12 mils  $\pm$ 1 mil)

## Interface Materials

### GLASSIVATION

Type: 12k $\text{Å}$  Silicon Nitride on 3k $\text{Å}$  Oxide

### TOP METALLIZATION

Type: 300 $\text{Å}$  TiN on 2.8 $\mu$ m AlCu  
In Bondpads, TiN has been removed.

### BACKSIDE FINISH

Silicon

### PROCESS

P6SOI

## Assembly Related Information

### SUBSTRATE POTENTIAL

Floating

### Additional Information

### WORST CASE CURRENT DENSITY

$1.6 \times 10^5 \text{A/cm}^2$

### TRANSISTOR COUNT

4055

### Weight of Packaged Device

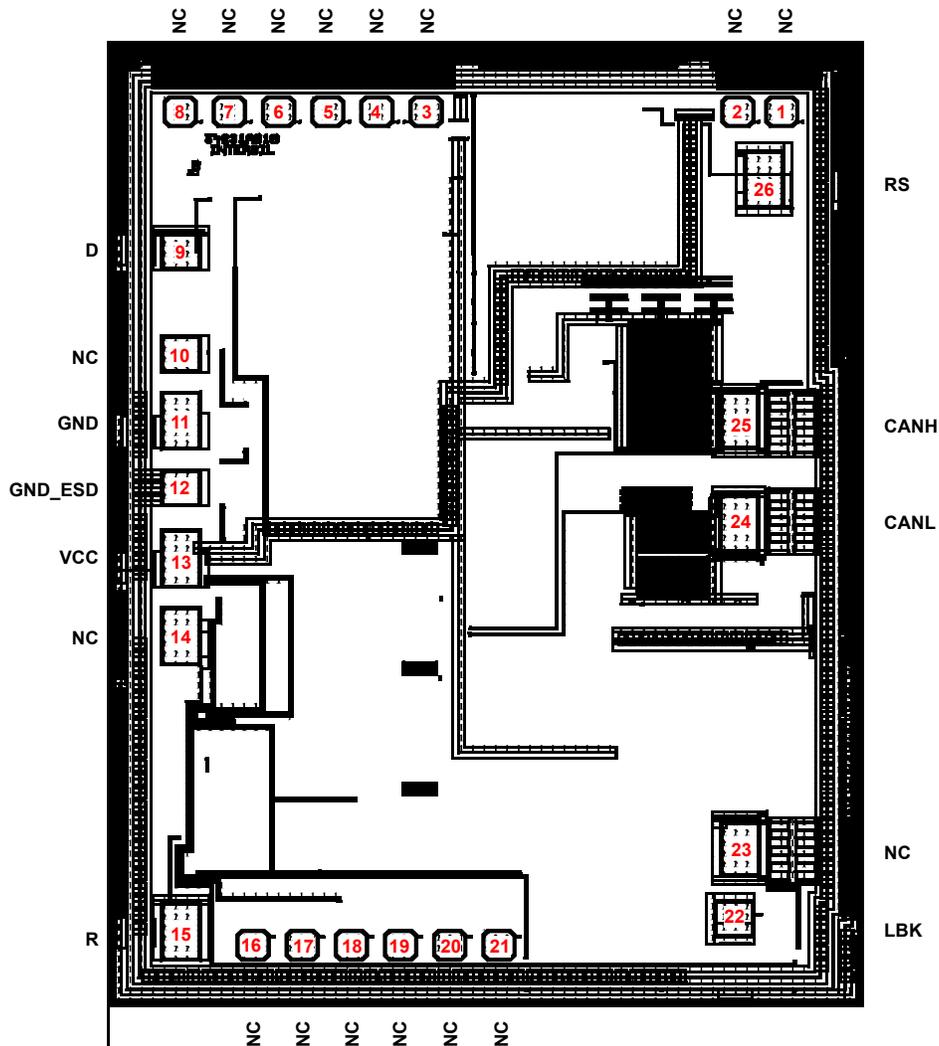
0.31 grams

### Lid Characteristics

Finish: Gold

Potential: Grounded, tied to package pin 2

## Metalization Mask Layout



# ISL72026SEH

TABLE 3. ISL72026SEH DIE LAYOUT X-Y COORDINATES

PAD NUMBER	PAD NAME	X ( $\mu\text{m}$ )	Y ( $\mu\text{m}$ )	X	Y
1	NC	90.0	90.0	901.4	1365.6
2	NC	90.0	90.0	767.4	1365.6
3	NC	90.0	90.0	-183.23	1365.6
4	NC	90.0	90.0	-333.25	1365.6
5	NC	90.0	90.0	-483.25	1365.6
6	NC	90.0	90.0	-633.25	1365.6
7	NC	90.0	90.0	-783.25	1365.6
8	NC	90.0	90.0	-933.25	1365.6
9	D	110.0	110.0	-931.1	901.85
10	NC	110.0	110.0	-931.1	563.25
11	GND	110.0	180.0	-931.1	342.25
12	GND_ESD	110.0	110.05	-931.1	119.42
13	VCC	110.0	180.0	-931.1	-115.05
14	NC	110.0	180.05	-931.1	-371.08
15	R	110.0	180.0	-931.1	-1350.0
16	NC	90.0	90.0	-711.1	-1394.95
17	NC	90.0	90.0	-561.1	-1394.95
18	NC	90.0	90.0	-411.1	-1394.95
19	NC	90.0	90.0	-261.1	-1394.95
20	NC	90.0	90.0	-111.1	-1394.95
21	NC	90.0	90.0	38.9	-1394.95
22	LBK	110.0	110.0	756.9	-1307.3
23	NC	110.0	180.0	775.3	-1072.3
24	CANL	110.0	180.0	772.1	2.15
25	CANH	110.0	180.05	772.1	343.33
26	RS	110.0	180.0	848.1	1140.6

NOTE: Origin of coordinates is the center of the die. NC - No Connect

## Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to the web to make sure that you have the latest revision.

DATE	REVISION	CHANGE
August 16, 2016	FN8762.3	"Absolute Maximum Ratings" on page 4 changed voltage value in VCC to GND With/Without Ion Beam From: -0.3V to 4.5V To: -0.3V to 5.5V.
April 28, 2016	FN8762.2	- Updated title. - Updated the test condition for Output Rise Time on page 6. - Changed maximum data rate from 1Mbps to 5Mbps in the following locations: - Second paragraph and "Features" section on page 1. - In "Overview" on page 10.
November 9, 2015	FN8762.1	Absolute Maximum Ratings table on page 4: changed the value for "CANH, CANL, VREF Under Ion Beam" from $\pm 16V$ to $\pm 18V$ .
October 26, 2015	FN8762.0	Initial Release

## About Intersil

Intersil Corporation is a leading provider of innovative power management and precision analog solutions. The company's products address some of the largest markets within the industrial and infrastructure, mobile computing and high-end consumer markets.

For the most updated datasheet, application notes, related documentation and related parts, please see the respective product information page found at [www.intersil.com](http://www.intersil.com).

You may report errors or suggestions for improving this datasheet by visiting [www.intersil.com/ask](http://www.intersil.com/ask).

Reliability reports are also available from our website at [www.intersil.com/support](http://www.intersil.com/support)

For additional products, see [www.intersil.com/en/products.html](http://www.intersil.com/en/products.html)

Intersil products are manufactured, assembled and tested utilizing ISO9001 quality systems as noted in the quality certifications found at [www.intersil.com/en/support/qualandreliability.html](http://www.intersil.com/en/support/qualandreliability.html)

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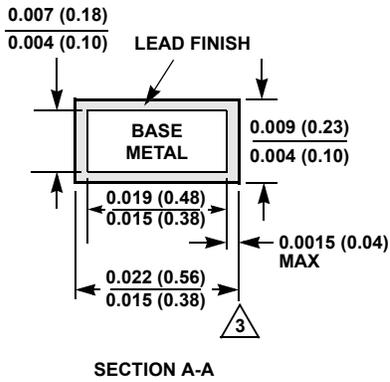
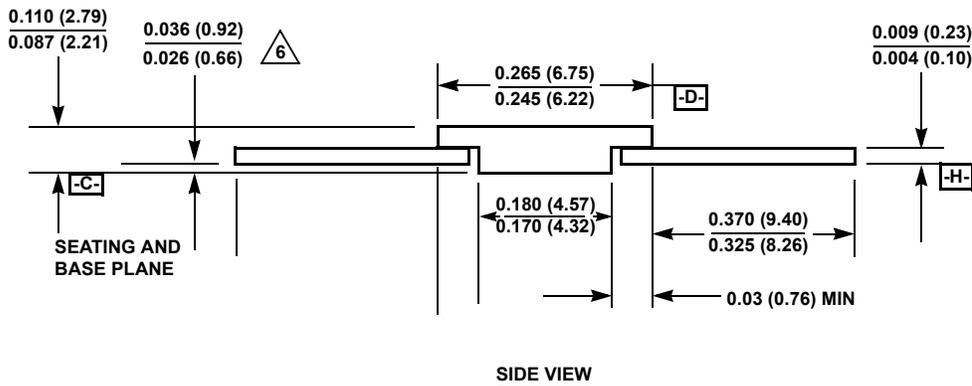
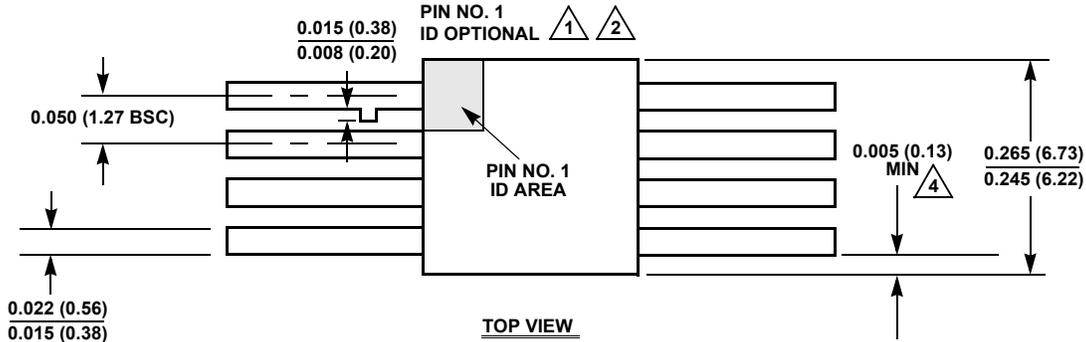
For information regarding Intersil Corporation and its products, see [www.intersil.com](http://www.intersil.com)

## Package Outline Drawing

### K8.A

8 LEAD CERAMIC METAL SEAL FLATPACK PACKAGE

Rev 4, 12/14



#### NOTES:

1. Index area: A notch or a pin one identification mark shall be located adjacent to pin one and shall be located within the shaded area shown. The manufacturer's identification shall not be used as a pin one identification mark. Alternately, a tab may be used to identify pin one.
2. If a pin one identification mark is used in addition to or instead of a tab, the limits of the tab dimension do not apply.
3. The maximum limits of lead dimensions (section A-A) shall be measured at the centroid of the finished lead surfaces, when solder dip or tin plate lead finish is applied.
4. Measure dimension at all four corners.
5. For bottom-brazed lead packages, no organic or polymeric materials shall be molded to the bottom of the package to cover the leads.
6. Dimension shall be measured at the point of exit (beyond the meniscus) of the lead from the body. Dimension minimum shall be reduced by 0.0015 inch (0.038mm) maximum when solder dip lead finish is applied.
7. Dimensioning and tolerancing per ANSI Y14.5M - 1982.
8. Controlling dimension: INCH.